# 视频编码解码芯片规格书 ——AC5200 芯片

珠海市杰理科技有限公司

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# AC5200 硬件设计说明书 V1.0

# 特别注意事项

- 1、 LDOIN、VDDIO、USBVDDT、USBVDDC 要求使用 3.3V(±5%范围内)供电。
- 2、 AVDDHP 要求使用 3.3V 供电, 纹波尽可能优化处理。
- 3、 AVSSREF 、AVSSHP 不能直接在芯片处连数字 GND,需要把其定义为模拟地作处理。
- 4、 晶振及其他时钟的走线要尽可能短,走线切勿与其他信号线平行走线,并需用地线或电源线包裹。
- 5、 AVDD18 和 AVDD28 为芯片输出电压,可供给摄像头模组等使用。

# 1. 版本信息

日期	版本号	描述
2015.09.16	V1.0	原始版本。



# 2. 引脚定义

# 2.1 引脚分配

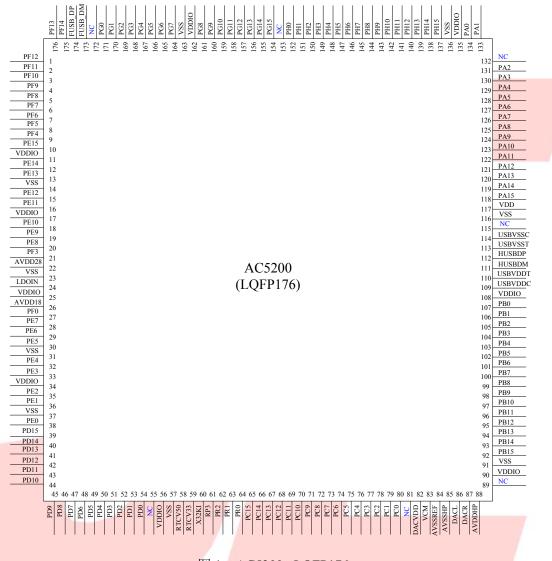


图 1 AC5200\_LQFP176

# 2.2 引脚描述

(AC5200)Pin#	Name	I/O Type	Function	Other Function
1	PF12	I/0	GPI0	SDR_A1_B:SDRAM A1 SENSOR1_D5_B: SENSOR1 Data 5
2	PF11	I/0	GPI0	SDR_AO_B:SDRAM AO SENSOR1_D4_B: SENSOR1 Data 4
3	PF10	I/0	GPI0	SDR_A10_B:SDRAM A10 SENSOR1_D3_B: SENSOR1 Data 3 MPWM_FPIN_B: MOTOR PWM FPIN
4	PF9	1/0	GPI0	SDR_BA1_B:SDRAM BA1 SENSOR1_D2_B: SENSOR1 Data 2 SD1_DAT1_A: SD Data 1 MPWM_H3_B: MOTOR PWM H3
5	PF8	1/0	GPI0	SDR_BAO_B:SDRAM BAO SENSOR1_D1_B: SENSOR1 Data 1 SD1_DATO_A: SD Data 0 MPWM_L3_B: MOTOR PWM L3
6	PF7	1/0	GPI0	SDR_CS_BC:SDRAM CS# SENSOR1_DO_B: SENSOR1 Data 0 SD1_CLK_A: SD CLK MPWM_H2_B: MOTOR PWM H2
7	PF6	I/0	GPI0	SDR_RAS_BC:SDRAM RAS# SENSOR1_VSYNC_B: SENSOR1 Vertical Synchronization SD1_CMD_A: SD CMD MPWM_L2_B: MOTOR PWM L2
8	PF5	1/0	GPI0	SDR_CAS_BC:SDRAM CAS# SENSOR1_HSYNC_B: SENSOR1 Horizontal Synchronization SD1_DAT3_A: SD Data 3 MPWM_H1_B: MOTOR PWMH H1
	PF4	I/0	GPI0	SDR_WE_BC:SDRAM WE# SENSOR1_CLK_B: SENSOR1 PCLK SD1_DAT2_A: SD Data 2 MPWM_L1_B: MOTOR PWMH L1
10	PE15	I/0	GPI0	SDR_DQ15
11	VDDIO	P	IO Power	
12	PE14	I/0	GPI0	SDR_DQ14 SDR_A3_C:SDRAM A3
13	PE13	1/0	GPI0	SDR_DQ13 SDR_A2_C:SDRAM A2

