### **UART Program Examples**

#### 1. Introduction

This Application Note provides to customers C and Assembler program examples for UART.

These examples are developped for the different configuration modes of this feature.

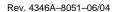
#### 1.1 References

• Atmel 8051 Microcontrollers Hardware Manual



8051 Microcontrollers

### **Application Note**







#### 2. C Example

## 2.1 Mode 1 (8 bit) with Timer1

```
* @file $RCSfile: uart_t1.c,v $
 * Copyright (c) 2004 Atmel.
 * Please read file license.txt for copyright notice.
 * @brief This file is an example to use uart with timer1.
 * UART will echo a received data.
 * This file can be parsed by Doxygen for automatic documentation
 * generation.
 * Put here the functional description of this file within the software
 * architecture of your program.
 * @version $Revision: 1.0 $ $Name: $
/* @section INCLUDES */
#include "reg_c51.h"
char uart_data;
/**
 * FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
 * timer 1 in mode 2 (8 bits auto reload timer).
 * FUNCTION INPUTS: void
 * FUNCTION_OUTPUTS: void
 * /
void main (void)
 SCON = 0x50; /* uart in mode 1 (8 bit), REN=1 */
 TMOD = TMOD | 0x20; /* Timer 1 in mode 2 */
 TH1 = 0xFD;
                              /* 9600 Bds at 11.059MHz */
 TL1 = 0xFD;
                 /* 9600 Bds at 11.059MHz */
 ES = 1;
                 /* Enable serial interrupt*/
 EA = 1;
                 /* Enable global interrupt */
             /* Timer 1 run */
 TR1 = 1;
                            /* endless */
while(1);
}
 * FUNCTION_PURPOSE: serial interrupt, echo received data.
 * FUNCTION_INPUTS: P3.0(RXD) serial input
 * FUNCTION_OUTPUTS: P3.1(TXD) serial output
void serial_IT(void) interrupt 4
 if (RI == 1)
                          /* if reception occur */
   RI = 0;
                     /* clear reception flag for next reception */
                             /* Read receive data */
   uart_data = SBUF;
   SBUF = uart_data;
                             /* Send back same data on uart*/
                     /* if emission occur */
 else TI = 0;
                   /* clear emission flag for next emission*/
```

### 2.2 Mode 1 (8 bit) with Timer2

```
* @file $RCSfile: uart_t2.c,v $
 * Copyright (c) 2004 Atmel.
 * Please read file license.txt for copyright notice.
 * @brief This file is an example to use uart with timer2.
 * UART will echo a received data.
 * This file can be parsed by Doxygen for automatic documentation
 * generation.
 * Put here the functional description of this file within the software
 * architecture of your program.
* @version $Revision: 1.0 $ $Name: $
* /
/* @section INCLUDES */
#include "reg c51.h"
char uart_data;
 * FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
 * timer 2 in baud rate generator mode.
 * FUNCTION_INPUTS: void
 * FUNCTION_OUTPUTS: void
 * /
void main (void)
 SCON = 0x50; /* uart in mode 1 (8 bit), REN=1 */
  T2CON &= 0 \times F0;
                              /* EXEN2=0; TR2=0; C/T2#=0; CP/RL2#=0; */
  T2CON = 0x30;
                               /* RCLK = 1; TCLK=1; */
  TH2=0xFF;
                               /* init value */
  TL2=0xFD;
                                /* init value */
  RCAP2H=0xFF;
                               /* reload value, 115200 Bds at 11.059MHz */
                                /* reload value, 115200 Bds at 11.059MHz */
  RCAP2L=0xFD;
  ES = 1;
                /* Enable serial interrupt */
  EA = 1;
                /* Enable global interrupt */
  TR2 = 1;
                                /* Timer 2 run */
while(1);
                             /* endless */
}
/**
 * FUNCTION_PURPOSE: serial interrupt, echo received data.
 * FUNCTION_INPUTS: P3.0(RXD) serial input
 * FUNCTION_OUTPUTS: P3.1(TXD) serial output
void serial_IT(void) interrupt 4
{
 if (RI == 1)
                          /* if reception occur */
                      /* clear reception flag for next reception */
   RI = 0;
   uart_data = SBUF;
                             /* Read receive data */
   SBUF = uart_data;
                             /* Send back same data on uart*/
 }
 else TI = 0;
                            /* if emission occur */
  }
                             /* clear emission flag for next emission*/
```





