



Topics in AI (CPSC 532S): Multimodal Learning with Vision, Language and Sound



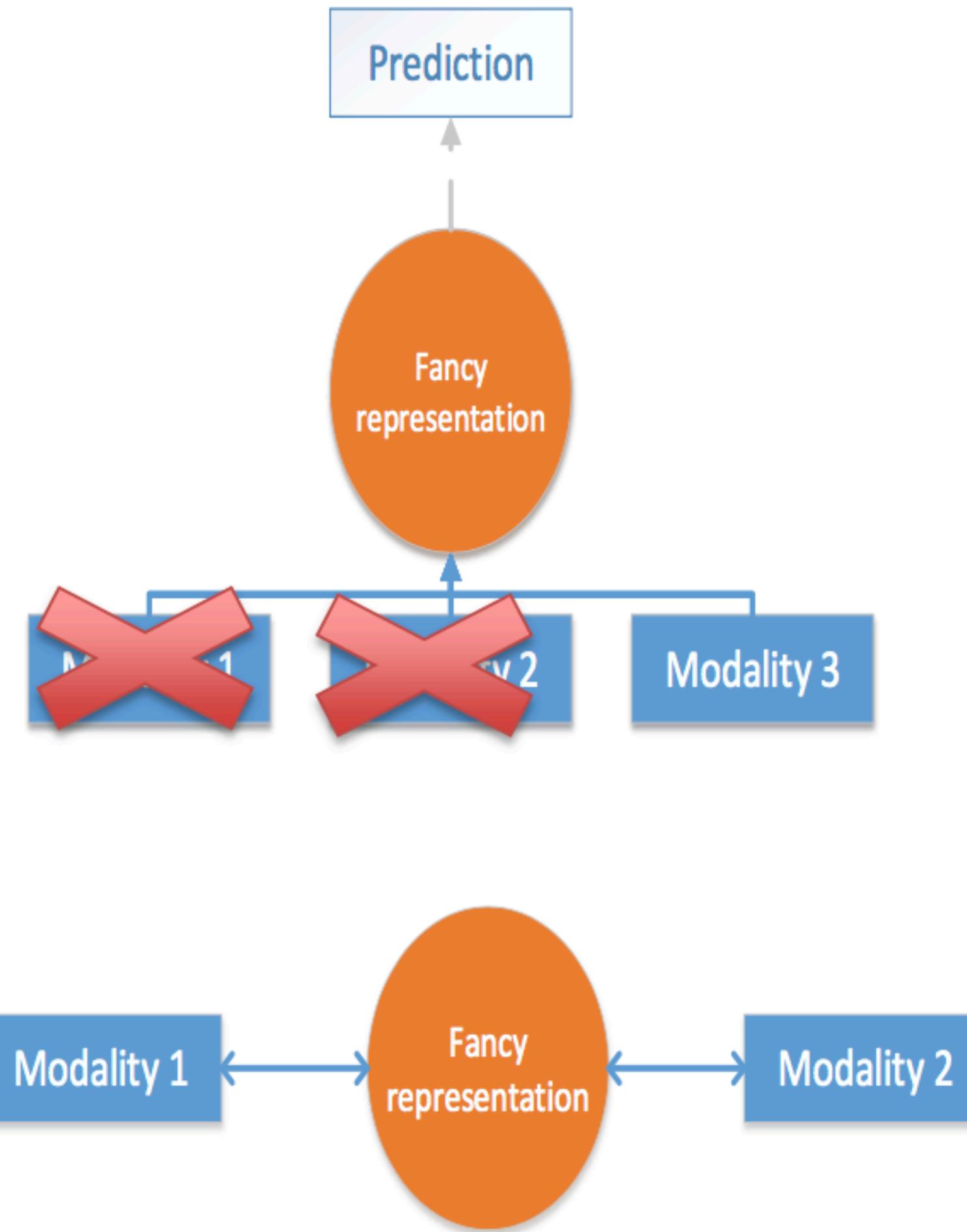
A decorative horizontal bar at the bottom of the slide, composed of five colored segments: light green, medium green, cyan, light blue, and purple.

Lecture 14: Coordinated Representations and Joint Embeddings

Multimodal Representations

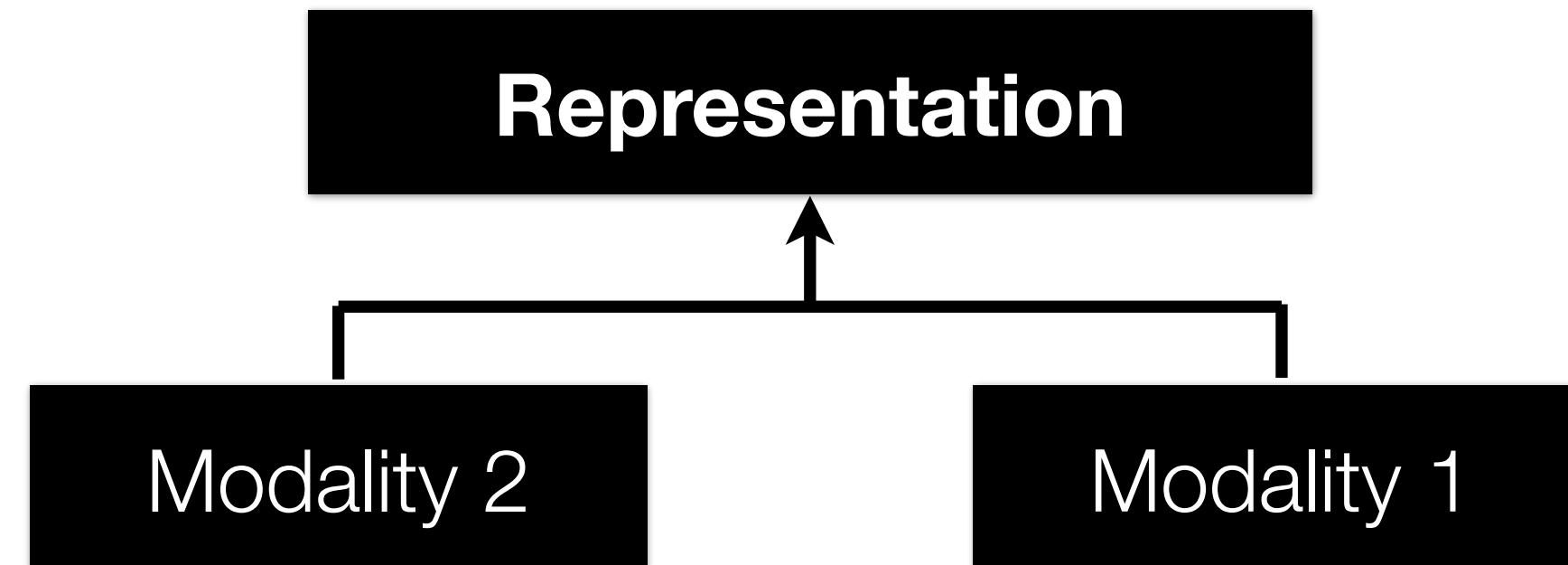
What is a **good** multimodal representation?

- **Similarity** in the representation (somehow) implies similarity in corresponding concepts (we saw this in word2vec)
- **Useful** for various **discriminative tasks** (retrieval, mapping, fusion, etc.)
- Possible to obtain **in absence of one or mere modalities**
- **Fill in missing modalities** given others (map or translate between modalities)



Multimodal Representation Types

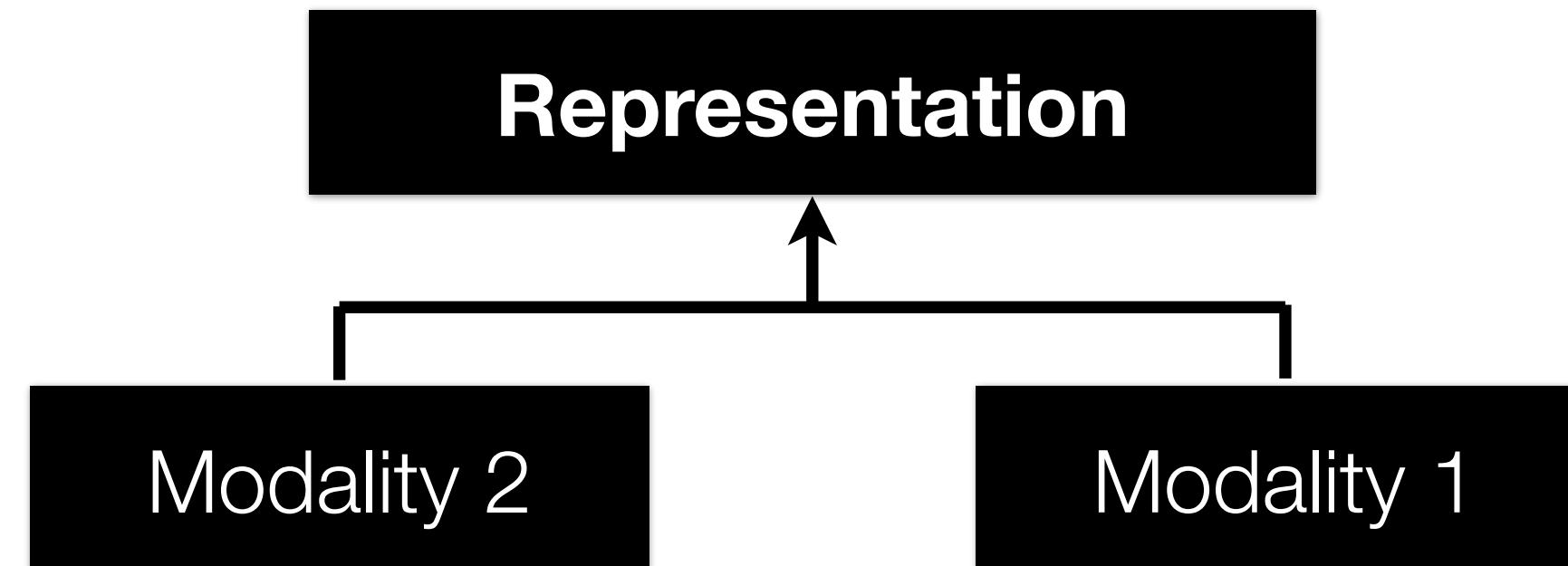
Joint representations:



- Simplest version: **modality concatenation** (early fusion)
- Can be learned **supervised** or **unsupervised**

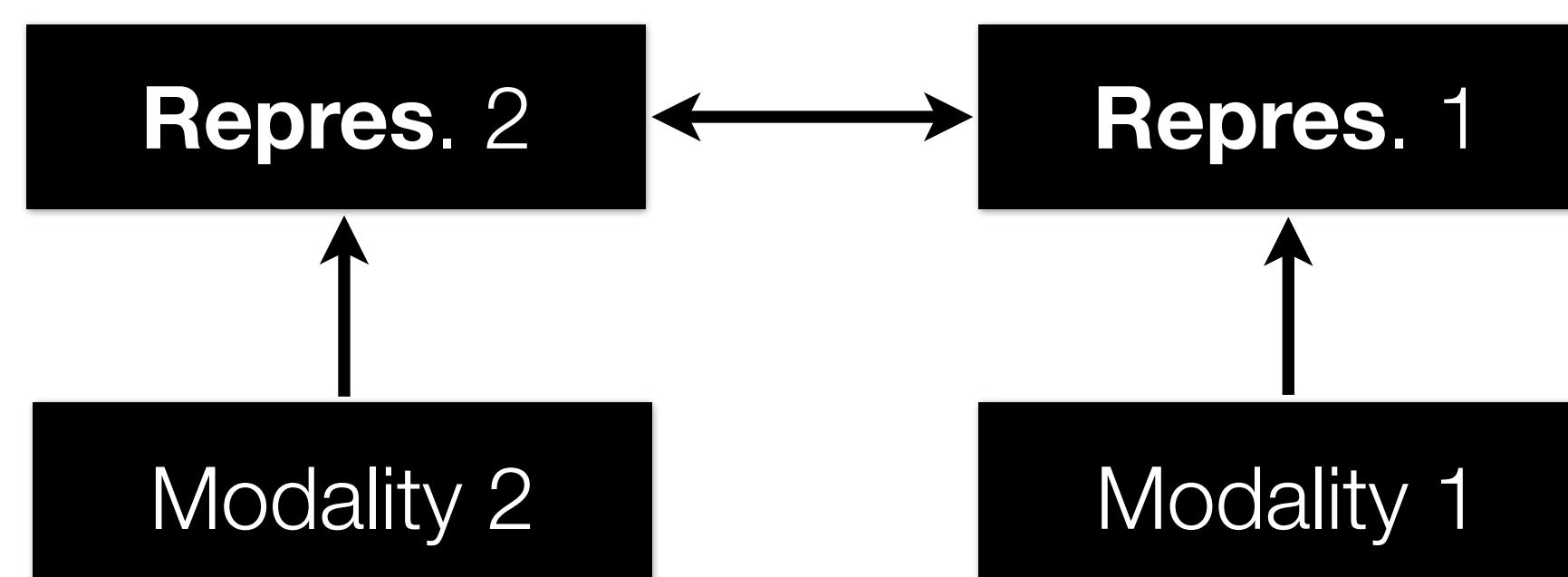
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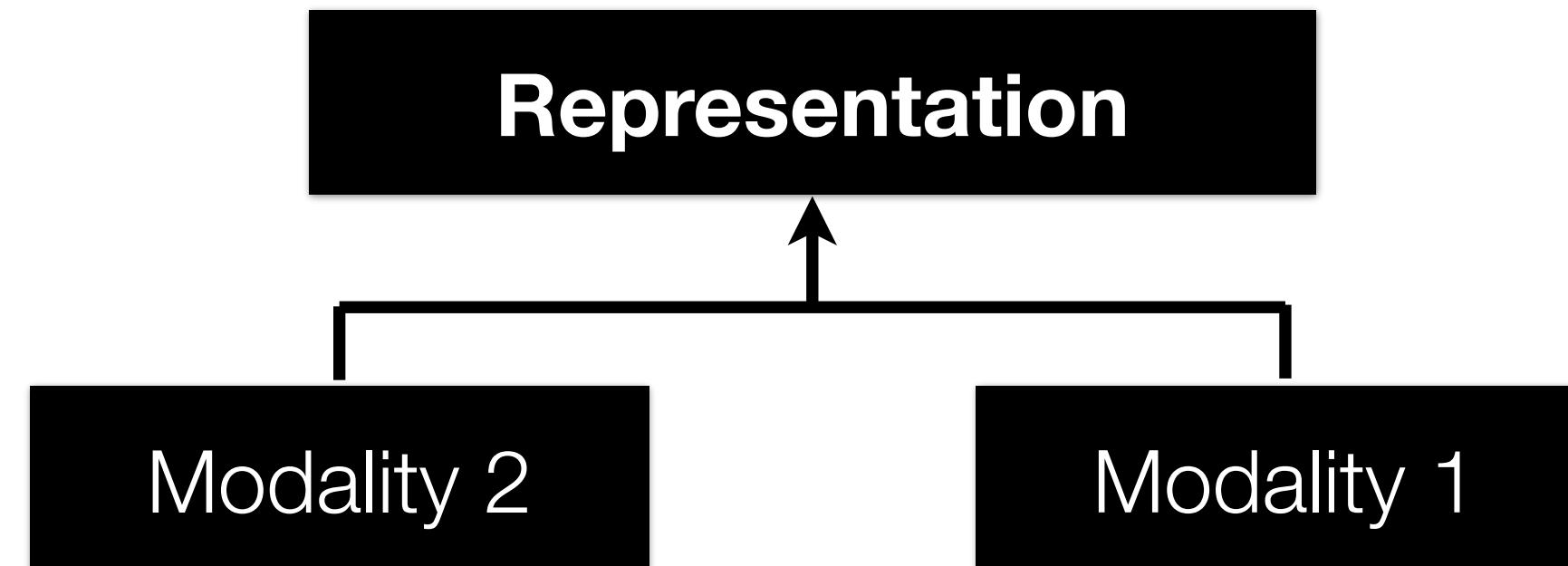
Coordinated representations:



