



Recap on Subtype



Principle of subsumption

Some types *are better* than others, in the sense that a value of one can always safely be used where a value of the other is expected.

This can be formalized by introducing:

1. a *subtyping relation* between types, written $S <: T$
2. a rule of *subsumption* stating that, if $S <: T$, then any value of type S can also be regarded as having type T , i.e.,

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$



Subtype Relation

$$S <: S \quad (\text{S-REFL})$$

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\{l_i : T_i \mid i \in 1..n+k\} <: \{l_i : T_i \mid i \in 1..n\} \quad (\text{S-RCDWIDTH})$$

$$\frac{\text{for each } i \quad S_i <: T_i}{\{l_i : S_i \mid i \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDDEPTH})$$

$$\frac{\{k_j : S_j \mid j \in 1..n\} \text{ is a permutation of } \{l_i : T_i \mid i \in 1..n\}}{\{k_j : S_j \mid j \in 1..n\} <: \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCDPERM})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



Issues in Subtyping

For a *given subtyping statement*, there are *multiple rules* that could be used in a derivation.

1. The conclusions of **S-RcdWidth**, **S-RcdDepth**, and **S-RcdPerm** *overlap with each other*.
2. **S-REFL** and **S-TRANS** overlap with every other rule.



Syntax-directed rules

In the simply typed lambda-calculus (without subtyping), each rule can be “*read from bottom to top*” in a straightforward way.

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$



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If we are given some Γ and some t of the form $t_1 \ t_2$, we can try to *find a type* for t by

1. finding (recursively) a type for t_1
2. checking that it has the form $T_{11} \rightarrow T_{12}$
3. finding (recursively) a type for t_2
4. checking that it is the same as T_{11}



Syntax-directed rules

Technically, the reason this works is that we can *divide the “positions” of the typing relation into **input positions** (i.e., Γ and t) and **output positions** (T).*

- For the input positions, all metavariables appearing in the *premises* also appear in the *conclusion* (so we can calculate inputs to the “*subgoals*” from the subexpressions of inputs to the main goal)
- For the output positions, all metavariables appearing in the *conclusions* also appear in the *premises* (so we can calculate outputs from the main goal from the outputs of the subgoals)

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_{11}}{\Gamma \vdash t_1 \ t_2 : T_{12}} \quad (\text{T-APP})$$



Syntax-directed sets of rules

The *second important point* about the simply typed lambda-calculus is that *the set of typing rules is syntax-directed*, in the sense that, for every “*input*” Γ and t , there is *one rule* that can be used to derive typing statements involving t .

E.g., if t is an *application*, then we must proceed by trying to use *T-App*. If we succeed, then we have found a type (indeed, the *unique type*) for t . If it *fails*, then we know that t is *not typable*.

⇒ no backtracking!



Non-syntax-directedness of typing

When we extend the system with *subtyping*, both aspects of syntax-directedness get broken.

1. The set of typing rules now includes *two* rules that can be used to give a type to terms of a given shape (the old one plus T-SUB)

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

2. Worse yet, the new rule T-SUB *itself is not syntax directed*: the *inputs* to the left-hand subgoal are exactly the same as the *inputs* to the main goal!
 - Hence, if we translated the typing rules naively into a typechecking function, the case corresponding to T-SUB would cause *divergence*



Non-syntax-directedness of subtyping

Moreover, the *subtyping relation* is *not syntax directed* either.

1. There are *lots of ways* to derive a given subtyping statement. (8.2.4 / 9.3.3 [uniqueness of types])
2. The transitivity rule

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

is *badly non-syntax-directed*: the premises contain a *metavariable* (in an “*input position*”) that does *not appear at all in the conclusion*.

To implement this rule naively, we have to *guess* a value for U !



What to do?

1. *Observation*: We don't *need* lots of ways to prove a given typing or subtyping statement — *one is enough*.
→ *Think more carefully about the typing and subtyping systems to see where we can get rid of excess flexibility.*
2. Use the resulting intuitions to formulate new “*algorithmic*” (i.e., syntax-directed) typing and subtyping relations.
3. Prove that the algorithmic relations are “*the same as*” the original ones in an appropriate sense.



What to do?

We'll turn the *declarative version* of subtyping into the *algorithmic version*.

