MATH 322 – Graph Theory Fall Term 2021

Notes for Lecture 25

Wednesday, December 8

Crossing Number of a Graph, and Plane/Planar Graphs

From last time

Definition 1

Given a (finite) graph G, we define its <u>crossing number</u> to be the minimum number of edge crossings that a (permissible) pictorial representation of G can have.

We usually denote this number by cr(G).

From last time

Definition 1

Given a (finite) graph G, we define its <u>crossing number</u> to be the minimum number of edge crossings that a (permissible) pictorial representation of G can have.

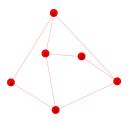
We usually denote this number by cr(G).

Definition 2

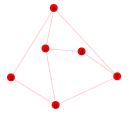
A graph G = (V, E) is called <u>planar</u> if we can draw it in the plane without any edge crossings. In other words, if cr(G) = 0.

Any such pictorial representation of G will be called a *planar embedding*, or equivalently a *plane representation*, of G.

Consider now a plane representation G_0 of a planar finite graph (note that G_0 for now denotes the specific plane representation we are considering); for instance, G_0 could be

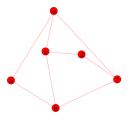


Consider now a plane representation G_0 of a planar finite graph (note that G_0 for now denotes the specific plane representation we are considering); for instance, G_0 could be



Consider also a point p which is NOT one of the vertices of G_0 , NOR is it found in the relative interior of any of the edges of G_0 . Then $p \in \mathbb{R}^2 \setminus G_0$, which is an open set. Thus we can also find a maximal connected open subset of $\mathbb{R}^2 \setminus G_0$ which contains p.

Consider now a plane representation G_0 of a planar finite graph (note that G_0 for now denotes the specific plane representation we are considering); for instance, G_0 could be

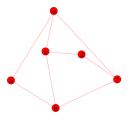


Consider also a point p which is NOT one of the vertices of G_0 , NOR is it found in the relative interior of any of the edges of G_0 . Then $p \in \mathbb{R}^2 \setminus G_0$, which is an open set. Thus we can also find a maximal connected open subset of $\mathbb{R}^2 \setminus G_0$ which contains p.

Definition 3

If G_0 is a plane representation of a planar finite graph, then the maximal connected open subsets of $\mathbb{R}^2 \setminus G_0$ are called the <u>faces</u> of G_0 .

Consider now a plane representation G_0 of a planar finite graph (note that G_0 for now denotes the specific plane representation we are considering); for instance, G_0 could be



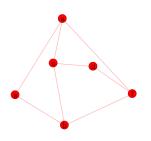
Consider also a point p which is NOT one of the vertices of G_0 , NOR is it found in the relative interior of any of the edges of G_0 . Then $p \in \mathbb{R}^2 \setminus G_0$, which is an open set. Thus we can also find a maximal connected open subset of $\mathbb{R}^2 \setminus G_0$ which contains p.

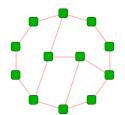
Definition 3

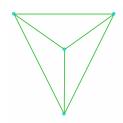
If G_0 is a plane representation of a planar finite graph, then the maximal connected open subsets of $\mathbb{R}^2 \setminus G_0$ are called the <u>faces</u> of G_0 .

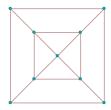
Note that since G_0 is finite, it will have exactly one unbounded face, the area 'outside' of/surrounding the graph/diagram, while all the other faces will be bounded sets.

Testing the definition on examples

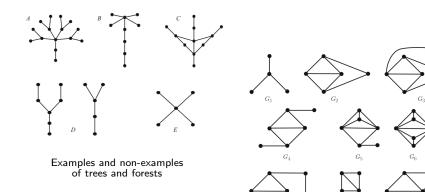








Testing the definition on examples (cont.)



The forbidden subgraphs from Beineke's thm (see Lec 8)

 G_7

Definition 4

Let G_0 be a plane representation of a planar finite graph, and let f_0 be a face of G_0 . We define the $length \ \ell(f_0)$ of the face f_0 to be

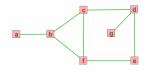
the length of a <u>closed</u> walk which bounds f_0 (in other words, which traces the boundary of f_0) and has minimum possible length.