- **Similarity-based** methods (e.g., cosine distance)
- **Structure constraints** (e.g., orthogonality, sparseness)
- Examples: CCA, joint embeddings

Multimodal Representation Types

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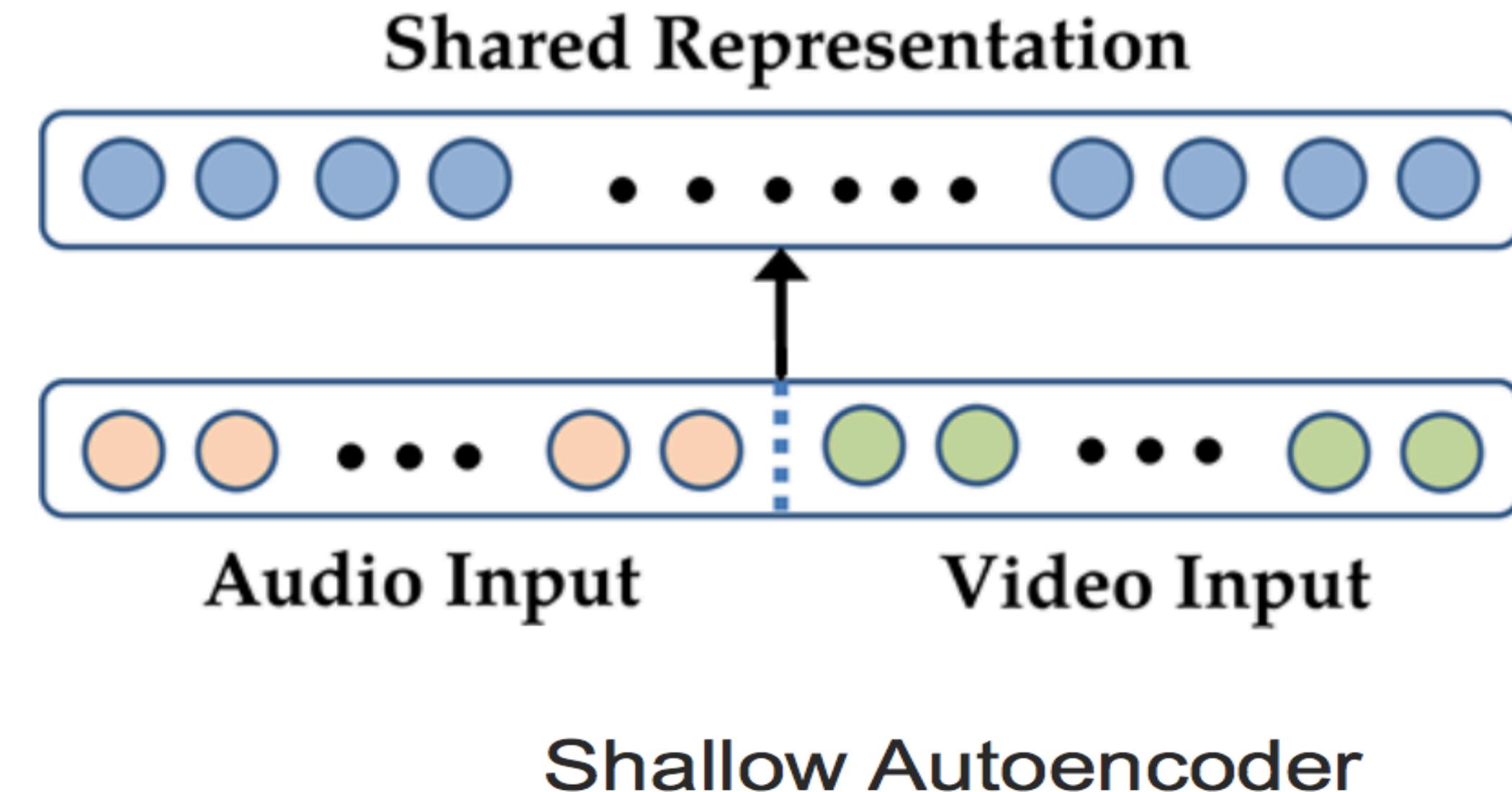
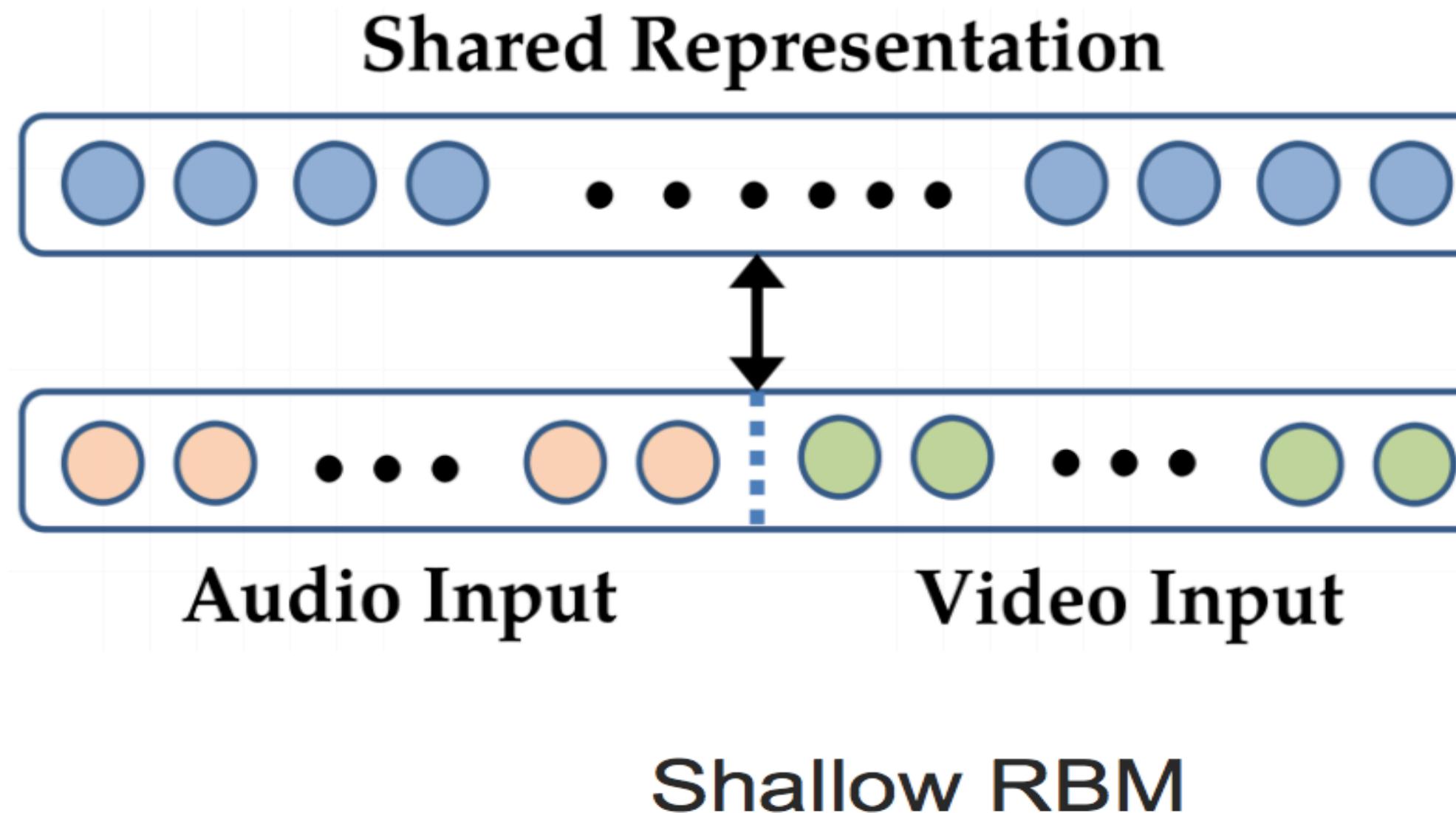


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Joint Representation: Simple Multimodal Autoencoders

Concatenating modalities is fine, but requires both modalities at test time

No ability to ensure there is indeed **sharing** in the representations space



Joint Representation: Deep Multimodal Autoencoders

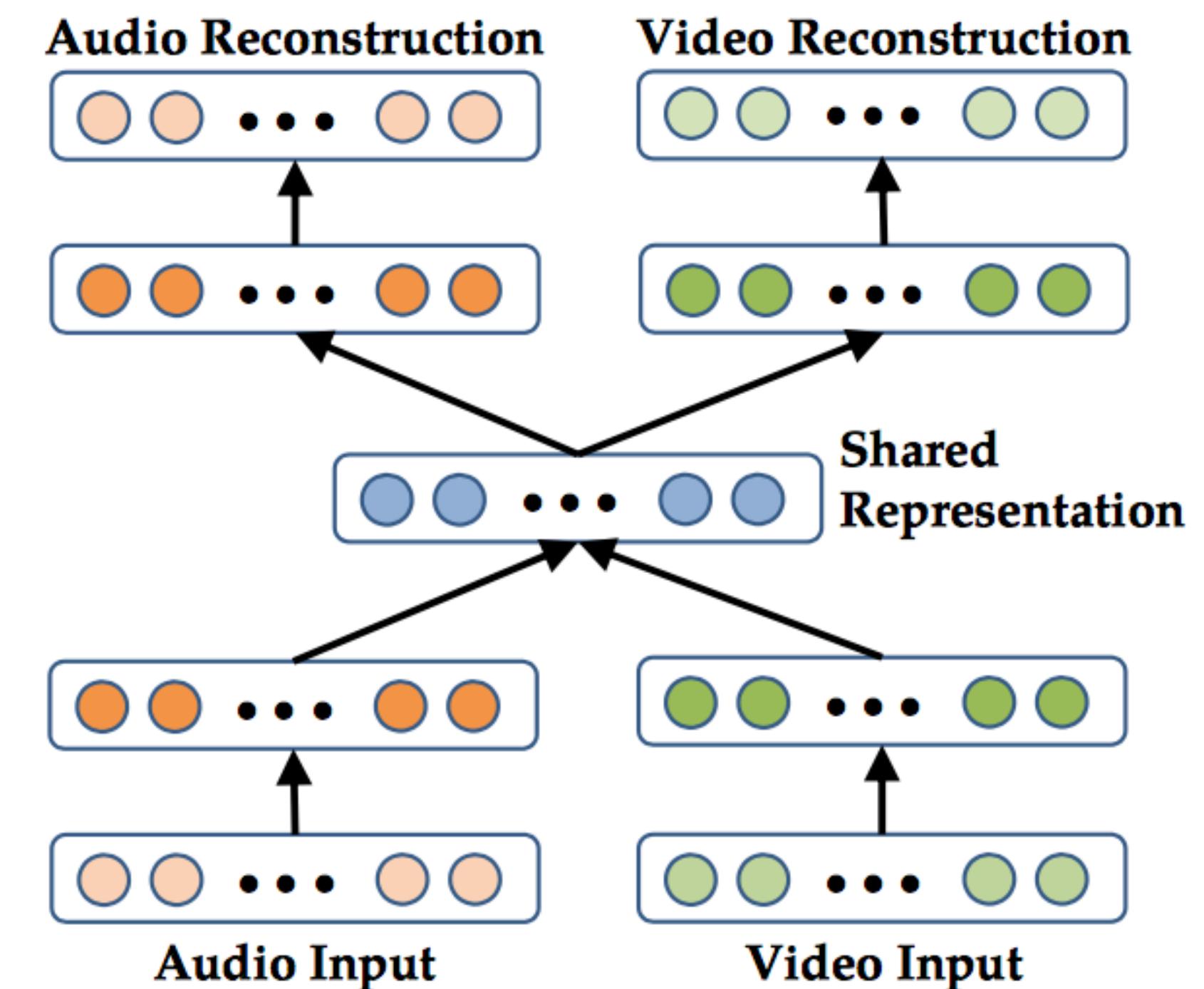
[Ngiam et al., 2011]

