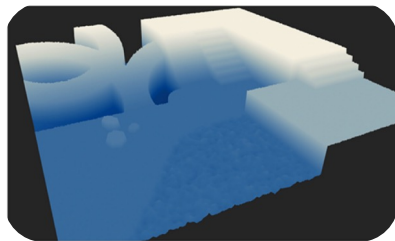
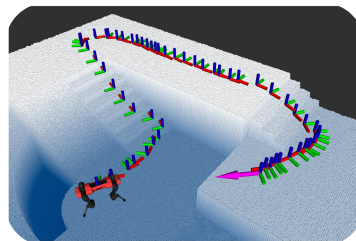




environment



static navigation  
map reconstruction



navigation trajectory  
generation



controller