

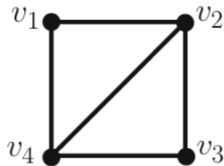
MATH 322 – Graph Theory

Fall Term 2021

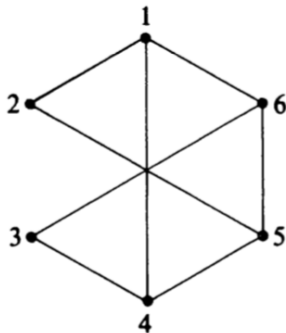
Notes for Lecture 3

Thursday, September 9

Examples/practice questions from last time



Graph G_1



Graph G_3

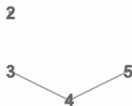
Question 1. Can we view G_1 as a subgraph of G_3 ? (here of course you do need to and you can relabel the vertices of G_1 using four of the numbers from $\{1, 2, 3, 4, 5, 6\}$)

Question 2. How many subgraphs of G_3 do we have on the vertices $\{2, 3, 4, 5\}$? Can you draw them? What is the induced subgraph here?

Question 3. What is the maximum length of a path in G_3 ? How many paths can you find with this length?

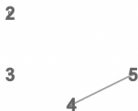
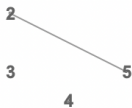
Isomorphic and Non-Isomorphic Graphs

Recall the subgraphs of G_3 that we found for Question 2:



Induced Subgraph

.....

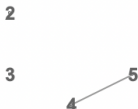


Isomorphic and Non-Isomorphic Graphs

Recall the subgraphs of G_3 that we found for Question 2:



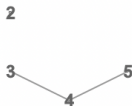
Induced Subgraph



In general, if a graph $H = (V(H), E(H))$ has m edges, and we want to find all subgraphs of H with vertex set the entire $V(H)$ (that is, if we don't want to remove any vertex), **then we will have 2^m different subgraphs** (because 2^m is the number of all subsets of a set with m elements, in this case the edge set E).

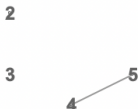
Isomorphic and Non-Isomorphic Graphs

Recall the subgraphs of G_3 that we found for Question 2:



Induced Subgraph

.....



In general, if a graph $H = (V(H), E(H))$ has m edges, and we want to find all subgraphs of H with vertex set the entire $V(H)$ (that is, if we don't want to remove any vertex), **then we will have 2^m different subgraphs** (because 2^m is the number of all subsets of a set with m elements, in this case the edge set E).

Question. But will all these subgraphs be essentially different?

Isomorphic Graphs: Definition

Let G, H be two graphs. An isomorphism from the graph G to the graph H is a bijective function

$$f : V(G) \rightarrow V(H)$$

that preserves adjacencies. That is, f has to be 1-1 and onto, and we must have that

$$e \in E(G) \text{ and has endvertices } v_i, v_j \in V(G) \\ \text{if and only if } \{f(v_i), f(v_j)\} \in E(H).$$

Isomorphic Graphs: Definition

Let G, H be two graphs. An isomorphism from the graph G to the graph H is a bijective function

$$f : V(G) \rightarrow V(H)$$

that preserves adjacencies. That is, f has to be 1-1 and onto, and we must have that

$$e \in E(G) \text{ and has endvertices } v_i, v_j \in V(G) \\ \text{if and only if } \{f(v_i), f(v_j)\} \in E(H).$$

If such an isomorphism from G to H exists, we say that G and H are isomorphic and we denote this by $G \cong H$.

Isomorphic Graphs: Definition

Let G, H be two graphs. An isomorphism from the graph G to the graph H is a bijective function

$$f : V(G) \rightarrow V(H)$$

that preserves adjacencies. That is, f has to be 1-1 and onto, and we must have that

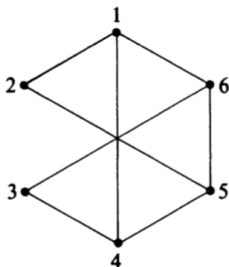
$$e \in E(G) \text{ and has endvertices } v_i, v_j \in V(G) \\ \text{if and only if } \{f(v_i), f(v_j)\} \in E(H).$$

If such an isomorphism from G to H exists, we say that G and H are isomorphic and we denote this by $G \cong H$.

Terminology. If two graphs are not isomorphic (that is, if no such bijection from the vertex set of the first graph onto the vertex set of the second graph exists), we say that the graphs are non-isomorphic.