Each **modality** can be pre-trained

- using denoising autoencoder

To train the model, **reconstruct both modalities** using

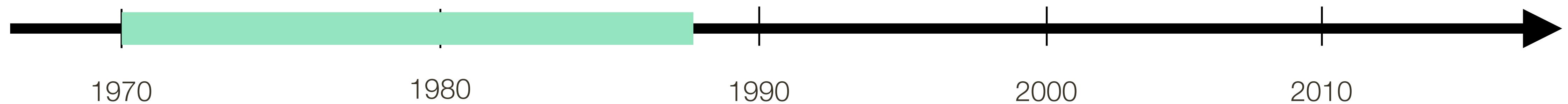
- both Audio & Video
- just Audio
- just Video



Multimodal Research: Historical Perspective

The McGurk Effect

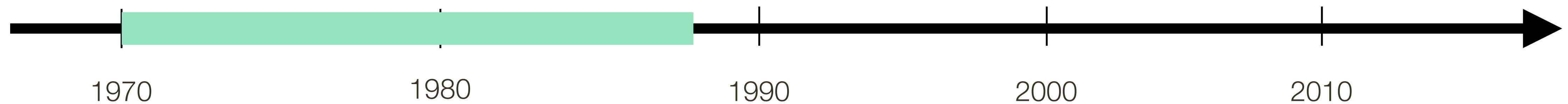
McGurk Effect (1976)



Multimodal Research: Historical Perspective

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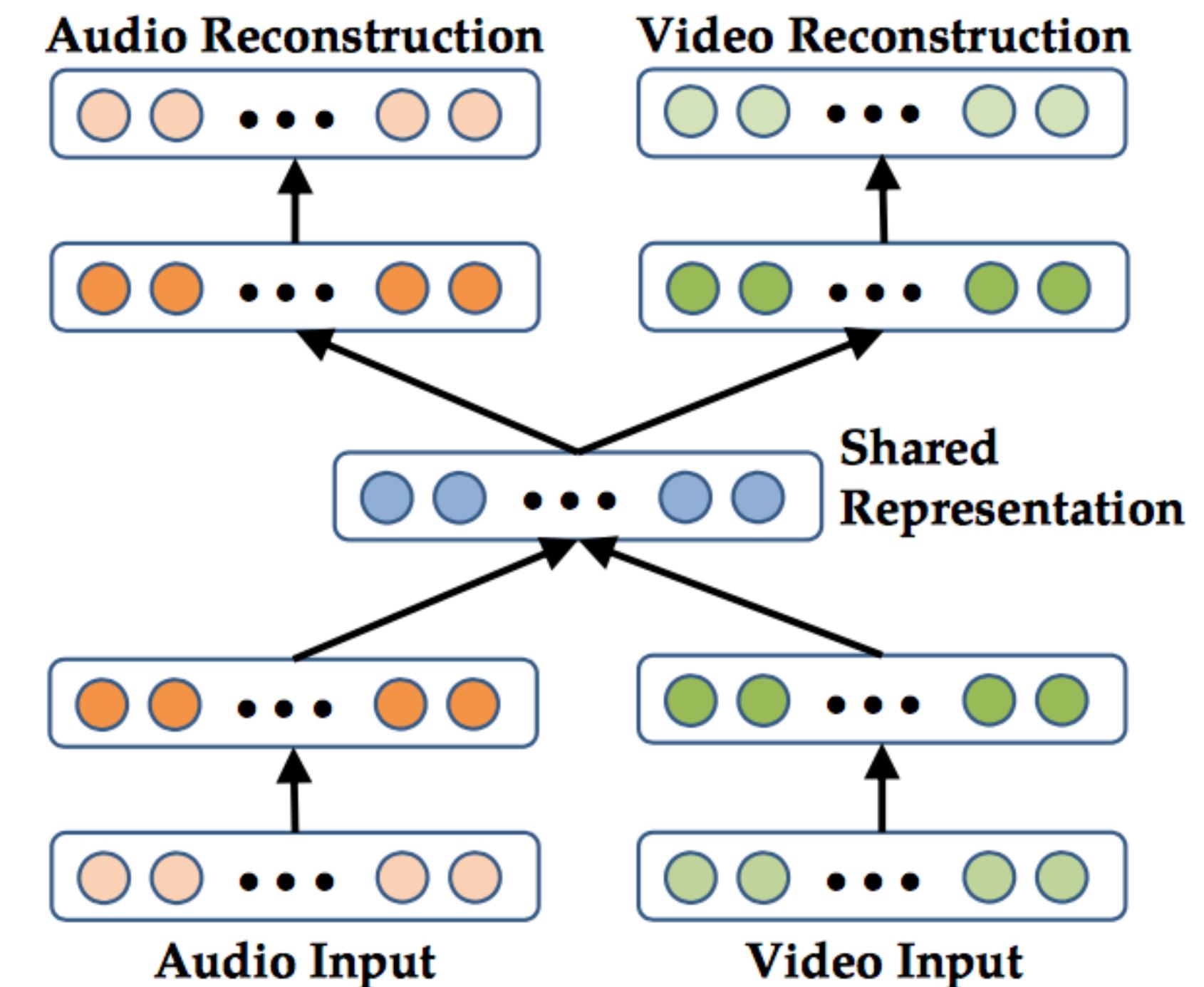


Joint Representation: Deep Multimodal Autoencoders

[Ngiam et al., 2011]

Table 3: McGurk Effect

Audio / Visual Setting	Model prediction		
	/ga/	/ba/	/da/
Visual /ga/, Audio /ga/	82.6%	2.2%	15.2%
Visual /ba/, Audio /ba/	4.4%	89.1%	6.5%
Visual /ga/, Audio /ba/	28.3%	13.0%	58.7%

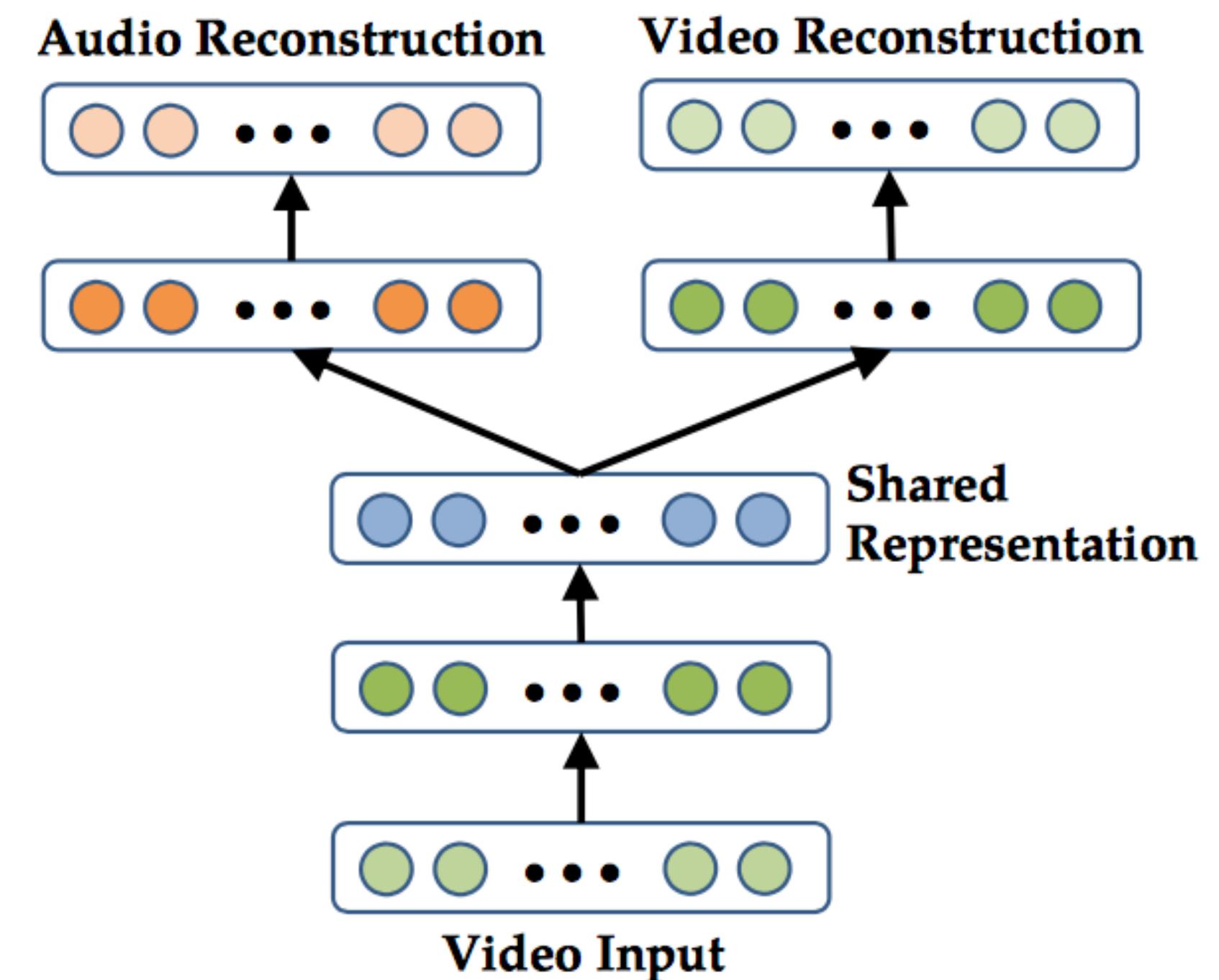


Joint Representation: Deep Multimodal Autoencoders

[Ngiam et al., 2011]

Useful when you know you may only be conditioning on one modality at test time

Can be regarded as a form of **regularization**

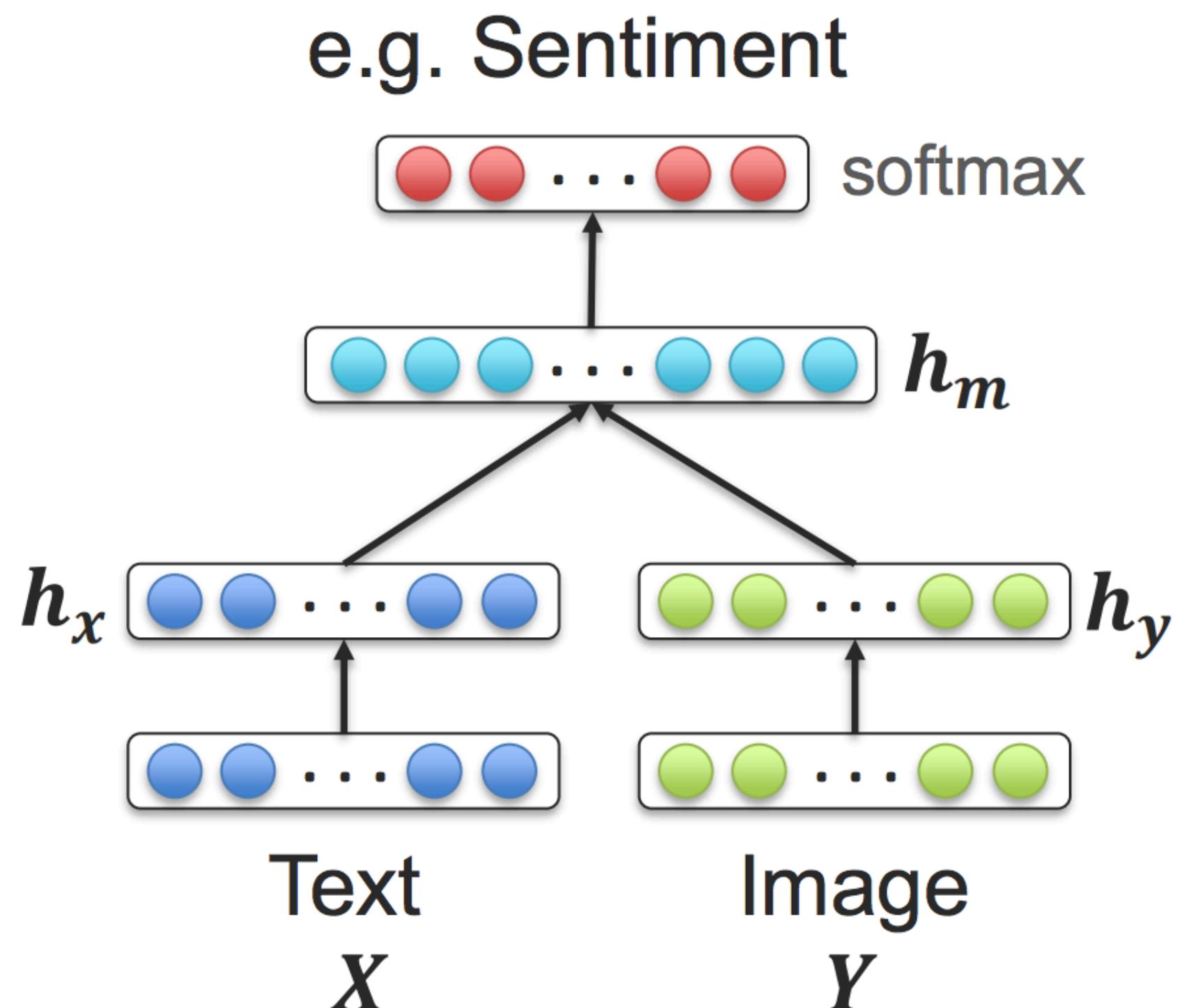


Supervised Joint Representation

For supervised learning tasks, we need to join unimodal representations

- Simple **concatenation**
- Element-wise **multiplicative** interactions
- many many others

