

DeepCare: A Deep Dynamic Memory Model for Predictive Medicine

Deep For Haramburger

Overview

A modified LSTM architecture is proposed that can analyze **Electronic Health Records** in order to predict **disease progression** and **unplanned readmissions** of patients.

INPUT: N = 12,000 Electronic Health Records from large hospital, 2002-13

OUTPUT: For post-discharge *diabetic* patients: Predicts (1) next stage of disease, (2) intervention recommendation (ARXIV version), and (3) readmission risk

MODEL: Modified LSTM

Electronic Health Records (HR)

Data related to patient admissions,
diagnoses, interventions,
treatments

Disease codes: International Classification
of diseases (ICD)

Created by and stored by institution
(e.g. Hospital)

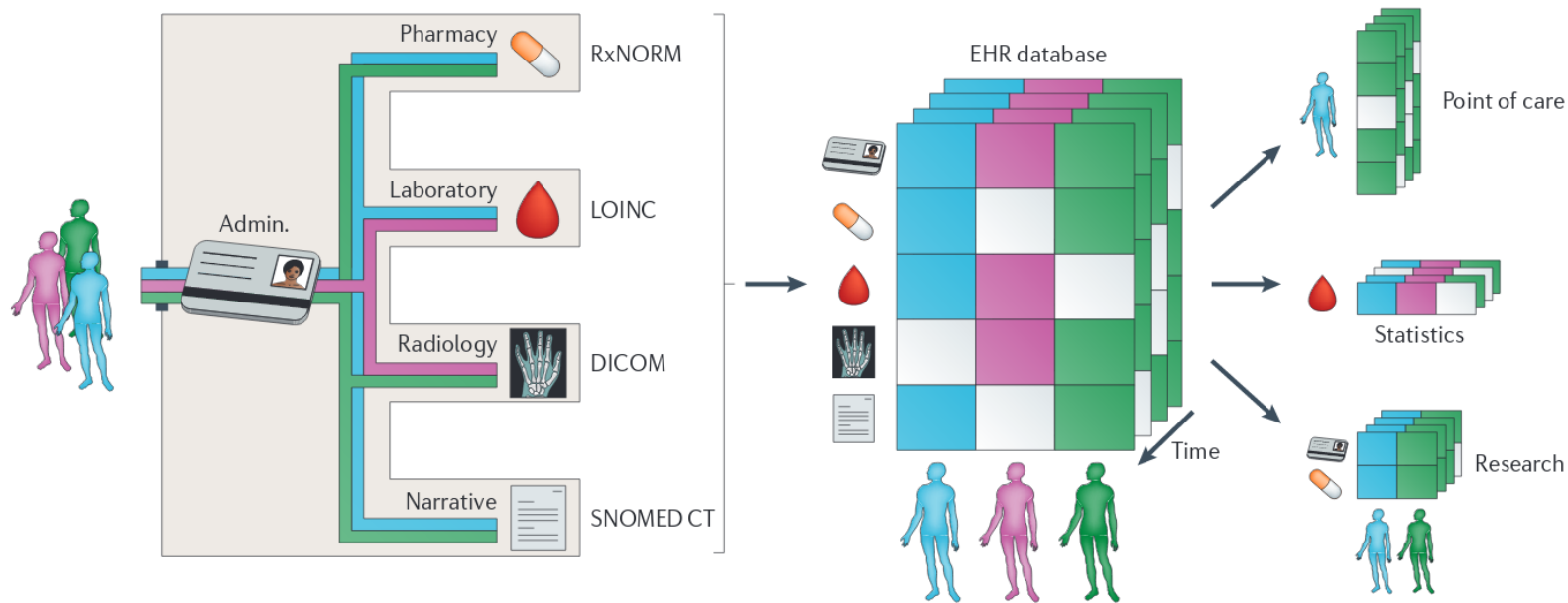
Contains both structured and
unstructured data

