

Project 4: Recoverable Virtual Memory

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1. Data Structure

Struct `rvm_info` contains:

- a. `map` which stores the mapping between memory address and disk file name.
- b. `busy` is another map which records the status of current segments, whether is busy(1) or not(0).
- c. `directory`: a variable stores the directory of disk files

`rvm`: the pointer type of `rvm_info` struct

`transaction_struct`:

- a. `numsegs`: a variable stores the number of segments specified in begin transaction
- b. `segbases`: a pointer points at the beginning segments array
- c. `rvm`: store the current rvm information during the same transaction
- d. `modified_segs`: a vector stores all the segments being modified, `offset`: a vector stores the starting points of corresponding segments, `size`: a vector stores the size modified of corresponding segments

`trans_t`: the pointer type of `transaction_struct`

`verbose_enabled`: a global variable which indicates enable verbose or not.

2. Design

- a. When trying to map a disk file to some memory, store the mapping into `map` in `rvm` struct. And when unmap, remove the mapping item in `map`.
- b. During begin transaction, set segments involved in the transaction to be busy. And set them back to be not busy during release.
- c. When committing transaction, open a log file and write information into the log file, and the format is as follows:

segment_name	offset	size
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content_been_modified

eg.

```
testseg 0 100  
hello, world
```

d. When truncating log, shrink the log file

3. Test Cases:

test.cpp: test simple functions and test `rvm_verbose()`

crash.c: simulate the scenario when a process crashed before commit or abort

map-test-case.cpp: trying to detect:

1. destroy before unmap test cases

2. map a segment already exists but with smaller size

map-twice.cpp: detect test case when trying to map the same segment twice