# 2.3 Mode 1 (8 bit) with internal baud rate generator

```
* @file $RCSfile: uart_int_brg.c,v $
* Copyright (c) 2004 Atmel.
* Please read file license.txt for copyright notice.
* @brief This file is an example to use uart with internal baud rate
 * UART will echo a received data.
* This file can be parsed by Doxygen for automatic documentation
* generation.
* Put here the functional description of this file within the software
 * architecture of your program.
* @version $Revision: 1.0 $ $Name: $
/* @section INCLUDES */
#include "reg_c51.h"
char uart_data;
/**
* FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
* internal baud rate generator.
* FUNCTION_INPUTS: void
* FUNCTION_OUTPUTS: void
* /
void main (void)
  CKCON0 = 0x7F;
  SCON = 0x50; /* uart in mode 1 (8 bit), REN=1 */
  BDRCON &=0xEE;
                               /* BRR=0; SRC=0; */
  BDRCON =0 \times 0 E;
                               /* TBCK=1; RBCK=1; SPD=1 */
                               /* 9600 Bds at 11.059MHz */
  BRL=0xFD;
  ES = 1;
                /* Enable serial interrupt*/
  EA = 1;
                /* Enable global interrupt */
  BDRCON =0 \times 10;
                               /* Baud rate generator run*/
                               /* endless */
  while(1);
}
/**
* FUNCTION_PURPOSE: serial interrupt, echo received data.
* FUNCTION_INPUTS: P3.0(RXD) serial input
* FUNCTION OUTPUTS: P3.1(TXD) serial output
void serial_IT(void) interrupt 4
{
 if (RI == 1)
                          /* if reception occur */
                     /* clear reception flag for next reception */
   RI = 0;
                             /* Read receive data */
   uart_data = SBUF;
                            /* Send back same data on uart*/
   SBUF = uart_data;
 }
 else TI = 0;
                               /* if emission occur */
                             /* clear emission flag for next emission*/
}
```

#### 2.4 Mode 3 (8 bit) Multiprocessor communications

#### 2.4.1 Master

```
/**
* @file $RCSfile: uart_multiproc_master.c,v $
* Copyright (c) 2004 Atmel.
* Please read file license.txt for copyright notice.
* @brief This file is an example to use uart with timer in
* multiprocessor mode.
* This file can be parsed by Doxygen for automatic documentation
* generation.
* Put here the functional description of this file within the software
* architecture of your program.
* @version $Revision: 1.0 $ $Name: $
/* @section INCLUDES */
#include "reg c51.h"
char uart_data;
char exemple_send_data=0x55;
char TxOK=0;
* FUNCTION_PURPOSE: This file set up uart in mode 3 (9 bits uart) with
* timer 1 in baud rate generator mode.
* FUNCTION_INPUTS: P3.2(INT0)
* FUNCTION_OUTPUTS: void
void main (void)
 SCON = 0xF0; /* uart in mode 3 (9 bit), REN=1 */
 SADDR=0x01;
                             /* local address */
 SADEN=0xFF;
                              /* address mask */
 TMOD = TMOD \mid 0x20;
                              /* Timer 1 in mode 2 */
 TH1 = 0xFD;
                              /* 9600 Bds at 11.059MHz */
 TL1 = 0xFD;
                 /* 9600 Bds at 11.059MHz */
 ES = 1;
                /* Enable serial interrupt */
                /* Enable global interrupt */
 EA = 1;
                              /* Timer 1 run */
 TR1 = 1;
 while(1)
                              /* endless */
  while(P3_2);
                              /* wait P3_2(INT0)=0 */
  while(!P3 2);
                               /* wait P3 2(INT0)=1 */
    TB8 = 1;
                               /* address mode */
    TxOK=1;
                               /* set software flag */
    SBUF = 0x03;
                               /* send slave adress */
```





```
while(TxOK);
                               /* wait the stop bit transmition */
    TB8 = 0;
                               /* data mode */
    TxOK=1;
                               /* set software flag */
    SBUF = exemple_send_data; /* send data */
    while(TxOK);
                               /* wait the stop bit transmition */
}
/**
* FUNCTION_PURPOSE: serial interrupt.
 * FUNCTION_INPUTS: P3.0(RXD) serial input
 * FUNCTION_OUTPUTS: none
* /
void serial_IT(void) interrupt 4
{
 if (TI == 1)
 {
                         /* if reception occur */
     TI=0;
                     /* clear transmition flag for next transmition */
                       /* clear software transmition flag */
     TxOK=0;
  }
 if (RI == 1)
                         /* if reception occur */
    RI = 0;
                      /* clear reception flag for next reception */
     if(RB8) SM2=0;
                               /* go into data mode */
     else
        uart_data = SBUF;
                              /* Read receive data */
        SM2=1;
                    /* return into address mode after receive data */
        }
  }
}
 * @file $RCSfile:uart_multiproc_slave.c,v $
 * Copyright (c) 2004 Atmel.
 * Please read file license.txt for copyright notice.
 * @brief This file is an example to use uart with timer in
 * multiprocessor mode.
 * Slave will echo a received data to master.
 * This file can be parsed by Doxygen for automatic documentation
 * Put here the functional description of this file within the software
 * architecture of your program.
```