Definition 4

Let G_0 be a plane representation of a planar finite graph, and let f_0 be a face of G_0 . We define the $length \ \ell(f_0)$ of the face f_0 to be

the length of a <u>closed</u> walk which bounds f_0 (in other words, which traces the boundary of f_0) and has minimum possible length.

Example. The plane graph below has 3 faces: the unbounded face f_1 , the face f_2 which is bounded by the 3-cycle $b\ c\ f\ b$, and the face f_3 which is contained within the 4-cycle $c\ d\ e\ f\ c$.

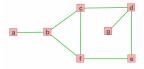


Definition 4

Let G_0 be a plane representation of a planar finite graph, and let f_0 be a face of G_0 . We define the *length* $\ell(f_0)$ of the face f_0 to be

the length of a <u>closed</u> walk which bounds f_0 (in other words, which traces the boundary of f_0) and has minimum possible length.

Example. The plane graph below has 3 faces: the unbounded face f_1 , the face f_2 which is bounded by the 3-cycle b c f b, and the face f_3 which is contained within the 4-cycle c d e f c.



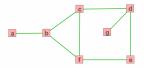
– Note that a closed walk tracing the boundary of f_2 is the 3-cycle b c f b (and this is also best possible), thus f_2 has length 3.

Definition 4

Let G_0 be a plane representation of a planar finite graph, and let f_0 be a face of G_0 . We define the *length* $\ell(f_0)$ of the face f_0 to be

the length of a <u>closed</u> walk which bounds f_0 (in other words, which traces the boundary of f_0) and has minimum possible length.

Example. The plane graph below has 3 faces: the unbounded face f_1 , the face f_2 which is bounded by the 3-cycle b c f b, and the face f_3 which is contained within the 4-cycle c d e f c.



- Note that a closed walk tracing the boundary of f_2 is the 3-cycle b c f b (and this is also best possible), thus f_2 has length 3.
- On the other hand, a closed walk tracing the entire boundary of f_3 is the walk

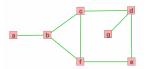
Note also that we cannot find any other closed walks (tracing the boundary of f_3) which will have even shorter length, and thus $\ell(f_3) = \text{length}$ of the above walk = 6.

Definition 4

Let G_0 be a plane representation of a planar finite graph, and let f_0 be a face of G_0 . We define the $length \ \ell(f_0)$ of the face f_0 to be

the length of a <u>closed</u> walk which bounds f_0 (in other words, which traces the boundary of f_0) and has minimum possible length.

Example. The plane graph below has 3 faces: the unbounded face f_1 , the face f_2 which is bounded by the 3-cycle $b\ c\ f\ b$, and the face f_3 which is contained within the 4-cycle $c\ d\ e\ f\ c$.



- Note that a closed walk tracing the boundary of f_2 is the 3-cycle b c f b (and this is also best possible), thus f_2 has length 3.
- On the other hand, a closed walk tracing the entire boundary of f_3 is the walk

Note also that we cannot find any other closed walks (tracing the boundary of f_3) which will have even shorter length, and thus $\ell(f_3) = \text{length}$ of the above walk = 6.

– Finally, similarly we can find that $\ell(f_1) = 7$. (which closed walk would you use here?)

Theorem 1

Let G_0 be a plane representation of a planar finite graph, and let f_1, f_2, \ldots, f_s be the faces of G_0 . Then we have that

$$\sum_{i=1}^s \ell(f_i) = 2e(G_0).$$

Observe that this result is reminiscent of the Handshaking Lemma (and its proof is also done in the same spirit).

Theorem 1

Let G_0 be a plane representation of a planar finite graph, and let f_1, f_2, \ldots, f_s be the faces of G_0 . Then we have that

$$\sum_{i=1}^s \ell(f_i) = 2e(G_0).$$

Observe that this result is reminiscent of the Handshaking Lemma (and its proof is also done in the same spirit).

Theorem 2 (Euler's formula, 1758)

Let G_0 be a plane representation of a <u>connected</u> planar finite graph, and write n for the number of vertices of G_0 , e for the number of edges of G_0 , and \tilde{f} for the number of faces of G_0 .

