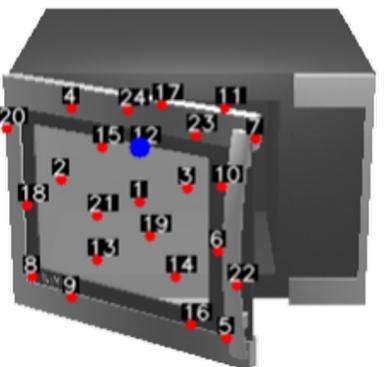


Novel Category



RGB-D

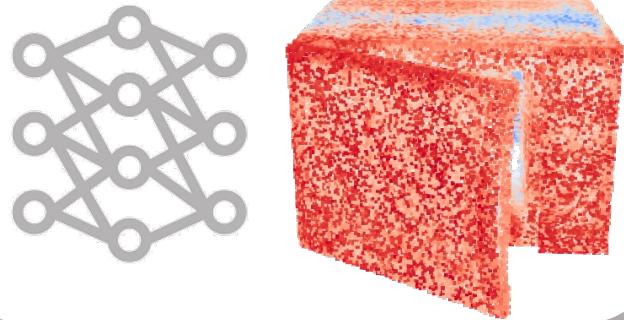
P2P Part to Point



Foundation Guided Exploration



Pretrained Affordance



O2P Object to Part



Finetuned Affordance