The **problem** was that we don't have an algorithm to decide when $S <: T$ or $\Gamma \vdash t : T$.

Both sets of rules are not *syntax-directed*.



Chap 16

Metatheory of Subtyping

Algorithmic Subtyping

Algorithmic Typing

Joins and Meets



Developing an algorithmic subtyping relation



Algorithmic Subtyping



What to do

How do we change the rules deriving $S <: T$ to be *syntax-directed*?

There are lots of ways to derive a given subtyping statement $S <: T$.

The general idea is to *change this system* so that there is *only one way* to derive it.



Step 1: simplify record subtyping

Idea: combine all three record subtyping rules into one “*macro rule*” that captures all of their effects

$$\frac{\{l_i \mid i \in 1..n\} \subseteq \{k_j \mid j \in 1..m\} \quad k_j = l_i; \text{ implies } S_j \leq T_i}{\{k_j : S_j \mid j \in 1..m\} \leq \{l_i : T_i \mid i \in 1..n\}} \quad (\text{S-RCD})$$



Simpler subtype relation

$$S \leq: S \quad (\text{S-REFL})$$

$$\frac{S \leq: U \quad U \leq: T}{S \leq: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i : T_i\}_{i \in 1..n} \subseteq \{k_j : T_j\}_{j \in 1..m} \quad k_j = l_i \text{ implies } S_j \leq: T_i}{\{k_j : S_j\}_{j \in 1..m} \leq: \{l_i : T_i\}_{i \in 1..n}} \quad (\text{S-RCD})$$

$$\frac{T_1 \leq: S_1 \quad S_2 \leq: T_2}{S_1 \rightarrow S_2 \leq: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S \leq: \text{Top} \quad (\text{S-TOP})$$



Step 2: Get rid of reflexivity

Observation: S-REFL is unnecessary.

Lemma: $S \leq S$ can be derived for every type S without using S-REFL.



Even simpler subtype relation

$$\frac{S <: U \quad U <: T}{S <: T} \quad (\text{S-TRANS})$$

$$\frac{\{l_i : i \in 1..n\} \subseteq \{k_j : j \in 1..m\} \quad k_j = l_i \text{ implies } S_j <: T_i}{\{k_j : S_j : j \in 1..m\} <: \{l_i : T_i : i \in 1..n\}} \quad (\text{S-RCD})$$

$$\frac{T_1 <: S_1 \quad S_2 <: T_2}{S_1 \rightarrow S_2 <: T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S <: \text{Top} \quad (\text{S-TOP})$$



Step 3: Get rid of transitivity

Observation: S-Trans is unnecessary.

Lemma: If $S <: T$ can be derived, then it can be derived without using S-Trans .



Even simpler subtype relation

$$\frac{\{l_i : i \in 1..n\} \subseteq \{k_j : j \in 1..m\} \quad k_j = l_i \text{ implies } S_j \leq T_i}{\{k_j : S_j : j \in 1..m\} \leq \{l_i : T_i : i \in 1..n\}} \quad (\text{S-RCD})$$

$$\frac{T_1 \leq S_1 \quad S_2 \leq T_2}{S_1 \rightarrow S_2 \leq T_1 \rightarrow T_2} \quad (\text{S-ARROW})$$

$$S \leq \text{Top} \quad (\text{S-TOP})$$



“Algorithmic” subtype relation

$\vdash \triangleright S <: \text{Top}$

(SA-TOP)

$$\frac{\vdash T_1 <: S_1 \quad \vdash S_2 <: T_2}{\vdash S_1 \rightarrow S_2 <: T_1 \rightarrow T_2}$$

(SA-ARROW)

$$\frac{\{l_i : T_i\}_{i \in 1..n} \subseteq \{k_j : S_j\}_{j \in 1..m} \quad \text{for each } k_j = l_i, \quad \vdash S_j <: T_j}{\vdash \{k_j : S_j\}_{j \in 1..m} <: \{l_i : T_i\}_{i \in 1..n}} \text{ (SA-RCD)}$$



Soundness and completeness

Theorem: $S <: T$ iff $\rightarrow S <: T$

Terminology:

- The *algorithmic presentation* of subtyping is *sound* with respect to the original, if $\rightarrow S <: T$ implies $S <: T$. (*Everything validated by the algorithm is actually true.*)
- The *algorithmic presentation* of subtyping is *complete* with respect to the original, if $S <: T$ implies $\rightarrow S <: T$. (*Everything true is validated by the algorithm.*)



Decision Procedures

Recall: A *decision procedure* for a relation $R \subseteq U$ is *a total function* p from U to $\{\text{true}, \text{false}\}$ such that $p(u) = \text{true}$ iff $u \in R$.