Theorem 1

Let G_0 be a plane representation of a planar finite graph, and let f_1, f_2, \ldots, f_s be the faces of G_0 . Then we have that

$$\sum_{i=1}^s \ell(f_i) = 2e(G_0).$$

Observe that this result is reminiscent of the Handshaking Lemma (and its proof is also done in the same spirit).

Theorem 2 (Euler's formula, 1758)

Let G_0 be a plane representation of a <u>connected</u> planar finite graph, and write n for the number of vertices of G_0 , e for the number of edges of G_0 , and \tilde{f} for the number of faces of G_0 . Then (regardless of what exactly G_0 looks like), we will always have that

$$n-e+\tilde{f}=2.$$

Proof of Euler's formula

We will be relying on a very famous theorem from set-theoretic topology:

The Jordan curve theorem

A curve $\mathcal C$ in $\mathbb R^2$ which is **simple** and **closed** divides its complement $\mathbb R^2\setminus \mathcal C$ into two maximal connected open subsets: a bounded (or 'interior') region (which is enclosed by $\mathcal C$), and an unbounded (or 'exterior') region.

 G_0 is connected, we must have $e = e(G_0) \ge n$ Base Case: e = n - 1.

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geq n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges.

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $\operatorname{e}(\widetilde{G}_0)>n-1$, and \widetilde{G}_0 is not a tree. Thus we can find an edge z_0 of \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , which also implies that z_0 is part of the boundary of at least one bounded face f_0 of \widetilde{G}_0).

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n$ –

connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $e(\widetilde{G}_0)>n-1$, and \widetilde{G}_0 is not a tree. Thus we can find an edge z_0 of \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , which also implies that z_0 is part of the boundary of at least one bounded face f_0 of \widetilde{G}_0). But then \widetilde{G}_0-z_0 is a connected subgraph of \widetilde{G}_0 (thus it is also a plane graph), and measure we have that

and moreover we have that $-\widetilde{G}_0 - z_0$ has the same number of vertices as \widetilde{G}_0 (in fact, it has the same vertices),

- $G_0 - Z_0$ has the same number of vertices as G_0 (in fact, it has the same vertices)

Base Case: e = n - 1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n - e + \tilde{f} = n - (n - 1) + 1 = 2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph G_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $e(G_0) > n-1$, and G_0 is not a tree. Thus we can find an edge z_0 of which also implies that z_0 is part of the boundary of at least one bounded face f_0 of

- \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , But then $G_0 - z_0$ is a connected subgraph of G_0 (thus it is also a plane graph), and moreover we have that
- $-\widetilde{G}_0-z_0$ has the same number of vertices as \widetilde{G}_0 (in fact, it has the same vertices),
- and $e(\widetilde{G}_0 z_0) = e(\widetilde{G}_0) 1 = \widetilde{e}$.

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $e(\widetilde{G}_0) > n-1$, and \widetilde{G}_0 is not a tree. Thus we can find an edge z_0 of \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , which also implies that z_0 is part of the boundary of at least one bounded face f_0 of \widetilde{G}_0). But then $\widetilde{G}_0 - z_0$ is a connected subgraph of \widetilde{G}_0 (thus it is also a plane graph), and moreover we have that

- \widetilde{G}_0-z_0 has the same number of vertices as \widetilde{G}_0 (in fact, it has the same vertices),
- and $e(\widetilde{G}_0 z_0) = e(\widetilde{G}_0) 1 = \widetilde{e}$.
- Finally, observe that, by removing edge z_0 , we definitely broke the cycle that contained it (in fact, any cycle that contained it), and we have also united \underline{two} faces of \widetilde{G}_0 into \underline{one} maximal connected open subset now. In other words, we have that

$$\widetilde{f}(\widetilde{G}_0-z_0)=\widetilde{f}(\widetilde{G}_0)-1$$

(note that this exact relation about the faces of the original graph and its connected subgraph can be rigorously justified by the Jordan curve theorem).