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2.4.2 Slave

```
* @version $Revision: 1.0 $ $Name: $
/* @section INCLUDES */
#include "reg_c51.h"
char uart data;
bit TxOK=0;
bit echo=0;
 * FUNCTION_PURPOSE: This file set up uart in mode 3 (9 bits uart) with
 * timer 1 in baud rate generator mode.
 * FUNCTION INPUTS: void
 * FUNCTION OUTPUTS: P3.1(TXD) serial output
void main (void)
 SCON = 0xF0; /* uart in mode 3 (9 bit), REN=1 */
  SADDR=0x03;
                              /* local address */
  SADEN=0xFF;
                              /* address mask */
 TMOD = TMOD \mid 0x20 ;
                            /* Timer 1 in mode 2 */
 TH1 = 0xFD;
                             /* 9600 Bds at 11.059MHz */
 TL1 = 0xFD; /* 9600 Bds at 11.059MHz */
 ES = 1;
                 /* Enable serial interrupt */
                /* Enable global interrupt */
 EA = 1;
  TR1 = 1;
                               /* Timer 1 run */
   while(1)
                               /* endless */
     {
        while(!echo);
                              /* wait data to echo */
        echo = 0;
                               /* disable echo */
        TB8 = 1;
                              /* address mode */
        TxOK=1;
                              /* set software flag */
        SBUF = 0 \times 01;
                              /* send master adress */
        while(TxOK);
                               /* wait the stop bit transmition */
        TB8 = 0;
                              /* data mode */
        TxOK=1;
                               /* set software flag */
        SBUF = uart_data;
                              /* send data */
        while(TxOK);
                               /* wait the stop bit transmition */
     }
}
 * FUNCTION_PURPOSE: serial interrupt, receive data to master
 * FUNCTION_INPUTS: P3.0(RXD) serial input
 * FUNCTION OUTPUTS: none
 * /
```





```
void serial IT(void) interrupt 4
 if (TI == 1)
 {
                       /* if reception occur */
     TI=0;
                    /* clear transmition flag for next transmition */
     TxOK=0;
                      /* clear software transmition flag */
  }
 if (RI == 1)
                        /* if reception occur */
                    /* clear reception flag for next reception */
    RI = 0;
                             /* go into data mode */
     if(RB8) SM2=0;
     else
                             /* Read receive data */
       uart_data = SBUF;
                            /* return into address mode after receive data
        echo=1;
                             /* enable echo */
     }
 }
```

