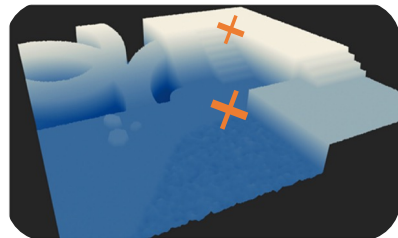
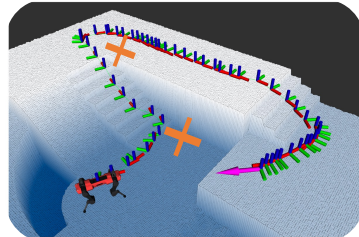




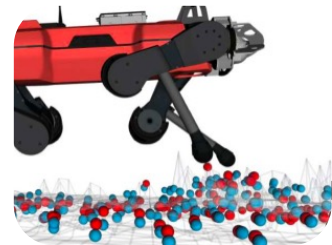
environment



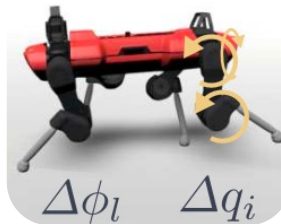
static navigation
map reconstruction



navigation trajectory
generation



Intervention by safe-
probing module



controller

If detecting anomalies “X”, update the map and generate another navigation path