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Algorithm 1 ANN search over the augmented neighborhood graph
     /* \mathbf{q}: the query; \mathcal{X}: the reference data vectors; \mathcal{Y}: the set of bridge vectors; G: the augmented
     neighborhood graph; Q: the main queue; R: the result set; T: the maximum number of discov-
     ered vectors: */
Procedure ANNSearch(\mathbf{q}, \mathcal{X}, \mathcal{Y}, G, O, R, T)
 1. /* Mark each reference vector undiscovered */
 2. for each \mathbf{x} \in \mathcal{X} do
 3.
        Color[\mathbf{x}] \leftarrow white;
 4. end for
 5. /* Extract the nearest bridge vector */
 6. (\mathbf{y}, D) \leftarrow \text{ExtractNextNearestBridgeVector}(\mathcal{Y});
 7. Q \leftarrow (\mathbf{y}, D);
 8. t \leftarrow 0
 9. /* Start the search */
10. while (O \neq \emptyset \&\& t \leq T) do
11.
        /* Pop out the best candidate vector and expand its neighbors */
12.
         (\mathbf{p}, D) \leftarrow Q. \operatorname{pop}();
                                                                           |根据优先队列确定前
13.
        for each \mathbf{x} \in Ad \ i[\mathbf{p}] do
14.
            if Color[x] = white then
                                                                           |沿数据点,每次扩充
15.
                D \leftarrow \operatorname{dist}(\mathbf{q}, \mathbf{x});
                                                                           到全部邻居。
16.
                O \leftarrow (\mathbf{x}, D);
17.
                Color[\mathbf{x}] \leftarrow black; /* Mark it discovered */
                                                                            每个邻居,既加入队
18.
                R \leftarrow (\mathbf{x}, D); /* Update the result set */
                                                                                 , 又更新结果
19.
                t \leftarrow t + 1;
20.
            end if
21.
        end for
22.
        /* Extract the next nearest bridge vector if p is a bridge vector */
23.
        if p \in \mathscr{Y} then
24.
            (\mathbf{y}, D) \leftarrow \text{ExtractNextNearestBridgeVector}(\mathcal{Y});
25.
            Q \leftarrow (\mathbf{y}, D);
26.
         end if
27. end while
28. return R:
```