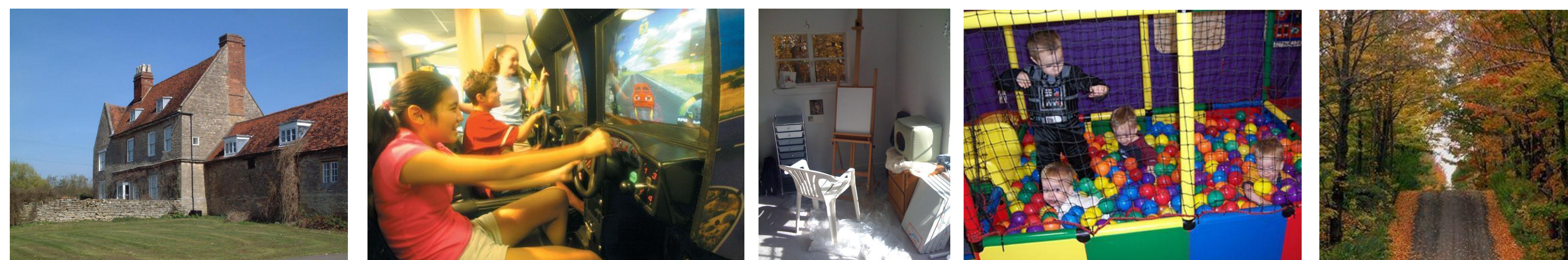


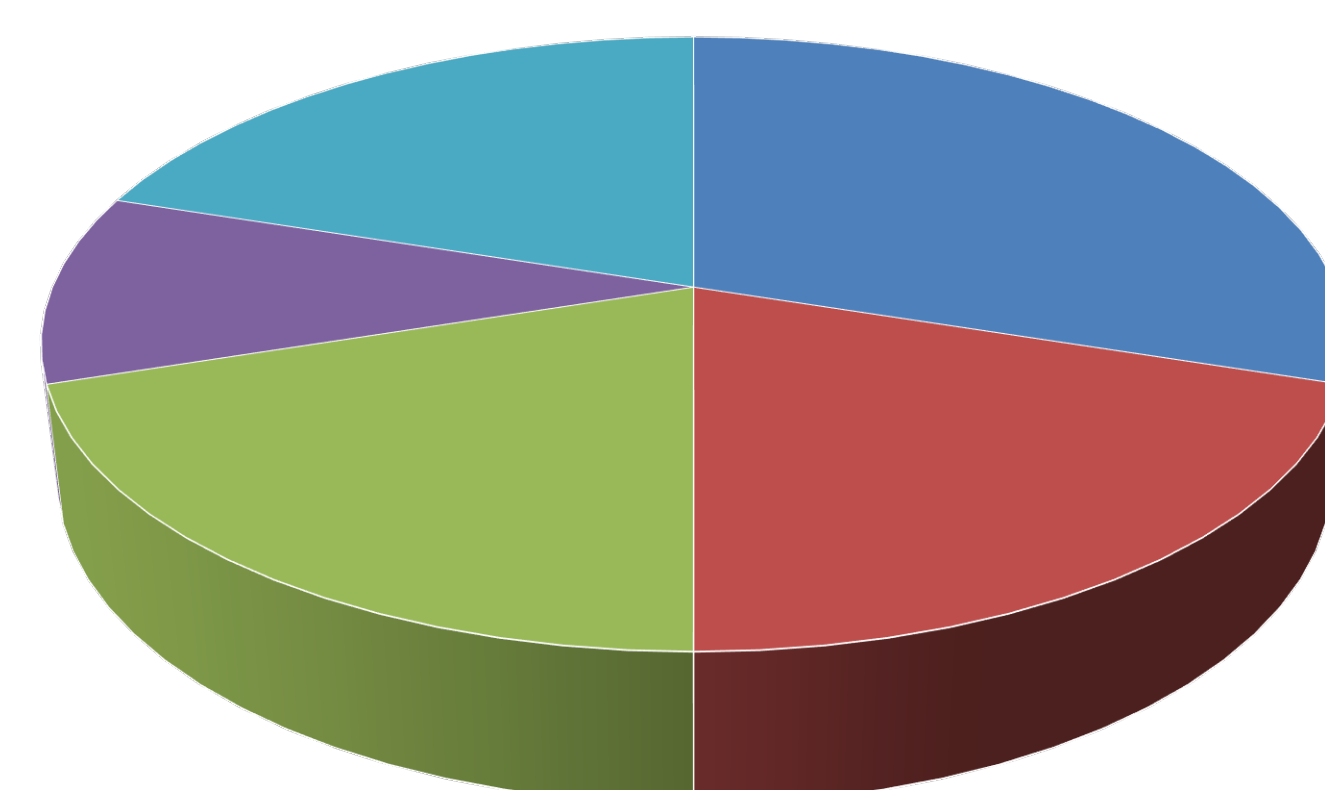


## Problem Definition

Predict the label of each pixel in wild scene



Error analysis for our baseline model



- Failure to sense image label
- Failure between confusion label
- Failure for inconspicuous objects
- Misaligned boundary
- Others

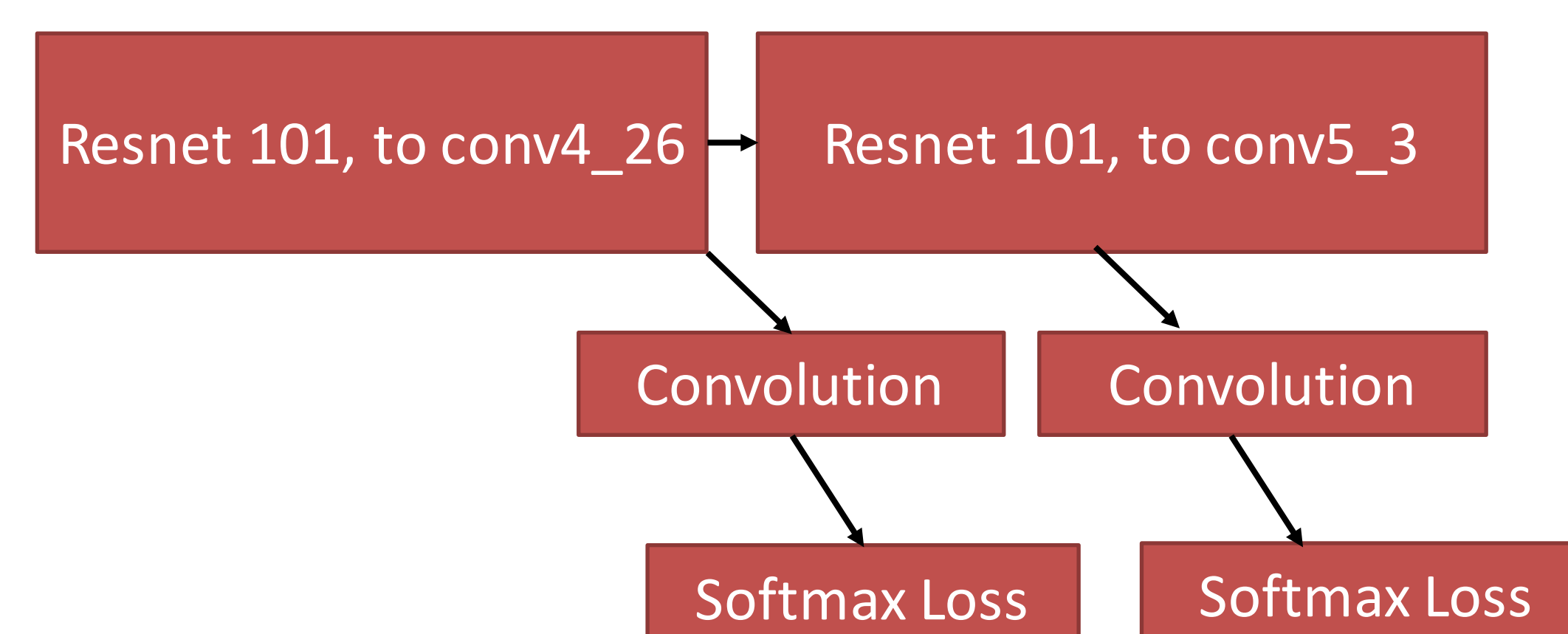
## Our Baseline

- Pretrained Resnet101
- Fully Convolutional Network
- Dilated convolution with stride 8

## Evils in the Details

- Various data augmentation
- Add dropout to the last convolution layers
- Using dilated convolution
- Learning rate policy
- Total iteration number
- Correct way to use batch normalization
- Larger crop size and larger receptive field
- etc.

