

JIUHONG XIAO

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EDUCATION

New York University
M.S. in Computer Science

Jan 2020 - Present
GPA: 3.93/4.0

University of Science and Technology Beijing
B.Eng. in Intelligence Science and Technology

Sep 2015 - Jun 2019
GPA: 3.65/4.0, Major GPA: 3.81/4.0

PUBLICATIONS

Toward Coordination Control of Multiple Fish-Like Robots: Real-Time Vision-Based Pose Estimation and Tracking via Deep Neural Networks 2021
Tianhao Zhang , JiuHong Xiao , Liang Li , Chen Wang, Guangming Xie
IEEE/CAA Journal of Automatica Sinica.

Image Encryption Algorithm Based on Memristive BAM Neural Networks 2018
JiuHong Xiao, Weiping Wang, Meiqi Wang
IEEE 3rd International Conference on Data Science in Cyberspace (DSC 2018), p205-212, July 16, 2018.

The Stability of Memristive Multidirectional Associative Memory Neural Networks With Time-varying Delays in the Leakage Terms via Sampled-data Control 2018
Weiping Wang, Xin Xiao Yu, Xiong Luo, Long Wang, Lixiang Li, Juergen Kurths, Wenbing Zhao, JiuHong Xiao
PLOS ONE, Volume: 13, Issue: 9, Pages: e0204002, September 24, 2018.

EXPERIENCE

Amazon May 2021 - Aug 2021
Applied Scientist Intern

- Developed a method to compress images from a specific domain, reducing **5x** compress ratio than using standard compression technique.

New York University May 2020 - May 2021
Research Assistant

- Developed a self-supervised learning model for object detection from multi-view images, researching using an architectural energy-based model to exploit unlabeled data.
- Implemented self-driving policy training based on generated maps inferred from past driving data, reducing the cost of lane annotation and increasing the generalization of training for different lane layouts.

Intelligent Biomimetic Design Laboratory, Peking University Jun 2019 - Jan 2020
Research Assistant

- Implemented a fish pose estimation method fusing top-down and bottom-up paradigms, increasing by **7.9%** and **10.9%** mAP compared with classical methods using single paradigm.
- Developed a fish pose tracking system based on keypoint matching, reducing tracking error by **72.7%**.
- Built a robotic fish dataset with over **1300** annotated frames as the benchmark for robotic fish pose estimation and the foundation of fish group control.

AbleCloud, Beijing Jun 2018 - Aug 2018
Product Intern

- Participated in developing a mobile APP for a smart lamp project, implementing a schedule and

monitor functions by AbleCloud PaaS Platform.

- Compiled technical documents of car network APIs and provided technical support for users and developers.

University of Science and Technology Beijing

Sep 2016 - Dec 2017

Tutor of Arduino

- Taught Arduino programming to high school students and led a section to develop Arduino-based projects with MP3 and LED modules.

PROJECTS

GPU Accelerated Applications with CUDA and OpenMP

Sept 2020 - Dec 2020

Advisors: Mohamed Zahran.

- Compared the performance of different GPU-friendly algorithms between CUDA and OpenMP systematically.

Autodetection: An End-to-end Autonomous Driving Detection System

Jan 2020 - May 2020

Advisors: Yann LeCun, Alfredo Canziani.

- Won the **2nd** place of general ranking on roadmap prediction and object detection task.
- Built an end-to-end autonomous driving detection system to predict bird-view roadmap and objects from multi-view images without measurement of camera parameters.
- Improved model performance with feature pyramid network and self-supervised learning by **7.72%** mAP on roadmap and **14.35%** mAP on detection.

A Survey of Bayesian Methods for Deep Learning

Jan 2020 - May 2020

Advisor: Joan Bruna.

- Surveyed recent works that apply principles of Bayesian inference to deep learning and noted special applications of Bayesian deep learning.
- Implemented PyTorch version of Bayesian methods like SGLD, Deep Ensembles, and MCDropout.

Object Identification System Based on Speech Feedback

Oct 2018 - Dec 2018

- Developed object detecting system on **Tensorflow** to predict objects without predefined categories.
- Implemented the users speech feedback program to improve the accuracy or add new categories based on Baidu speech recognition APIs.

CT Image Reconstruction System

Apr 2017

- Implemented an algorithm to find the center and rotation of CT scanner from one projected image and reconstruct CT image based on the filtered back-projection algorithm on **MATLAB**.

TECHNICAL SKILLS

Programming	C/C++, Java, Python, Matlab, SQL.
Platform/tools	Opencv, Keras, Pytorch, MySQL, CUDA.

HONORS AND AWARDS

Excellent Award of Undergraduate Thesis	2019
Third Prize, Chinese College Students Intelligence Design Contest	2018
Peoples Scholarship, USTB	2015 - 2018
First Prize, Mathematical Modeling Competition, Beijing	2017
Excellence Award, Boer National College Students Innovation Entrepreneurship Competition, Beijing	2017
Second Prize, Sensor Design Competition, USTB	2016
Third Prize, iCAN International Contest of Innovation, China	2016