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $e(\widetilde{G}_0)>n-1$, and \widetilde{G}_0 is not a tree. Thus we can find an edge z_0 of \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , which also implies that z_0 is part of the boundary of at least one bounded face f_0 of \widetilde{G}_0). But then \widetilde{G}_0-z_0 is a connected subgraph of \widetilde{G}_0 (thus it is also a plane graph), and moreover we have that

- \widetilde{G}_0-z_0 has the same number of vertices as \widetilde{G}_0 (in fact, it has the same vertices),
- and $e(\widetilde{G}_0 z_0) = e(\widetilde{G}_0) 1 = \widetilde{e}$.
- Finally, observe that, by removing edge z_0 , we definitely broke the cycle that contained it (in fact, any cycle that contained it), and we have also united \underline{two} faces of \widetilde{G}_0 into \underline{one} maximal connected open subset now. In other words, we have that

$$\widetilde{f}(\widetilde{G}_0-z_0)=\widetilde{f}(\widetilde{G}_0)-1$$

(note that this exact relation about the faces of the original graph and its connected subgraph can be rigorously justified by the Jordan curve theorem).

But then, by the Inductive Hypothesis, we can write

$$2 = |\widetilde{G}_0 - z_0| - e(\widetilde{G}_0 - z_0) + \widetilde{f}(\widetilde{G}_0 - z_0)$$

Base Case: e=n-1. Then we have that G_0 is a tree, and thus (as we also verified on examples) it will only have one face, the unbounded one. But then $\tilde{f}=1$, and $n-e+\tilde{f}=n-(n-1)+1=2$, as we wanted.

Induction Step: Assume now that we have already confirmed Euler's formula for connected plane graphs with n vertices and \tilde{e} edges, where \tilde{e} is some integer $\geqslant n-1$. Consider then a connected plane graph \widetilde{G}_0 with n vertices and $\tilde{e}+1$ edges. Then we definitely have $e(\widetilde{G}_0)>n-1$, and \widetilde{G}_0 is not a tree. Thus we can find an edge z_0 of \widetilde{G}_0 which is NOT a bridge of \widetilde{G}_0 (in other words, z_0 is contained in some cycle of \widetilde{G}_0 , which also implies that z_0 is part of the boundary of at least one bounded face f_0 of \widetilde{G}_0). But then \widetilde{G}_0-z_0 is a connected subgraph of \widetilde{G}_0 (thus it is also a plane graph), and moreover we have that

- $-\widetilde{G}_0-z_0$ has the same number of vertices as \widetilde{G}_0 (in fact, it has the same vertices),
- and $e(\widetilde{G}_0 z_0) = e(\widetilde{G}_0) 1 = \widetilde{e}$.
- Finally, observe that, by removing edge z_0 , we definitely broke the cycle that contained it (in fact, any cycle that contained it), and we have also united two faces of \widetilde{G}_0 into one maximal connected open subset now. In other words, we have that

$$\widetilde{f}(\widetilde{G}_0-z_0)=\widetilde{f}(\widetilde{G}_0)-1$$

(note that this exact relation about the faces of the original graph and its connected subgraph can be rigorously justified by the Jordan curve theorem).

But then, by the Inductive Hypothesis, we can write

$$2=|\widetilde{G}_0-z_0|-e(\widetilde{G}_0-z_0)+\widetilde{f}(\widetilde{G}_0-z_0)=n-\big(e(\widetilde{G}_0)-1\big)+\big(\widetilde{f}(\widetilde{G}_0)-1\big)=n-e(\widetilde{G}_0)+\widetilde{f}(\widetilde{G}_0),$$

as we wanted.

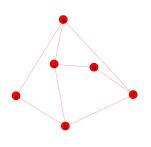
One immediate and very useful consequence of Euler's formula

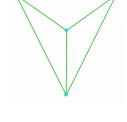
Important corollary of Euler's formula

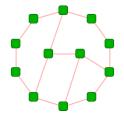
Let G = (V, E) be a (connected) finite planar graph.

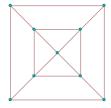
Then the number of faces of a planar embedding of G does NOT depend on the particular embedding we will consider. In other words, we can talk about the faces of G even before drawing G in the plane in a way that results in no edge crossings.

