#### Learning to Detect Sepsis with a Multitask Gaussian Process RNN Classifier

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**Presented by William Hang for CS273B** 

## What is sepsis?

Body's own immune response to infection causes huge inflammatory response in the rest of the body

Usually caused by bacterial or fungal infections

Sepsis is totally treatable with IV and antibiotics

Causes millions of deaths worldwide annually

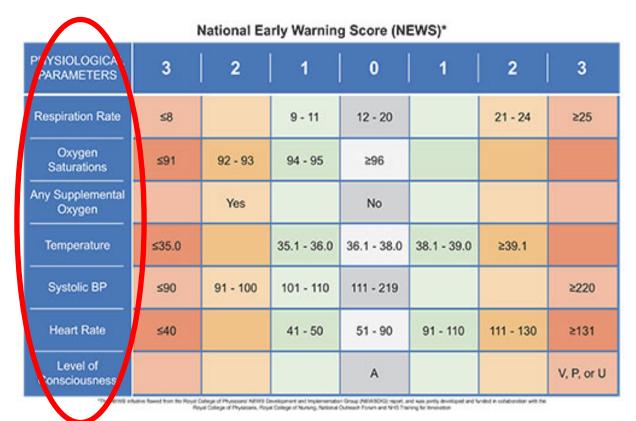
Detecting and then treating this early is key

## How do you detect it early right now?

Duke Hospital uses NEWS

Looks at 6 physiological variables to determine a score

Really low specificity, almost 63.4% false positive rate in Duke Hospital



Please see next page for eighanatory text about this chart.





## Challenges to early detection

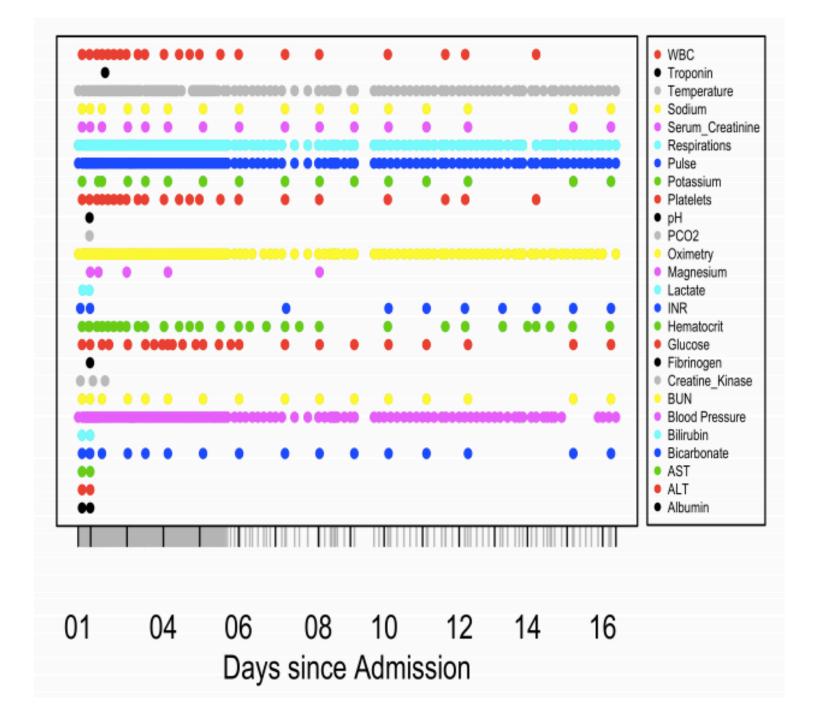
Every patient is different!

Time series prediction problem

Lots of missing data per patient at various points in time

Sepsis start time is generally unknown

When do you serve timely alarms?