#### 2.5 SFR Register Definition

```
/*----*/
/* BYTE Register */
Sfr (P0 , 0x80);
Sbit (P0_7 , 0x80, 7);
Sbit (P0_6 , 0x80, 6);
Sbit (P0_5 , 0x80, 5);
Sbit (P0_4 , 0x80, 4);
Sbit (P0_3 , 0x80, 3);
Sbit (P0_2 , 0x80, 2);
Sbit (P0_1 , 0x80, 1);
Sbit (P0_0 , 0x80, 0);
Sfr (P1 , 0x90);
Sbit (P1_7 , 0x90, 7);
Sbit (P1_6 , 0x90, 6);
Sbit (P1_5 , 0x90, 5);
Sbit (P1_4 , 0x90, 4);
Sbit (P1_3 , 0x90, 3);
Sbit (P1_2 , 0x90, 2);
Sbit (P1_1 , 0x90, 1);
Sbit (P1_0 , 0x90, 0);
Sfr (P2 , 0xA0);
Sbit (P2_7 , 0xA0 , 7);
Sbit (P2_6 , 0xA0, 6);
Sbit (P2_5 , 0xA0, 5);
Sbit (P2_4 , 0xA0, 4);
Sbit (P2_3 , 0xA0, 3);
Sbit (P2_2 , 0xA0, 2);
Sbit (P2_1 , 0xA0, 1);
Sbit (P2_0 , 0xA0, 0);
Sfr (P3 , 0xB0);
Sbit (P3_7 , 0xB0, 7);
Sbit (P3_6 , 0xB0, 6);
Sbit (P3_5 , 0xB0, 5);
Sbit (P3_4 , 0xB0, 4);
Sbit (P3_3 , 0xB0, 3);
Sbit (P3_2 , 0xB0, 2);
Sbit (P3_1 , 0xB0, 1);
Sbit (P3_0 , 0xB0, 0);
Sbit (RD , 0xB0, 7);
```





```
Sbit (WR , 0xB0, 6);
Sbit (T1 , 0xB0, 5);
Sbit (T0 , 0xB0, 4);
Sbit (INT1 , 0xB0, 3);
Sbit (INTO , 0xB0, 2);
Sbit (TXD , 0xB0, 1);
Sbit (RXD , 0xB0, 0);
Sfr (P4 , 0xC0);
Sbit (P4_7 , 0xC0, 7);
Sbit (P4_6 , 0xC0, 6);
Sbit (P4_5 , 0xC0, 5);
Sbit (P4_4 , 0xC0, 4);
Sbit (P4_3 , 0xC0, 3);
Sbit (P4_2 , 0xC0, 2);
Sbit (P4_1 , 0xC0, 1);
Sbit (P4_0 , 0xC0, 0);
Sfr (P5 , 0xE8);
Sbit (P5_7 , 0xE8, 7);
Sbit (P5_6 , 0xE8, 6);
Sbit (P5_5 , 0xE8, 5);
Sbit (P5_4 , 0xE8, 4);
Sbit (P5_3 , 0xE8, 3);
Sbit (P5_2 , 0xE8, 2);
Sbit (P5_1 , 0xE8, 1);
Sbit (P5_0 , 0xE8, 0);
Sfr (PSW , 0xD0);
Sbit (CY , 0xD0 , 7);
Sbit (AC , 0xD0
                  , 6);
Sbit (F0 , 0 \times D0 , 5);
Sbit (RS1 , 0xD0 , 4);
Sbit (RS0 , 0xD0 , 3);
Sbit (OV , 0xD0 , 2);
Sbit (UD , 0xD0 , 1);
Sbit (P , 0xD0 , 0);
Sfr (ACC , 0xE0);
Sfr (B , 0xF0);
Sfr (SP , 0x81);
Sfr (DPL , 0x82);
Sfr (DPH , 0x83);
Sfr (PCON , 0x87);
Sfr (CKCON0 , 0x8F);
Sfr (CKCON1 , 0xAF);
```

```
/*----*/
Sfr (TCON , 0x88);
Sbit (TF1 , 0x88, 7);
Sbit (TR1 , 0x88, 6);
Sbit (TF0 , 0x88, 5);
Sbit (TR0 , 0x88, 4);
Sbit (IE1 , 0x88, 3);
Sbit (IT1 , 0x88, 2);
Sbit (IE0 , 0x88, 1);
Sbit (IT0 , 0x88, 0);
Sfr (TMOD , 0x89);
Sfr (T2CON , 0xC8);
Sbit (TF2 , 0xC8, 7);
Sbit (EXF2 , 0xC8, 6);
Sbit (RCLK , 0xC8, 5);
Sbit (TCLK , 0xC8, 4);
Sbit (EXEN2 , 0xC8, 3);
Sbit (TR2
         , 0xC8, 2);
Sbit (C_T2 , 0xC8, 1);
Sbit (CP_RL2, 0xC8, 0);
Sfr (T2MOD , 0xC9);
Sfr (TL0 , 0x8A);
Sfr (TL1 , 0x8B);
Sfr (TL2 , 0xCC);
Sfr (TH0 , 0x8C);
Sfr (TH1 , 0x8D);
Sfr (TH2 , 0xCD);
Sfr (RCAP2L , 0xCA);
Sfr (RCAP2H , 0xCB);
Sfr (WDTRST , 0xA6);
Sfr (WDTPRG , 0xA7);
/*----*/
Sfr (SCON , 0x98);
Sbit (SM0 , 0x98, 7);
Sbit (FE
         , 0x98, 7);
Sbit (SM1 , 0x98, 6);
Sbit (SM2 , 0x98, 5);
Sbit (REN , 0x98, 4);
Sbit (TB8 , 0x98, 3);
Sbit (RB8 , 0x98, 2);
Sbit (TI
         , 0x98, 1);
Sbit (RI
          , 0x98, 0);
Sfr (SBUF , 0x99);
Sfr (SADEN , 0xB9);
```





```
Sfr (SADDR , 0xA9);
/*----*/
Sfr (BRL , 0x9A);
Sfr (BDRCON , 0x9B);
/*----*/
Sfr (IEN0 , 0xA8);
Sfr (IEN1 , 0xB1);
Sfr (IPH0 , 0xB7);
Sfr (IPH1 , 0xB3);
Sfr (IPLO , 0xB8);
Sfr (IPL1 , 0xB2);
/* IENO */
Sbit (EA , 0xA8, 7);
Sbit (EC , 0xA8, 6);
Sbit (ET2 , 0xA8, 5);
Sbit (ES , 0xA8, 4);
Sbit (ET1 , 0xA8, 3);
Sbit (EX1 , 0xA8, 2);
Sbit (ETO , 0xA8, 1);
Sbit (EX0 , 0xA8, 0);
/*----*/
Sfr (CCON , 0xD8);
Sfr (CMOD , 0xD9);
Sfr (CH , 0xF9);
Sfr (CL , 0xE9);
Sfr (CCAPOH , 0xFA);
Sfr (CCAPOL , 0xEA);
Sfr (CCAPMO , 0xDA);
Sfr (CCAP1H , 0xFB);
Sfr (CCAP1L , 0xEB);
Sfr (CCAPM1 , 0xDB);
Sfr (CCAP2H , 0xFC);
Sfr (CCAP2L , 0xEC);
Sfr (CCAPM2 , 0xDC);
Sfr (CCAP3H , 0xFD);
Sfr (CCAP3L , 0xED);
Sfr (CCAPM3 , 0xDD);
Sfr (CCAP4H , 0xFE);
Sfr (CCAP4L , 0xEE);
Sfr (CCAPM4 , 0xDE);
/* CCON */
```

```
Sbit (CF , 0xD8, 7);
Sbit (CR , 0xD8, 6);
Sbit (CCF4 , 0xD8, 4);
Sbit (CCF3 , 0xD8, 3);
Sbit (CCF2 , 0xD8, 2);
Sbit (CCF1 , 0xD8, 1);
Sbit (CCF0 , 0xD8, 0);
/*----*/
Sfr ( SSCON , 0x93);
Sfr ( SSCS , 0x94);
Sfr ( SSDAT , 0x95);
Sfr ( SSADR , 0x96);
Sfr ( PI2, 0xF8);
Sbit (PI2_1 , 0xF8, 1);
Sbit (PI2_0 , 0xF8, 0);
/*----*/
Sfr ( CKSEL , 0x85 );
Sfr ( OSCCON , 0x86 );
Sfr ( CKRL , 0x97 );
/*----*/ Keyboard control registers -----*/
Sfr ( KBLS , 0x9C );
Sfr ( KBE , 0x9D );
Sfr ( KBF , 0x9E );
/*----*/
Sfr ( SPCON, 0xC3 );
Sfr ( SPSTA, 0xC4 );
Sfr ( SPDAT, 0xC5 );
/*---- Misc -----*/
Sfr( AUXR , 0x8E);
Sfr ( AUXR1, 0xA2);
Sfr ( FCON, 0xD1);
/*---- E data -----*/
Sfr ( EECON, 0xD2 );
```