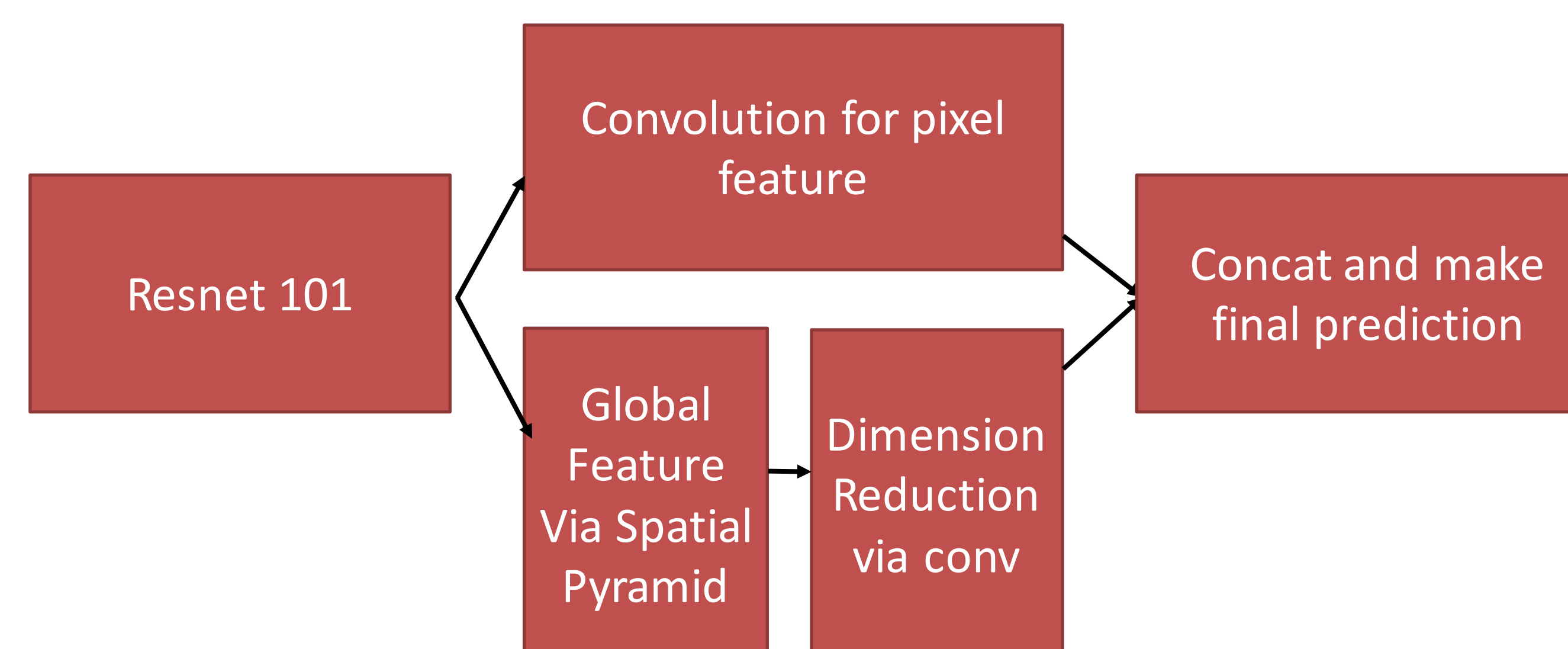
## Deeply Supervised Loss



Auxiliary loss, loss weight 0.4

## Scene Parsing by Scene Understanding

- State-of-the-art Image classification  
FCN + Average Pooling
- Classical scene understanding  
Spatial Pyramid Matching
- Better scene recognition  
FCN + Spatial Pyramid Matching Pooling