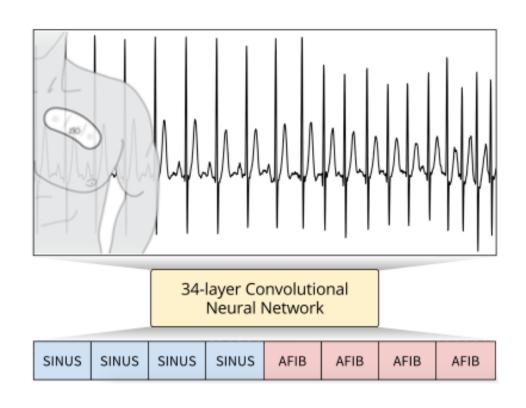


## Other research trying to tackle this problem

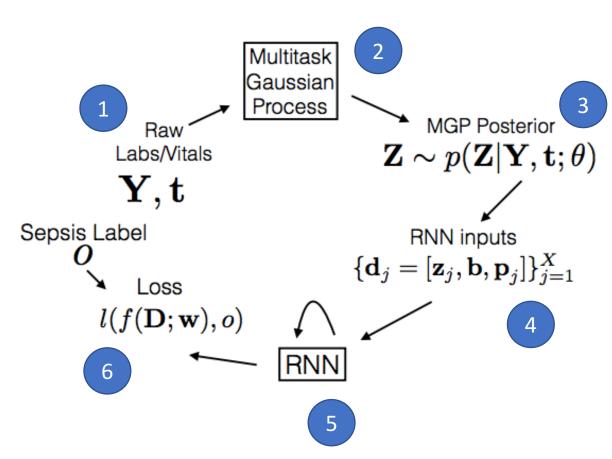
Rothman Index + Cox regression don't operate on time series data

Works on chronic kidney disease and glaucoma prediction operate on months and years timescale; sepsis is important on the order of hours

Other works use RNNs to classify clinical time series



# This paper's approach



Data for a single patient:

$$\mathcal{D}_i = \{\mathbf{b}_i, \mathbf{t}_i, \mathbf{Y}_i, \mathcal{P}_i, o_i\}$$

 $\mathbf{b}$  = baseline state

t = time

**Y** = physiological variables: vitals and lab tests

**P** = administered drugs at various time steps

 $\mathbf{o}$  = whether the patient got sepsis

#### Predict o!

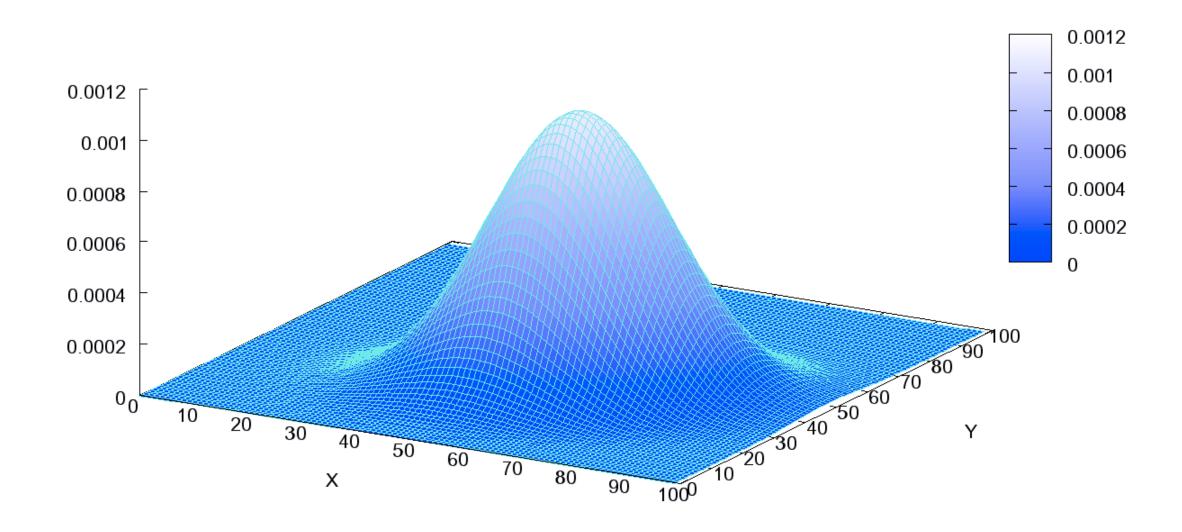
## Okay, what's a Gaussian Process?