Encoder-decoder Architectures



Multi-modal Sentiment Analysis

For supervised learning tasks, we need to join unimodal representations

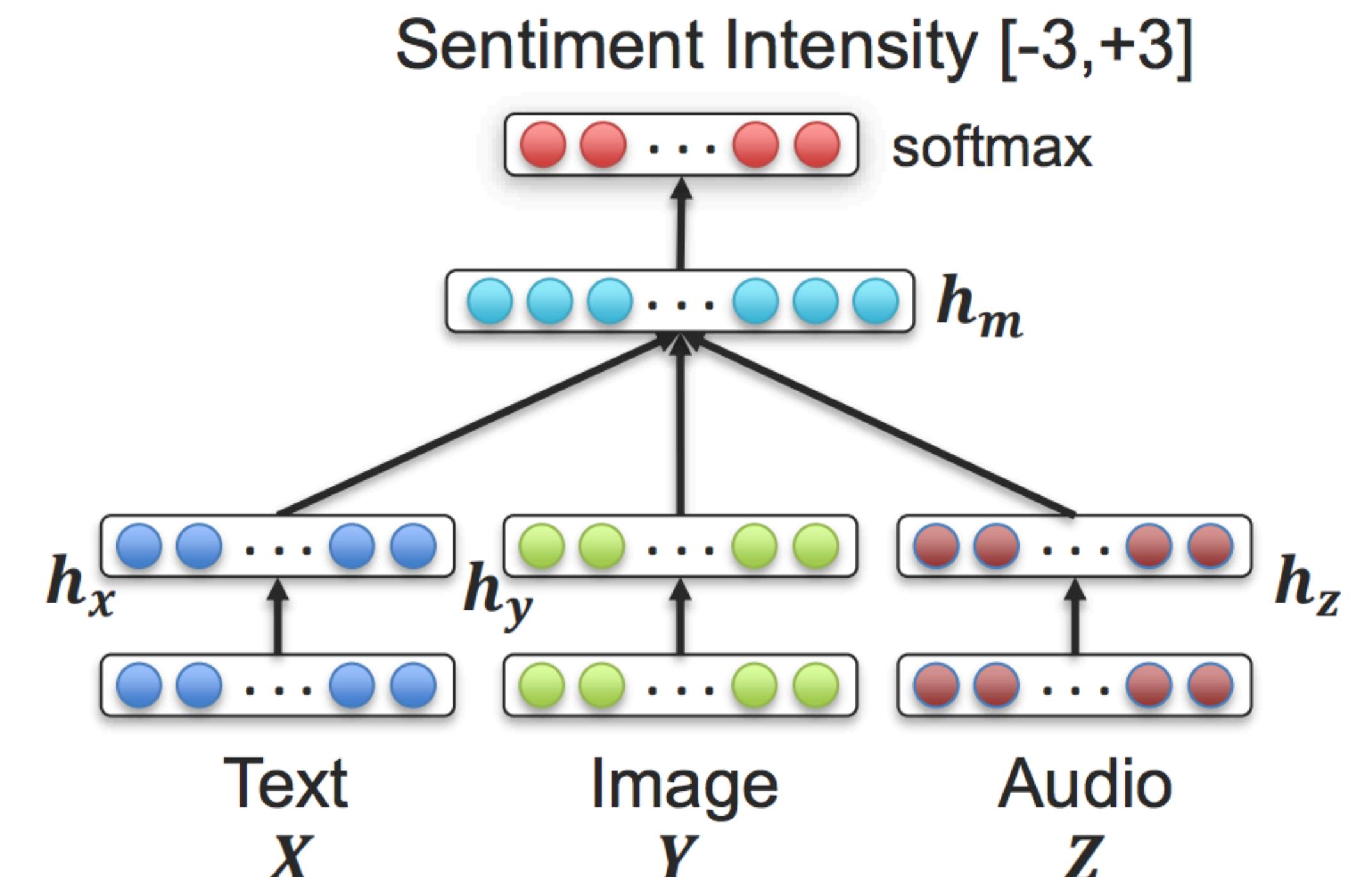
- Simple **concatenation**

MOSI dataset (Zadeh et al, 2016)



- 2199 subjective video segments
- Sentiment intensity annotations
- 3 modalities: text, video, audio

$$\mathbf{h}_m = \sigma(\mathbf{W} \cdot [\mathbf{h}_x, \mathbf{h}_y, \mathbf{h}_z]^T)$$



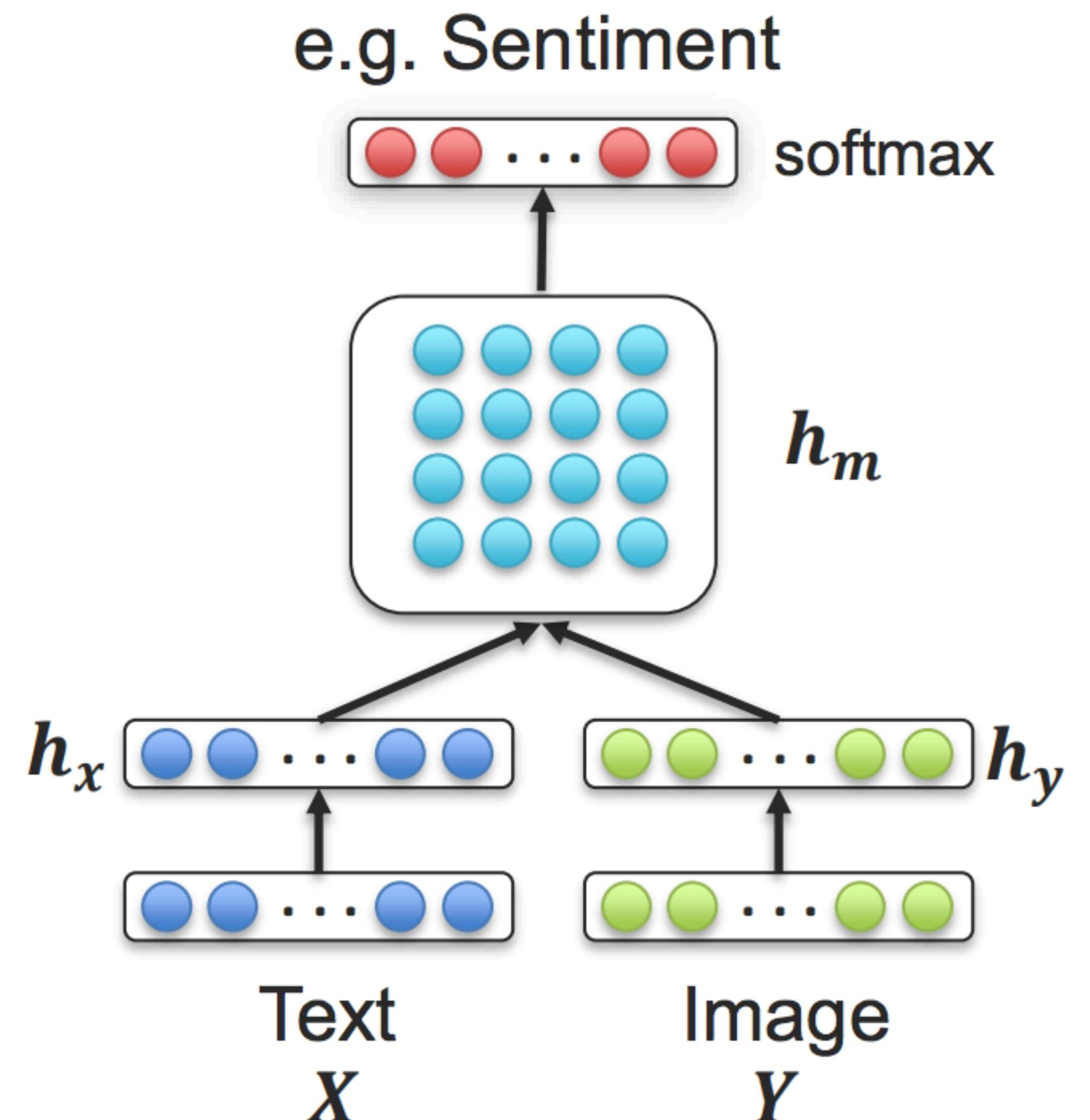
Bilinear Pooling

For supervised learning tasks, we need to join unimodal representations

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$$\mathbf{h}_m = \mathbf{h}_x \otimes \mathbf{h}_y$$

[Tenenbaum and Freeman, 2000]



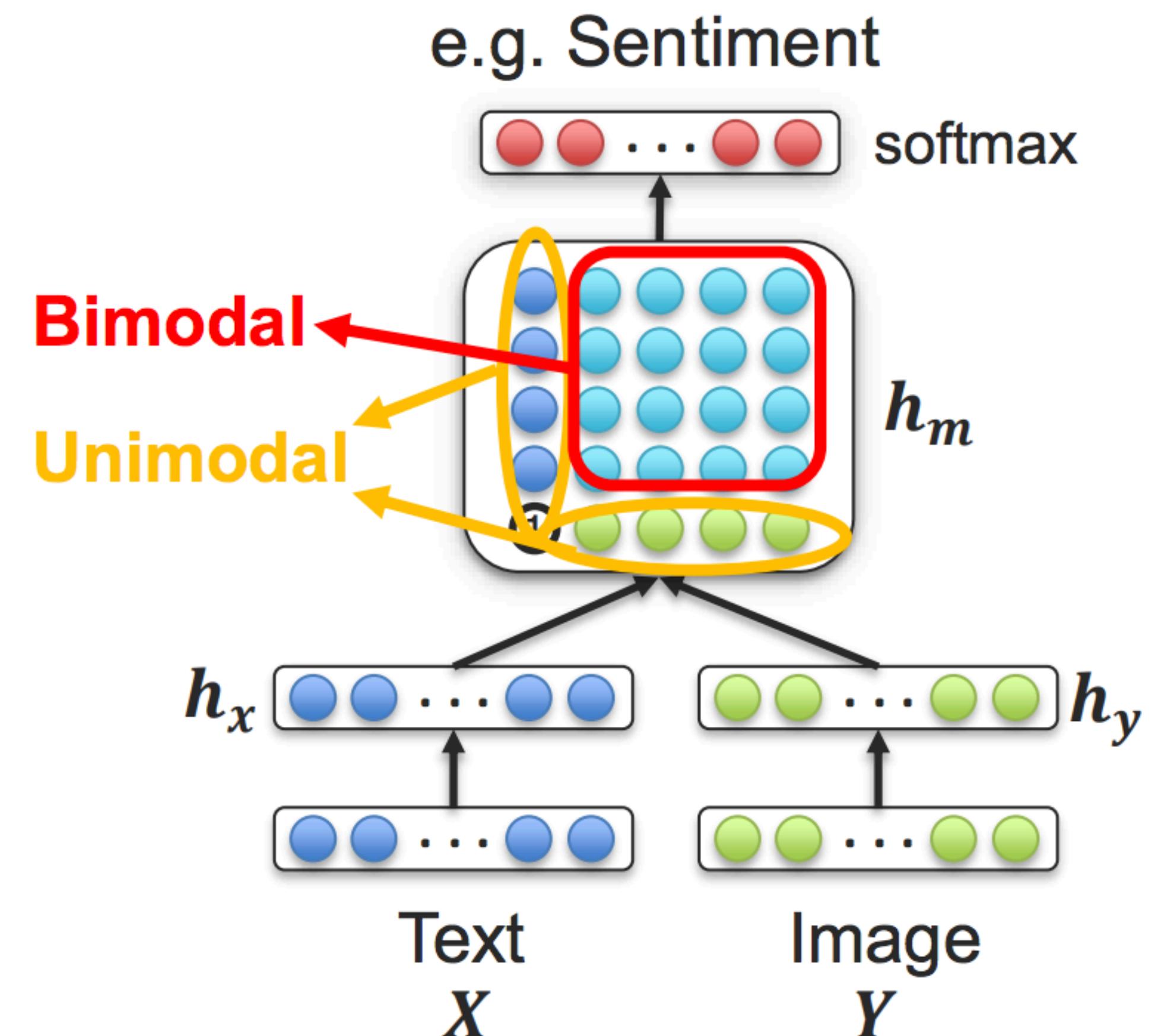
Multimodal Tensor Fusion Network (TFN)

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$$\mathbf{h}_m = \begin{bmatrix} \mathbf{h}_x \\ 1 \end{bmatrix} \otimes \begin{bmatrix} \mathbf{h}_y \\ 1 \end{bmatrix} = \begin{bmatrix} \mathbf{h}_x & \mathbf{h}_x \otimes \mathbf{h}_y \\ 1 & \mathbf{h}_y \end{bmatrix}$$

[Zadeh, Jones and Morency, EMNLP 2017]