Structured: drug prescriptions and dosages

	Assigned diagnosis				Medications			Laboratory values			Demographics	
	C1	C2	C3	C4	M1	M2	M3	L1	L2	L3	D1	D2
Patient 1	■		■	■			■
Patient 2					■
Patient 3				■			■	■
Patient 4	■					■		■	■	
Patient 5			■	■			■
Patient 6		■	
Patient 7				■	■		■	■
Patient 8			■			■				■
Patient 9	■				■	■	■		■
	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮

Simplified representation of EHR
P. Jensen, L. Jensen, S. Brunak - 2012

Electronic Health Records (EHR)



EHR generation, storage and uses
P. Jensen, L. Jensen, S. Brunak - 2012

Electronic Health Records (EHR)

Characteristics of EHR

Variable length

Episodic at Irregular time intervals

Interactions between disease progression and intervention

Both structured and unstructured data

Structured: disease/procedure codes

Unstructured: Doctor's notes

Long term dependencies

DeepCare Architecture

End-to-end dynamic memory network for modeling illness trajectories and predicting future outcomes

Extends the basic LSTM to deal with three issues:

- 1. Variable-size discrete inputs**
- 2. Confounding interactions between disease progression and intervention**
- 3. Irregular timing**

DeepCare Model

Input Construction

Input admission contains **diagnoses codes** (current condition) and **interventions** (procedures and medications)

Codes and interventions are each embedded into embedding matrices*: $A \in \mathbb{R}^{M \times |\mathcal{D}|}$ $B \in \mathbb{R}^{M \times |\mathcal{I}|}$.

Admission t has h diagnoses and k interventions:

$$d_1, d_2, \dots, d_h \in \{1, 2, \dots, |\mathcal{D}|\} \quad s_1, s_2, \dots, s_k \in \{1, 2, \dots, |\mathcal{I}|\}$$



Admission Pooling

*unclear what method is actually implemented for learning the embedding.
It could be Continuous BoW or RNN based

DeepCare Model

Input Construction

*Max Pooling Admission
Pooling*

$$\mathbf{x}_t^i = \max \left(A_i^{d_1}, A_i^{d_2}, \dots, A_i^{d_h} \right)$$

$$\mathbf{p}_t^i = \max \left(B_i^{s_1}, B_i^{s_2}, \dots, B_i^{s_k} \right)$$

Normalized Sum Pooling

$$\mathbf{x}_t^i = \frac{A_i^{d_1} + A_i^{d_2} + \dots + A_i^{d_h}}{\sqrt{|A_i^{d_1} + A_i^{d_2} + \dots + A_i^{d_h}|}}$$

$$\mathbf{p}_t^i = \frac{B_i^{s_1} + B_i^{s_2} + \dots + B_i^{s_k}}{\sqrt{|B_i^{s_1} + B_i^{s_2} + \dots + B_i^{s_k}|}}$$

Mean

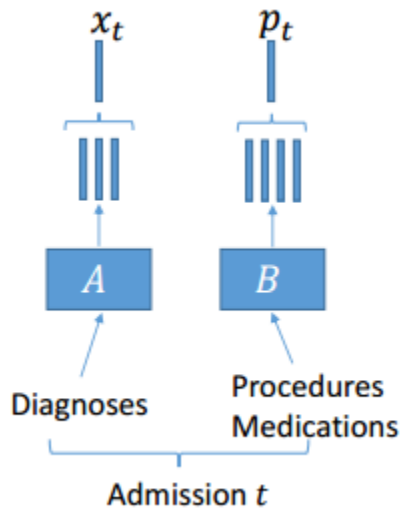
$$\mathbf{x}_t = \frac{A^{d_1} + A^{d_2} + \dots + A^{d_h}}{h}$$

$$\mathbf{p}_t = \frac{B^{s_1} + B^{s_2} + \dots + B^{s_k}}{k}$$

DeepCare Model

Input Construction

Final admission embedding is a $2M$ dimension vector $[x_t, p_t]$



DeepCare Model

High Level Architecture

Given input admission embedding ($[\mathbf{x}_t, \mathbf{p}_t]$), admission type (m_t), and elapsed time between current admission and previous one (Δt).

