## Computing a QRE Branch Turocy (2005) & Turocy (2010)

#### **Environment and Notation**

- Set of players  $N = \{1, ..., n\}$
- $S_i$  set of strategies available to each player  $i \in N$
- $ullet J_i$  the number of strategies in  $S_i$
- $s_{ij} \in S_i$  with  $1 \le j \le J_i$
- The set of strategy profiles  $S=\times_{i=1}^n S_i$  is the Cartesian product of  $S_i$
- $J = \sum_{i=1}^{n} J_i$
- $u_i : S \to \mathbb{R}$  is the payoff/utility function for player i
- $\pi_{ij}$  the probability assigned to a strategy  $s_{ij}$  of player i
- ullet  $\Delta_i$  the set of probability distributions (mixed strategy) over  $\mathcal{S}_i$
- $\Delta = \times_{i=1}^n \Delta_i$ ,  $\pi \in \Delta$  mixed strategy profile

#### **Environment and Notation**

- $(s_{ij}, \pi_{-i})$  mixed strategy profile where player i plays  $s_{ij}$  with probability 1, while all other players play according to the mixed strategy  $\pi$
- $\overline{u}_{ij}(\pi) \equiv u_i(s_{ij}, \pi_{-i})$  expected payoff/utility to player i from playing his jth strategy, holding fixed his opponents' mixed strategies  $\pi_{-i}$
- In the quantal response framework players observe a noisy evaluation of the strategy values

$$-\hat{u}_{ij}(\pi) = \bar{u}_{ij}(\pi) + \epsilon_{ij}$$

—where the  $\epsilon_{ij}$  are random variables drawn according to some joint distribution. When  $\epsilon_{ij}$  are drawn from an extreme value distribution with parameter  $\lambda$ , a logistic quantal response equilibrium profile (logit equilibrium) is given by

$$\pi_{ij} = \frac{e^{\lambda \, \overline{u}_{ij}(\pi)}}{\sum_{k=1}^{J_i} e^{\lambda \, \overline{u}_{ik}(\pi)}}$$

### **Computational Problem**

- Trace out a path of mixed strategy profiles  $\pi$  for different  $\lambda$
- The logit equilibria are expressed as the zeros of a system of equations  $H(\pi,\lambda)=0$
- $\sum_{i=1}^{n} J_i$  equations comprising the system  $H(\pi, \lambda)$  are indexed  $H_{ij}(\pi, \lambda)$  corresponding to the jth strategy of player i

$$H_{ij}(\pi,\lambda) = e^{\lambda \, \overline{u}_{ij}(\pi)} - \pi_{ij} \sum_{k=1}^{J_i} e^{\lambda \, \overline{u}_{ik}(\pi)} = 0$$

ullet n equations comprising the system  $H(\pi,\lambda)$  are indexed  $H_i(\pi,\lambda)$ 

$$H_i(\boldsymbol{\pi}, \boldsymbol{\lambda}) = 1 - \sum_{k=1}^{J_i} \boldsymbol{\pi}_{ik} = \mathbf{0}$$

### **Computational Problem Simplified**

ullet For each agent i we can choose some reference strategy  $\mathbf{s}_{i\mathbf{k}} \in \mathcal{S}_i$ , then

$$\frac{\pi_{ij}}{\pi_{ik}} = \frac{e^{\lambda \, \overline{u}_{ij}(\pi)}}{e^{\lambda \, \overline{u}_{ik}(\pi)}}$$

• We can also convert to logs:

$$ln(\pi_{ij}) - ln(\pi_{ik}) = \lambda [u_{ij}(\pi) - u_{ik}(\pi)]$$

• Then the system  $H(\pi,\lambda)=0$  is defined by  $\sum_{i=1}^n (J_i-1)$  equations of the form

$$H_{ijk}(\pi,\lambda) = \ln(\pi_{ij}) - \ln(\pi_{ik}) - \lambda [u_{ij}(\pi) - u_{ik}(\pi)] = 0$$

• And *n* equations of the form

$$H_i(\pi,\lambda)=1-\sum_{k=1}^{J_i}\pi_{ik}=0$$

#### **Computational Problem Simplified**

- Let  $p_{ij} = \ln(\pi_{ij})$
- Then the system  $H(p,\lambda)=0$  is defined by  $\sum_{i=1}^n (J_i-1)$  equations of the form  $H_{iik}(p,\lambda) = p_{ii} - p_{ik} - \lambda \left[ u_{ii}(e^p) - u_{ik}(e^p) \right] = 0$
- And *n* equations of the form

$$H_i(p,\lambda)=1-\sum_{k=1}^{J_i}e^{p_{ik}}=0$$
 These  $n$  equations can also be imposed as a constraint for minimization algorithm

These *n* equations can minimization algorithm

The objective function is:

$$F(p,\lambda) = H(p,\lambda)^{\mathsf{T}}H(p,\lambda)$$

A quantal response equilibrium is at 0 (minimum) of  $F(p, \lambda)$ 

## **Computational Steps**

- 1. Let  $\{\lambda_t\}$  be a sequence such that  $\lambda_t > \lambda_{t+1}$
- 2. Initialize

$$-\lambda_0=0$$

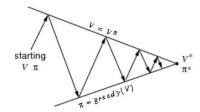
$$- \pi_{ij} = \frac{1}{J_i}$$

$$- p_{ij} = \ln(\pi_{ij})$$

3. Find minimum of  $F(\lambda_t, \pi)$  using  $\pi_{t-1}$  as initial guess

# A different approach to QRE: Policy Iteration

- Policy iteration consists of two simultaneous, interacting processes, one making the value function consistent with the current policy (policy evaluation), and the other making the policy "greedy" with respect to the current value function (policy improvement)
  - In policy iteration these two alternate, each completing before the other begins.



For our problem policy is  $\pi_i$ , and value associated with that policy is  $u_i(\pi)$ 

For a given  $\lambda$ 

1. Initialize 
$$\pi_{ij} = \frac{1}{J_i}$$

- 2. Evaluate  $u_i(\pi)$
- 3. Improve

$$-\pi'_{ij} = \frac{e^{\lambda \bar{u}_{ij}(\pi)}}{\sum_{k=1}^{J_i} e^{\lambda \bar{u}_{ik}(\pi)}}$$

-If  $\pi' = \pi$  then stop; else go to 2.

- In practice the improvement step is incremental
  - $-\pi'$ =(1- $\alpha$ ) $\pi$ + $\alpha$  $\pi'$