ME 491 Lecture 9.

Ch.4 Regression and Model Selection

- Most basic regression techniques is curve fitting. With Polynomial and exponential fitting from solving the linear equation Ax = b
  - · When the model is not prescribed, often, our goal is to select the best model, so we will normally have
    - over-determined optimization problem argmin ( $IIAx-bII_2+\lambda g(x)$ )
    - under-determined optimization problem

      argmin g(x) Subject to 11Ax-6112 < 6
    - g(x): given penalization
    - Cross-validation
       if a proposed model has overfit or under fit the data.



model is constructed on training and validation data, and tested on withhold.

## Ch4.1 Classic Curve Fitting

· Regression: attempts to estimate the relationship among variables.

X: independent variables, Y: dependent variables

B: unknown parameters.

Least-Squares Filling Methods use a simple function to describe a trend by minimizing the sum-square error between the selected function f(.) and its fit to data.

Consider a set of n data points  $(x_1, y_1), (x_2, y_2), (x_3, y_3), \dots, (x_n, y_n)$ we want to approximate the line using  $f(x) = \beta_1 x + \beta_2$ 

This gives us the linear regression model  $Y = f(X, \beta) = \beta_1 X + \beta_2$ 

Many different error metrics can be used to solve for f(x). three standard ones are

1. maximum error  $loo: E_{\infty}(f) = \max_{1 < k < n} |f(x_k) - y_k|$ 

2. Mean absolute error 
$$l_i: E_i(f) = \frac{1}{n} \sum_{k=1}^{n} |f(x_k) - y_k|$$

3. least-square error 
$$2: E_z(f) = \left(\frac{1}{N} \sum_{k=1}^{N} |f(x_k) - y_k|^2\right)^{1/2}$$

We can generalized to the lp norm
$$E_{p}(f) = \left(\frac{1}{N} \sum_{k=1}^{N} |f(\chi_{k}) - y_{k}|^{p}\right)^{p}$$

normally, the difference to different-norm fit is small, unless there are outliers in data.

## - Least-Squares Line

Least square fitting is preferred as it is inexpensive and can be solved analytically

We want to fit to the curve:  $f(x) = \beta_1 x + \beta_2$ 

the error is: Ez(f) = = | f(xx) - yx |2 = = (\beta, \chi\_1 \chi\_2 + \beta\_2 - yx)^2

To minimize Ez, we want to solve

$$\frac{\partial E_z}{\beta_1} = 0: \sum_{k=1}^{N} 2(\beta_1 \chi_k + \beta_2 - y_k) \chi_k = 0$$

$$\frac{\partial E_z}{\beta_z} = 0: \sum_{k=1}^{N} 2(\beta_1 \chi_k + \beta_2 - y_k) = 0$$

$$\beta_2 = 0$$
:  $\angle (\beta_1 \times + \beta_2 - y_k) =$ 

Rearrange the two equations, we get 2B1 5 Xx + 2B25 Xx = 5 2 Xxyk

We can Write them in a 2x2 system of linear equations

$$\begin{pmatrix} \sum_{k=1}^{n} \chi_{k}^{2} & \sum_{k=1}^{n} \chi_{k} \\ \sum_{k=1}^{n} \chi_{k} & N \end{pmatrix} \begin{pmatrix} \beta_{1} \\ \beta_{2} \end{pmatrix} = \begin{pmatrix} \sum_{k=1}^{n} \chi_{k} y_{k} \\ \sum_{k=1}^{n} y_{k} \end{pmatrix} \Rightarrow Ax = b$$

This method can be easily generated to higher polynomial fit.

For example:  $f(x) = \beta_1 \chi^2 + \beta_2 \chi + \beta_3$ 

we will need to solve a 3x3 system to minimize the error

$$E_{z}(\beta_{1}, \beta_{2}, \beta_{3})$$
 by taking:  
 $\frac{\partial E_{z}}{\beta_{1}} = 0$ ;  $\frac{\partial E_{z}}{\beta_{2}} = 0$ ;  $\frac{\partial E_{z}}{\beta_{3}} = 0$ 

Generally, we can find a degree- k fit by solving (k+1)(k+1) linear system of equations Ax = b.

-Data Linearization

Sometime, we need to Pre-Process the data to use the method at hand consider

$$f(x) = \beta_2 \exp(\beta_1 x)$$
  
The evror to be minimized is

 $E_2(\beta_1, \beta_2) = \sum_{k=1}^{n} (\beta_2 \exp(\beta_1 \chi_k) - y_k)^2$ 

Applying the minimization condition, we get

$$\frac{\partial E_z}{\partial \beta_1} = 0 : \sum_{k=1}^{n} 2(\beta_2 \exp(\beta_1 \chi_k) - y_k) \beta_2 \chi_k \exp(\beta_1 \chi_k) = 0$$

$$\frac{\partial E_z}{\partial \beta_2} = 0 : \sum_{k=1}^{n} 2(\beta_2 \exp(\beta_1 \chi_k) - y_k) \exp(\beta_1 \chi_k) = 0$$

The 2x2 system we are solving is

$$\beta_{2}^{2}\sum_{k=1}^{\infty}\chi_{k}\exp(z\beta_{1}\chi_{k})-\beta_{2}\sum_{k=1}^{\infty}\chi_{k}y_{k}\exp(\beta_{1}\chi_{k})=0$$

$$\beta_2 \sum_{k=1}^{n} P \times P(2\beta_1 \chi_k) - \sum_{k=1}^{n} y_k e \times P(\beta_1 \chi_k) = 0$$

This system is nonlinear and might not have a solution, but in this particular case, we can linearize the system

Let  $Y = \ln(y)$ , X = X,  $\beta_3 = \ln \beta_2$ Taking the In of both side of the original equation, we get  $\ln(y) = \beta_1 X + \ln \beta_2 \Rightarrow Y = \beta_1 X + \beta_3$