Testing Euler's formula on our examples

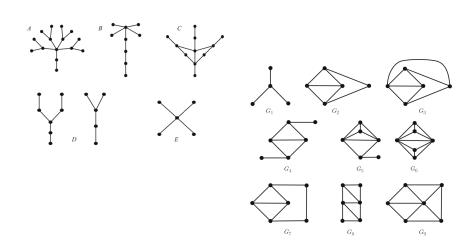








Testing Euler's formula on our examples (cont.)



Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Moreover, if G is also triangle-free, then

$$e(G) \leqslant 2|G| - 4$$
.

Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Moreover, if *G* is also **triangle-free**, then

$$e(G) \leqslant 2|G| - 4$$
.

Justification. It suffices to consider connected graphs (because otherwise we could just add some edges (without introducing any edge crossings, or any new cycles) in order to get a connected supergraph \widetilde{G} ; but then we would have $|\widetilde{G}| = |G|$, while $e(G) \leqslant e(\widetilde{G})$, and thus if we could establish the inequalities for \widetilde{G} , then the corresponding inequalities for G would also hold).

Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Moreover, if G is also triangle-free, then

$$e(G) \leqslant 2|G| - 4$$
.

Justification. It suffices to consider connected graphs (because otherwise we could just add some edges (without introducing any edge crossings, or any new cycles) in order to get a connected supergraph \widetilde{G} ; but then we would have $|\widetilde{G}| = |G|$, while $e(G) \leq e(\widetilde{G})$, and thus if we could establish the inequalities for \widetilde{G} , then the corresponding inequalities for G would also hold).

Moreover, if we have any vertex in G which is a leaf (that is, it has degree 1), then by removing it we only decrease the quantities 3|G| - e(G) - 6 or 2|G| - e(G) - 4 (now calculated for the resulting subgraph we get).

Other important consequences of Euler's formula

Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Moreover, if *G* is also **triangle-free**, then

$$e(G) \leqslant 2|G| - 4$$
.

Justification. It suffices to consider connected graphs (because otherwise we could just add some edges (without introducing any edge crossings, or any new cycles) in order to get a connected supergraph \widetilde{G} ; but then we would have $|\widetilde{G}| = |G|$, while $e(G) \leq e(\widetilde{G})$, and thus if we could establish the inequalities for \widetilde{G} , then the corresponding inequalities for G would also hold).

Moreover, if we have any vertex in G which is a leaf (that is, it has degree 1), then by removing it we only decrease the quantities 3|G|-e(G)-6 or 2|G|-e(G)-4 (now calculated for the resulting subgraph we get). Thus, if we could still show that these quantities are $\geqslant 0$, then the original inequalities we want would also hold.

Other important consequences of Euler's formula

Theorem 3

It G is a planar graph with at least 3 vertices, then

$$e(G) \leq 3|G| - 6.$$

Moreover, if G is also triangle-free, then

$$e(G) \leqslant 2|G| - 4$$
.

Justification. It suffices to consider connected graphs (because otherwise we could just add some edges (without introducing any edge crossings, or any new cycles) in order to get a connected supergraph \widetilde{G} ; but then we would have $|\widetilde{G}| = |G|$, while $e(G) \leq e(\widetilde{G})$, and thus if we could establish the inequalities for \widetilde{G} , then the corresponding inequalities for G would also hold).

Moreover, if we have any vertex in G which is a leaf (that is, it has degree 1), then by removing it we only decrease the quantities 3|G|-e(G)-6 or 2|G|-e(G)-4 (now calculated for the resulting subgraph we get). Thus, if we could still show that these quantities are ≥ 0 , then the original inequalities we want would also hold.

Important Note. If we started with a graph *G* which has exactly 3 vertices, then we shouldn't be able to remove any of those vertices (attention to our assumptions!). But for graphs with exactly 3 vertices, we can verify the desired inequalities simply by inspection.

Based on the above, it suffices to verify the desired inequalities for an arbitrary connected planar graph G

which has at least 3 vertices, and which has NO leaves.

which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).

for an arbitrary connected planar graph G

Based on the above, it suffices to verify the desired inequalities

which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each bounded face will contain at least 3 edges, and thus the same will be true for the unbounded face.

for an arbitrary connected planar graph G

Based on the above, it suffices to verify the desired inequalities

which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each bounded face will contain at least 3 edges, and thus the same will be true for the unbounded face. But then the length of each face is also at least 3.

for an arbitrary connected planar graph G which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each <u>bounded</u> face will contain at least 3 edges, and thus the same will be true for the unbounded face. But then the length of each face is also at least 3.