An example

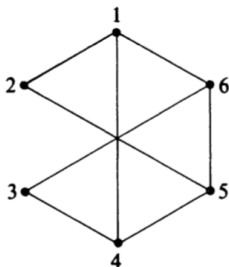
Recall one of our previous examples:



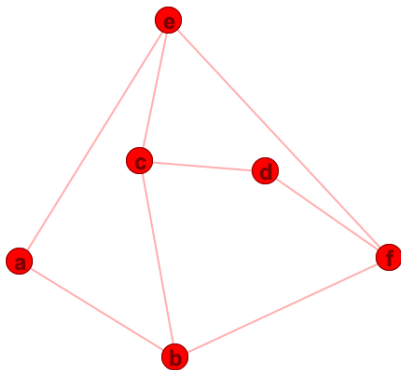
Graph G_3

An example

Recall one of our previous examples:



Graph G_3



Graph G_4

We have that $G_3 \cong G_4$ (that is, the graphs G_3 and G_4 are isomorphic).

Indeed, observe that the bijective function $f : V(G_3) \rightarrow V(G_4)$ given by

$$\begin{aligned} f(1) &= b, & f(2) &= a, & f(3) &= d \\ f(4) &= f, & f(5) &= e, & \text{and } f(6) &= c, \end{aligned}$$

which we can also encode more simply as

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ b & a & d & f & e & c \end{pmatrix}$$

gives an isomorphism between the graphs G_3 and G_4 .

Indeed, observe that the bijective function $f : V(G_3) \rightarrow V(G_4)$ given by

$$\begin{aligned} f(1) &= b, & f(2) &= a, & f(3) &= d \\ f(4) &= f, & f(5) &= e, & \text{and } f(6) &= c, \end{aligned}$$

which we can also encode more simply as

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ b & a & d & f & e & c \end{pmatrix}$$

gives an isomorphism between the graphs G_3 and G_4 .

To verify this, note that

$$E(G_3) = \{12, 14, 16, 25, 34, 36, 45, 56\}$$

and

$$E(G_4) = \{ab, bf, bc, ae, df, cd, ef, ce\}$$

Indeed, observe that the bijective function $f : V(G_3) \rightarrow V(G_4)$ given by

$$\begin{aligned} f(1) &= b, & f(2) &= a, & f(3) &= d \\ f(4) &= f, & f(5) &= e, & \text{and } f(6) &= c, \end{aligned}$$

which we can also encode more simply as

$$\begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 \\ b & a & d & f & e & c \end{pmatrix}$$

gives an isomorphism between the graphs G_3 and G_4 .

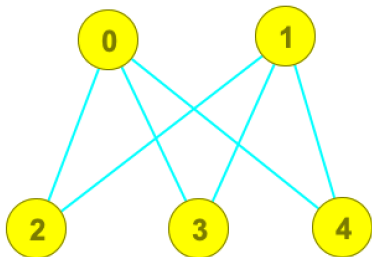
To verify this, note that

$$E(G_3) = \{12, 14, 16, 25, 34, 36, 45, 56\}$$

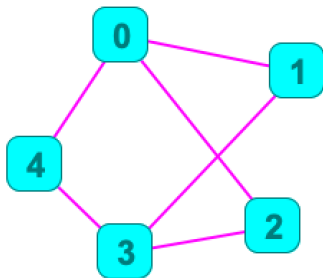
and

$$\begin{aligned} E(G_4) &= \{ab, bf, bc, ae, df, cd, ef, ce\} \\ &= \{f(1)f(2), f(1)f(4), f(1)f(6), f(2)f(5), \\ &\quad f(3)f(4), f(3)f(6), f(4)f(5), f(5)f(6)\}. \end{aligned}$$

Another pair of isomorphic graphs



Graph G_5



Graph G_6

Left as an exercise: Find an isomorphism from G_5 to G_6 .

Important Remarks on Isomorphic Graphs

- Isomorphic graphs must have the same order (that is, they must have the same number of vertices).

Important Remarks on Isomorphic Graphs

- Isomorphic graphs must have the same order (that is, they must have the same number of vertices).
- Isomorphic graphs must have the same size (that is, they must have the same number of edges).

Important Remarks on Isomorphic Graphs

- Isomorphic graphs must have the same order (that is, they must have the same number of vertices).
- Isomorphic graphs must have the same size (that is, they must have the same number of edges).
- Isomorphic graphs must have the same degree sequences, up to reordering of the sequences (*much more about degree sequences very soon*).

Just as a small clarification for now, if $G = (V, E)$ is a finite graph, with $V = \{v_1, v_2, \dots, v_n\}$, then the degree sequence of G is the sequence $(\deg(v_1), \deg(v_2), \dots, \deg(v_n))$ (as we will see, we often reorder this sequence so that it becomes decreasing; however there are instances where it's preferable to keep it like this).

