

软件科学基础

Maps: Total and Partial Maps

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复习: Lists章节的Map定义



```
Inductive id : Type :=
    | Id (n : nat).

Definition eqb_id (x1 x2 : id) :=
    match x1, x2 with
    | Id n1, Id n2 => n1 =? n2
    end.
```

复习: Lists章节的Map定义



```
Inductive partial map : Type :=
  | empty
  | record (i : id) (v : nat) (m : partial_map).
Definition update (d : partial map)
                  (x : id) (value : nat)
                  : partial_map :=
  record x value d.
Fixpoint find (x : id) (d : partial_map) : natoption :=
  match d with
  empty => None
  | record y v d' => if eqb_id x y
                    then Some v
                     else find x d'
  end.
```

问题:同样的映射可能对应多个map,未定义完全映射

重新用函数定义Map



可以应用函数相关的定理,使得一些证明更简单





重新用函数定义Map



```
Definition partial map (A : Type) := total map (option A
).
Definition empty {A : Type} : partial map A :=
  t_empty None.
Definition update {A : Type} (m : partial_map A)
           (x : string) (v : A) :=
  (x !-> Some v ; m).
Notation "x '|->' v ';' m" := (update m x v)
  (at level 100, v at next level, right associativity).
Notation "x '|->' v" := (update empty x v)
  (at level 100).
Example examplepmap :=
  ("Church" |-> true; "Turing" |-> false).
```

作业



- 完成Maps中2道standard非optional的习题
 - 请使用最新英文版教材