Let f_1, f_2, \ldots, f_s be the faces of G. Then, by Theorem 1 we have that

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 3 = 3\tilde{f}(G)$$

$$\Rightarrow \quad \tilde{f}(G) \leqslant \frac{2}{3}e(G).$$
(1)

for an arbitrary connected planar graph G which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each <u>bounded</u> face will contain at least 3 edges, and thus the same will be true for the unbounded face. But then the length of each face is also at least 3.

Let f_1, f_2, \ldots, f_s be the faces of G. Then, by Theorem 1 we have that

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 3 = 3\tilde{f}(G)$$

$$\Rightarrow \quad \tilde{f}(G) \leqslant \frac{2}{3}e(G).$$
(1)

But then, combining the last inequality with Euler's formula, we get

$$|G| - e(G) + \frac{2}{3}e(G) \geqslant |G| - e(G) + \tilde{f}(G) = 2,$$

which implies the 1st inequality in Theorem 3.

for an arbitrary connected planar graph ${\cal G}$ which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each <u>bounded</u> face will contain at least 3 edges, and thus the same will be true for the unbounded face. But then the length of each face is also at least 3.

Let f_1, f_2, \ldots, f_s be the faces of G. Then, by Theorem 1 we have that

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 3 = 3\tilde{f}(G)$$

$$\Rightarrow \quad \tilde{f}(G) \leqslant \frac{2}{3}e(G).$$
(1)

But then, combining the last inequality with Euler's formula, we get

$$|G|-e(G)+\frac{2}{3}e(G)\geqslant |G|-e(G)+\tilde{f}(G)=2,$$

which implies the 1st inequality in Theorem 3.

Finally, if G is also triangle-free, then each face will instead have length at least 4, and thus we will be able to replace (1) by the stronger

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 4 = 4\tilde{f}(G).$$

for an arbitrary connected planar graph ${\cal G}$ which has at least 3 vertices, and which has NO leaves.

- Since we are now assuming G is connected, it will have more than one face (thus it will have at least one bounded face).
- Moreover, the boundary of each <u>bounded</u> face will contain at least 3 edges, and thus the same will be true for the unbounded face. But then the length of each face is also at least 3.

Let f_1, f_2, \ldots, f_s be the faces of G. Then, by Theorem 1 we have that

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 3 = 3\tilde{f}(G)$$

$$\Rightarrow \quad \tilde{f}(G) \leqslant \frac{2}{3}e(G).$$
(1)

But then, combining the last inequality with Euler's formula, we get

$$|G| - e(G) + \frac{2}{3}e(G) \geqslant |G| - e(G) + \tilde{f}(G) = 2,$$

which implies the 1st inequality in Theorem 3.

Finally, if G is also triangle-free, then each face will instead have length at least 4, and thus we will be able to replace (1) by the stronger

$$2e(G) = \sum_{i=1}^{s} \ell(f_i) \geqslant \sum_{i=1}^{s} 4 = 4\tilde{f}(G).$$

Then, continuing as before, we will obtain the 2nd inequality of the theorem.

Immediate Corollaries of Thm 3

Corollary 1

If G is a planar (not-necessarily complete) bipartite graph with order $|G| = n \ge 3$, then G has at most 2n - 4 edges.

Immediate Corollaries of Thm 3

Corollary 1

If G is a planar (not-necessarily complete) bipartite graph with order $|G| = n \ge 3$, then G has at most 2n - 4 edges.

Corollary 2

Neither of the graphs $K_{3,3}$ and K_5 is planar.

Immediate Corollaries of Thm 3

Corollary 1

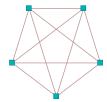
If G is a planar (not-necessarily complete) bipartite graph with order $|G| = n \ge 3$, then G has at most 2n - 4 edges.

Corollary 2

Neither of the graphs $K_{3,3}$ and K_5 is planar.