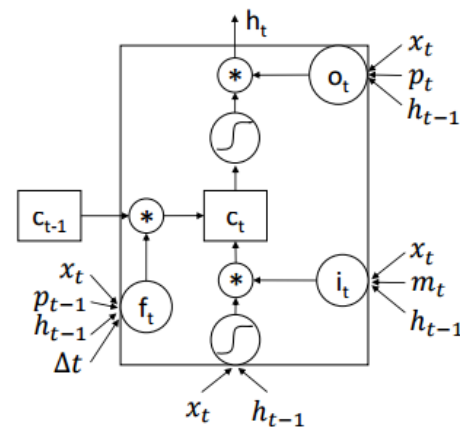
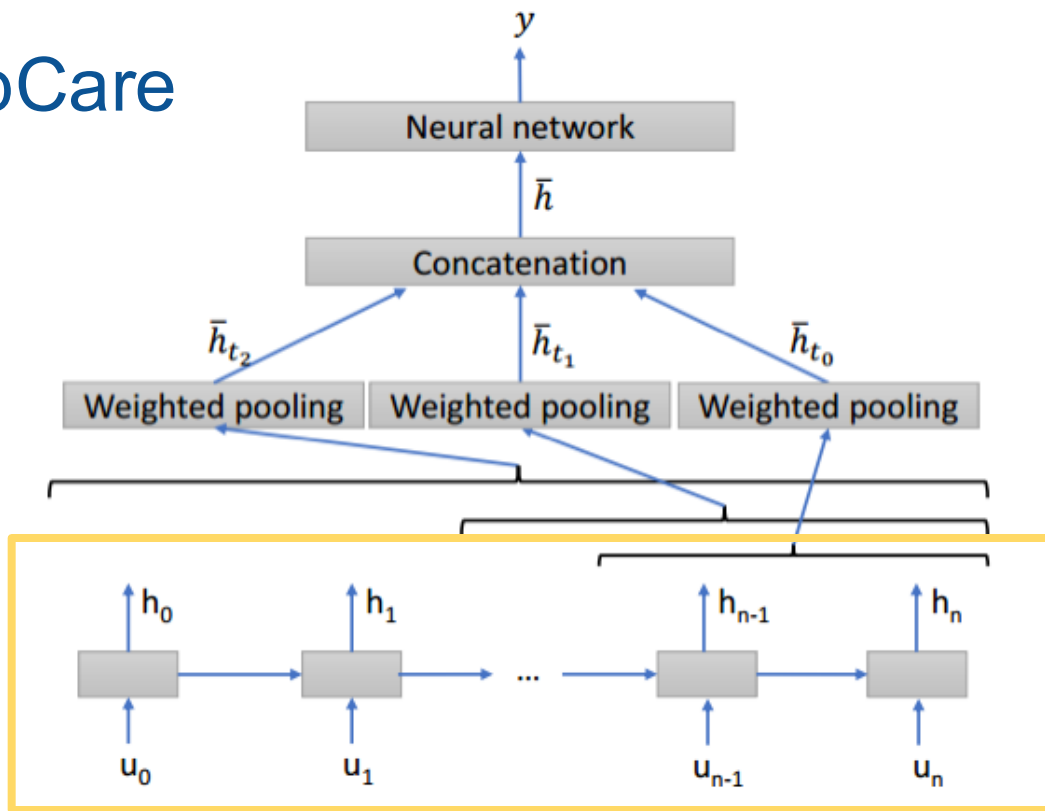
Input sequence: $\mathbf{u}_0, \mathbf{u}_1, \dots, \mathbf{u}_n$ $\mathbf{u}_t = [\mathbf{x}_t, \mathbf{p}_t, m_t, \Delta t]$.

LSTM output sequence: distributed illness states $\mathbf{h}_0, \mathbf{h}_1, \dots, \mathbf{h}_n$, where $\mathbf{h}_t \in \mathbb{R}^K$

Aggregate illness states: $\bar{\mathbf{h}} = \{\mathbf{h}_0, \mathbf{h}_1, \dots, \mathbf{h}_n\}$, where $\bar{\mathbf{h}} \in \mathbb{R}^{sK}$ for s scales.