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Is our *subtype* function a decision procedure?

Since *subtype* is just an implementation of the algorithmic subtyping rules, we have

1. if $\text{subtype}(S, T) = \text{true}$, then $\rightarrow S <: T$ hence,
by **soundness** of the algorithmic rules, $S <: T$
2. if $\text{subtype}(S, T) = \text{false}$, then not $\rightarrow S <: T$
hence, by **completeness** of the algorithmic rules, not $S <: T$



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Q: What's missing?



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Q: What's missing?

A: How do we know that *subtype* is a *total function*?

Prove it!



Decision Procedures

Recall: A *decision procedure* for a relation $R \subseteq U$ is *a total function* p from U to $\{\text{true}, \text{false}\}$ such that $p(u) = \text{true}$ iff $u \in R$.

Example:

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

Note that, we are saying nothing about *computability*.



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The function p' whose graph is

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is *not* a decision function for R .



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The function p'' whose graph is

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is also *not* a decision function for R .



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$$\begin{aligned} & \{ ((1, 2), \text{true}), ((2, 3), \text{true}), \\ & \quad ((1, 1), \text{false}), ((1, 3), \text{false}), \\ & \quad ((2, 1), \text{false}), ((2, 2), \text{false}), \\ & \quad ((3, 1), \text{false}), ((3, 2), \text{false}), ((3, 3), \text{false}) \} \end{aligned}$$

is a decision function for R .



Decision Procedures (take 2)

We want a decision procedure to be a *procedure*.

A *decision procedure* for a relation $R \subseteq U$ is a *computable total function* p from U to $\{\text{true}, \text{false}\}$ such that $p(u) = \text{true}$ iff $u \in R$.



Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The function

$p(x, y) = \begin{cases} \text{true} & \text{if } x = 2 \text{ and } y = 3 \\ \text{true} & \text{else if } x = 1 \text{ and } y = 2 \\ \text{false} & \text{else} \end{cases}$

whose graph is

$\{ ((1, 2), \text{true}), ((2, 3), \text{true}),$
 $((1, 1), \text{false}), ((1, 3), \text{false}),$
 $((2, 1), \text{false}), ((2, 2), \text{false}),$
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is a decision procedure for R .



Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

$p(x, y) = \begin{cases} \text{true} & \text{if } x = 2 \text{ and } y = 3 \\ \text{true} & \text{else if } x = 1 \text{ and } y = 2 \\ \text{false} & \text{else if } x = 1 \text{ and } y = 3 \\ p(x, y) & \text{else} \end{cases}$



Example

$$U = \{1, 2, 3\}$$

$$R = \{(1, 2), (2, 3)\}$$

The recursively defined *partial function*

```
p(x, y) = if x = 2 and y = 3 then true  
           else if x = 1 and y = 2 then true  
           else if x = 1 and y = 3 then false  
           else p(x, y)
```

whose graph is

$$\{ ((1, 2), \text{true}), ((2, 3), \text{true}), ((1, 3), \text{false}) \}$$

is **not** a decision procedure for R .



Subtyping Algorithm

This *recursively defined total function* is a decision procedure for the subtype relation:

```
subtype(S, T) =  
    if T = Top, then true  
    else if S = S1 → S2 and T = T1 → T2  
        then subtype(T1, S1) ∧ subtype(S2, T2)  
    else if S = {kj: Sjj ∈ 1..m} and T = {li: Tii ∈ 1..n}  
        then {lii ∈ 1..n} ⊆ {kjj ∈ 1..m}  
            ∧ for all i ∈ 1..n there is some j ∈ 1..m with kj = li  
            and subtype(Sj, Ti)  
    else false.
```