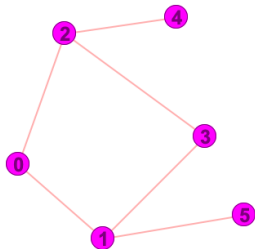
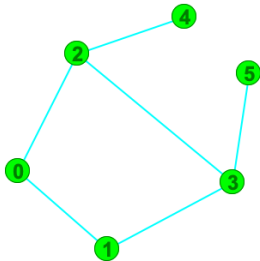
Are these remarks enough?

Are these remarks enough?

Unfortunately not!

Are these remarks enough?

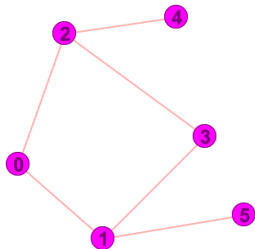
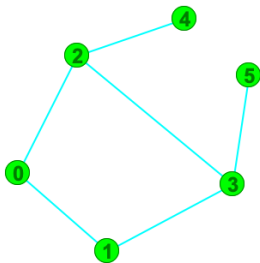
Unfortunately not! Here is an example of two graphs with the same order, the same size, and the same degree sequences (up to reordering) (check that these claims are true).



Are these remarks enough?

Unfortunately not! Here is an example of two graphs with the same order, the same size, and the same degree sequences (up to reordering) (check that these claims are true).

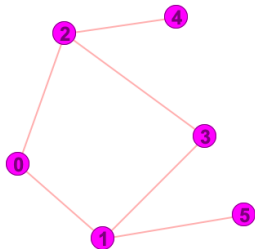
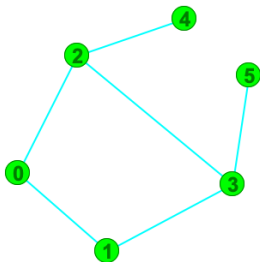
However they are not isomorphic (can you find one reason why?).



Are these remarks enough?

Unfortunately not! Here is an example of two graphs with the same order, the same size, and the same degree sequences (up to reordering) (check that these claims are true).

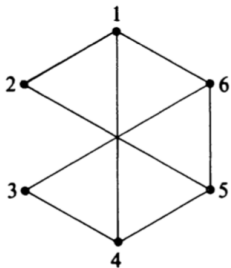
However they are not isomorphic (can you find one reason why?).



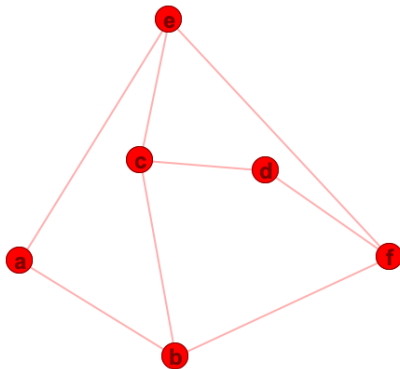
One possible approach: What is the maximum length of a path in each graph? Shouldn't it be the same if two graphs are isomorphic?

Isomorphic Graphs and Adjacency Matrix

Back to the graphs G_3 and G_4 which we saw are isomorphic:



Graph G_3



Graph G_4

Isomorphic Graphs and Adjacency Matrix

Back to the graphs G_3 and G_4 which we saw are isomorphic:

$$A_{G_3} = \begin{matrix} & \begin{matrix} 1 & 2 & 3 & 4 & 5 & 6 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \\ 6 \end{matrix} & \begin{pmatrix} 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 & 1 & 0 \end{pmatrix} \end{matrix}$$

$$\text{and } A_{G_4} = \begin{matrix} & \begin{matrix} a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} & \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \end{pmatrix} \end{matrix}.$$

Note that the matrices are different.

Isomorphic Graphs and Adjacency Matrix

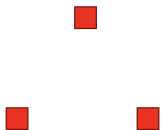
However, if two graphs G and H are isomorphic, then there exists a permutation matrix P (that is, a 0-1 matrix which has exactly one entry equal to 1 in each row, and also exactly one entry equal to 1 in each column) such that

$$A_G = P \cdot A_H \cdot P^T.$$

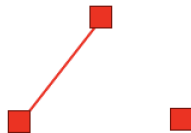
In other words, A_H can be turned into A_G by permuting the rows of A_H in a suitable way, and by permuting its columns too in the same way.

Related question: How many
essentially different graphs on 3 vertices?

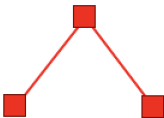
Related question: How many essentially different graphs on 3 vertices?