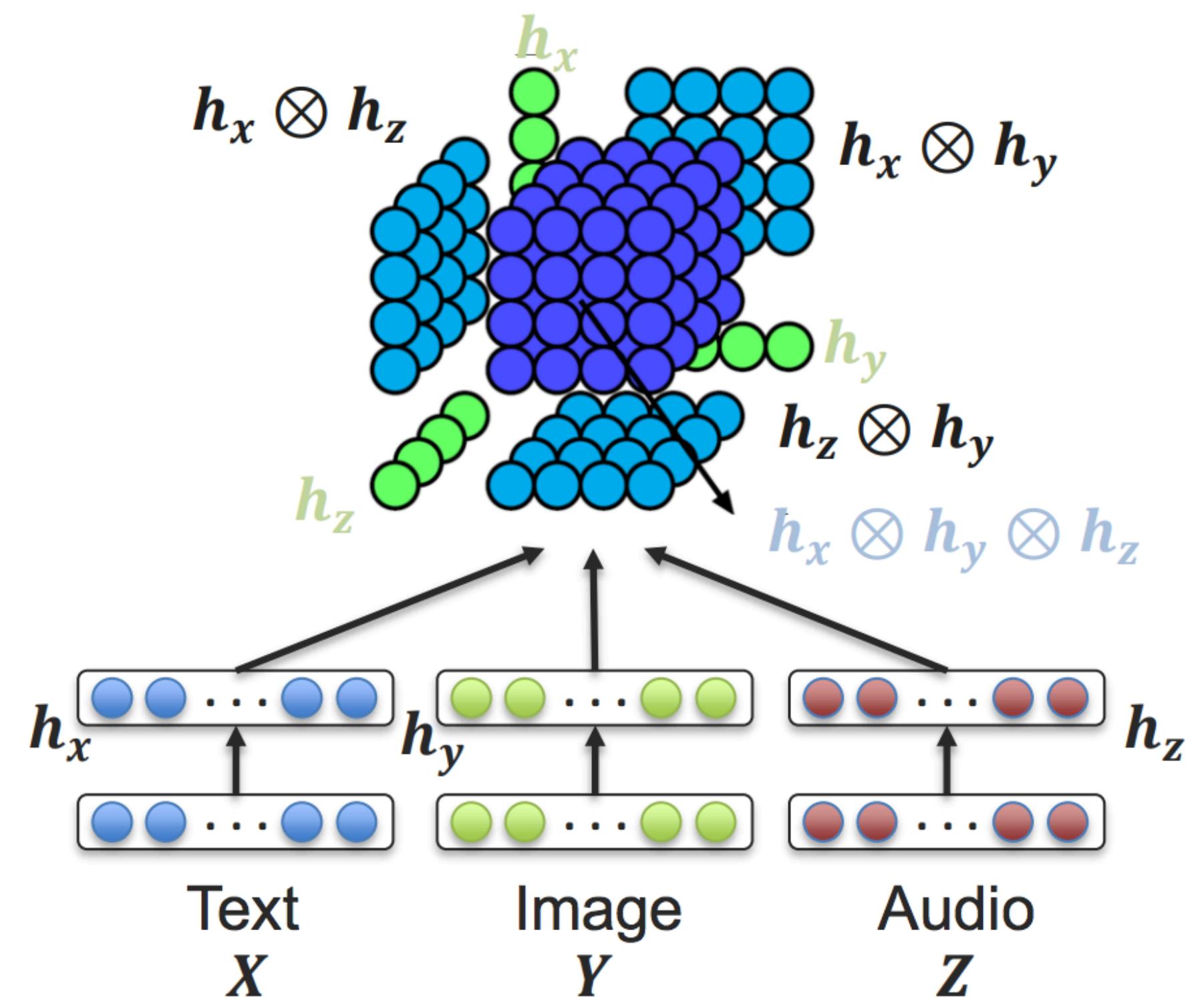


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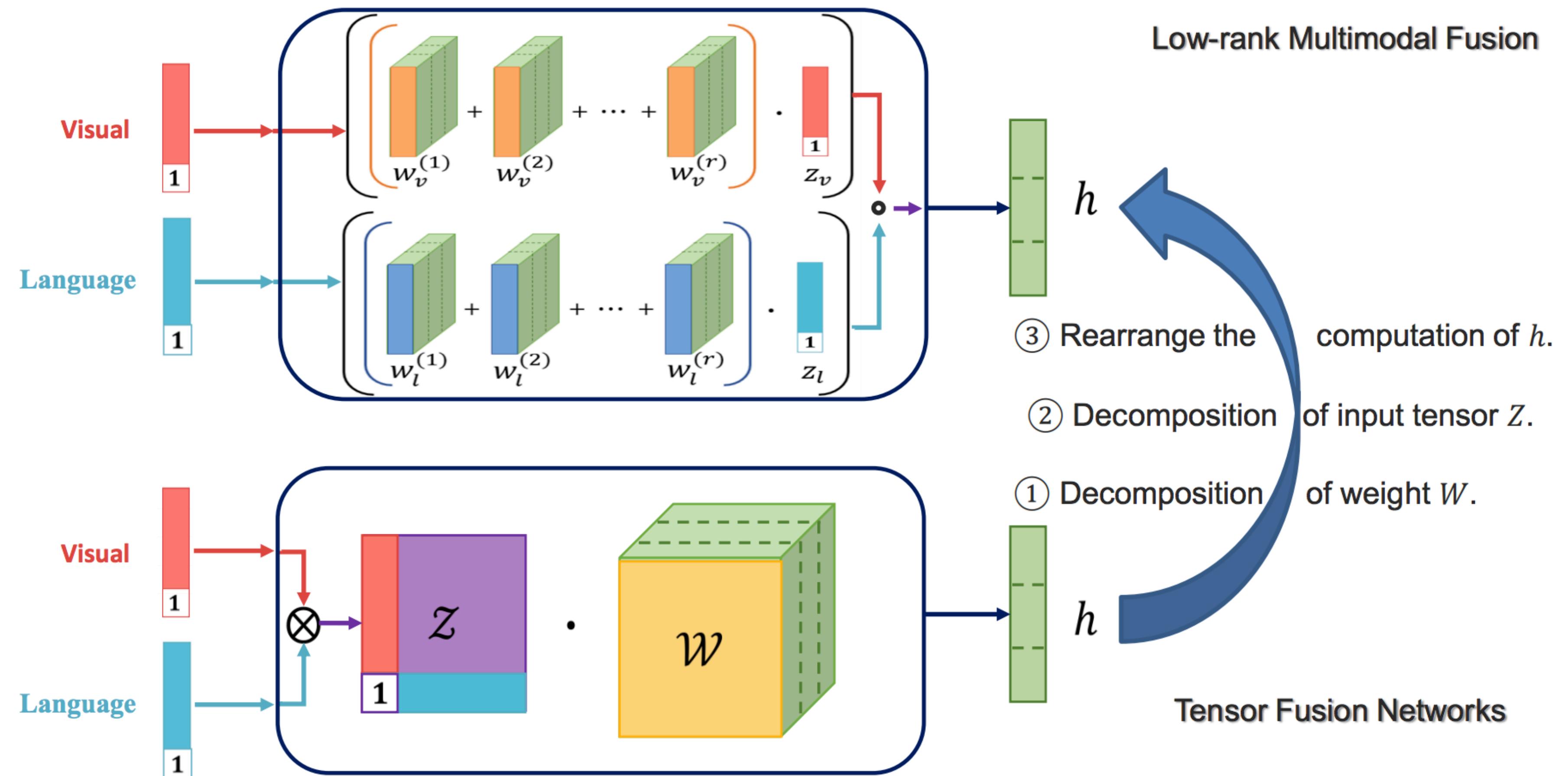
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[Zadeh, Jones and Morency, EMNLP 2017]

Low-rank Tensor Fusion



Tucker tensor decomposition leads to MUTAN fusion

[Ben-younes et al., ICCV 2017]

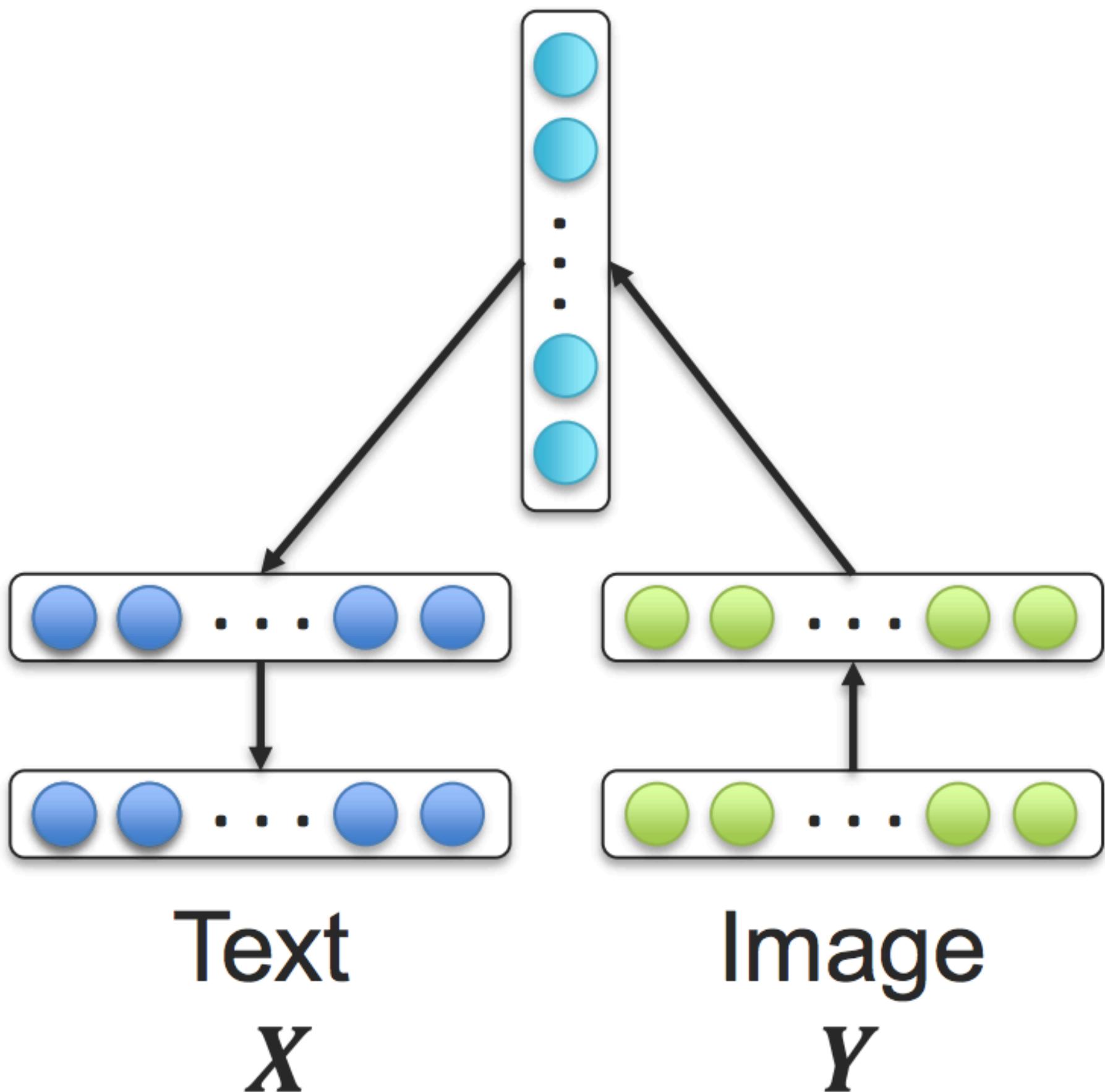
*slide from Louis-Philippe Morency

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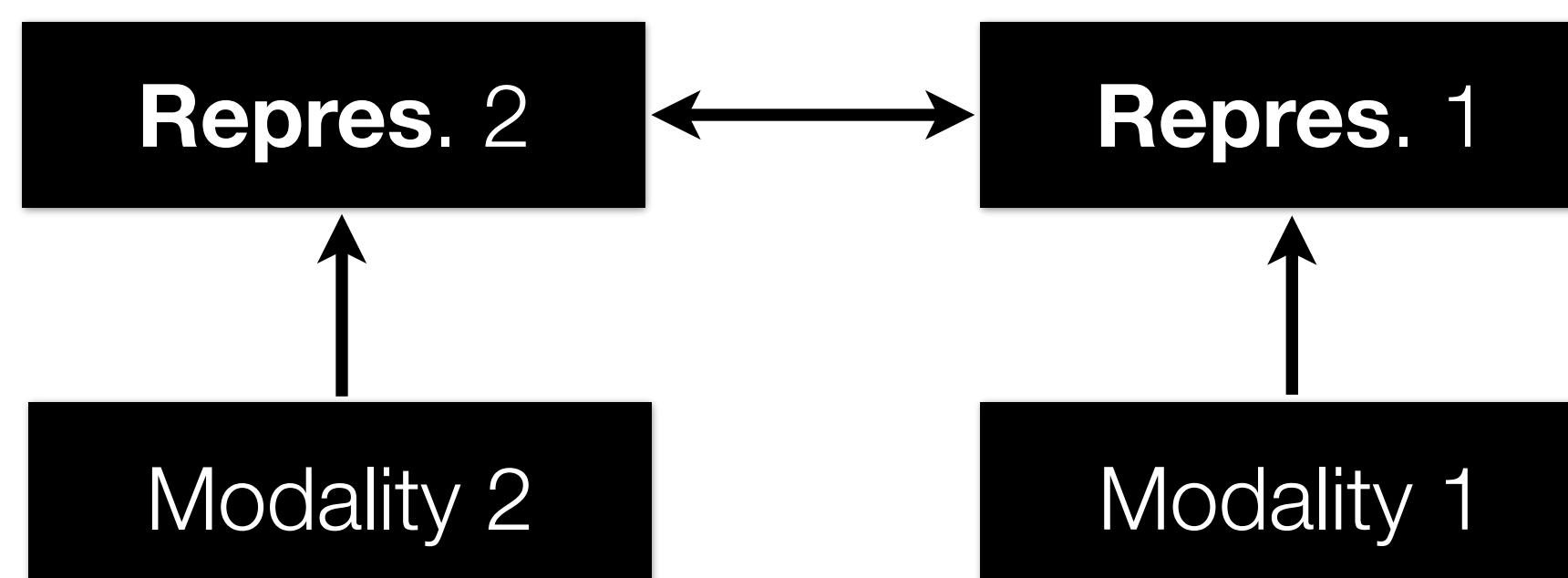
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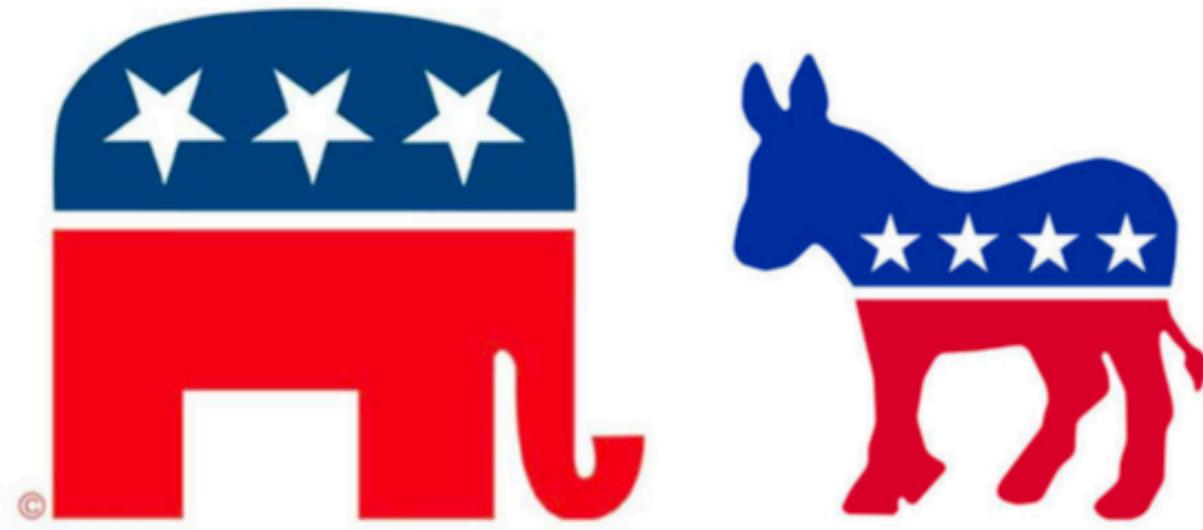
Data with Multiple Views

