



## Matlab HW5: Exercise from Chap 3

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## Matlab HW5

### **1** Nonlinear and Partially Linear Signals

## Nonlinear and Partially Linear Signals

### Example 1 (Least Squares Estimator for Partially Linear Signal)

Considered  $p = 1$  in previous example, the sinusoids signal is given by

$$s[n] = \alpha_1 \cos(2\pi f_0 n) + \alpha_2 \sin(2\pi f_0 n)$$

Actual data  $x[n]$  for  $n = 0, 1, \dots, N - 1$  is available. Determine the unknown parameters  $\{\alpha_1, \alpha_2, f_0\}$  to minimize the least squares error

$$\begin{aligned} J(\alpha_1, \alpha_2, f_0) \\ = \sum_{n=0}^{N-1} \left( x[n] - [\alpha_1 \cos(2\pi f_0 n) + \alpha_2 \sin(2\pi f_0 n)] \right)^2 \end{aligned}$$

## Nonlinear and Partially Linear Signals

- Written in the usual matrix/vector form as

$$\mathbf{s} = \underbrace{\begin{bmatrix} 1 & 0 \\ \cos(2\pi f_0) & \sin(2\pi f_0) \\ \vdots & \vdots \\ \cos[2\pi f_0(N-1)] & \sin[2\pi f_0(N-1)] \end{bmatrix}}_{\mathbf{H}(f_0)} \underbrace{\begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}}_{\boldsymbol{\theta}}$$

- $\mathbf{H}$  is no longer a known matrix since it depends upon the unknown parameter  $f_0$
- The minimization of  $J(\alpha_1, \alpha_2, f_0)$  can be carried out by performing a numerical maximization, by maximizing the function

$$J(f_0) = \mathbf{x}^T \mathbf{H}(f_0) \left( \mathbf{H}^T(f_0) \mathbf{H}(f_0) \right)^{-1} \mathbf{H}^T(f_0) \mathbf{x} \quad (1)$$

over  $0 < f_0 < 1/2$  to yield the maximizing value  $\hat{f}_0$

## Nonlinear and Partially Linear Signals

- Treating  $\mathbf{H}(\hat{\mathbf{f}}_0)$  as a known matrix, the remaining parameters are given by the least squares estimator

$$\begin{bmatrix} \hat{\alpha}_1 \\ \hat{\alpha}_2 \end{bmatrix} = \left( \mathbf{H}^T(\hat{\mathbf{f}}_0) \mathbf{H}(\hat{\mathbf{f}}_0) \right)^{-1} \mathbf{H}^T(\hat{\mathbf{f}}_0) \mathbf{x}$$

- The amplitude and phase estimates can now be found from

$$\hat{A} = \sqrt{\hat{\alpha}_1^2 + \hat{\alpha}_2^2}$$

$$\hat{\phi} = \arctan\left(\frac{-\hat{\alpha}_2}{\hat{\alpha}_1}\right)$$

- For  $p$  sinusoids the numerical maximization must be carried out over the  $p$ -dimensional space for  $\{\mathbf{f}_1, \mathbf{f}_2, \dots, \mathbf{f}_p\}$

## Nonlinear and Partially Linear Signals

### Example 2 (Exercise 3.8: Numerical maximization)

Assume that the data is noiseless so that  $x[n] = \cos(2\pi(0.12)n + \pi/4)$  for  $n = 0, 1, \dots, N-1$ , where  $N = 20$ . Substitute  $x[n]$  into (1) and then maximize  $J(f_0)$  over  $0 < f_0 < 1/2$  by computing the values of  $J(f_0)$  explicitly for each value of  $f_0$ .

- 1 Choose the values of  $f_0$  as  $f_0 = 0.1, 0.2, 0.3, 0.4$ .
- 2 Choose the values as  $f_0 = 0.01, 0.02, \dots, 0.49$ .
- 3 Repeat the above test by modifying  $N$ . Does the correct value depend on the number of observation  $N$ ?

Do you obtain the correct value of  $f_0$ ?

[Hint: Modify the program **FSSP3exer3\_8.m** ]

## Nonlinear and Partially Linear Signals

### Example 3 (Modified of Exercise 3.8: Numerical maximization)

Redo the Exercise 3.8 by assuming the additive noise. Assume that the data is noiseless so that  $x[n] = \cos(2\pi(0.12)n + \pi/4) + w[n]$  for  $n = 0, 1, \dots, N-1$ , where  $N = 20$  and  $w[n] \sim \mathcal{N}(0, 1^2)$ . Substitute  $x[n]$  into (1) and then maximize  $J(f_0)$  over  $0 < f_0 < 1/2$  by computing the values of  $J(f_0)$  explicitly for each value of  $f_0$ .

- 1 Choose the values of  $f_0$  as  $f_0 = 0.1, 0.2, 0.3, 0.4$ .
- 2 Choose the values as  $f_0 = 0.01, 0.02, \dots, 0.49$ .
- 3 Repeat the above test by modifying  $w[n] \sim \mathcal{N}(0, 0.1^2)$
- 4 Repeat the above test by modifying  $N$ . Does the correct value depend on the number of observation  $N$ ?

Do you obtain the correct value of  $f_0$ ? [Hint: Modify the program **FSSP3exer3\_8.m**]

# Question & Answer