14	VSS	P	Digital Ground	
15	PE12	I/0	GPI0	SDR_DQ12 SDR_A1_C:SDRAM A1
16	PE11	I/0	GPI0	SDR_DQ11 SDR_AO_C:SDRAM AO
17	VDDIO	P	IO Power	
18	PE10	I/0	GPI0	SDR_DQ10 SDR_A10_C:SDRAM A10
19	PE9	I/0	GPI0	SDR_DQ9 SDR_BA1_C:SDRAM BA1
20	PE8	I/0	GPI0	SDR_DQ8 SDR_BAO_C:SDRAM BAO
21	PF3	1/0	GPI0	UART2_RX_B: Uart2 Data In SDR_DQMH_BC: SDRAM DQ Mask High
22	AVDD28	P	LDO OUT	2.8V Output
23	VSS	Р	Digital Ground	
24	LDOIN	Р	LDO Power In	
25	VDDIO	Р	IO Power	
26	AVDD18	Р	LDO OUT	1.8V Output
27	PF0	I/0	GPI0	UART2_TX_B: Uart2 Data Out SDR_DQML_BC: SDRAM DQ Mask Low
28	PE7	I/0	GPI0	SDR_DQ7 SDR_A12_C:SDRAM A12
29	PE6	I/0	GPI0	SDR_DQ6 SDR_A11_C:SDRAM A11
30	PE5	I/0	GPI0	SDR_DQ5 SDR_A9_C:SDRAM A9
31	VSS	Р	Digital Ground	
32	PE4	I/0	GPI0	SDR_DQ4 SDR_A8_C:SDRAM A8
33	PE3	I/0	GPI0	SDR_DQ3 SDR_A7_C:SDRAM A7
34	VDDIO	Р	IO Power	
35	PE2	I/0	GPI0	SDR_DQ2 SDR_A6_C:SDRAM A6
36	PE1	I/0	GPI0	SDR_DQ1 SDR_A5_C:SDRAM A5
37	VSS	Р	Digital Ground	

38	PE0	I/0	GPI0	SDR_DQO SDR A4 C:SDRAM A4
200	DD15	T /O	CDIO	SDR_CLK_BC: SDRAM CLK
39	PD15	1/0	GPI0	SENSORO_DO_A: SENSORO Data O
40	PD14	I/0	GPI0	SDR_CKE_BC: SDRAM CKE
		-		SENSORO_D1_A: SENSORO Data 1
41	PD13	I/0	GPI0	SDR_A12_B:SDRAM A12 SENSORO D2 A: SENSORO Data 2
	DD 40	7./0	anto	SDR A11 B:SDRAM A11
42	PD12	I/0	GPI0	SENSORO_D3_A: SENSORO Data 3
				SDR_A9_B:SDRAM A9
43	PD11	I/0	GPI0	SENSORO_D4_A: SENSORO Data 4
			7	SD1_DAT1_C:SD1_Data1
44	PD10	I/0	GPI0	SDR_A8_B:SDRAM A8 SENSORO D5 A: SENSORO Data 5
	1010	17 0	0110	SD1_DATO_C:SD1_Data0
			77	SDR_A7_B:SDRAM A7
45	PD9	I/0	GPI0	SENSORO_D6_A: SENSORO Data 6
				SD1_CLK_C:SD1_CLK
46	PD8	T /O	GPI0	SDR_A6_B: SDRAM A6
40	PD8	I/0	61 10	SENSORO_D7_A: SENSORO Data 7 SD1_CMD_C:SD1_CMD
			7 / -	SDR A5 B:SDRAM A5
47	PD7	I/0	GPI0	SENSORO_D8_A: SENSORO Data 8
				SD1_DAT3_C:SD1 Data3
	DD 0	T (0	anto	SDR_A4_B:SDRAM A4
48	PD6	I/0	GPI0	SENSORO_D9_A: SENSORO Data 9 SD1 DAT2 C:SD1 Data2
				UARTO RX D: UartO Data In
		-/-		SENSORO_VSYNC_A: SENSORO Vertical
49	PD5	I/0	GPI0	Synchronization
				IIC_SDA_A:IIC SDA
427				UARTO_TX_D: UartO Data Out
50	PD4	I/0	GPI0	SENSORO_HSYNC_A: SENSORO Horizontal Synchronization
				IIC_SCL_A:IIC SCL
51	PD3	I/0	GPI0	SENSORO_CLK_A: SENSORO PCLK
52	PD2	I/0	GPI0	SPI1_DI_B :SPI1 Data In
53	PD1	I/0	GPI0	SPI1_DO_B :SPI1 Data Out
30	121	1,0	0.10	UART2_RX_C: Uart2 Data In
E 4	DDΩ	T /O	CDIO	SPI1_CLK_B:SPI1 Clock
54	PD0	1/0	GPI0	UART2_TX_C: Uart2 Data Out CAP2:TIMER2 Capture
				om 2.11MEN2 capture