$x_1^{(i)}$

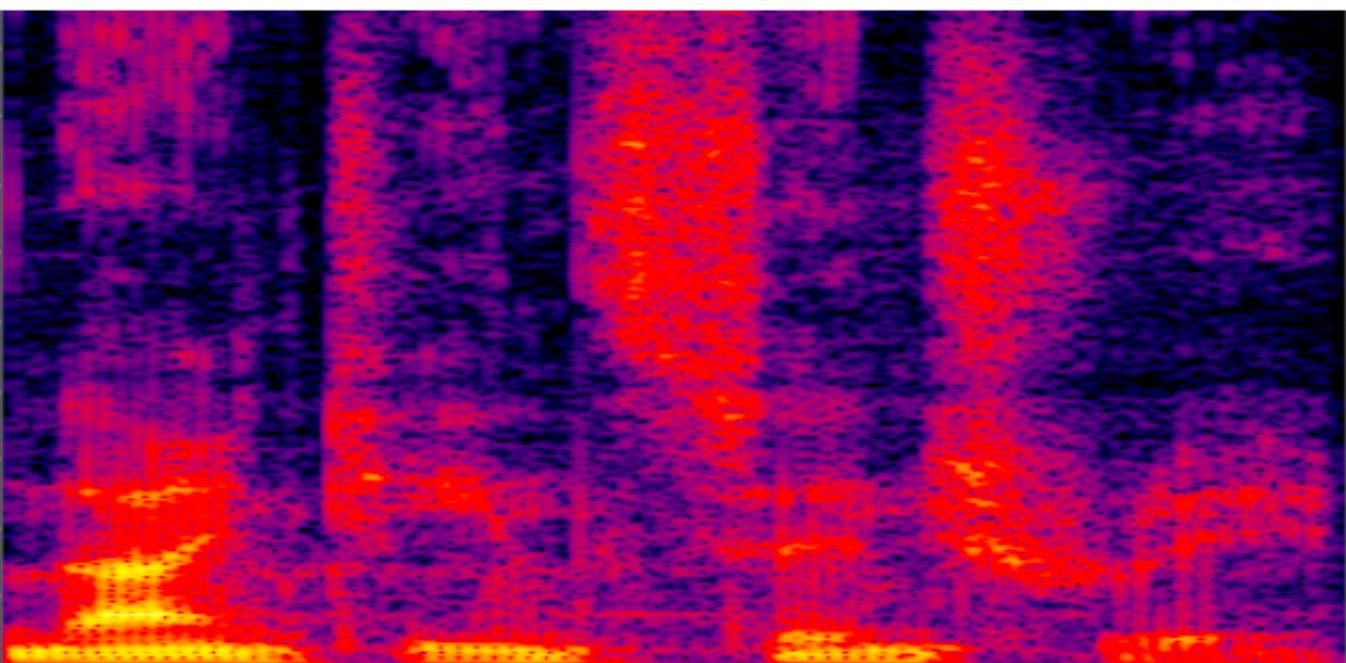


demographic properties

$x_2^{(i)}$



responses to survey



audio features at time i



video features at time i

Correlated Representations

Goal: Find representations $f_1(\mathbf{x}_1), f_2(\mathbf{x}_2)$ for each view that maximize correlation:

$$\text{corr}(f_1(\mathbf{x}_1), f_2(\mathbf{x}_2)) = \frac{\text{cov}(f_1(\mathbf{x}_1), f_2(\mathbf{x}_2))}{\sqrt{\text{var}(f_1(\mathbf{x}_1)) \cdot \text{var}(f_2(\mathbf{x}_2))}}$$

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Finding correlated representations can be **useful** for

- Gaining insights into the data
- Detecting of asynchrony in test data
- Removing noise uncorrelated across views
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Has been **applied widely** to problems in computer vision, speech, NLP, medicine, chemometrics, metrology, neurology, etc.

CCA: Canonical Correlation Analysis

Classical technique to find **linear** correlated representations, i.e.,

$$\begin{aligned} f_1(\mathbf{x}_1) &= \mathbf{W}_1^T \mathbf{x}_1 & \mathbf{W}_1 \in \mathbb{R}^{d_1 \times k} \\ f_2(\mathbf{x}_2) &= \mathbf{W}_2^T \mathbf{x}_2 & \text{where} \\ && \mathbf{W}_2 \in \mathbb{R}^{d_2 \times k} \end{aligned}$$

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The first columns ($\mathbf{w}_{1,:1}, \mathbf{w}_{2,:1}$) of the matrices \mathbf{W}_1 and \mathbf{W}_2 are found to maximize the **correlation of the projections**:

$$(\mathbf{w}_{1,:1}, \mathbf{w}_{2,:1}) = \arg \max \mathbf{corr}(\mathbf{w}_{1,:1}^T \mathbf{X}_1, \mathbf{w}_{2,:1}^T \mathbf{X}_2)$$

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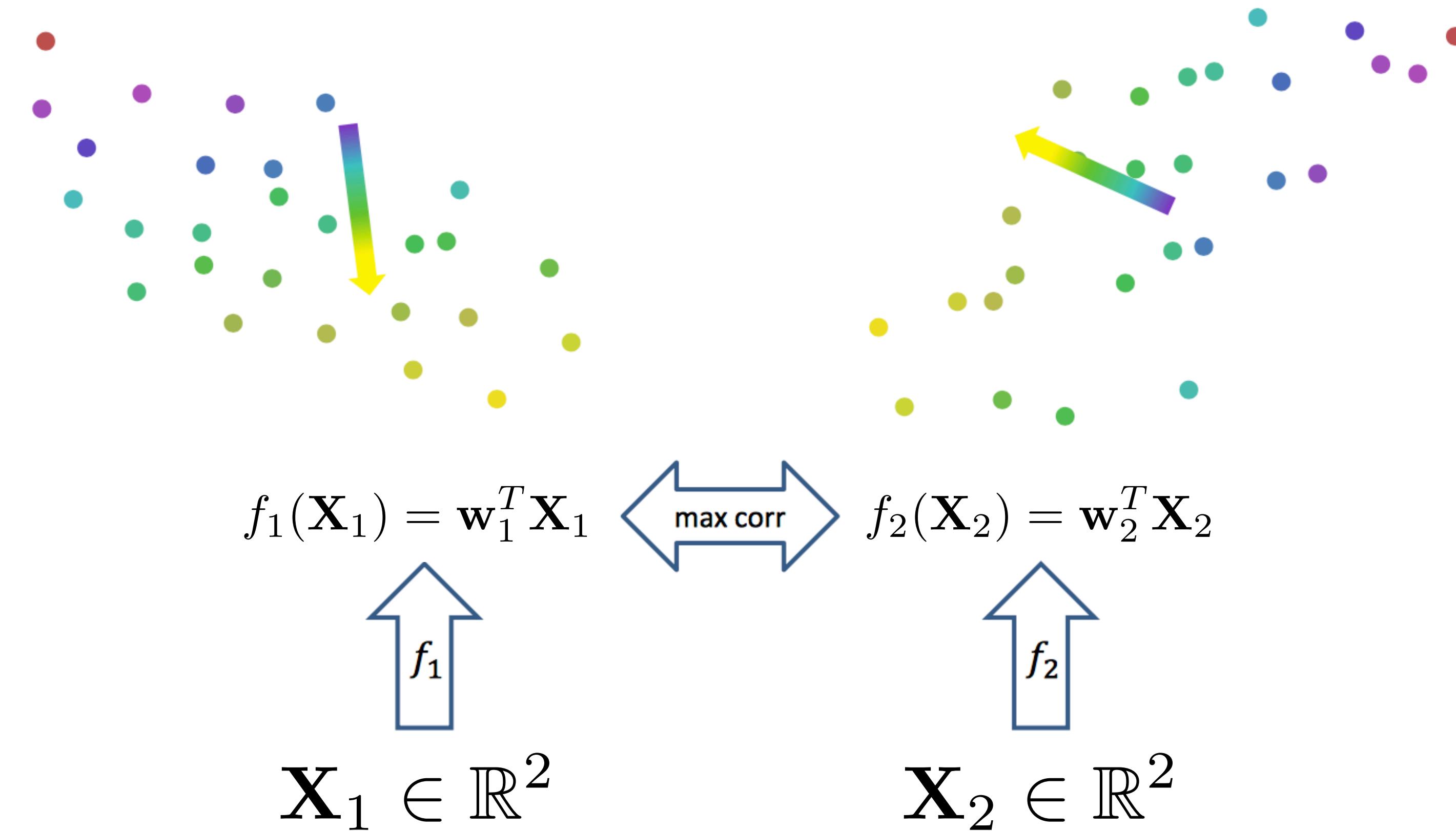
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Subsequent pairs are constrained to be **uncorrelated with previous components** (i.e., for $j < i$)

$$\mathbf{corr}(\mathbf{w}_{1,:i}^T \mathbf{X}_1, \mathbf{w}_{1,:j}^T \mathbf{X}_1) = \mathbf{corr}(\mathbf{w}_{2,:i}^T \mathbf{X}_2, \mathbf{w}_{2,:j}^T \mathbf{X}_2) = 0$$

CCA Illustration



Two views of each instance have the same color

CCA: Canonical Correlation Analysis

1. Estimate **covariance matrix** with regularization:

$$\Sigma_{11} = \frac{1}{N-1} \sum_{i=1}^N (\mathbf{x}_1^{(i)} - \bar{\mathbf{x}}_1)(\mathbf{x}_1^{(i)} - \bar{\mathbf{x}}_1)^T + r_1 \mathbf{I}$$

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$$\Sigma = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{12} & \Sigma_{22} \end{bmatrix} \quad \mathbf{W}_1^* \quad \mathbf{W}_2^* \quad \Rightarrow \quad \begin{bmatrix} 1 & 0 & 0 & \lambda_1 & 0 & 0 \\ 0 & 1 & 0 & 0 & \lambda_2 & 0 \\ 0 & 0 & 1 & 0 & 0 & \lambda_3 \\ \hline \lambda_1 & 0 & 0 & 1 & 0 & 0 \\ 0 & \lambda_2 & 0 & 0 & 1 & 0 \\ 0 & 0 & \lambda_3 & 0 & 0 & 1 \end{bmatrix}$$

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4. The optimal projection matrices are: $\mathbf{W}_1^* = \Sigma_{11}^{-1/2} \mathbf{U}_k$
 $\mathbf{W}_2^* = \Sigma_{22}^{-1/2} \mathbf{V}_k$

where \mathbf{U}_k is the first k columns of \mathbf{U} .

