# **Professorship in Transportation Analytics**

Teaching Concept & Philosophy

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#### **Education Mission**

"Education is not the learning of facts, but the training of the mind to think."



Albert Einstein

- TUM School of Management in Heilbronn:
  - o Bachelor in Management & Data Science
  - o Master in Management
  - o Master in Management & Digital Technology
  - o Master in Management & Innovation
- My targets: Fostering curiosity and empowering students to take ownership of their learning; Creating an inclusive and engaging environment that supports diverse students.

## **Teaching Methods**

#### Format & Assessment:

- Research-based techniques & guest talks (critical thinking skills)
- Class quiz (problem solving)
- Project-oriented examination (problem solving)
- Mid-term/final-term presentation

#### Classroom is a family:

- Making learning fun
- Making it as simple and clear as possible
- Offee time for discussion (guidance & support & thought exchange)

#### Collaboration:

- Approaching advanced AI techniques
- Building blog posts (e.g., ICLR blogposts track)





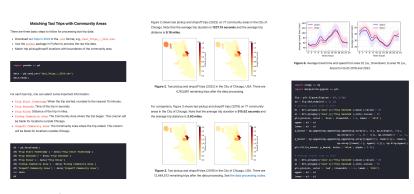
Source: ICLR 2024

# Methods for Assessing Students' Learning

## Learning with Data Example

#### Well-documented data files:

- Beginners to build coding skills
- @ Graduate students to build research projects



Source: https://spatiotemporal-data.github.io/Chicago-mobility/taxi-data

### **Tutorials**

Intuitive understanding of core concepts in data science:

- O Creating graphics
- 2 Examining with realistic data
- Oeveloping toy examples
- Providing Python implementation

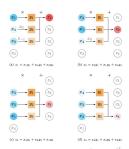


Figure 2. Illustration of the circular convolution between  $x = (x_1, x_2, x_3, x_4)^{\top}$  and  $y = (y_1, y_2, y_3)^{\top}$ . (a) Computing  $z_1$  involves  $x_0 = x_4$  and  $x_{-1} = x_5$ . (b) Computing  $z_2$  involves  $x_0 = x_4$ . The figure insoired by Prince (2023).

Example 2. Given vectors  $\mathbf{x} = (0, 1, 2, 3, 4)^{\top}$  and  $\mathbf{y} = (2, -1, 3)^{T}$ , the circular convolution  $\mathbf{z} = \mathbf{x} * \mathbf{y}$  can be expressed as:  $\mathbf{z} = \mathbf{x} * \mathbf{y} = C_1(\mathbf{z}) \mathbf{y} = (5, 14, 3, 7, 11)^{\top}$  where  $C_2(\mathbf{z})$  is the convolution matrix with  $\tau = 3$  columns. Specifically, the convolution matrix is structured as follows,  $C_3(\mathbf{z}) = \begin{bmatrix} 0 & 4 & 3 \\ 2 & 1 & 0 \\ 3 & 2 & 1 \\ 4 & 3 & 2 \end{bmatrix}$  As a result, it gives  $\mathbf{z} = C_3(\mathbf{z}) \mathbf{y} = \begin{bmatrix} 0 & 4 & 3 \\ 1 & 0 & 4 \\ 2 & 2 & 0 \\ 1 & 2 & 2 \\ 2 & 2 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ 1 \\ 3 \\ 1 & 3 \end{bmatrix}$ 

This representation shows that the circular convolution is equivalent to a matrix-vector

multiplication, making it easier to understand, especially in signal processing applications.

Source: https://spatiotemporal-data.github.io/posts/ts\_conv

## Reproducible Classes

#### Open-source repositories:

- Providing supplementary materials
- Examining examples and codes
- Reproducing graphics in LaTeX

# 

## Explanation style



awesome-beamer

(100+ GitHub stars)

Class website will be available at https://spatiotemporal-data.github.io

### References

- 3Blue1Brown
  - A math YouTube channel created and run by Grant Sanderson
  - o Website: https://www.3blue1brown.com/



Source: Wiki

- Prof. Steve Brunton (UW)
  - o Data-driven dynamics and control
  - o Website: https://www.youtube.com/@Eigensteve

# Thank you!

# Any Questions?

#### About me:

- ★ Homepage: https://xinychen.github.io
- MIT sites: https://sites.mit.edu/xinychen