Outcome estimate: $P(y \mid \mathbf{u}_{0:n}) = P(\text{nnet}_y(\text{pool}\{\text{LSTM}(\mathbf{u}_{0:n})\}))$

DeepCare



$$q_{\Delta_{t-1:t}} = \left(\frac{\Delta_{t-1:t}}{60}, \left(\frac{\Delta_{t-1:t}}{180} \right)^2, \left(\frac{\Delta_{t-1:t}}{365} \right)^3 \right)$$

DeepCare Model

Modified LSTM Structure

Incorporating admission type

$$\mathbf{i}_t = \frac{1}{m_t} \sigma(W_i \mathbf{x}_t + U_i \mathbf{h}_{t-1} + \mathbf{b}_i) \quad m_t = 1 \text{ if the admission method is unplanned, } m_t = 2 \text{ otherwise.}$$

Modeling Effect of Interventions

$$\mathbf{o}_t = \sigma(W_o \mathbf{x}_t + U_o \mathbf{h}_{t-1} + P_o \mathbf{p}_t + \mathbf{b}_o)$$

P_o is the intervention weight matrix for the output gate and \mathbf{p}_t is intervention at time step t .

$$\mathbf{f}_t = \sigma(W_f \mathbf{x}_t + U_f \mathbf{h}_{t-1} + P_f \mathbf{p}_{t-1} + \mathbf{b}_f)$$

\mathbf{p}_{t-1} is intervention embedded vector at time step $t - 1$ and P_f is the intervention weight matrix

DeepCare Model

Modified LSTM Structure

Dealing with Time Irregularity

1. Natural Time Decay

$$\mathbf{f}_t \leftarrow d(\Delta_{t-1:t}) \mathbf{f}_t$$

$\Delta_{t-1:t}$ is the time passed between step $t - 1$ and step t .
 $d(\Delta_{t-1:t}) = [\log(e + \Delta_{t-1:t})]^{-1}$, where $\Delta_{t-1:t}$ is measured in days

1. Parametric Time

$$\mathbf{f}_t = \sigma \left(W_f \mathbf{x}_t + U_f \mathbf{h}_{t-1} + Q_f \mathbf{q}_{\Delta_{t-1:t}} + P_f \mathbf{p}_{t-1} + \mathbf{b}_f \right)$$

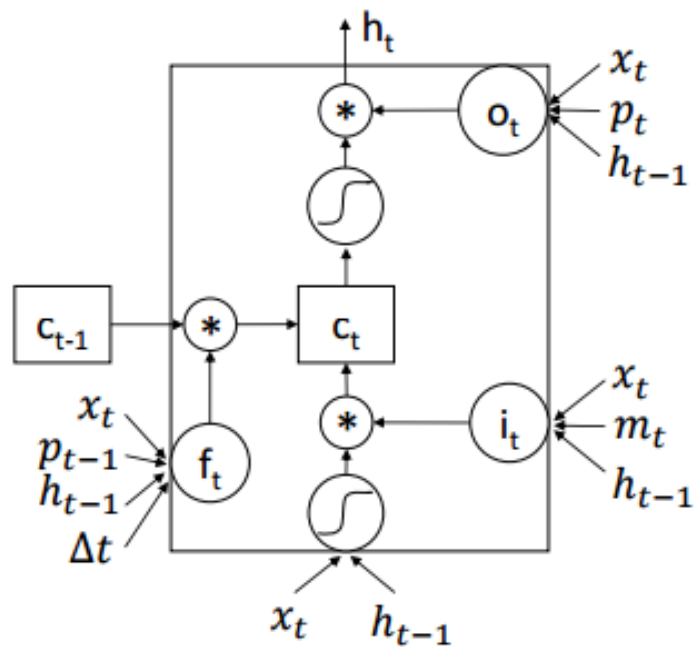
$\mathbf{q}_{\Delta_{t-1:t}}$ is a vector derived from the time difference $\Delta_{t-1:t}$:

$$\mathbf{q}_{\Delta_{t-1:t}} = \left(\frac{\Delta_{t-1:t}}{60}, \left(\frac{\Delta_{t-1:t}}{180} \right)^2, \left(\frac{\Delta_{t-1:t}}{365} \right)^3 \right)$$