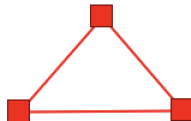
No edges



1 edge

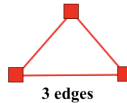
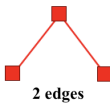
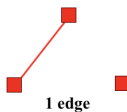
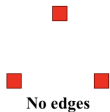


2 edges

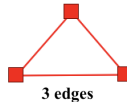
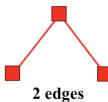
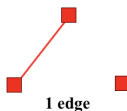
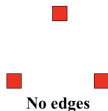


3 edges

Related question: How many essentially different graphs on 3 vertices?



Related question: How many essentially different graphs on 3 vertices?



Takeaway here: In order to avoid 'repetitions' of graph structures that cannot really offer us any new information, **most of the time:**

- we work with unlabelled graphs (or start with an unlabelled graph, and consider some labelling of it mainly for clarity),
- we identify two such graphs if they are isomorphic,
- and we consider only one 'representative' from each class of isomorphic graphs.

**A few more important concepts
concerning graphs**

Incidence Matrix of a Graph

Recall the adjacency matrix of a (finite) graph, which encodes all information about the graph.

Incidence Matrix of a Graph

Recall the adjacency matrix of a (finite) graph, which encodes all information about the graph. A similar way of encoding a graph $G = (V, E)$ is the (unoriented) incidence matrix of G : *this matrix now captures which vertex of G is incident with which edge.*

Incidence Matrix of a Graph

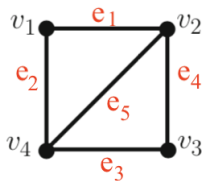
Recall the adjacency matrix of a (finite) graph, which encodes all information about the graph. A similar way of encoding a graph $G = (V, E)$ is the (unoriented) incidence matrix of G : *this matrix now captures which vertex of G is incident with which edge.*

In other words, if the set of vertices $V(G)$ of G is, say, the set $\{v_1, v_2, v_3, \dots, v_n\}$, and if the set of edges $E(G)$ of G is the set $\{e_1, e_2, e_3, \dots, e_m\}$, then the (unoriented) incidence matrix of G is an $n \times m$ $0 - 1$ matrix, such that

- the (i, j) -th entry is equal to 1 if the vertex v_i is incident with the edge e_j ,
- the (i, j) -th entry is equal to 0 otherwise.

Example: The incidence matrix of G_1

Recall G_1 :

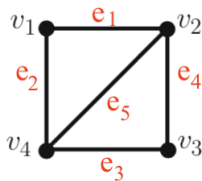


Recall its adjacency matrix:

$$\begin{array}{c} v_1 \\ v_2 \\ v_3 \\ v_4 \end{array} \begin{pmatrix} v_1 & v_2 & v_3 & v_4 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$$

Example: The incidence matrix of G_1

Recall G_1 :



Recall its adjacency matrix:

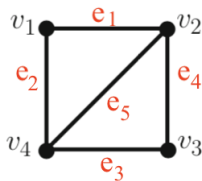
$$\begin{array}{c} v_1 \quad v_2 \quad v_3 \quad v_4 \\ \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \end{array}$$

On the other hand, its incidence matrix is

$$\begin{array}{c} e_1 \quad e_2 \quad e_3 \quad e_4 \quad e_5 \\ \begin{pmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \end{pmatrix} \end{array}$$

Example: The incidence matrix of G_1

Recall G_1 :



Recall its adjacency matrix:

$$\begin{array}{c} \begin{matrix} & v_1 & v_2 & v_3 & v_4 \end{matrix} \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{matrix} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix} \end{array}$$

On the other hand, its incidence matrix is

$$\begin{array}{c} \begin{matrix} e_1 & e_2 & e_3 & e_4 & e_5 \end{matrix} \\ \begin{matrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{matrix} \begin{pmatrix} 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \end{pmatrix} \end{array}$$

Just as with the adjacency matrix, the incidence matrix depends on the ordering we choose for the vertices. Moreover, the incidence matrix depends on the ordering we choose for the edges too.

Complement of a Graph

Let $G = (V, E)$ be a graph. Recall that E is a subset of the set of 2-element subsets of V (sometimes we denote this set by $[V]^2$).

Complement of a Graph

Let $G = (V, E)$ be a graph. Recall that E is a subset of the set of 2-element subsets of V (sometimes we denote this set by $[V]^2$).

We can construct a new graph H on the same set of vertices by setting

$$H = (V, [V]^2 \setminus E),$$

that is, by setting the edge set of H to be the *complement* of E in $[V]^2$.