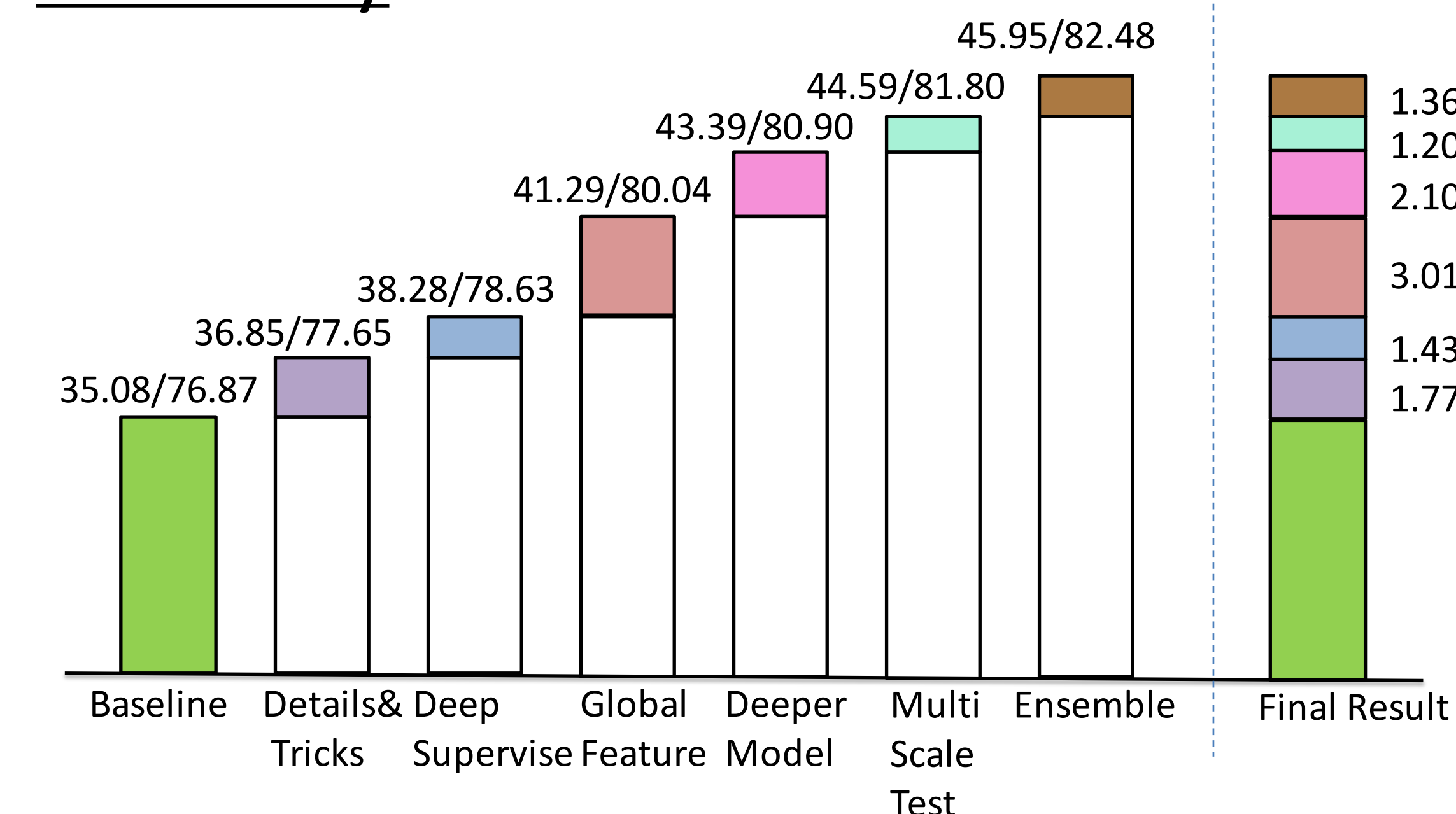
## Deeper Pretrained Model

Pretrained Model	Result
Resnet 50	40.11/79.55
Resnet 101	41.29/80.04
Resnet 152	42.23/80.46
Resnet 269	43.39/80.90

## Test & Ensemble

Method	Result
Resnet 269 Single Scale Test	43.39/80.90
Resnet 269 Multi Scale Test	44.59/81.80
Ensemble of 5 Models	45.95/82.48

## Summary



## Learn by Failure

- Sample training image to uniform distribution
- Hard sample mining
- CRF
- Stochastic depth
- Stuff / object training
- ASPP
- Using predefined class correlation

## Visual Result