Subtyping Algorithm

This *recursively defined total function* is a decision procedure for the subtype relation:

subtype(S, T) =

- if $T = \text{Top}$, then *true*
- else if $S = S_1 \rightarrow S_2$ and $T = T_1 \rightarrow T_2$
 - then *subtype(T₁, S₁) \wedge subtype(S₂, T₂)*
- else if $S = \{k_j : S_j^{j \in 1..m}\}$ and $T = \{l_i : T_i^{i \in 1..n}\}$
 - then $\{l_i^{i \in 1..n}\} \subseteq \{k_j^{j \in 1..m}\}$
 - \wedge for all $i \in 1..n$ there is some $j \in 1..m$ with $k_j = l_i$ and *subtype(S_j, T_i)*
- else *false*.

To show this, we *need to prove*:

1. that it returns *true* whenever $S <: T$, and
2. that it returns either *true* or *false* on *all inputs*



Algorithmic Typing



Algorithmic typing

How do we implement a *type checker* for the lambda-calculus *with subtyping*?

Given a context Γ and a term t , how do we determine its type T , such that $\Gamma \vdash t : T$?

Issue



For the typing relation, we have *just one problematic rule* to deal with: *subsumption rule*

$$\frac{\Gamma \vdash t : S \quad S <: T}{\Gamma \vdash t : T} \quad (\text{T-SUB})$$

Q: where is this rule really needed?



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Q: where is this rule really needed?

For applications, e.g., the term

$$(\lambda r: \{x: \text{Nat}\}. r.x) \{x = 0, y = 1\}$$

is *not typable* without using subsumption.

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For the typing relation, we have *just one problematic rule* to deal with: *subsumption rule*

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For *applications*, e.g., the term

$(\lambda r: \{x: \text{Nat}\}. r.x) \{x = 0, y = 1\}$

is *not typable* without using subsumption.

Where else??

Nowhere else!

Uses of subsumption rule to help typecheck *applications* are the only interesting ones.



Plan

1. Investigate *how subsumption is used* in typing derivations by *looking at examples* of how it can be “*pushed through*” other rules
2. Use the intuitions gained from these examples to design a new, algorithmic typing relation that
 - *Omits subsumption*
 - Compensates for its absence by *enriching the application rule*
3. *Show that the algorithmic typing relation is essentially equivalent* to the original, *declarative one*



Example (T-ABS)

$$\frac{\vdots \quad \vdots}{\Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2} \frac{}{(T\text{-SUB})} \frac{\Gamma, x:S_1 \vdash s_2 : T_2}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2} (T\text{-ABS})$$



Example (T-ABS)

$$\frac{\vdots \quad \vdots}{\Gamma, x:S_1 \vdash s_2 : S_2 \qquad S_2 <: T_2} \frac{}{(T\text{-SUB})} \frac{\Gamma, x:S_1 \vdash s_2 : T_2}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2} \frac{}{(T\text{-ABS})}$$

becomes

$$\frac{\vdots}{\Gamma, x:S_1 \vdash s_2 : S_2} \frac{}{(T\text{-ABS})} \frac{S_1 <: S_1}{\frac{}{(S\text{-REFL})}} \qquad \frac{S_2 <: T_2}{\frac{}{(S\text{-ARROW})}} \frac{\vdots}{S_1 \rightarrow S_2 <: S_1 \rightarrow T_2} \frac{}{(T\text{-SUB})} \frac{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow S_2}{\Gamma \vdash \lambda x:S_1. s_2 : S_1 \rightarrow T_2}$$



Intuitions

These examples show that we do not need T-SUB to “enable” T-ABS :

given any typing derivation, we can construct a derivation *with the same conclusion* in which T-SUB is never used immediately before T-ABS.

What about T-APP?

We've already observed that T-SUB is required for typechecking some *applications*.

So we expect to find that we *cannot* play the same game with T-APP as we've done with T-ABS.

Let's see why.