Complement of a Graph

Let $G = (V, E)$ be a graph. Recall that E is a subset of the set of 2-element subsets of V (sometimes we denote this set by $[V]^2$).

We can construct a new graph H on the same set of vertices by setting

$$H = (V, [V]^2 \setminus E),$$

that is, by setting the edge set of H to be the *complement* of E in $[V]^2$.

In essence, what we are doing is removing any edges/‘connections’ we have in G , and then we are joining any two vertices that were not joined in G .

Complement of a Graph

Let $G = (V, E)$ be a graph. Recall that E is a subset of the set of 2-element subsets of V (sometimes we denote this set by $[V]^2$).

We can construct a new graph H on the same set of vertices by setting

$$H = (V, [V]^2 \setminus E),$$

that is, by setting the edge set of H to be the *complement* of E in $[V]^2$.

In essence, what we are doing is removing any edges/‘connections’ we have in G , and then we are joining any two vertices that were not joined in G .

Definition. The new graph is called the complement of G , and is denoted by \overline{G} .

Complement of a Graph

Examples. 1. If $G_1 = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_2, v_1 v_4, v_2 v_3, v_2 v_4, v_3 v_4\})$,
what is $\overline{G_1}$?

Complement of a Graph

Examples. 1. If $G_1 = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_2, v_1 v_4, v_2 v_3, v_2 v_4, v_3 v_4\})$, what is $\overline{G_1}$? We have

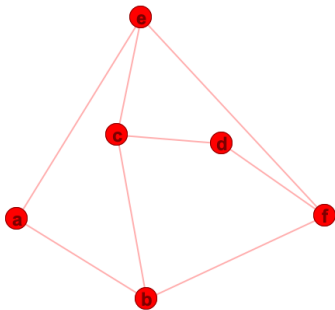
$$\overline{G_1} = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_3\}).$$

Complement of a Graph

Examples. 1. If $G_1 = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_2, v_1 v_4, v_2 v_3, v_2 v_4, v_3 v_4\})$, what is $\overline{G_1}$? We have

$$\overline{G_1} = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_3\}).$$

2. If G_4 is

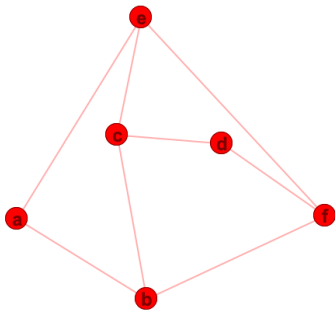


Complement of a Graph

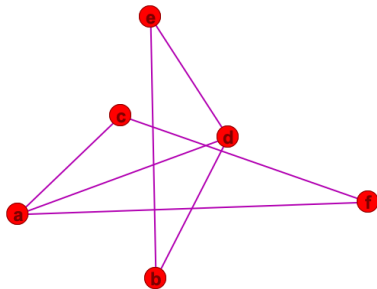
Examples. 1. If $G_1 = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_2, v_1 v_4, v_2 v_3, v_2 v_4, v_3 v_4\})$, what is $\overline{G_1}$? We have

$$\overline{G_1} = (\{v_1, v_2, v_3, v_4\}, \{v_1 v_3\}).$$

2. If G_4 is



then $\overline{G_4}$ will be



Complement and Adjacency Matrix

If we have the adjacency matrix A_G of a graph G , how can we obtain the adjacency matrix of the complement \overline{G} of G (*just by manipulating A_G*)?

Complement and Adjacency Matrix

If we have the adjacency matrix A_G of a graph G , how can we obtain the adjacency matrix of the complement \overline{G} of G (*just by manipulating A_G*)?

Recall that:

$$A_{G_4} = \begin{matrix} & \begin{matrix} a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} & \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \end{pmatrix} \end{pmatrix}.$$

Complement and Adjacency Matrix

If we have the adjacency matrix A_G of a graph G , how can we obtain the adjacency matrix of the complement \overline{G} of G (*just by manipulating A_G*)?

Recall that:

$$A_{G_4} = \begin{array}{c} \begin{matrix} & a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} \end{array} \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \end{pmatrix}.$$

Then

$$A_{\overline{G_4}} = \begin{array}{c} \begin{matrix} & a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} \end{array} \begin{pmatrix} 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \end{pmatrix}.$$

Complement and Adjacency Matrix

If we have the adjacency matrix A_G of a graph G , how can we obtain the adjacency matrix of the complement \overline{G} of G (*just by manipulating A_G*)?