In other words, $\operatorname{cr}(K_{3,3})\geqslant 1$, and similarly $\operatorname{cr}(K_5)\geqslant 1$.





These examples of non-planar graphs are the most characteristic ones

Reminder from last time: Definition of the graph operation of 'subdivision'

Let G = (V, E) be a graph. A <u>subdivision</u> of G is a graph H which satisfies the following:

- H contains all the vertices of G, and perhaps a few more vertices;
- every edge $e = \{v_1, v_2\}$ in G
 - either appears as an edge of H as well,

These examples of non-planar graphs are the most characteristic ones

Reminder from last time: Definition of the graph operation of 'subdivision'

Let G = (V, E) be a graph. A <u>subdivision</u> of G is a graph H which satisfies the following:

- H contains all the vertices of G, and perhaps a few more vertices;
- every edge $e = \{v_1, v_2\}$ in G
 - either appears as an edge of H as well,
 - or is replaced in H by the path $v_1 \ w_1 \ w_2 \ \dots \ w_{s-1} \ w_s \ v_2$, where $w_1 \ (= w_1(v_1, v_2)), w_2 \ (= w_2(v_1, v_2)), \dots, \ w_s \ (= w_s(v_1, v_2))$ are new vertices that we add to the vertex set of H (and are only meant as internal vertices of this new path in H, that is, they will only be used in relation to vertices v_1 and v_2 , to 'elongate' the previous edge $\{v_1, v_2\}$).

These examples of non-planar graphs are the most characteristic ones

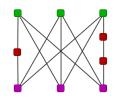
Reminder from last time: Definition of the graph operation of 'subdivision'

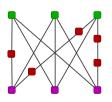
Let G = (V, E) be a graph. A <u>subdivision</u> of G is a graph H which satisfies the following:

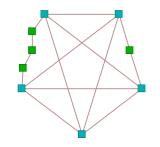
- H contains all the vertices of G, and perhaps a few more vertices;
- every edge $e = \{v_1, v_2\}$ in G
 - either appears as an edge of H as well,
 - or is replaced in H by the path $v_1 \ w_1 \ w_2 \ \dots \ w_{s-1} \ w_s \ v_2$, where $w_1 \ (= w_1(v_1, v_2)), w_2 \ (= w_2(v_1, v_2)), \dots, \ w_s \ (= w_s(v_1, v_2))$ are new vertices that we add to the vertex set of H (and are only meant as internal vertices of this new path in H, that is, they will only be used in relation to vertices v_1 and v_2 , to 'elongate' the previous edge $\{v_1, v_2\}$).

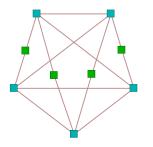
In other words, in the second case, $e = \{v_1, v_2\}$ is replaced by the edges $\{v_1, w_1\}$, $\{w_1, w_2\}$, ..., $\{w_{s-1}, w_s\}$ and $\{w_s, v_2\}$.

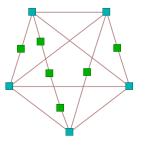
Some subdivisions of $K_{3,3}$ and of K_5











irks about

Kuratowski's theorem on planar graphs

Theorem (Kuratowski, 1930)

A finite graph G is planar **if and only if** none of its subgraphs is a subdivision of $K_{3,3}$ or of K_5 .

Kuratowski's theorem on planar graphs

Theorem (Kuratowski, 1930)

A finite graph G is planar **if and only if** none of its subgraphs is a subdivision of $K_{3,3}$ or of K_5 .

Terminology

If G contains a subgraph H which is a subdivision of $K_{3,3}$ or of K_5 , then H is called a *Kuratowski subgraph* of G.

Kuratowski's theorem on planar graphs

Theorem (Kuratowski, 1930)

A finite graph G is planar **if and only if** none of its subgraphs is a subdivision of $K_{3,3}$ or of K_5 .

Terminology

If G contains a subgraph H which is a subdivision of $K_{3,3}$ or of K_5 , then H is called a *Kuratowski subgraph* of G.

With this terminology at hand, Kuratowski's theorem can be more simply stated as:

a finite graph G is planar if and only if G does not have any Kuratowski subgraphs.