Ex. Third-order effects:

DeepCare Model

Modified LSTM Structure



DeepCare Model

Multiscale Pooling

Problem: max-pooling only reflects a single illness state in patient's history

Solution: DeepCare uses a simple attention mechanism for pooling

Weighted sum over all historical states

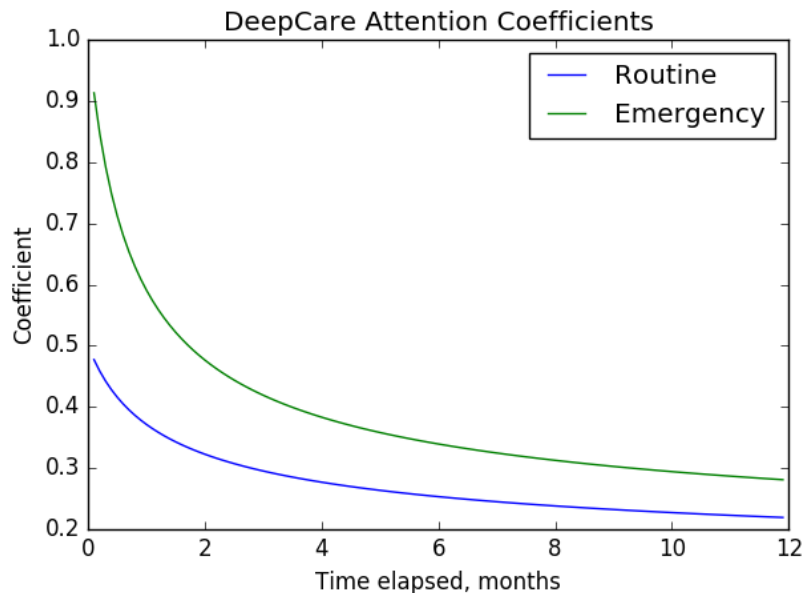
Recent events more heavy

Emergency admissions more heavy

Illness states pooled over multiple

$$\bar{h} = \left(\sum_{t=t_0}^n r_t h_t \right) / \sum_{t=t_0}^n r_t$$

$$r_t = [m_t + \log(1 + \Delta_{t:n})]^{-1}$$



DeepCare Model

Model FC/Readout layers

Fully-connected hidden layer

$$\mathbf{a}_h = \sigma(U_h \bar{\mathbf{h}} + \mathbf{b}_h)$$

Softmax readout layer

$$\begin{aligned} \mathbf{z}_y &= U_y \mathbf{a}_h + \mathbf{b}_y \\ P(y \mid \mathbf{u}_{1:n}) &= f_{prob}(\mathbf{z}_y) \end{aligned}$$

DeepCare Model

Training

Cross-entropy loss via SGD with minibatch size 16

Learning rate adjusts to loss decreases

After 5 iterations of no change, cut LR in half

Regularization

L2-regularization on LSTM outputs

Dropout on initial embedding layer and hidden FC layer

Pretraining

Results

Performance of DeepCare assessed on two fronts:

1. Prediction of future disease diagnosis

1. Prediction of readmission within 12 months after discharge

Predicting future disease diagnoses

- Predict the next n_{pred} diagnoses after each discharge
- 243 possible disease diagnoses

Table 1. Precision@ n_{pred} diagnoses prediction.