Recall that:

Then

$$A_{G_4} = \begin{matrix} & \begin{matrix} a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} & \begin{pmatrix} 0 & 1 & 0 & 0 & 1 & 0 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 & 1 & 0 \end{pmatrix} \end{matrix}.$$

$$A_{\overline{G_4}} = \begin{matrix} & \begin{matrix} a & b & c & d & e & f \end{matrix} \\ \begin{matrix} a \\ b \\ c \\ d \\ e \\ f \end{matrix} & \begin{pmatrix} 0 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 0 & 0 \end{pmatrix} \end{matrix}.$$

Attention. In contrast, there is not such a straightforward way to get the incidence matrix of \overline{G} from the incidence matrix of G (can you find one reason why?).

Connected components of a graph

Let $G = (V, E)$ be a graph. Define a relation on the vertex set V of G by setting

$$v_i \sim v_j \quad \text{if and only if} \\ v_i = v_j \quad \text{or} \quad \text{there is a path in } G \text{ from } v_i \text{ to } v_j.$$

Connected components of a graph

Let $G = (V, E)$ be a graph. Define a relation on the vertex set V of G by setting

$$v_i \sim v_j \quad \text{if and only if} \\ v_i = v_j \quad \text{or} \quad \text{there is a path in } G \text{ from } v_i \text{ to } v_j.$$

Then this is an equivalence relation on V (**verify this**), and thus it gives us a *partition* of V : the different blocks of the partition are the different equivalence classes, where e.g. the equivalence class $[v_i]_{\sim}$ of a vertex v_i of G is the maximal subset of vertices that we can reach when we start at v_i and travel on a path in G (with the vertex v_i itself included).

Connected components of a graph

Let $G = (V, E)$ be a graph. Define a relation on the vertex set V of G by setting

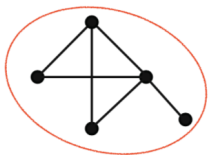
$$v_i \sim v_j \quad \text{if and only if} \\ v_i = v_j \quad \text{or} \quad \text{there is a path in } G \text{ from } v_i \text{ to } v_j.$$

Then this is an equivalence relation on V (**verify this**), and thus it gives us a *partition* of V : the different blocks of the partition are the different equivalence classes, where e.g. the equivalence class $[v_i]_{\sim}$ of a vertex v_i of G is the maximal subset of vertices that we can reach when we start at v_i and travel on a path in G (with the vertex v_i itself included).

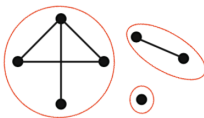
For each such equivalence class, the induced subgraph of G that we get is one of the so-called connected components of G (and as the name indicates, it is a (maximal) connected subgraph of G).

Connected components of a graph

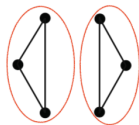
Examples



1 connected component



3 connected components



2 connected components

Important examples of (families of) graphs

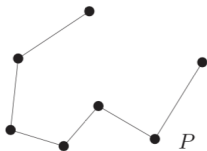
Reminder: Paths

Definition. A path P is a graph of the form

$$\left(\{x_0, x_1, x_2, \dots, x_l\}, \{x_0x_1, x_1x_2, \dots, x_{l-1}x_l\} \right)$$

where l is an integer ≥ 1 .

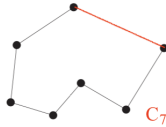
The number l is called the *length* of the path P (note that it is also the number of edges of P , that is, it is equal to the size of P).



A path P on 7 vertices, thus of length 6

Cycles

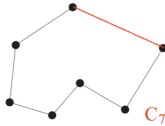
If we 'closed' the path P by joining the initial and the terminal vertex as well, then we would get what we call a cycle graph.



A cycle on 7 vertices, or equivalently a 7-cycle

Cycles

If we 'closed' the path P by joining the initial and the terminal vertex as well, then we would get what we call a cycle graph.

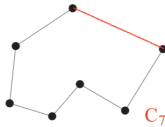


A cycle on 7 vertices, or equivalently a 7-cycle

In other words, $C_7 = \left(\{x_0, x_1, x_2, \dots, x_6\}, \{x_0x_1, x_1x_2, \dots, x_5x_6, \textcolor{red}{x_6x_0}\} \right)$.

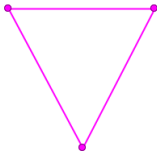
Cycles

If we 'closed' the path P by joining the initial and the terminal vertex as well, then we would get what we call a cycle graph.