55	NC			
56	VDDIO	P	IO Power	
30	VDD10	1	Digital	
57	VSS	P	Ground	
F0	DTCUEO	D		
58	RTCV50	P	RTC Power	
59	RTCV33	P	RTC Power	
60	X32KI	I/0	RTC 32K OSC	_
			In	Y
61	PR3	I/0	RTCIO	RTC32K OSC OUT
62	PR2	I/0	RTCIO	ADC12:ADC Input Channel 12
63	PR1	I/0	RTCIO	ADC13:ADC Input Channel 13
64	PR0	I/0	RTCIO	
65	PC15	1/0	GPI0	UART3_RX_C: Uart3 Data In SENSOR1_D7_A: SENSOR1 Data 7
66	PC14	I/0	GPI0	UART3_TX_C: Uart3 Data Out SENSOR1 D6_A: SENSOR1 Data 6
			7 7	ALNK D3 B: AUDIO LINK Data3
			V A	SENSOR1 D5 A: SENSOR1 Data 5
67	PC13	I/0	GPI0	SDO DAT1 C:SDO Data1
			7.4	SPIO DAT3 B:SPIO Data3
				CAP3:TIMER3 Capture
			7.7	ALNK D2 B: AUDIO LINK Data2
		- 1-	V A	SENSOR1 D4 A: SENSOR1 Data 4
68	PC12	I/0	GPI0	SDO DATO C:SDO Data0
				SPIO_CLK_B:SPIO_Clock
			/	ALNK D1 B: AUDIO LINK Datal
4			/	SENSOR1 D3 A: SENSOR1 Data 3
69	PC11	I/0	GPI0	SDO CLK C:SDO CLK
				SPIO_DO(0)_B:SPIO_DO(Data_0)
		71		ALNK DO B: AUDIO LINK DataO
				SENSOR1 D2 A: SENSOR1 Data 2
70	PC10	I/0	GPI0	SDO CMD C:SDO CMD
				SPIO_DAT2_B:SPIO_Data2
				ALNK WS B:AUDIO LINK WS
				SENSOR1 D1 A: SENSOR1 Data 1
71	PC9	I/0	GPI0	SDO DAT3 C:SDO Data3
	100	1,0	31.10	SPIO DI(1) B:SPIO DI(Data 1)
₩				5. 10_D1 (1) _D. 51 10 D1 (Data 1)
				ALNK_CK_B:AUDIO LINK CLK
				SENSOR1 DO A: SENSOR1 Data 0
72	PC8	I/0	GPI0	SDO_DAT2_C:SDO_Data2
12	100	1/0	01.10	SPIO_CS_B :SPIO Chip Select
				Siro_oo_b .Siro onip Serect

73	PC7	I/0	GPI0	UART1_RX_D: Uart1 Data In SENSOR1_VSYNC_A: SENSOR1 Vertical Synchronization
74	PC6	I/0	GPI0	UART1_TX_D: Uart1 Data Out SENSOR1_HSYNC_A: SENSOR1 Horizontal Synchronization
75	PC5	I/0	GPI0	SENSOR1_CLK_A: SENSOR1 PCLK CAPO:TIMERO Capture UART2_RX_A: Uart2 Data In
76	PC4	I/0	GPI0	UART2_TX_A: Uart2 Data Out
77	PC3	I/0	GPI0	VPP UART1_RX_A: Uart1 Data In PWM3:TIMER3 PWM Output
78	PC2	I/0	GPI0	UART1_TX_A: Uart1 Data Out CAP1:TIMER1 Capture
79	PC1	1/0	GPI0	AMUX1R: Simulator Channel 1 Right UARTO_RX_A: UartO Data In LADC7
80	PC0	1/0	GPI0	AMUX1L: Simulator Channel 1 Left UARTO_TX_A: UARTO Data Out PWMO:TIMERO PWM Output LADC6
81	NC		/ /	
82	DACVDD	Р	DAC Power	
83	VCM	P	VCM	/
84	AVSSREF	Р	REF Gound	<del></del>
85	AVSSHP	Р	Head Phone Ground	
86	DACL	0	DAC Left Channel	DACL
87	DACR	0	DAC Right Channel	DACR
88	AVDDHP	Р	Head Phone Power	_
89	NC			
90	VDDIO	Р	IO Power	
91	VSS	Р	Digital Ground	
92	PB15	I/0	GPI0	UART3_RX_B: Uart3 Data In MIC LADC5