#### 3. Assembler 51 Examples

# 3.1 UART Mode 1 (8 bit) with Timer1

```
$INCLUDE (reg_c51.INC)
org 000h
ljmp begin
org 23h
ljmp serial_IT
; * FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
; * timer 1 in mode 2 (8 bits auto reload timer).
; * FUNCTION_INPUTS: void
; * FUNCTION_OUTPUTS: void
; */
org 0100h
begin:
 MOV SCON, #50h; /* uart in mode 1 (8 bit), REN=1 */
 ORL TMOD, #20h;
                      /* Timer 1 in mode 2 */
 MOV TH1, #0FDh;
                              /* 9600 Bds at 11.059MHz */
 MOV TL1, #0FDh; /* 9600 Bds at 11.059MHz */
 SETB ES;
            /* Enable serial interrupt*/
                 /* Enable global interrupt */
 SETB EA;
 SETB TR1; /* Timer 1 run */
  JMP $;
                               /* endless */
; * FUNCTION_PURPOSE: serial interrupt, echo received data.
; * FUNCTION_INPUTS: P3.0(RXD) serial input
; * FUNCTION_OUTPUTS: P3.1(TXD) serial output
; */
serial_IT:
  JNB RI, EMIT_IT
                              ; test if it is a reception
                ; clear reception flag for next reception
      CLR RI
 MOV A, SBUF
                             ; read data from uart
       MOV SBUF, A
                        ; write same data to uart
 LJMP END_IT
EMIT_IT:
  CLR TI
                             ; clear transmition flag for next transmition
END_IT:
  RETI
```