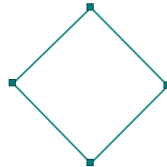


A cycle on 7 vertices, or equivalently a 7-cycle

In other words, $C_7 = (\{x_0, x_1, x_2, \dots, x_6\}, \{x_0x_1, x_1x_2, \dots, x_5x_6, \textcolor{red}{x_6x_0}\})$.



A 3-cycle, denoted by C_3



A 4-cycle, denoted by C_4

Null Graphs / Complete Graphs

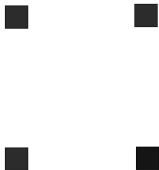
Given a set of vertices $V = \{v_1, v_2, \dots, v_n\}$, the two 'extreme' cases of graphs with vertex set V are:

- the *null graph* on V , that is, the graph on V that has no edges at all,
- the *complete graph* on V , that is, the graph $(V, [V]^2)$, in which any two elements of V are joined.

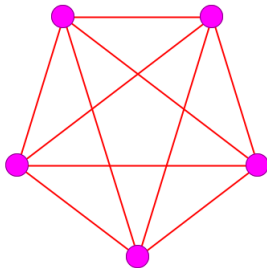
Null Graphs / Complete Graphs

Given a set of vertices $V = \{v_1, v_2, \dots, v_n\}$, the two 'extreme' cases of graphs with vertex set V are:

- the *null graph* on V , that is, the graph on V that has no edges at all,
- the *complete graph* on V , that is, the graph $(V, [V]^2)$, in which any two elements of V are joined.

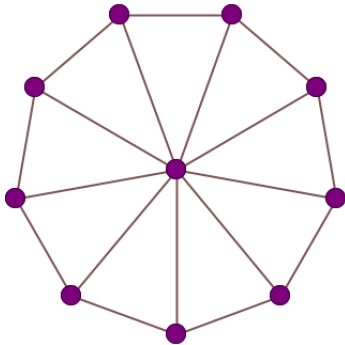


The null graph on 4 vertices, denoted by N_4



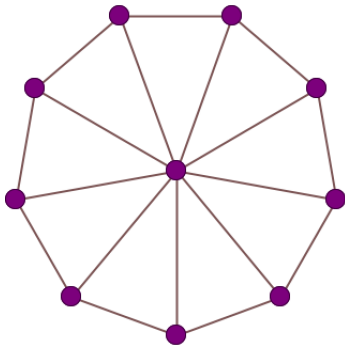
The complete graph on 5 vertices, denoted by K_5

Wheels



The wheel graph on 10 vertices, denoted by W_{10}

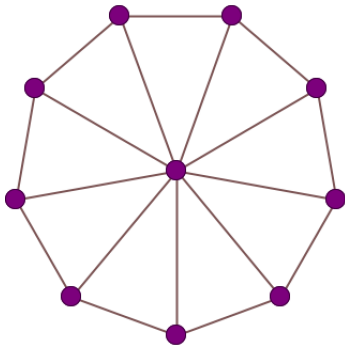
Wheels



The wheel graph on 10 vertices, denoted by W_{10}

Question. How do we form a wheel graph?

Wheels

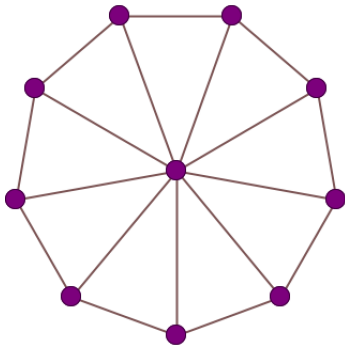


The wheel graph on 10 vertices, denoted by W_{10}

Question. How do we form a wheel graph?

Answer. If we want to form a wheel graph on n vertices, then we start with the graph C_{n-1} (that is, an $(n-1)$ -cycle), and then we add one more vertex which we join with every other vertex in our graph.

Wheels



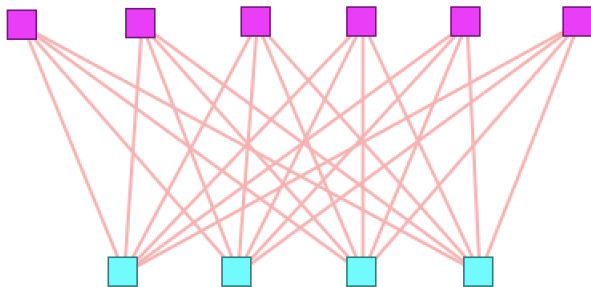
The wheel graph on 10 vertices, denoted by W_{10}

Question. How do we form a wheel graph?

Answer. If we want to form a wheel graph on n vertices, then we start with the graph C_{n-1} (that is, an $(n-1)$ -cycle), and then we add one more vertex which we join with every other vertex in our graph.