				HAPTO TV P H (0 P )
93	PB14	I/0	GPI0	UART3_TX_B: Uart3 Data Out AMUXOR: Simulator Channel O Right IIC_SDA_B:IIC SDA WAKEUP9: Port Wakeup LADC4
94	PB13	I/0	GPI0	AVOUT: AV Output WAKEUP8: Port Wakeup LADC3 PWM1:TIMER1 PWM Output
95	PB12	I/0	GPI0	AMUXOL: Simulator Channel 0 Left SENSORO_DO_B: SENSORO Data 0 IIC_SCL_B:IIC_SCL
96	PB11	I/0	GPI0	SDR_DQML_A: SDRAM DQ Mask Low SENSORO_D1_B: SENSORO Data 1
97	PB10	I/0	GPI0	SDR_WE_A: SDRAM WE# SENSORO_D2_B: SENSORO Data 2
98	PB9	I/0	GPI0	SDR_CAS_A: SDRAM CAS# SENSORO_D3_B: SENSORO Data 3
99	PB8	I/0	GPI0	SDR_RAS_A: SDRAM RAS# SENSORO_D4_B: SENSORO Data 4
100	PB7	I/0	GPI0	SDR_CS_A: SDRAM CS# SENSORO_D5_B: SENSORO Data 5
101	PB6	I/0	GPI0	SDR_BAO_A: SDRAM BAO SENSORO_D6_B: SENSORO Data 6
102	PB5	I/0	GPI0	SDR_BA1_A: SDRAM BA1 SENSORO_D7_B: SENSORO Data 7
103	PB4	I/0	GPI0	SDR_A10_A: SDRAM A10 SENSOR0_D8_B: SENSOR0 Data 8
104	PB3	I/0	GPI0	SDR_AO_A: SDRAM AO SENSORO_D9_B: SENSORO Data 9
105	PB2	I/0	GPI0	SDR_A1_A: SDRAM A1 SENSORO_VSYNC_B: SENSORO Vertical Synchronization
106	PB1	I/0	GPI0	SDR_A2_A: SDRAM A2 SENSORO_HSYNC_B: SENSORO Horizontal Synchronization Timer1:TIMER1 Clock In
107	PB0	I/0	GPI0	SDR_A3_A: SDRAM A3 SENSORO_CLK_B: SENSORO PCLK
108	VDDIO	Р	IO Power	
109	USBVDDC	Р	USB Power	
110	USBVDDT	Р	USB Power	

111	HUSBDM	I/0	HUSB DM	
112	HUSBDP	I/0	HUSB DP	
113	USBVSST	Р	USB Ground	
114	USBVSSC	Р	USB Ground	
115	NC			
116	VSS	Р	Digital Ground	
117	VDD	Р	Core Power	
118	PA15	I/0	GPI0	SDR_A4_A: SDRAM A4 SENSOR1_CLK_C: SENSOR1 PCLK SD1_DAT1_D: SD Data 1 MPWM_H3_A: MOTOR PWM H3
119	PA14	1/0	GPI0	SDR_A5_A: SDRAM A5 SENSOR1_D7_C: SENSOR1 Data 7 SD1_DATO_D: SD Data 0 MPWM_L3_A: MOTOR PWM L3
120	PA13	1/0	GPI0	SDR_A6_A: SDRAM A6 SENSOR1_D6_C: SENSOR1 Data 6 SD1_CLK_D: SD CLK MPWM_H2_A: MOTOR PWM H2
121	PA12	I/0	GPI0	SDR_A7_A: SDRAM A7 SENSOR1_D5_C: SENSOR1 Data 5 SD1_CMD_D: SD CMD MPWM_L2_A: MOTOR PWM L2
122	PA11	1/0	GPI0	SDR_A8_A: SDRAM A8 SENSOR1_D4_C: SENSOR1 Data 4 SD1_DAT3_D: SD Data 3 MPWM_H1_A: MOTOR PWM H1
123	PA10	1/0	GPI0	SDR_A9_A: SDRAM A9 SENSOR1_D3_C: SENSOR1 Data 3 SD1_DAT2_D: SD Data 2 MPWM_L1_A: MOTOR PWM L1
124	PA9	I/0	GPIO	SDR_A11_A: SDRAM A11 SENSOR1_D2_C: SENSOR1 Data 2 MPWM_FPIN_A: MOTOR PWM FPIN
125	PA8	I/0	GPI0	SDR_A12_A: SDRAM A12 SENSOR1_D1_C: SENSOR1 Data 1 UART3_RX_A: Uart3 Data In
126	PA7	1/0	GPI0	SDR_CKE_A: SDRAM CKE SENSOR1_DO_C: SENSOR1 Data 0 UART3_TX_A: Uart3 Data Out

