

JIUHONG XIAO

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EDUCATION

New York University <i>Ph.D. in Electronic Engineering</i>	Sep 2022 - May 2027 GPA: 4.0/4.0
New York University <i>M.S. in Computer Science</i>	Jan 2020 - Dec 2020 GPA: 3.94/4.0
University of Science and Technology Beijing <i>B.Eng. in Intelligence Science and Technology</i>	Aug 2015 - Jun 2019 GPA: 3.65/4.0, Major GPA: 3.84/4.0

RESEARCH INTERESTS

Computer Vision, Robotics, Visual Geo-localization.

PUBLICATIONS

Identity Preserving Loss for Learnt Image Compression <i>Jiuhong Xiao, Lavisha Aggarwal, Prithviraj Banerjee, Manoj Aggarwal, Gerard Medioni</i> <i>Computer Vision and Pattern Recognition (CVPR) Workshops</i> (2022), 517-526.	2022
Multi-Robot Collaborative Perception with Graph Neural Networks <i>Yang Zhou, Jiuhong Xiao, Yue Zhou, Giuseppe Loianno</i> <i>IEEE Robotics and Automation Letters</i> 7, no. 2 (2022), 2289-2296.	2022
Toward Coordination Control of Multiple Fish-Like Robots: Real-Time Vision-Based Pose Estimation and Tracking via Deep Neural Networks <i>Tianhao Zhang, Jiuhong Xiao, Liang Li, Chen Wang, Guangming Xie</i> <i>IEEE/CAA Journal of Automatica Sinica</i> 8, no. 12 (2021), 1964-1976.	2021
Image Encryption Algorithm Based on Memristive BAM Neural Networks <i>Jiuhong Xiao, Weiping Wang, Meiqi Wang</i> <i>IEEE 3rd International Conference on Data Science in Cyberspace</i> (2018), 205-212.	2018
The Stability of Memristive Multidirectional Associative Memory Neural Networks With Time-varying Delays in the Leakage Terms via Sampled-data Control <i>Weiping Wang, Xin Yu, Xiong Luo, Long Wang, Lixiang Li, Juergen Kurths, Wenbing Zhao, Jiuhong Xiao</i> <i>PLOS ONE</i> 13, no. 9 (2018), e0204002.	2018

EXPERIENCE

Amazon <i>Applied Scientist</i> <ul style="list-style-type: none">• Worked in Amazon Go/Just walk out (JWO) technology.• Built a multi-view occlusion detection system to reduce errors caused by unknown occluders.	Jan 2022 - Aug 2022
New York University <i>Graduate Teaching Assistant</i> <ul style="list-style-type: none">• Supported Deep Learning course with 100+ students.• Created the homework materials, graded assignments, and answered students' questions for homework and lectures.	Sep 2021 - Present
Amazon <i>Applied Scientist Intern</i> <ul style="list-style-type: none">• Developed a VAE-based compression method specific to face images, achieving 5x compression ratio of High Efficiency Video Coding (HEVC) format with acceptable image quality.• Jointly optimized compression model with face recognition downstream model, and reduced the file size to 27.4% of HEVC with lower False Rejection Rate (FRR) under same False Acceptance Rate (FAR).	May 2021 - Aug 2021
New York University <i>Research Assistant (advised by Alfredo canziani, Yann LeCun)</i> <ul style="list-style-type: none">• Implemented an offline autonomous driving policy-training pipeline based on annotated lane maps with limited historical driving data.	May 2020 - May 2021

- Designed the training strategy and specific loss functions to reduce lane annotation cost and improve the generalization performance of the policy for different lane layouts.
- Increased mean survival rate from 75% to **86%** compared to the baseline offline RL method to reduce collision and offroad crashes.

Intelligent Biomimetic Design Laboratory, Peking University

Jun 2019 - Jan 2020

Research Assistant (advised by Guangming Xie)

- Implemented a fish pose estimation method fusing top-down and bottom-up paradigms, increasing mAP by **7.9%** and **10.9%** compared with classical methods using single paradigm.
- Developed a fish pose tracking system based on keypoint matching, reducing tracking error by **72.7%**.
- Built a robotic fish dataset with over **1,300** annotated frames as the benchmark for robotic fish pose estimation and the foundation of fish group control.

SELECTED PROJECTS

Autonomous Drone Inspection with Deep Reinforcement Learning

Sep 2021 - Dec 2021

Advisors: Lerrel Pinto. New York University

- Developed a reinforcement learning framework for real-life UAV autonomous inspection experiments with ROS.
- Analyzed the impact of different environment setups on inspection performance.

Autodetection: An End-to-end Autonomous Driving Detection System

Jan 2020 - May 2020

Advisors: Yann LeCun, Alfredo Canziani. New York University

- Won **2nd** place in the general ranking on roadmap prediction and object detection task.
- Built an end-to-end autonomous driving detection system to predict bird-view roadmap and objects from multi-view images without measurement of camera parameters.
- Improved model performance with feature pyramid network and self-supervised learning by **7.72%** mAP on roadmap and **14.35%** mAP on detection.

A Survey of Bayesian Methods for Deep Learning

Jan 2020 - May 2020

Advisor: Joan Bruna. New York University

- Surveyed recent works that apply principles of Bayesian inference to deep learning and noted special applications of Bayesian deep learning.
- Implemented PyTorch version of Bayesian methods like SGLD, Deep Ensembles, and MCDropout.

HONORS AND AWARDS

School of Engineering Fellowship, NYU	2022
Excellence Award for Undergraduate Thesis, USTB	2019
Peoples Scholarship, USTB	2015 - 2018
First Prize, Mathematical Modeling Competition, Beijing	2017

SKILLS

Programming	C/C++, Java, Python, Matlab, SQL.
Platform/tools	Opencv, Pytorch, MySQL, CUDA.
Languages	English, Mandarin.