end

#### 3.2 Mode 1 (8 bit) with Timer2

```
$INCLUDE (reg_c51.INC)
org 000h
ljmp begin
org 23h
ljmp serial_IT
;/**
; * FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
; * timer 2 in baud rate generator mode.
; * FUNCTION_INPUTS: void
; * FUNCTION_OUTPUTS: void
; */
org 0100h
begin:
 MOV SCON, #50h; /* uart in mode 1 (8 bit), REN=1 */
                               /* EXEN2=0; TR2=0; C/T2#=0; CP/RL2#=0; */
  ANL T2CON, #0F0h;
  ORL T2CON, #30h;
                               /* RCLK = 1; TCLK=1; */
   MOV TH2, #0FFh;
                               /* init value */
   MOV TL2, #0FDh;
                               /* init value */
   MOV RCAP2H, #0FFh;
                               /* reload value, 115200 Bds at 11.059MHz */
  MOV RCAP2L, #0FDh;
                               /* reload value, 115200 Bds at 11.059MHz */
  SETB ES;
             /* Enable serial interrupt */
                /* Enable global interrupt */
  SETB EA;
   SETB TR2;
                                /* Timer 2 run */
   JMP $;
                                /* endless */
;/**
; * FUNCTION_PURPOSE: serial interrupt, echo received data.
; * FUNCTION_INPUTS: P3.0(RXD) serial input
; * FUNCTION_OUTPUTS: P3.1(TXD) serial output
; */
serial_IT:
   JNB RI, EMIT_IT
                               ; test if it is a reception
      CLR RI ; clear reception flag for next reception
 MOV A, SBUF
                              ; read data from uart
       MOV SBUF, A
                         ; write same data to uart
 LJMP END_IT
EMIT IT:
  CLR TI
                              ; clear transmition flag for next transmition
END_IT:
  RETI
```



end



#### 3.3 Mode 1 (8 bit) with internal baud rate generator

```
$INCLUDE
          (reg_c51.INC)
org 000h
ljmp begin
org 23h
ljmp serial_IT
;/**
; * FUNCTION_PURPOSE: This file set up uart in mode 1 (8 bits uart) with
; * internal baud rate generator.
; * FUNCTION_INPUTS: void
; * FUNCTION_OUTPUTS: void
; */
org 0100h
begin:
 MOV SCON, #50h; /* uart in mode 1 (8 bit), REN=1 */
  ANL BDRCON, #0EEh;
                               /* BRR=0; SRC=0; */
  ORL BDRCON, #0Eh;
                              /* TBCK=1; RBCK=1; SPD=1 */
  MOV BRL, #0FDh;
                               /* 9600 Bds at 11.059MHz */
  SETB ES; /* Enable serial interrupt*/
                 /* Enable global interrupt */
  SETB EA;
                               /* Baud rate generator run*/
   ORL BDRCON, #10h;
   JMP $;
                               /* endless */
;/**
; * FUNCTION_PURPOSE: serial interrupt, echo received data.
; * FUNCTION_INPUTS: P3.0(RXD) serial input
; * FUNCTION_OUTPUTS: P3.1(TXD) serial output
; */
serial_IT:
  JNB RI, EMIT_IT
                              ; test if it is a reception
      CLR RI ; clear reception flag for next reception
 MOV A, SBUF
                             ; read data from uart
                        ; write same data to uart
       MOV SBUF, A
 LJMP END_IT
EMIT_IT:
  CLR TI
                            ; clear transmition flag for next transmition
END_IT:
  RETI
end
```