127	PA6	I/0	GPI0	SDR_CLK_A: SDRAM CLK SENSOR1_VSYNC_C: SENSOR1 Vertical Synchronization Timer0:TIMERO Clock In
128	PA5	1/0	GPI0	SDR_DQMH_A: SDRAM DQ Mask High SENSOR1_HSYNC_C: SENSOR1 Horizontal Synchronization
129	PA4	I/0	GPI0	ADC1:ADC Input Channel 1 SPIO_CLK_A:SPIO Clock SFC_CLK:SFC Clock SDO_DATO_A: SD Data 0
130	PA3	1/0	GPI0	SPIO_DO(0)_A:SPIO DO(Data 0) SFC_DO(0):SFC DO(Data 0) SDO_DAT2_A: SD Data 2
131	PA2	I/0	GPI0	ADCO:ADC Input Channel 0 IIC_SCL_A:IIC SCL SPI0_DAT2_A:SPI0 Data2 SFC_DAT2:SFC Data2 SD0_CLK_A: SD CLK
132	NC	1		
133	PA1	1/0	GPI0	IIC_SDA_C:IIC SDA SPIO_DI(1)_A:SPIO DI(Data 1) SFC_DI(1): SFC_Data 1 SDO_CMD_A: SD CMD
134	PA0	I/0	GPI0	SPIO_CS_A :SPIO Chip Select SFC_CS :SFC Chip Select
135	VDDIO	P	IO Power	<del>-</del>
136	VSS	Р	Digital Ground	
				UART1_RX_C: Uart1 Data In ADC11:ADC Input Channel 11 CLKOUT2: Clock Out 2
137	PH15	1/0	GPI0	WAKEUP15: Port Wakeup SPIO_DAT3_A:SPIO Data 3 SFC_DAT3:SFC Data 3 SDO_DAT1_A: SD Data 1
138	PH14	I/0	GPI0	UART1_TX_C: Uart1 Data Out ADC6:ADC Input Channel 6 CLKOUT1: Clock Out 1 WAKEUP14: Port Wakeup

	1	1	T	
139	РН13	1/0	GPI0	UARTO_RX_C: UartO Data In CLKOUTO: Clock Out O Timer3:TIMER3 Clock In SDO_DAT3_A: SD Data 3
140	PH12	I/0	GPI0	UARTO_TX_C: UartO Data Out ALNK_MCK:AUDIO LIN MASTER CLK PWM2:TIMER2 PWM Output LVD: LVD Test Pin
141	PH11	1/0	GPI0	LCD_DAT23:LCD Data23 SD0_DAT1_B: SD Data 1 LCD_COM5:LCD Com Output5 ALNK_D3A:AUDIO LINK Data3 UART3_RX_D: Uart3 Data In
142	РН10	1/0	GPI0	LCD_DAT22:LCD Data22 ADC10:ADC Input Channel 10 SD0_DAT0_B: SD Data 0 LCD_COM4:LCD Com Output4 ALNK_D2A:AUDIO LINK Data2 WAKEUP13: Port Wakeup UART3_TX_D: Uart3 Data Out
143	РН9	1/0	GPI0	LCD_DAT21:LCD Data21 ADC9:ADC Input Channel 9 SD0_DAT2_B: SD Data 2 LCD_COM3:LCD Com Output3 ALNK D1A:AUDIO LINK Data1
144	РН8	1/0	GPI0	LCD_DAT20:LCD Data20 ADC8:ADC Input Channel 8 SD0_CLK_B: SD Clock LCD_COM2:LCD Com Output2 ALNK_DOA:AUDIO LINK Data0 IIC_SDA_D:IIC_SDA
145	PH7	I/0	GPI0	LCD_DAT19:LCD Data19 ADC7:ADC Input Channel 7 SD0_CMD_B: SD CMD LCD_COM1:LCD Com Output1 ALNK_WSA:AUDIO LINK WS WAKEUP12: Port Wakeup IIC_SCL_D:IIC SCL
146	РН6	1/0	GPI0	LCD_DAT18:LCD Data18 SD0_DAT3_B: SD Data 3 LCD_COM0:LCD Com Output0 ALNK_CKA:AUDIO LINK CLK