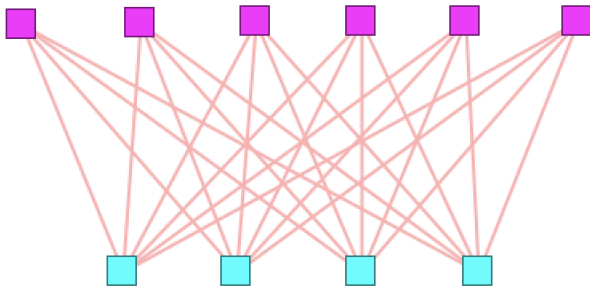
Notice that this implies that, in the wheel graph W_n , one vertex has degree $n-1$, while all the other vertices have degree = ?

Bipartite Graphs



The bipartite graph $K_{6,4}$

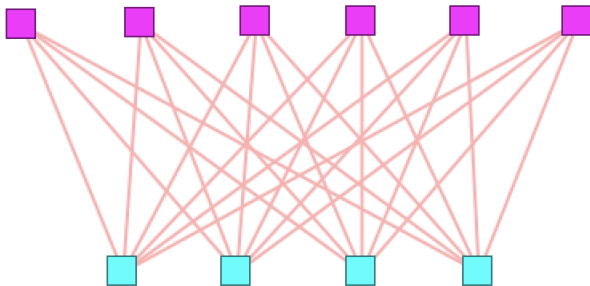
Bipartite Graphs



The bipartite graph $K_{6,4}$

Question. How do we construct a bipartite graph?

Bipartite Graphs

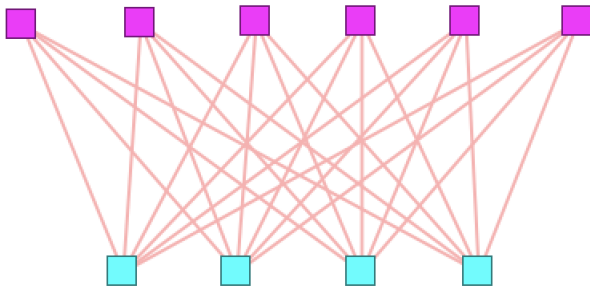


The bipartite graph $K_{6,4}$

Question. How do we construct a bipartite graph?

Answer. As the name suggests, the vertex set V of a bipartite graph is divided into **two parts**, say part V_1 and part V_2 . Every vertex in V_1 is joined with every vertex in V_2 ; on the other hand, there is NO edge joining two vertices in V_1 , and similarly there is NO edge joining two vertices in V_2 .

Bipartite Graphs



The bipartite graph $K_{6,4}$

Question. How do we construct a bipartite graph?

Answer. As the name suggests, the vertex set V of a bipartite graph is divided into **two parts**, say part V_1 and part V_2 . Every vertex in V_1 is joined with every vertex in V_2 ; on the other hand, there is NO edge joining two vertices in V_1 , and similarly there is NO edge joining two vertices in V_2 .

If the cardinality $|V_1|$ of the part V_1 is m , and the cardinality $|V_2|$ of the part V_2 is n , then the bipartite graph we just described is denoted by $K_{m,n}$ (or equivalently, $K_{n,m}$).

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

Examples: 1. Any n -cycle is a 2-regular graph.

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

Examples: 1. Any n -cycle is a 2-regular graph.

2. The bipartite graph $K_{5,5}$ is 5-regular. (*can you justify this?*)

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

Examples: 1. Any n -cycle is a 2-regular graph.

2. The bipartite graph $K_{5,5}$ is 5-regular. (*can you justify this?*)

3. Are there any paths which are regular graphs?

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

Examples: 1. Any n -cycle is a 2-regular graph.

2. The bipartite graph $K_{5,5}$ is 5-regular. (*can you justify this?*)

3. Are there any paths which are regular graphs? YES, any path which has exactly two vertices and one edge joining them:



that is, any path of length 1, is a 1-regular graph.

d -Regular Graphs

Definition. A graph $G = (V, E)$ is called **regular** if all its vertices have the same degree.

If all these degrees are equal to the non-negative integer d , then we say that G is **d -regular**.

Examples: 1. Any n -cycle is a 2-regular graph.

2. The bipartite graph $K_{5,5}$ is 5-regular. (*can you justify this?*)

3. Are there any paths which are regular graphs? YES, any path which has exactly two vertices and one edge joining them:



that is, any path of length 1, is a 1-regular graph.

On the other hand, note that paths of length > 1 are not regular graphs. (*can you justify this?*)