#### 3.4 Mode 3 (9 bit) Multiprocessor Communications

3.4.1 Master

```
$INCLUDE (reg_c51.INC)
TxOK BIT 21H; software flag
org 000h
ljmp begin
org 23h
limp serial IT
;/**
; * FUNCTION_PURPOSE: This file set up uart in mode 3 (9 bits uart) with
; * timer 1 in baud rate generator mode.
; * FUNCTION_INPUTS: P3.2(INT0)
; * FUNCTION_OUTPUTS: void
; */
org 0100h
begin:
 MOV SCON, #0F0h; /* uart in mode 3 (9 bit), REN=1 */
  MOV SADDR, #01h;
                              /* local address */
  MOV SADEN, #0FFh;
                              /* address mask */
 ORL TMOD, #20h;
                              /* Timer 1 in mode 2 */
 MOV TH1, #0FDh;
                              /* 9600 Bds at 11.059MHz */
 MOV TL1, #0FDh; /* 9600 Bds at 11.059MHz */
 SETB ES; /* Enable serial interrupt*/
                 /* Enable global interrupt */
 SETB EA;
 SETB TR1; /* Timer 1 run */
loop:
                               /* wait P3_2(INT0)=0 */
JB
        P3.2,$;
JNB
        P3.2,$;
                               /* wait P3 2(INT0)=1 */
  SETB
           TB8;
                               /* address mode */
  SETB
           TxOK;
                               /* set software flag */
  MOV
           SBUF,#03h;
                               /* send slave adress */
           TxOK,$;
                               /* wait the stop bit transmition */
  JΒ
                               /* data mode */
  CLR
           TB8;
                               /* set software flag */
           TXOK;
  SETB
                               /* send data example */
  MOV
           SBUF, #55h;
           TxOK,$;
                               /* wait the stop bit transmition */
  JΒ
SJMP
        loop
; * FUNCTION_PURPOSE: serial interrupt,
; * FUNCTION_INPUTS: P3.0(RXD) serial input
```





```
; * FUNCTION OUTPUTS: none
; */
serial_IT:
           TI, END Test TI
  CLR
           ΤI
  CLR
           TxOK
END_Test_TI:
                                /* test if it is a reception */
  JNB
           RI,END_Test_RI;
  CLR
                                /* clear reception flag for next reception */
           RI;
  JNB
           RB8,address_mode
           SM2;
                                /* go into data mode */
  CT.R
  LJMP END Test RB8
address_mode:
                                /* Read receive data */
  MOV
           A,SBUF;
  SETB
           SM2;
                              /* return into address mode after receive data
  MOV
           P2,A
END_Test_RB8:
END_Test_RI:
  RETI
end
$INCLUDE (reg c51.INC)
echo BIT 20H; echo enable bit
TxOK BIT 21H; software flag
org 000h
ljmp begin
org 23h
ljmp serial_IT
 * FUNCTION_PURPOSE: This file set up uart in mode 3 (9 bits uart) with
 * timer 1 in baud rate generator mode.
 * FUNCTION_INPUTS: void
 * FUNCTION_OUTPUTS: void
* /
org 0100h
begin:
 MOV SCON, #0F0h; /* uart in mode 3 (9 bit), REN=1 */
 MOV SADDR, #03h;
                              /* local address */
 MOV SADEN, #0FFh;
                              /* address mask */
 ORL TMOD, #20h;
                              /* Timer 1 in mode 2 */
 MOV TH1, #0FDh;
                              /* 9600 Bds at 11.059MHz */
 MOV TL1, #0FDh; /* 9600 Bds at 11.059MHz */
 SETB ES; /* Enable serial interrupt*/
```

3.4.2 Slave

```
SETB EA;
                /* Enable global interrupt */
 SETB TR1; /* Timer 1 run */
loop:
  JNB
           echo,$;
                              /* wait data to echo */
  CLR
           echo ;
                               /* disable echo */
  SETB
           TB8;
                               /* address mode */
  SETB
           TxOK;
                               /* set software flag */
  MOV
           SBUF,#01h;
                               /* send master adress */
                               /* wait the stop bit transmition */
  JB
           TxOK,$;
           TB8;
                               /* data mode */
  CLR
                               /* set software flag */
  SETB
           TxOK;
                               /* send data */
  MOV
           SBUF, A;
           TxOK,$;
                               /* wait the stop bit transmition */
  JΒ
LJMP
        1000
```

```
;/**
; * FUNCTION_PURPOSE: serial interrupt, echo receive data to master
; * FUNCTION_INPUTS: P3.0(RXD) serial input
; * FUNCTION_OUTPUTS: none
; */
serial_IT:
                              /* if reception occur */
  JNB
           TI,END_Test_TI;
                             /* clear transmition flag for next transmition
  CLR
           TI;
  CLR
           TxOK;
                               /* clear software transmition flag */
END_Test_TI:
                               /* test if it is a reception */
  JNB
           RI,END_Test_RI;
           RI;
                               /* clear reception flag for next reception */
  CLR
  JNB
           RB8,address_mode
           SM2;
                               /* go into data mode */
  CLR
  LJMP END Test RB8
address_mode:
                               /* Read receive data */
  MOV
           A,SBUF;
                  /* return into address mode after receive data */
  SETB
            echo
END_Test_RB8:
END_Test_RI:
  RETI
```