KCCA: Kernel CCA

There maybe **non-linear** functions $f_1(\mathbf{x}_1), f_2(\mathbf{x}_2)$ that produce more highly correlated (better) representations than linear projections

Kernel CCA is a principal method for finding such function

- Learns functions from any reproducing kernel Hilbert space
- May use different kernels for each view

Using **RBF** (Gaussian) kernel in KCCA is akin to finding sets of instances that form clusters in both views

KCCA vs. CCA

Pros:

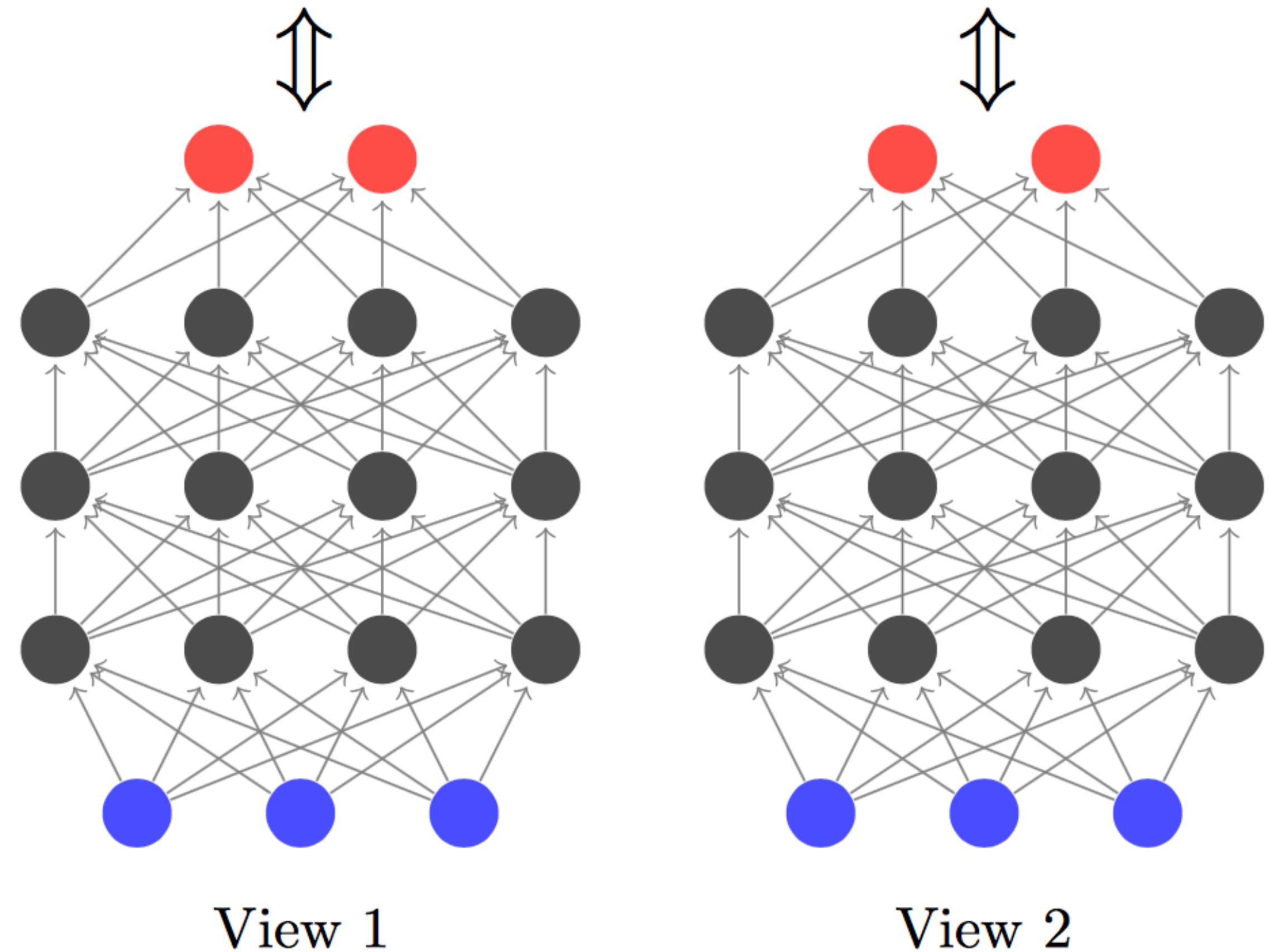
- More complex function space of KCCA can yield dramatically higher correlations

Cons:

- KCCA is slower to train
- For KCCA training set must be stored and referenced at test time
- KCCA model is more difficult to interpret

Deep CCA

Canonical Correlation Analysis



Benefits of Deep CCA

Pros:

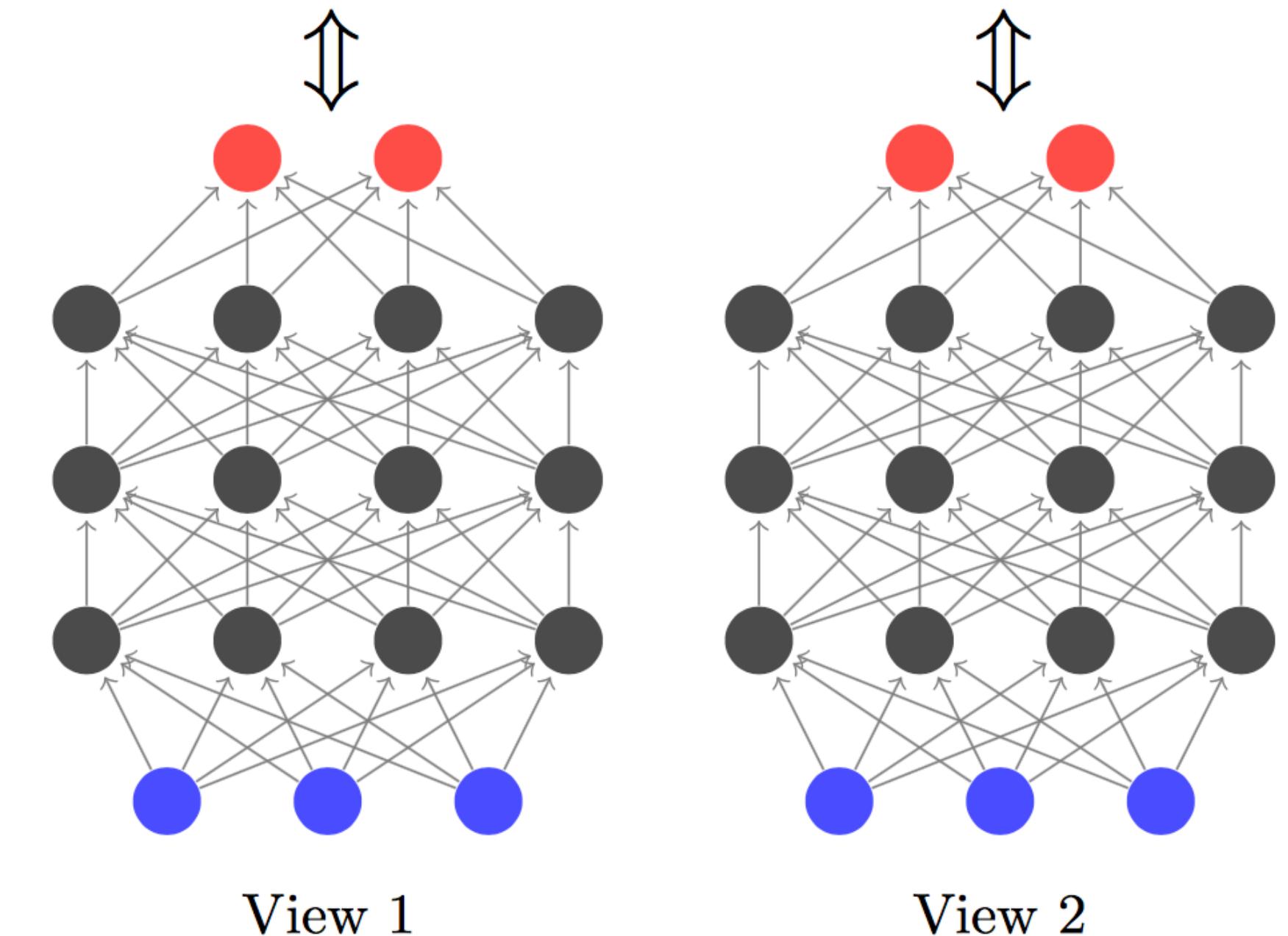
- Better suited for natural, real-world data
- **Parametric model**
 - The training set can be disregarded once the model is learned
 - Computational speed at test time is fast

Deep CCA: Training

Training a Deep CCA model:

1. **Pretrain** the layers of **each side** individually
2. **Jointly fine-tune** all parameters to maximize the total correlation of the output layers.
Requires computing correlation gradient:
 - Forward propagate activations on both sides.
 - Compute correlation and its gradient w.r.t. output layers.
 - Backpropagate gradient on both sides.

Canonical Correlation Analysis

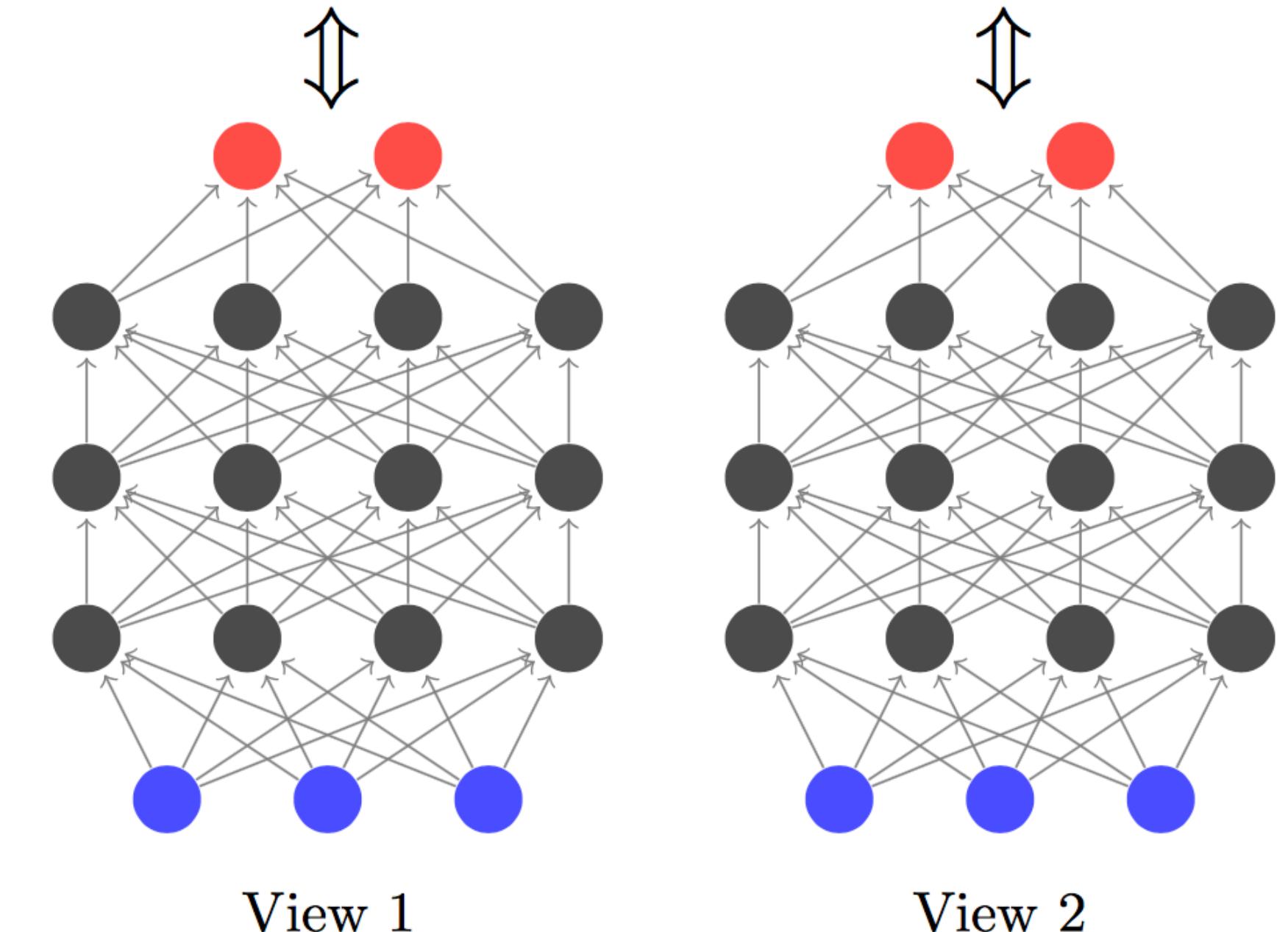


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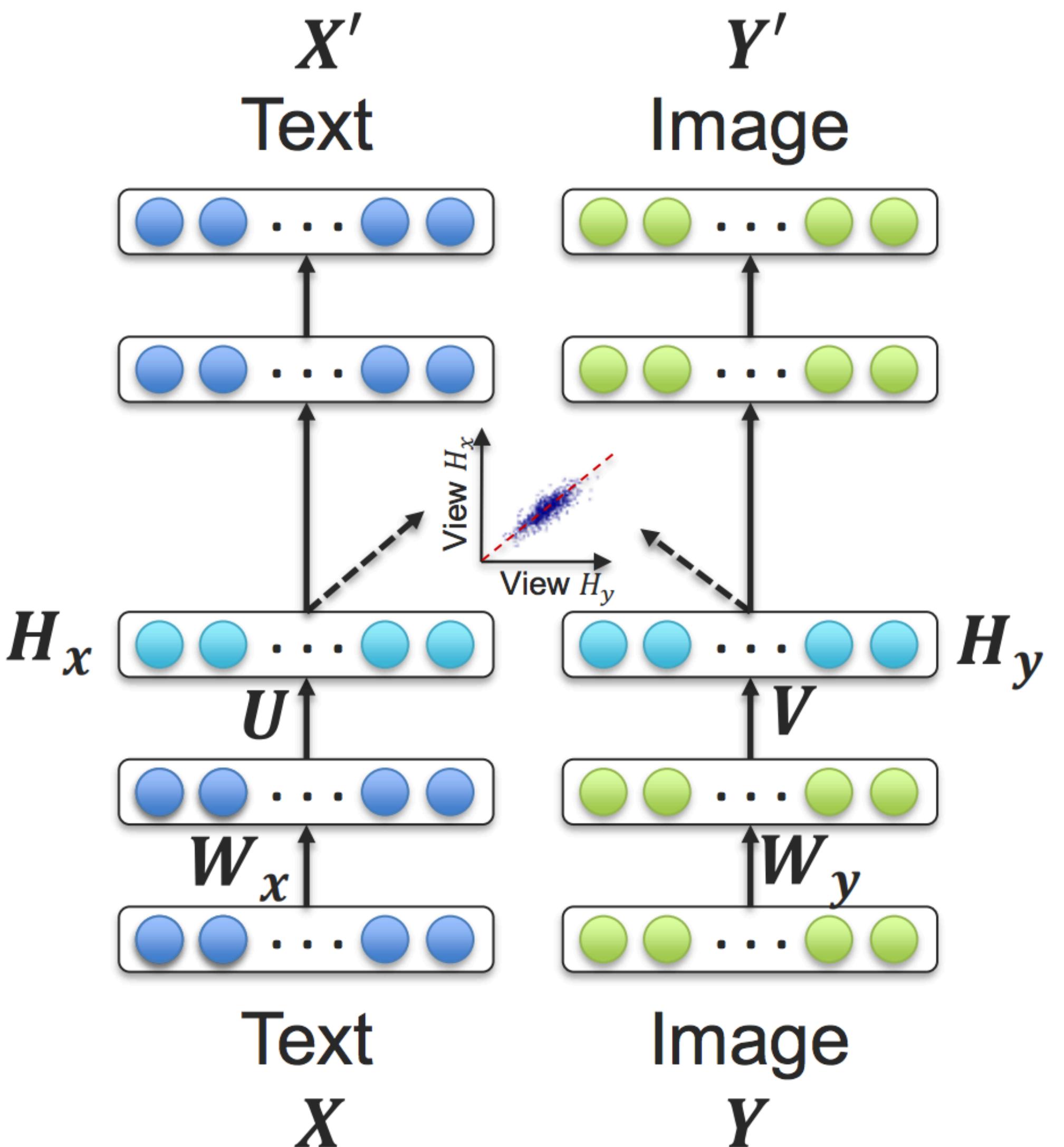