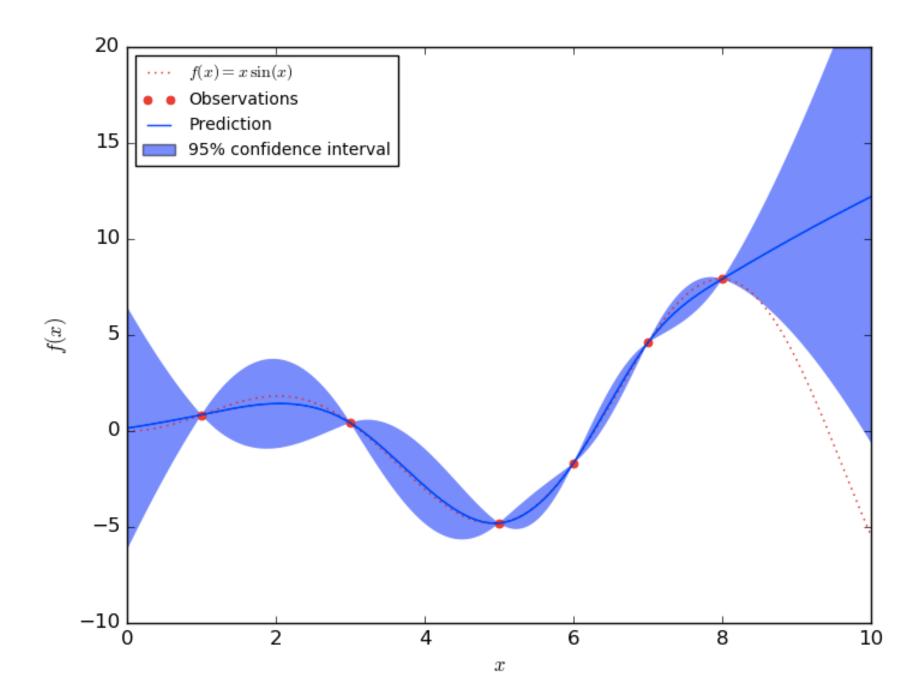
Estimates the probability distribution over  $f(\mathbf{X})$  given training data  $X_{train}$ 

We do this by trying to calculate a posterior over possible  $f(\mathbf{X})$  by comparing how similar  $\mathbf{X}$  is to  $\mathbf{X}_{\text{train}}$  through the use of covariance matrices. This covariance matrix is computed with a kernel function

If you have something in X that looks kind of like stuff you've seen in  $X_{\text{train}}$ , you could say that its mean and variance is distributed like things you've already seen

#### Multivariate Normal Distribution





### So what?

If you give a GP input values, you can draw output values from a correlated Gaussian distribution that knows how similar your input values are to things it's seen in the past

This sampling technique is super useful with missing values at various time steps

We will see how we train this GP to give us what we want

#### Now what's a Multitask Gaussian Process?

Correlation kernel also operates across time

$$cov(f_{im}(t), f_{im'}(t')) = K_{mm'}^{M} k^{t}(t, t')$$

You can learn the covariance of each pair of features, across time! This information will allow us to estimate the posterior distribution among all features, across time.

$$\Sigma_i = K^M \otimes K^{T_i} + D \otimes I,$$

This covariance matrix is actually MT × MT, so you know the distribution of feature values at each time step

#### How are GPs used with an LSTM?

$$\mu_{z_i} = (K^M \otimes K^{X_i T_i}) \Sigma_i^{-1} \mathbf{y}_i$$

$$\Sigma_{z_i} = (K^M \otimes K^{X_i}) - (K^M \otimes K^{X_i T_i}) \Sigma_i^{-1} (K^M \otimes K^{T_i X_i})$$

$$(6)$$

Feed in all the y's and sample a big Z that gives you imputed values across all time steps

$$\mathbf{D}_s = [\mathbf{Z}_s^{\top}, \mathbf{B}^{\top}, \mathbf{P}^{\top}]^{\top}, \quad \text{vec}(\mathbf{Z}_s) \equiv \mathbf{z}_s \sim N(\mu_z, \Sigma_z; \boldsymbol{\theta})$$

The z's go into your LSTM as inputs

## How do you even train this thing?

z is a random variable! So you need to optimize the expected loss instead of average loss

$$oldsymbol{w}^*, oldsymbol{ heta}^* = \operatorname{argmin}_{w, heta} \sum_{i=1}^N \mathbb{E}_{z_i \sim N(\mu_{z_i}, \Sigma_{z_i}; heta)}[l(f(\mathbf{D}_i; oldsymbol{w}), o_i)].$$

According to them, you can't take the gradient of this function, so you approximate the loss using Monte Carlo

$$\mathbb{E}_{z \sim N(\mu_z, \Sigma_z; \theta)}[l(f(\mathbf{D}; \boldsymbol{w}), o)] \approx \frac{1}{S} \sum_{s=1}^{S} l(f(\mathbf{D}_s; \boldsymbol{w}), o),$$

Everything is good now because you have a loss value whose gradients you can backprop through LSTM **and** the MGP because you can represent

 $z = \mu + Rx$ , where x is noise and R is a matrix such that  $\Sigma = RR^T$ 

So if you know the gradients to **z**, you can train the MGP as well!