Model	$n_{pred} = 1$	$n_{pred} = 2$	$n_{pred} = 3$
Markov	55.1	34.1	24.3
Plain RNN	63.9	58.0	52.0
DeepCare (interven. + param. time)	66.0	59.7	54.1

Markov model: memoryless disease transition probabilities:

$$P\left(d_t^i \mid d_{t+1}^j\right) \text{ from disease } d^j \text{ to } d^i \text{ at time } t$$

Probability of d_t^i as next disease :

$$\frac{1}{|D_t|} \sum_{j \in D_t} P\left(d_t^i \mid d_{t+1}^j\right)$$

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Predicting disease diagnoses using LSTM output:

output states \mathbf{h}_t

$$P(y_t = l \mid \mathbf{x}_{1:t}) = \text{softmax}(\mathbf{v}_l^\top \mathbf{h}_t)$$

label specific parameters \mathbf{v}_l

Predicting unplanned readmission

- a discharge is randomly chosen as prediction point
- unplanned readmission after 12 months is predicted

	Model	F-score (%)
1	SVM (<i>max-pooling</i>)	64.0
2	SVM (<i>sum-pooling</i>)	66.7
3	Random Forests (<i>max-pooling</i>)	68.3
4	Random Forests (<i>sum-pooling</i>)	71.4
5	LSTM (<i>mean-pooling + logit. regress.</i>)	75.9
6	DeepCare (<i>mean-pooling + nnets</i>)	76.5
7	DeepCare (<i>[interven. + time decay] + recent.multi.pool. + nnets</i>)	77.1
8	DeepCare (<i>[interven. + param. time] + recent.multi.pool. + nnets</i>)	79.1

F-score is harmonic mean of the precision and recall:
$$F_1 = 2 \frac{1}{\frac{1}{recall} + \frac{1}{precision}}$$

Contribution of time irregularity to predicting unplanned readmission

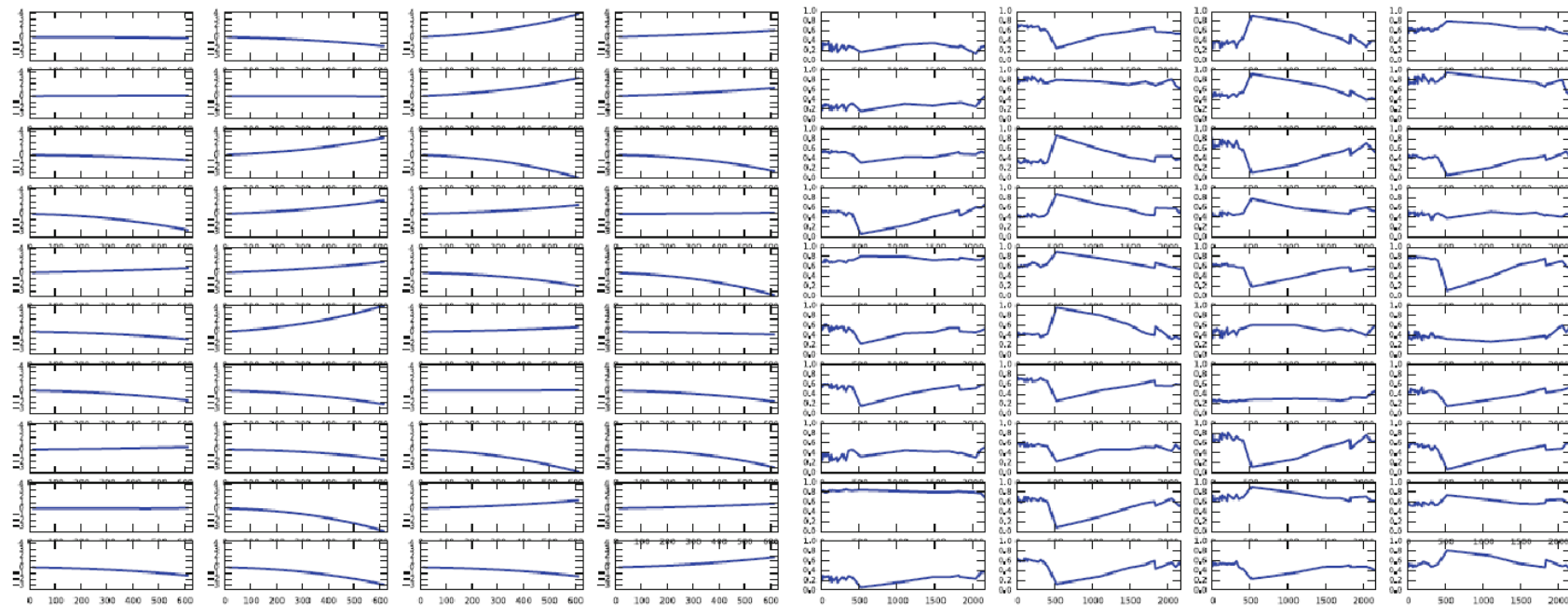
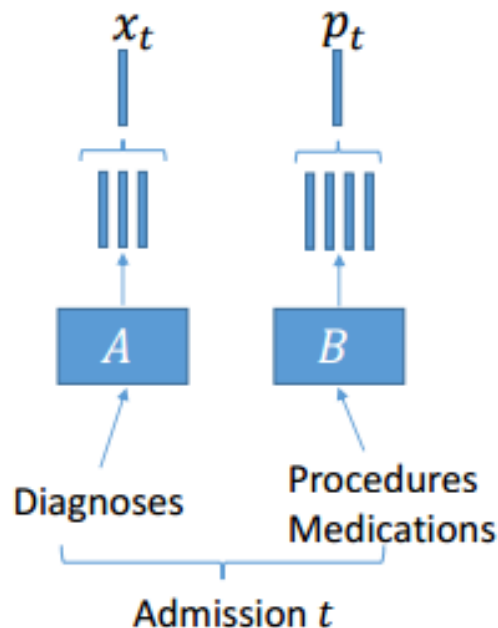