Example (T-Sub with T-APP on the left)

$$\frac{\vdots \quad \vdots}{\frac{\Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \quad \frac{T_{11} <: S_{11} \quad S_{12} <: T_{12}}{S_{11} \rightarrow S_{12} <: T_{11} \rightarrow T_{12}} \text{(S-ARROW)}}{(T\text{-SUB})} \quad \frac{\vdots}{\Gamma \vdash s_2 : T_{11}} \text{(T-APP)}}{\Gamma \vdash s_1 \ s_2 : T_{12}}$$

becomes

$$\frac{\vdots \quad \vdots}{\frac{\Gamma \vdash s_1 : S_{11} \rightarrow S_{12} \quad \frac{\Gamma \vdash s_2 : T_{11} \quad T_{11} <: S_{11}}{\Gamma \vdash s_2 : S_{11}} \text{(T-SUB)}}{(T\text{-APP})} \quad \frac{\vdots}{S_{12} <: T_{12}} \text{(T-SUB)}}{\Gamma \vdash s_1 \ s_2 : T_{12}}$$



Example (T-Sub with T-APP on the right)

$$\frac{\vdots \quad \vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{\Gamma \vdash s_2 : T_2 \quad T_2 <: T_{11}}{\Gamma \vdash s_2 : T_{11}} \quad \frac{}{(T\text{-SUB})}$$
$$\frac{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash s_2 : T_{11}}{\Gamma \vdash s_1 \ s_2 : T_{12}} \quad (T\text{-APP})$$

becomes

$$\vdots \quad \vdots$$
$$\frac{\vdots \quad \vdots}{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12}} \quad \frac{T_2 <: T_{11} \quad T_{12} <: T_{12}}{(S\text{-REFL})} \quad \frac{}{(S\text{-ARROW})}$$
$$\frac{\Gamma \vdash s_1 : T_{11} \rightarrow T_{12} \quad T_{11} \rightarrow T_{12} <: T_2 \rightarrow T_{12}}{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}} \quad (T\text{-SUB}) \quad \frac{}{\Gamma \vdash s_2 : T_2} \quad (T\text{-APP})$$
$$\frac{\Gamma \vdash s_1 : T_2 \rightarrow T_{12}}{\Gamma \vdash s_1 \ s_2 : T_{12}}$$



Observations

So we've seen that **uses of subsumption rule** can be “*pushed*” from one of immediately before T-APP’s premises to the other, but *cannot be completely eliminated*.



Example (nested uses of T-Sub)

$$\frac{\vdots \quad \vdots}{\Gamma \vdash s : s \quad s <: U} \frac{}{(T\text{-SUB})} \frac{\vdots}{U <: T} \frac{}{(T\text{-SUB})} \Gamma \vdash s : T$$



Example (nested uses of T-Sub)

$$\frac{\vdots \quad \vdots}{\Gamma \vdash s : S} \qquad \frac{}{S <: U} \qquad \frac{\vdots}{U <: T}$$
$$\frac{\Gamma \vdash s : S \quad S <: U}{\Gamma \vdash s : U} \text{ (T-SUB)} \qquad \frac{\Gamma \vdash s : U \quad U <: T}{\Gamma \vdash s : T} \text{ (T-SUB)}$$

becomes

$$\vdots \quad \vdots$$
$$\frac{\vdots \quad \vdots}{\Gamma \vdash s : S} \qquad \frac{S <: U \quad U <: T}{S <: T}$$
$$\frac{\Gamma \vdash s : S \quad S <: T}{\Gamma \vdash s : T} \text{ (T-SUB)}$$



Summary

What we've learned:

- Uses of the **T-Sub** rule can be “*pushed down*” through typing derivations until they encounter either
 1. a use of **T-App** , or
 2. the **root** of the derivation tree.
- In both cases, multiple uses of **T-Sub** can be coalesced into a single one.



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What we've learned:

- Uses of the T-Sub rule can be “pushed down” through typing derivations until they encounter either
 1. a use of **T-App** or
 2. the *root* of the derivation tree.
- In both cases, multiple uses of **T-Sub** can be collapsed into a single one.

This suggests a notion of “**normal form**” for typing derivations, in which there is

- **exactly one use** of **T-Sub** before each use of **T-App**,
- **one use** of **T-Sub** at **the very end** of the derivation,
- no uses of **T T-Sub** anywhere else.



