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## Research Interests

My primary area of focus has been within computer vision. For the years of 2015-2017, I have worked on generative models, specifically GANs, coming up with both a measure and a method to use GANs to interpret other classifiers. I have since begun exploring techniques to make models more robust. The majority of my research focuses on applications of machine learning.

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## Education

### **Doctor of Philosophy (Computer Science) 2014 to ongoing**

University of Chicago, Chicago, Illinois

### **Bachelor of Science (Biochemistry and Computer Science) 2010 to 2014**

University of Miami, Miami, Florida

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## Courses

Machine Learning

Robot Planning/AI

Computer Vision

Algorithms

Databases

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## Teaching

[Computational Biology](#) (Autumn 2015) [Intro. to Computer Science](#) (Winter 2016)

[Machine Learning](#)(Spring 2016)

[Intro. to Computer Science](#) (Autumn 2016)

[Machine Learning](#) (Autumn 2017)

[Intro. to Computer Science](#) (Autumn 2018)

[Machine Learning](#) (Winter 2019)

[Machine Learning and Large-Scale Data Analysis](#) (Spring 2019)

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## Research Experience

### Computer Science 2014 to current

I am working with Dr. Greg Shakhnarovich at TTIC in the areas of machine learning and computer vision.

### Biochemistry 2011 to 2014

I worked with Dr. Richard Myers at the University of Miami trying to create a generic genetic therapy via transducible gene editing proteins. I ran western blots, gel electrophoresis, transductions, PCR, and electroporation

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## Technical

Python

C

Java

Pytorch/Tensorflow

Git / SVN

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## Experience

### Google Brain Research Intern Summer 2018

I worked in NLP and collaborated with several teams. I worked in the area of Fact Checking related to this [paper](#) to deal with the problem of content abuse and also worked with the Google News team. **python, pytorch, tensorflow, apache-beam, flume**

### Here Maps Research Intern Summer 2017

I worked on models to better predict arrival times (ETA estimates) and lane level navigation prediction which can be used for autonomous vehicles. **python, pytorch**

### Here Maps Research Intern Summer 2016

I developed a model that creates road probability maps that can be used to detect differences between artificial maps and the real roads. **python, tensorflow**

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## Projects

### OpenGL Renderer

[myRenderer](#)

I created a simple OpenGL renderer to render some height maps and draw some objects. Applies simple lighting and texturing.

## **BattleShip game over internet**

[BattleShip](#)

I created a simple Battleship game in C that has a client, server interface.

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## *Publications*

### **Natural Adversarial Examples ICML 2019 Workshop**

In this work we construct a dataset which captures long tail distributions to highlight where current models fail in terms of generalization.

### **DIODE: A Dense Indoor and Outdoor DEpth Dataset 2019**

In this work we use a single depth sensor to capture both indoor and outdoor scenes to create the most accurate depth dataset to date.

### **Analysis of Generative Adversarial Models 2017**

This is my master's work in which I introduce a novel measure for quantitatively assessing the quality of generative models and present a method for utilizing GANs to interpret classifiers.