Correlation is a population objective, so instead of one instance (or minibatch) training, requires L-BFGS second-order method (with full-batch)

Deep Canonically Correlated Autoencoders (DCCAE)

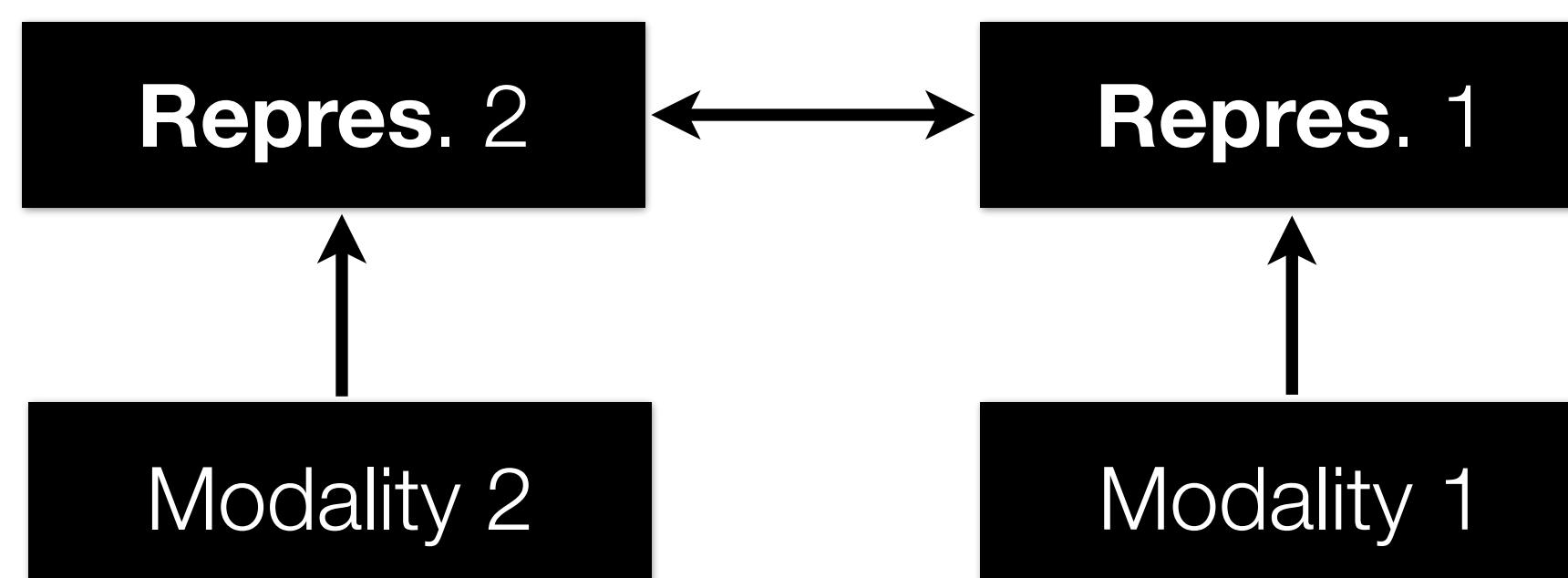
Jointly optimize for DCCA and auto encoders loss functions

- A trade-off between multi-view correlation and reconstruction error from individual views



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Coordinated representations:



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- **Structure constraints** (e.g., orthogonality, sparseness)
- Examples: CCA, joint embeddings

Correlated Representations vs. Joint Embeddings

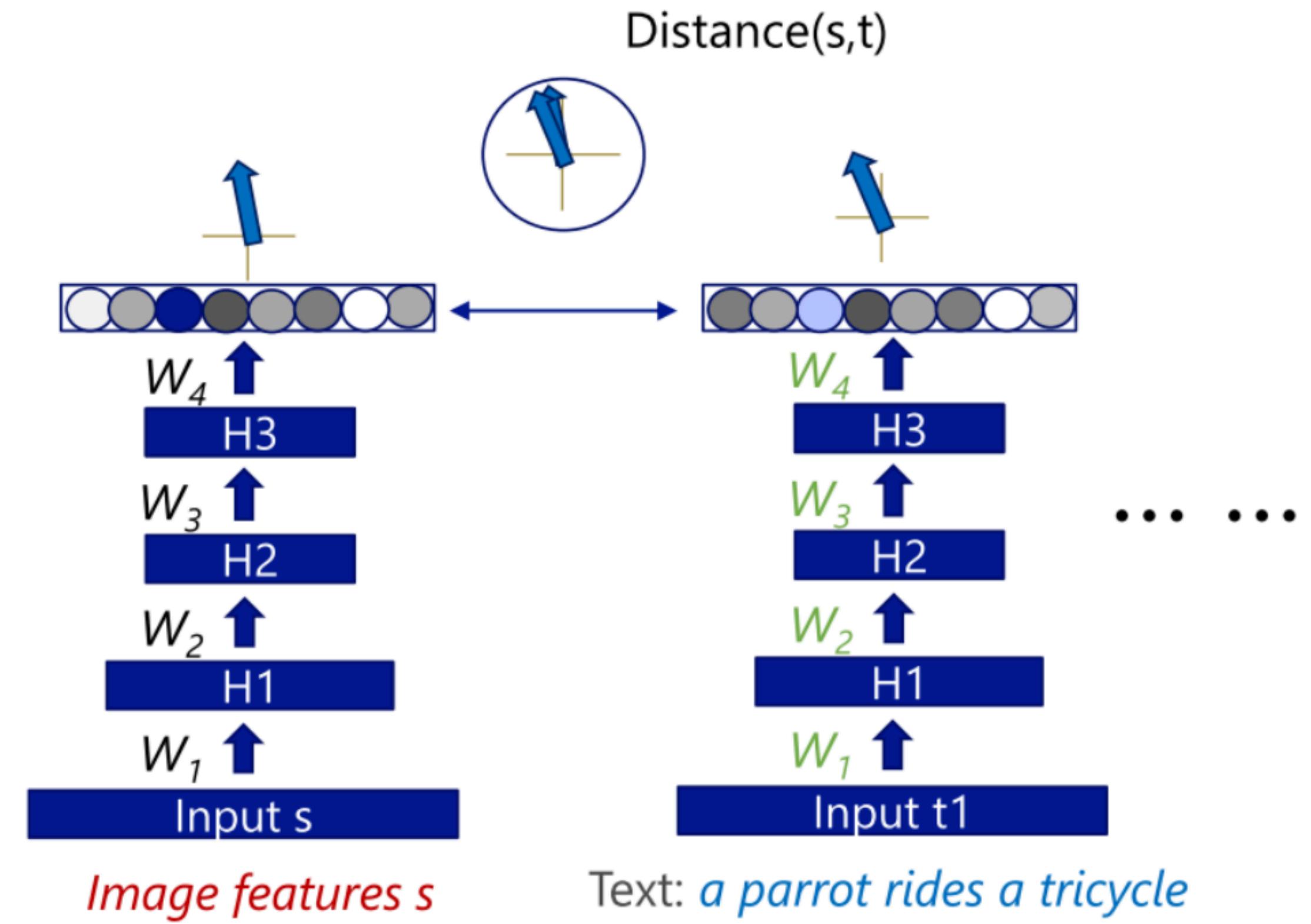
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Joint Embeddings: Models that minimize distance between ground truth pairs of samples:

$$\min_{f_1, f_2} D \left(f_1(\mathbf{x}_1^{(i)}), f_2(\mathbf{x}_2^{(i)}) \right)$$

Joint Embeddings



Joint Embeddings

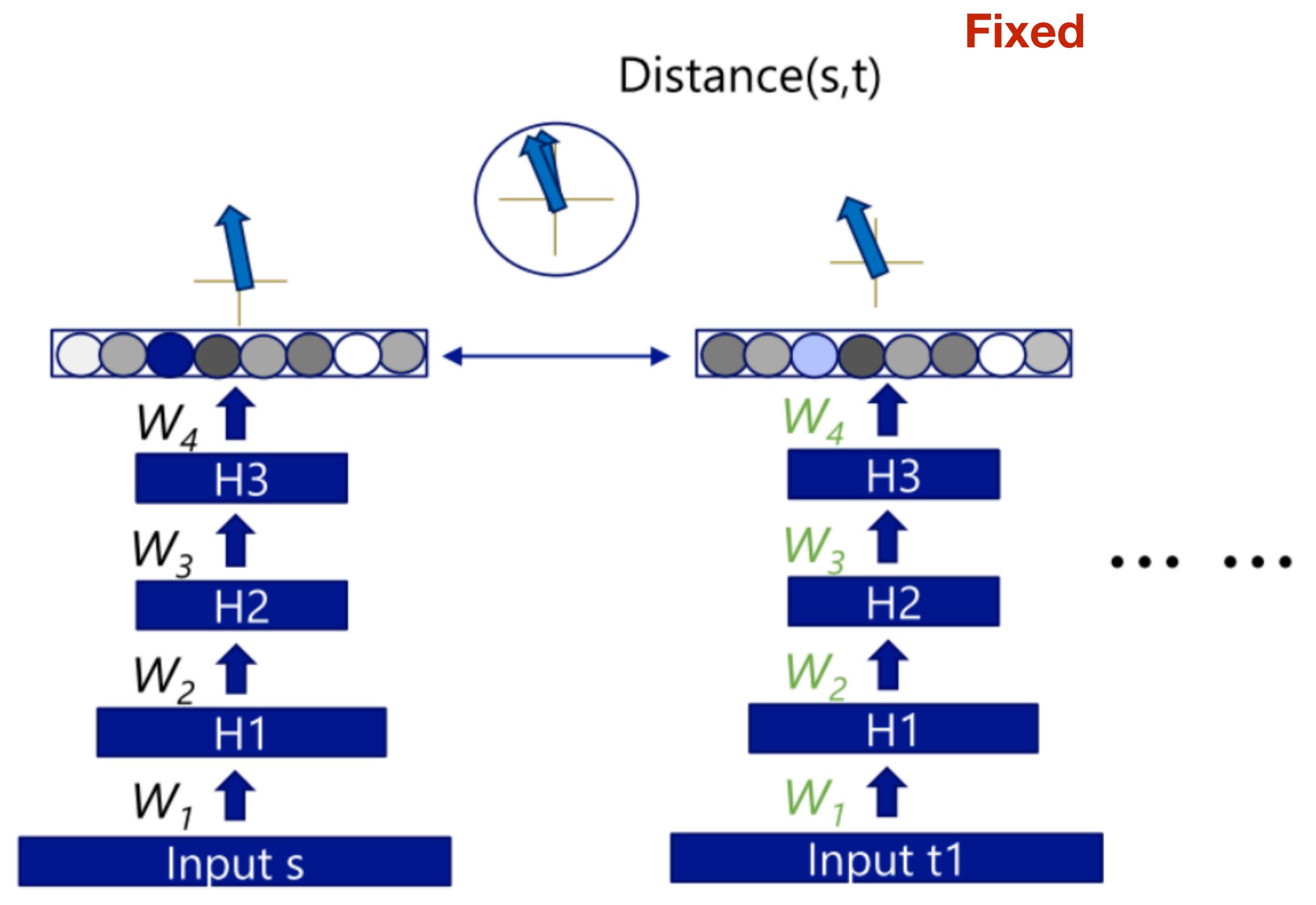


Fixed

Image features s

Text: *a parrot rides a tricycle*

Fixed



Joint Embeddings



- blue + red =



- blue + yellow =



- yellow + red =



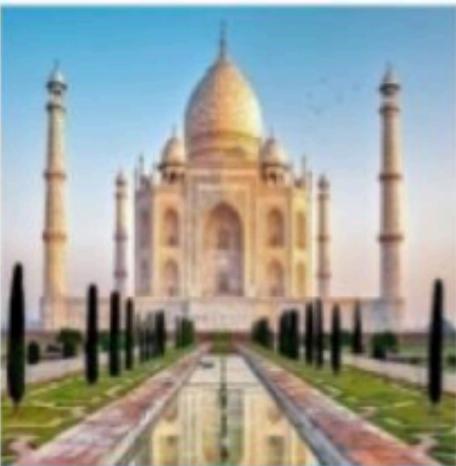
- white + red =



Nearest images

Joint Embeddings

Nearest images



- day + night =



- flying + sailing =



- bowl + box =



- box + bowl =



[Kiros et al., Unifying Visual-Semantic Embeddings with Multimodal Neural Language Models, 2014]