Algorithmic Typing

The next step is to “build in” the use of subsumption rule in *application rules*, by *changing* the T-App rule to *incorporate a subtyping premise*

$$\frac{\Gamma \vdash t_1 : T_{11} \rightarrow T_{12} \quad \Gamma \vdash t_2 : T_2 \quad \boxed{\vdash T_2 \leq T_{11}}}{\Gamma \vdash t_1 t_2 : T_{12}}$$

Given any typing derivation, we can now

1. normalize it, to *move all uses of subsumption rule* to either just *before applications* (in the right-hand premise) or *at the very end*
2. replace uses of **T-App** with **T-SUB** in the right-hand premise by uses of the extended rule above

This yields a derivation in which there is just *one* use of subsumption, at the very end!



Minimal Types

But... if subsumption is only used at the very end of derivations, then it is actually *not needed* in order to show that *any term is typable*!

It is just used to give *more* types to terms that have already been shown to have a type.

In other words, if we *dropped subsumption completely* (after refining the application rule), we would still be able to give types to exactly the same set of terms — we just would not be able to give as *many types* to some of them.

If we drop subsumption, then the remaining rules will assign a *unique, minimal* type to *each typable term*.

For purposes of building a typechecking algorithm, this is enough.



Final Algorithmic Typing Rules

$$\frac{x:T \in \Gamma}{\Gamma \triangleright x : T} \quad (\text{TA-VAR})$$

$$\frac{\Gamma, x:T_1 \triangleright t_2 : T_2}{\Gamma \triangleright \lambda x:T_1. t_2 : T_1 \rightarrow T_2} \quad (\text{TA-ABS})$$

$$\frac{\Gamma \triangleright t_1 : T_1 \quad T_1 = T_{11} \rightarrow T_{12} \quad \Gamma \triangleright t_2 : T_2}{\Gamma \triangleright t_1 \ t_2 : T_{12}} \quad \boxed{\triangleright T_2 <: T_{11}}$$

(TA-APP)

$$\frac{\text{for each } i \quad \Gamma \triangleright t_i : T_i}{\Gamma \triangleright \{l_1=t_1 \dots l_n=t_n\} : \{l_1:T_1 \dots l_n:T_n\}} \quad (\text{TA-RCD})$$

$$\frac{\Gamma \triangleright t_1 : R_1 \quad R_1 = \{l_1:T_1 \dots l_n:T_n\}}{\Gamma \triangleright t_1.l_i : T_i} \quad (\text{TA-PROJ})$$



Completeness of the algorithmic rules

Theorem [Minimal Typing]:

If $\Gamma \vdash t : T$, then $\Gamma \mapsto t : S$ for some $S <: T$.



Completeness of the algorithmic rules

Theorem [Minimal Typing]:

If $\Gamma \vdash t : T$, then $\Gamma \mapsto t : S$ for some $S <: T$.

Proof: Induction on *typing derivation*.

N.b.: All the messing around with transforming derivations was just to build intuitions and *decide what algorithmic rules* to write down and *what property* to prove:

the proof itself is a straightforward induction on typing derivations.



Meets and Joins



Adding Booleans

Suppose we want to add *booleans* and *conditionals* to the language we have been discussing.

For the declarative presentation of the system, we just add in the appropriate *syntactic forms*, *evaluation rules*, and *typing rules*.

$$\frac{\Gamma \vdash \text{true} : \text{Bool} \quad \Gamma \vdash \text{false} : \text{Bool} \quad \Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T \quad \Gamma \vdash t_3 : T}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T} \quad (\text{T-IF})$$



A Problem with Conditional Expressions

For the algorithmic presentation of the system, however, we encounter a little difficulty.

What is the minimal type of

if true then {x = true, y = false} else {x = true, z = ture} ?



The Algorithmic Conditional Rule

More generally, we can use subsumption to give an expression

if t_1 then t_2 else t_3

any type that is a possible type of both t_2 and t_3 .

So the *minimal type* of the *conditional* is the *least common supertype* (or *join*) of the minimal type of t_2 and the minimal type of t_3 .

$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$



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$$\frac{\Gamma \vdash t_1 : \text{Bool} \quad \Gamma \vdash t_2 : T_2 \quad \Gamma \vdash t_3 : T_3}{\Gamma \vdash \text{if } t_1 \text{ then } t_2 \text{ else } t_3 : T_2 \vee T_3} \quad (\text{T-IF})$$

Q: Does such a type exist for every T_2 and T_3 ??