end



# 3.5 SFR Register Definition

\$SAVE \$NOLIST

P0	DATA	80H	
TCONDATA	H88 <i>A</i>		
; TO	CON Bits		
TF1	BIT	8FH	
TR1	BIT	8EH	
TF0	BIT	8DH	
TR0	BIT	8CH	
IE1	BIT	8BH	
IT1	BIT	HA8	
IE0	BIT	89H	
IT0	BIT	88H	
P1	DATA	90H	
SCON	DATA	98H	
; SC	ON Bits -		
SM0	BIT	9FH	
SM1	BIT	9EH	
SM2	BIT	9DH	
REN	BIT	9CH	
TB8	BIT	9вн	
RB8	BIT	9AH	
TI	BIT	99Н	
RI	BIT	98H	
P2	DATA	0A0H	
IEN0	DATA	0A8H	
; IEI	NO Bits -		
EA BI	r0AFH		
EC BITOAEH			
ET2 BITOADH			
ES BITOACH			
ET1 BITOABH			
EX1 BI	гоаан		
ETO BIT	ОА9Н		
EXOBITO2	A8H		
Р3	DATA	0в0н	
; P3			
RD	BIT	0в7н	
WR	BIT	0В6Н	
T1	BIT	0B5H	
TO	BIT	0B4H	
INT1	BIT	0B3H	
T111 T	חדד	ODOM	

INT0

BIT

0B2H

TXD BIT 0B1H RXD BIT 0B0H

P4 DATA 0C0H P5 DATA 0E8H

#### IPL0DATA0B8H

;--- IPLO Bits -----

PPCL BITOBEH

PT2L BIT0BDH

PSL BITOBCH

PT1L BIT0BBH

PX1L BITOBAH

PTOL BITOB9H

PX0LBIT0B8H

T2CON	DATA	0C8H	
; T2			
TF2	BIT	0CFH	
EXF2	BIT	0CEH	
RCLK	BIT	0CDH	
TCLK	BIT	0CCH	
EXEN2	BIT	0СВН	
TR2	BIT	0CAH	
C_T2	BIT	0С9Н	
CP_RL2	BIT	0C8H	
PSW	DATA	0D0H	
; PSW bits			
CY	BIT	0D7H	
AC	BIT	0D6H	
F0	BIT	0D5H	
RS1	BIT	0D4H	
RS0	BIT	0D3H	

#### CCONDATA0D8H

OV BIT

P

;--- CCON bits ---CF BIT ODFH
CR BIT ODCH
CCF4 BIT ODCH
CCF3 BIT ODBH
CCF2 BIT ODAH
CCF1 BIT OD9H
CCF0 BIT OD8H

BIT

ACC DATA 0E0H



0D2H

0D0H



B DATA OFOH

SP DATA 81H DPL DATA 82H

DPH DATA 83H

PCON DATA 87H

TMOD DATA 89H

TL0 DATA 8AH
TL1 DATA 8BH

THO DATA 8CH

TH1 DATA 8DH

AUXRDATA08EH

CKCON0DATA08Fh

SBUF DATA 99H

; -- Baud Rate generator

BRL DATA09AH

BDRCON DATA 09BH

;--- Keyboard

KBLSDATA09CH

KBEDATA09DH

KBFDATA09EH

;--- Watchdog timer

WDTRSTDATA0A6H

WDTPRG DATA0A7H

SADDRDATA0A9H

CKCON1DATA0AFH

IEN1DATA0B1H

IPL1DATA0B2H

IPH1DATA0B3H

IPH0DATA0B7H

SADENDATA0B9H

T2MODDATA 0C9h

RCAP2L DATA 0CAH
RCAP2H DATA 0CBH
TL2 DATA 0CCH
TH2 DATA 0CDH

CMODDATA0D9H

CCAPM0DATA0DAH

CCAPM1DATA0DBH

CCAPM2DATA0DCH

CCAPM3DATA0DDH

CCAPM4DATA0DEH

CHDATA0F9H

CCAP0HDATA0FAH

CCAP1HDATA0FBH

CCAP2HDATA0FCH

CCAP3HDATA0FDH

CCAP4HDATA0FEH

CLDATA0E9H

CCAP0LDATA0EAH

CCAP1LDATA0EBH

CCAP2LDATA0ECH

CCAP3LDATA0EDH

CCAP4LDATA0EEH

; SPI

SPCON DATA 0C3H SPSTA DATA 0C4H SPDAT DATA 0C5H

; TWI

PI2DATA 0F8h

SSCONDATA093H

SSCSDATA094H

SSDATDATA095H

SSADRDATA096H

PI2\_OBIT0F8H

PI2\_1BIT0F9H

; Clock Control

OSCCONDATA086H

CKSELDATA085H

CKRLDATA097H

;MISC

AUXR1DATA0A2H





; Flash control FCON DATA 0D1H

;EEData EECONDATA0D2H

\$RESTORE

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