Fig. 4. (Left) 40 channels of forgetting due to time elapsed. (Right) The forget gates of a patient in the course of their illness.

$$f_t = \sigma \left(W_f x_t + U_f h_{t-1} + Q_f q_{\Delta_{t-1:t}} + P_f p_{t-1} + b_f \right) \quad q_{\Delta_{t-1:t}} = (\Delta_{t-1:t}, \Delta_{t-1:t}^2, \Delta_{t-1:t}^3)$$

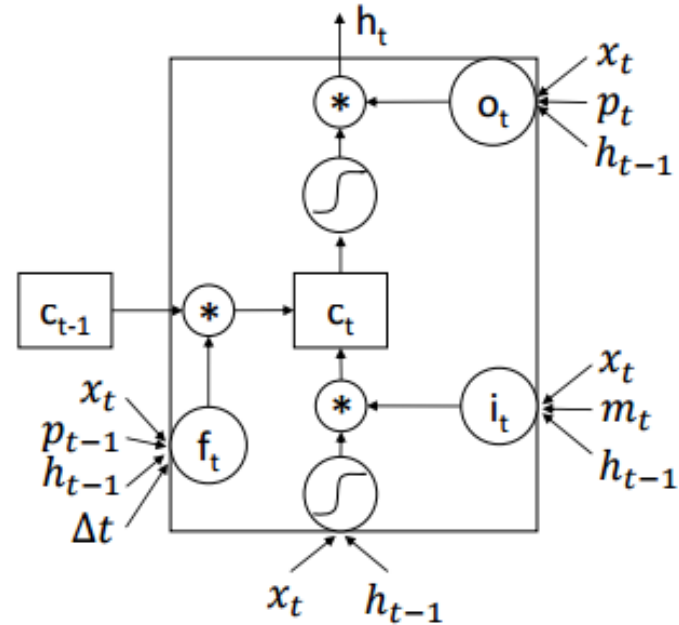
Summary: solve four major problems

- Representation of variable inputs
- Long-term dependencies
- Episodic recording and irregular timing
- Interactions between disease progression and intervention



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- Representation of variable inputs
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Conclusions

- DeepCare's primary value is that it frees model designers from manually designing features from EMRs.
- It uses modified LSTM and pooling units to handle timing irregularities with which existing techniques struggle.
- The full progression of a disease is embedded into a vector which is then used to make risk and readmission predictions.
- Results are competitive against current state-of-the-arts.