				LCD_VSYNC: LCD Vertical
				Synchronization
147	PH5	I/0	GPI0	UART1_RX_B: Uart1 Data In
				SPI1_DI_A :SPI1 Data In
				LCD_SEG21:LCD SEG Output21
				LCD_HSYNC:LCD Horizontal
				Synchronization
148	PH4	I/0	GPI0	SPI1_DO_A :SPI1 Data Out
				LCD_SEG20:LCD SEG Output20
				EMI_RD:EMI Read
				LCD_DEN:LCD Data Enable
149	РН3	I/0	GPI0	EMI_WR:EMI Write
149	1119	1/0	Gr 10	SPI1_CLK_A:SPI1 Clock
				LCD_SEG19:LCD SEG Output19
			y y	LCD_DCLK:LCD Data CLK
150	PH2	I/0	GPIO	UART1_TX_B: Uart1 Data Out
				LCD_SEG18:LCD SEG Output18
				LCD_DAT17:LCD Data17
				UART2_RX_D: Uart2 Data In
			- Y A	ADC5:ADC Input Channel 5
151	PH1	I/0	GPI0	LCD_SEG17:LCD SEG Output17
			7.4	Timer2:TIMER2 Clock In
		P.		WAKEUP11: Port Wakeup
				OSCO:OSC Out
				LCD_DAT16:LCD Data16
			/	UART2_TX_D: Uart2 Data Out
152	PHO	I/0	GPI0	ADC4:ADC Input Channel 4
152	1110	1/0	GI 10	LCD_SEG16:LCD SEG Output16
				WAKEUP10: Port Wakeup
		- 7 A		OSCI:OSC In
153	NC	///		
				LCD_DAT15:LCD Data15
154	PG15	I/0	GPI0	EMI_D15:EMI Data15
				LCD_SEG15:LCD SEG Output15
				LCD_DAT14:LCD Data14
155	PG14	I/0	GPI0	EMI_D14:EMI Data14
	1011	1/0	01.10	LCD_SEG14:LCD SEG Output14
				LCD_DAT13:LCD Data13
				EMI_D13:EMI Data13
156	PG13	I/0	GPI0	SDO_DAT1_D: SD Data 1
				LCD_SEG13:LCD SEG Output13

157	PG12	I/0	GPI0	LCD_DAT12:LCD Data12 EMI_D12:EMI Data12 SD0_DAT0_D: SD Data 0 LCD_SEG12:LCD SEG Output12
158	PG11	I/0	GPI0	LCD_DAT11:LCD Data11 EMI_D11:EMI Data11 SD0_CLK_D: SD Clock LCD_SEG11:LCD SEG Output11
159	PG10	I/0	GPI0	LCD_DAT10:LCD Data10 EMI_D10:EMI Data10 SD0_CMD_D: SD Command LCD_SEG10:LCD SEG Output10
160	PG9	1/0	GPI0	LCD_DAT9:LCD Data9 EMI_D9:EMI Data9 SD0_DAT3_D: SD Data 3 LCD_SEG9:LCD SEG Output9
161	PG8	1/0	GPI0	LCD_DAT8:LCD Data8 EMI_D8:EMI Data8 SD0_DAT2_D: SD Data 2 LCD_SEG8:LCD SEG Output8
162	VDDIO	Р	IO Power	
163	VSS	Р	Digital Ground	
164	PG7	I/0	GPI0	LCD_DAT7:LCD Data7 EMI_D7:EMI Data7 UART0_RX_B: Uart0 Data In LCD_SEG7:LCD SEG Output7 ADC3:ADC Input Channel 3
165	PG6	1/0	GPI0	LCD_DAT6:LCD Data6  EMI_D6:EMI Data6  UART0_TX_B: Uart0 Data Out  LCD_SEG6:LCD SEG Output6  ADC2:ADC Input Channel 2
166	PG5	1/0	GPI0	LCD_DAT5:LCD Data5 EMI_D5:EMI Data5 SD1_DAT1_B: SD Data 1 LCD_SEG5:LCD SEG Output5
167	PG4	I/0	GPI0	LCD_DAT4:LCD Data4  EMI_D4:EMI Data4  SD1_DAT0_B: SD Data 0  LCD_SEG4:LCD SEG Output4