Existence of Joins

Theorem: For every pair of types S and T , there is a type J such that

1. $S \leq J$
2. $T \leq J$
3. If K is a type such that $S \leq K$ and $T \leq K$, then $J \leq K$.

i.e., J is the *smallest type* that is a supertype of both S and T .

How to prove it?



Calculating Joins

$$S \vee T = \begin{cases} \text{Bool} & \text{if } S = T = \text{Bool} \\ M_1 \rightarrow J_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & S_1 \wedge T_1 = M_1 \quad S_2 \vee T_2 = J_2 \\ \{j_I : J_I \mid I \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & T = \{l_i : T_i \mid i \in 1..n\} \\ & \{j_I \mid I \in 1..q\} = \{k_j \mid j \in 1..m\} \cap \{l_i \mid i \in 1..n\} \\ & S_j \vee T_i = J_I \quad \text{for each } j_I = k_j = l_i \\ \text{Top} & \text{otherwise} \end{cases}$$



Examples

What are the joins of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?



Meets

To calculate joins of arrow types, we also need to be able to calculate **meets** (greatest lower bounds)!

Unlike joins, meets *do not necessarily exist*.

E.g., $\text{Bool} \rightarrow \text{Bool}$ and $\{\}$ have *no common subtypes*, so they certainly don't have a greatest one!

However...



Existence of Meets

Theorem: For every pair of types S and T , if there is any type N such that $N <: S$ and $N <: T$, then there is a type M such that

1. $M <: S$
2. $M <: T$
3. If O is a type such that $O <: S$ and $O <: T$, then $O <: M$.

i.e., M (when it exists) is the *largest type* that is a subtype of both S and T .



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i.e., M (when it exists) is the *largest type* that is a subtype of both S and T .

Jargon: In the simply typed lambda calculus with subtyping, records, and booleans ...

- The subtype relation *has joins*
- The subtype relation *has bounded meets*



Calculating Meets

$S \wedge T =$

$$\left\{ \begin{array}{ll} S & \text{if } T = \text{Top} \\ T & \text{if } S = \text{Top} \\ \text{Bool} & \text{if } S = T = \text{Bool} \\ J_1 \rightarrow M_2 & \text{if } S = S_1 \rightarrow S_2 \quad T = T_1 \rightarrow T_2 \\ & \quad S_1 \vee T_1 = J_1 \quad S_2 \wedge T_2 = M_2 \\ \{m_i : M_i \mid i \in 1..q\} & \text{if } S = \{k_j : S_j \mid j \in 1..m\} \\ & \quad T = \{l_i : T_i \mid i \in 1..n\} \\ & \quad \{m_i \mid i \in 1..q\} = \{k_j \mid j \in 1..m\} \cup \{l_i \mid i \in 1..n\} \\ & \quad S_j \wedge T_i = M_i \quad \text{for each } m_i = k_j = l_i \\ & \quad M_i = S_j \quad \text{if } m_i = k_j \text{ occurs only in } S \\ & \quad M_i = T_i \quad \text{if } m_i = l_i \text{ occurs only in } T \\ fail & \text{otherwise} \end{array} \right.$$



Examples

What are the meets of the following pairs of types?

1. $\{x: \text{Bool}, y: \text{Bool}\}$ and $\{y: \text{Bool}, z: \text{Bool}\}$?
2. $\{x: \text{Bool}\}$ and $\{y: \text{Bool}\}$?
3. $\{x: \{a: \text{Bool}, b: \text{Bool}\}\}$ and $\{x: \{b: \text{Bool}, c: \text{Bool}\}, y: \text{Bool}\}$?
4. $\{\}$ and Bool ?
5. $\{x: \{\}\}$ and $\{x: \text{Bool}\}$?
6. $\text{Top} \rightarrow \{x: \text{Bool}\}$ and $\text{Top} \rightarrow \{y: \text{Bool}\}$?
7. $\{x: \text{Bool}\} \rightarrow \text{Top}$ and $\{y: \text{Bool}\} \rightarrow \text{Top}$?

Homework



- Read and digest chapter 16 & 17
- HW: 16.1.2; 16.2.6, 16.3.4