

# Parallel Two-dimensional Fast Fourier Transform

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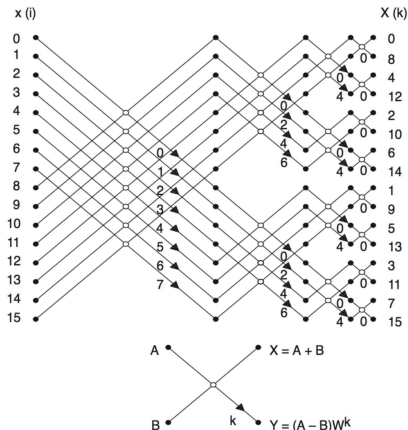
# 1D FFT

FFT computation is based on a repeated application of an elementary transform known as a “butterfly”.

Step 1: append zeroes to make the total length  $N$  a power of 2.

Step 2: repeat doing butterfly operations.

Step 3: adjust the order of outputs.



Fastest Fourier Transform in the West (FFTW) is known as the fastest free software implementation of the FFT algorithm. It supports a variety of algorithms and chooses the one it estimates to be preferable in the particular circumstances.

# Sequential 2D Discrete Fourier Transform (DFT)

Suppose the 2D signals are stored in a  $N_1 \times N_2$  matrix  $\mathbf{x}$ . The 2D DFT of  $\mathbf{x}$  is defined as

$$X_{r_1, r_2} = \sum_{l_1=0}^{N_1-1} \sum_{l_2=0}^{N_2-1} x_{l_1, l_2} \exp\left(-\frac{2\pi i}{N_1} r_1 l_1\right) \exp\left(-\frac{2\pi i}{N_2} r_2 l_2\right)$$

$$r_1 = 0, 1, \dots, N_1 - 1, \text{ and } r_2 = 0, 1, \dots, N_2 - 1$$

Total computational cost:  $O(N_1^2 N_2^2)$ .

This can be reduced significantly by separating the 2D-DFT into a series of 1D-DFTs, which can each be implemented using a fast 1D-FFT algorithm.

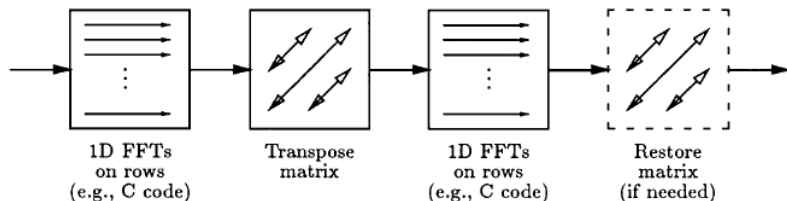
## Sequential 2D FFT

$$\begin{aligned} X_{r_1, r_2} &= \sum_{l_1=0}^{N_1-1} \sum_{l_2=0}^{N_2-1} x_{l_1, l_2} \exp\left(-\frac{2\pi i}{N_1} r_1 l_1\right) \exp\left(-\frac{2\pi i}{N_2} r_2 l_2\right) \\ &= \sum_{l_1=0}^{N_1-1} \exp\left(-\frac{2\pi i}{N_1} r_1 l_1\right) \left( \sum_{l_2=0}^{N_2-1} x_{l_1, l_2} \exp\left(-\frac{2\pi i}{N_2} r_2 l_2\right) \right) \\ &= \sum_{l_1=0}^{N_1-1} \exp\left(-\frac{2\pi i}{N_1} r_1 l_1\right) \tilde{X}_{l_1, r_2} \\ &= \sum_{l_1=0}^{N_1-1} \tilde{X}_{l_1, r_2} \exp\left(-\frac{2\pi i}{N_1} r_1 l_1\right) \end{aligned}$$

Do 1D FFTs on the  $N_1$  rows (of length  $N_2$ ), and then do 1D FFTs on the  $N_2$  columns (of length  $N_1$ ). Total computational cost is  $O(N_1 N_2 \log_2(N_1 N_2))$ .

# Row-Column Method

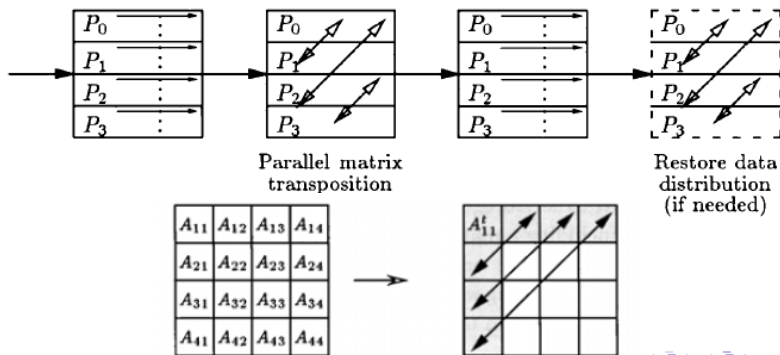
- ▶ Step 1: 1D FFTs on the rows (locally).
- ▶ Step 2: matrix transposition.
- ▶ Step 3: 1D FFTs on the rows again (locally).
- ▶ Step 4: matrix transposition.



# Parallel 2D FFT

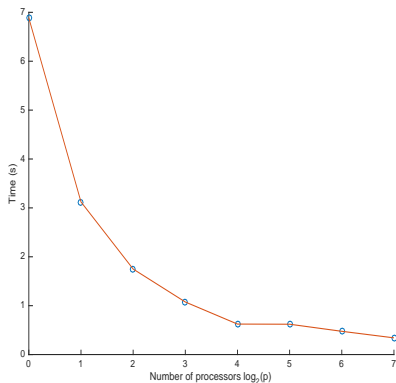
- ▶ 1D FFT can be computed locally. Use FFTW library to do the 1D FFT.
- ▶ Communication is only needed during the transposition step (hardest). Imagine there are blocks in each processor and use MPI Alltoall function to exchange blocks of data with every other processor. Then transpose each block of data locally.

Each processor performs 1D FFTs on allocated rows:

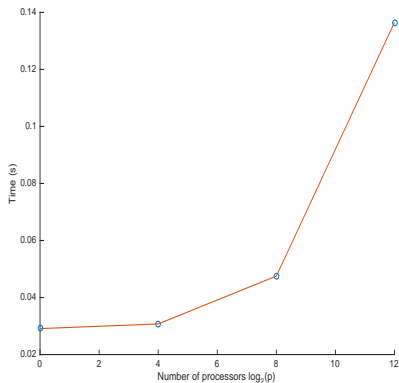


# Scalability

- ▶ Strong scalability: square matrix  $N=8192$ , number of processors:  $2^j, j = 0, \dots, 10$ .
- ▶ Weak scalability: keep the number of data in each processor fixed  $512 \times 512$ .



(a) Strong scalability



(b) Weak scalability

- ▶ Strong and weak scalability are clear when  $p$  is small.
- ▶ Communication in the transposition step dominates when  $p$  is large.
- ▶ When  $p$  is too large, running time may increase.
- ▶ 2D version FFTW takes 10s to compute this problem when  $N=8192$ . Parallel version is faster.
- ▶ Efficient matrix transposition algorithm is needed to improve the performance.





Chu, Eleanor and Alan George

Inside the FFT black box: serial and parallel fast Fourier transform algorithms..

CRC Press, 1999.



Matteo Frigo and Steven G. Johnson

FFTW Manual



Piedra, Rose Marie.

Parallel 1-D FFT: Implementation with TMS320C4x DSPs.

Texas Instruments, 1992.