168	PG3	I/0	GPI0	LCD_DAT3:LCD Data3 EMI_D3:EMI Data3 SD1_CLK_B: SD Clock LCD_SEG3:LCD SEG Output3		
169	PG2	I/0	GPI0	LCD_DAT2:LCD Data2 EMI_D2:EMI Data2 SD1_CMD_B: SD Command LCD_SEG2:LCD SEG Output2		
170	PG1	1/0	GPI0	LCD_DAT1:LCD Data1  EMI_D1:EMI Data1  SD1_DAT3_B: SD Data 3  LCD_SEG1:LCD SEG Output1		
171	PG0	1/0	GPI0	LCD_DATO:LCD Data0 EMI_DO:EMI Data0 SD1_DAT2_B: SD Data 2 LCD_SEGO:LCD SEG Output0		
172	NC		1/2/4			
173	FUSB_DM	I/0	GPIO			
174	FUSB_DP	I/0	GPIO			
175	PF14	I/0	GPI0	SDR_A3_B:SDRAM A3 SENSOR1_D7_B: SENSOR1 Data 7		
176	PF13	1/0	GPI0	SDR_A2_B:SDRAM A2 SENSOR1_D6_B: SENSOR1 Data 6		

(★说明: 1、P----Power Supply 2、I----Input 3、O----Output 4、I/O----Bi-direction)

# 3. 电气特性

# 3.1 I/O 输入、输出高低逻辑特性

IO 输入	IO 输入特性						
符号	参数	最小	典型	最大	单位	测试条件	
$V_{\rm IL}$	Low-Level Input Voltaget	-0.3	_	0.3* VDDIO	V	VDDIO = 3.3V	
$V_{\mathrm{IH}}$	High-Level Input Voltage	0.7* VDDIO	-	VDDIO+0.3	V	VDDIO = 3.3V	
输出特性	输出特性						
$V_{OL}$	Low-Level Output Voltaget	1	-	0.33	V	VDDIO = 3.3V	
$V_{\mathrm{OH}}$	High-Level Output Voltaget	2.7	_	<u> </u>	V	VDDIO = 3.3V	

# 3.2 I/O 输出能力、上下拉电阻特性

Port □	输出能力	上拉电阻	下拉电阻	备注
PA0 – PA15 PB0 - PB15 PC0 - PC2 PC4 - PC15 PD0 - PD15 PE0 - PE15 PF0 PF3 - PF15 PH12 - PH15	强驱: 24mA 弱驱: 8mA	10K	60K	
PG0 – PG15 PH0 – PH11	强驱: 24 mA 弱驱: 8mA(片内串接 200Ω 电阻)	10K	60K	
PC3	8 mA(无强弱驱之分)	10K	60K	
PRO – PR3	8mA(片内串接 200Ω 电阻)	10K	60K	RTC 模块需供电
FUSB_DP	10 mA	1.5K	15K	用作普通 10 时
FUSB_DM	10 mA	180K	15K	用作普通 10 时
AVDD18	电压可调: 1.5V-1.9V (电流约为 60 mA)			LDOIN=3.3V
AVDD28	电压可调: 2.7V-3.1V (电流约为 100 mA)			LDOIN=3.3V

## (★说明:上下拉电阻的精度约为±20%)

### 3 3 DAC 特性

符号	参数	最小	典型	最大	单位	测试条件
SNR	Signal to Noise Ratio		86		dB	1KHz, SR=44.1K, 静音文件, CR=192Kbps
THD+N	Total Harmoni Distortion+Noise		-78		dB	(-1.5db) 1KHz, SR=44.1K, CR=192Kbps

# 4. 封装规格

### 4.1 LQFP-176PIN 封装图