#### Dataset

34 physiological variables per patient, some variables only present 2-4% of the time

35 baseline variables, 8 drugs, 49k patient admissions

Well defined clinical definition to figure out when a patient gets sepsis

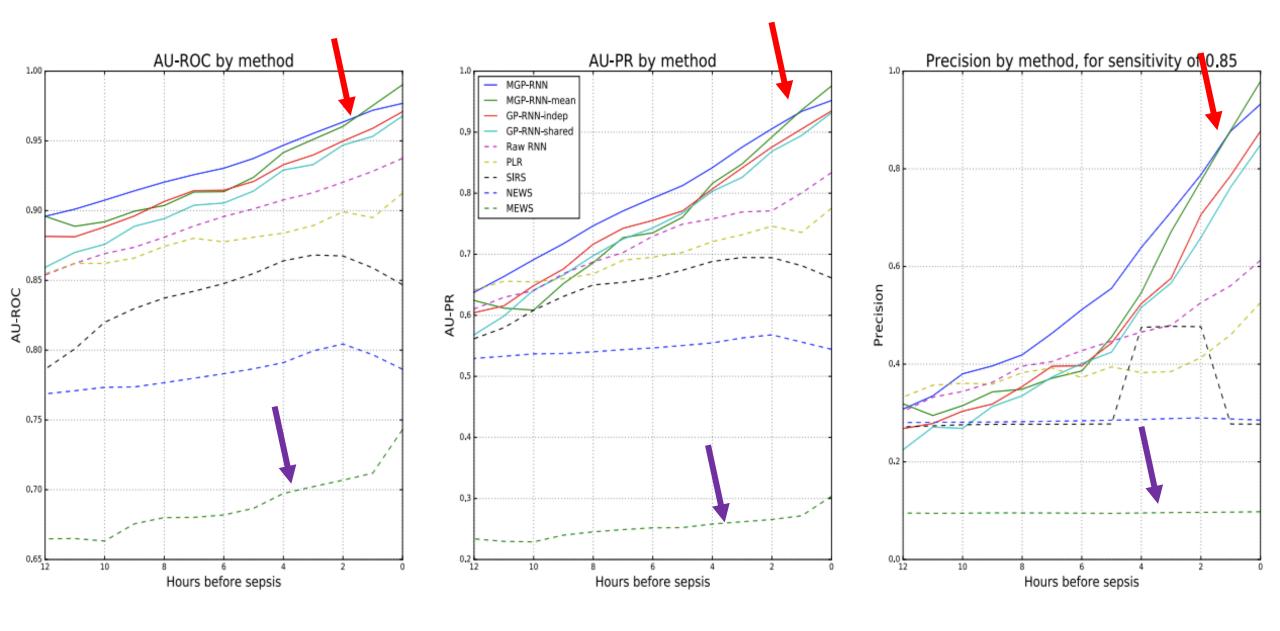
21.4% of patients in this dataset ended up getting sepsis

## Training and Testing

80/10/10 split, L2, Adam, Tensorflow

Baselines: crappy hospital methods, baseline LSTMs, and their own modifications to their model

Most notable is MGP-RNN-mean, where they swap out z with  $\mu$ 



#### Performance

About 5 times fewer false alarms than NEWS, four hours in advance!

Better than MEWS and NEWS by 19.4% and 55.5% AUCROC

One of the first deep learning papers tackling sepsis detection

#### **Extensions and Limitations**

Clustering patients together and training a model for each

Using reinforcement learning or VAEs

Marginalize or subtract away known drug interactions with vital signs (using more domain specific knowledge)

Applying to other datasets

They're actively trying to productize this system to plug into EHRs and make predictions for hospitals (go them!)