CBMC

Henrich Lauko



Masaryk University Brno, Czech Republic

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CBMC



- CBMC concepts
- Verification of concurrent programs
- 3 Closer look on memory models

CBMC Concept



- Bounded Model Checker for C and C++ programs
 - \blacksquare constructs a propositional formula ϕ describing all possible executions of the system of bounded length
 - $(\phi \land \neg specification)$ is fed do SAT solver
- can deal with pointers, arrays and real size integers
- threads, and simulate various memory models

CBMC Workflow



- create SSA form of program such program can be viewed as set of constraints
- unroll loops
- inline functions and bound number of recursion calls create goto program
- 3 transform to SSA form (generate set of constraints)

Example



■ bound is 2

```
 \begin{array}{ll} x=3;\\ while & (x>1) \{\\ & if \ (x\%2==0) \\ & else \end{array} \quad \begin{array}{ll} x=x/2;\\ & x=3*x+1; \end{array}
```

Example – Unroll Loops



bound is 2

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```

Example – Generating Constraints



```
x = 3:
                            (0) x_0 = 3
if (x > 1){
                            (1) quard_1 = x_0 > 1
  if (x\%2 == 0)
                            (2) quard_2 = quard_1 \& x_0\%2 == 0
     x = x/2:
                            (3) x_1 = (quard_2?x_0/2:x_0)
  else x = 3 * x + 1:
                            (4) quard_3 = quard_1 \& !(x_0\%2 == 0)
  if(x > 1){
                            (5) x_2 = (quard_3?3 * x_1 + 1 : x_1)
     if (x\%2 == 0) (6) quard_4 = quard_1 \& x_2 > 1
                  (7) quard_5 = quard_4 \& x_2\%2 == 0
        x = x/2;
     else x = 3 * x + 1; (8) x_3 = (quard_5?x_2/2 : x_2)
     assert(x \le 1); (9) quard_6 = quard_4 \& !(x_2\%2 == 0)
                            (10) x_4 = (quard_6?3 * x_3 + 1 : x_3)
                            Specification: !(x_4 \le 1)
```

Pointers and Arrays



 every assignment to a dereference of pointer is instantiated to several assignments (one for each possible value of pointer)

```
1 *p_1 = 3;
```

possible generated constraints:

```
1 x_12 = (p_1 == &x) ? 3 : x_11;

2 y_7 = (p_1 == &y) ? 3 : y_6;

3 z_4 = (p_1 == &z) ? 3 : z_3;

4 ...
```

- assignment to an array cell is treated similarly (instantiating for each possible value of the array index)
- allocated memory is treated as a regular global variable
- number of malloc calls is bounded

CBMC for Concurrent Programs



Problems:

- access to global variables
 - race conditions
 - it is not possible to index assignments to global variables statically
- modeling threads in bounded environment
 - allowing context switches only before visible statements

Translation process:

- preprocessing modeling nonatomic statements
- 2 applying CBMC separately on each thread
- generating constraints for concurrency

Stage 1 – Preprocessing



problems with access to more than one global variable

$$1 x_1 = g_1 + g_2;$$

■ in assembly:

$$r_a = g_1; r_b = g_2; r_c = r_a + r_b; x_1 = r_c;$$

- have to allow context switches between instructions
- CBMC generates similar code:

$$y_1 = g_1; y_2 = g_2; x_1 = y_1 + y_2;$$

accesses in conditions and loops are treated similarly



- create list of constraints for each thread template
 - each variable has several copies
 - each copy appears only once on left-hand side of constraint
- created assignment statement types:
 - expression over local variables to local variable

$$I_k = (guard_r?Ix_c * 2 : I_{k-1})$$

expression over local variables to global variable

$$g_k = (guard_r?lx_c * 2 : g_{k-1})$$

global variable to local variable

$$I_k = (guard_r?gx_k : I_{k-1})$$

4 assignment to a guard variable

$$guard_r = guard_{r-1} \land x_k > y_c$$

Stage 3 – Generating Constraints for Concurrency



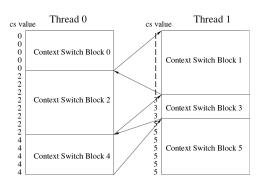
- 1 constraints on context switches
- 2 constraints on global variables
- 3 constraints on assignment statements



- main idea to associate with each line in template a variable indicating number of context switches that occurs before this line thread_t_cs(I)
- assignment to thread_t_cs(I) determines a concurrent execution over the thread templates
- added constraints on $thread_t_cs(I)$:
 - Monotonicity $\forall_{0 < l < m-1} thread_t _cs(l) \le thread_t _cs(l+1)$
 - Interleaving bound $thread_t _cs(m-1) \le n$
 - Parity $\forall_{0 \le l \le m-1} (thread_t _cs(l) \mod 2) = t$
- m-1 number of constraints in template
- \blacksquare n interleaving bound

Stage 3 – Context Switching





Stage 3 – Constraints on Global Variables



- generate n new variables x_val; for each global variable x
 - x_val_i is value of variable x at the end of i-th context switch block
- x_val_i should get its value according to the last assignment that was made to x in the i-th context switch block
 - if x was assigned in the i-th context switch block, x_vali will be equal to the last assignment to x in this block
 - else $x_val_i = x_val_{i-1}$ preserves the value it had at the end of the previous block

Stage 3 – Translation of Statements to Constraints



- expression over local variables to local variable
 - add the thread prefix
- **2** assignment of global variable x_i to local variable l_k
 - \blacksquare if assignment to x_i in the same context, simply add thread prefix
 - otherwise is used x_val of previous block
- expression over local variables to global variable
 - similarly as previous
- assignment to a guard variable
 - guards are local, so add only prefixes

Concurrency - Pointers and Arrays



- no special treatment to support assignments to a pointer dereference or to cell in an array
- only problem is dereference of pointer to global variable

$$1 v_1 = *p + v_2;$$

break statement to more small statements:

$$1 y = *p; v_1 = y + v_2;$$

More Than Two Threads



- change to parity constraint
- 1 round-robin
 - thread may do nothing, but increases number of context switches
- 2 add new variables *run*; representing thread that runs in context switch block

Modeling Synchronization Primitives



atomic sections - add constraints to force $thread_t_cs$ values to be identical in atomic section

mutexes - model only *wait-free* executions – if a thread tries to lock a mutex, it either succeeds or this execution is eliminated - own mutex implementation of lock and unlock:

```
lock:
1 atomic {
     assume(*mutex == U);
3
    *mutex = L;
4 }
unlock:
1 atomic {
2
     assert(*mutex == L);
3
     *mutex = U;
```

Detecting races



created new variable x_write_flag that is raised whenever x is defined and lowered in the next instruction

```
1 atomic {
2    assert(x_write_flag == 0);
3    x = 3;
4    x_write_flag = 1;
5 }
6 x_write_flag = 0;
```

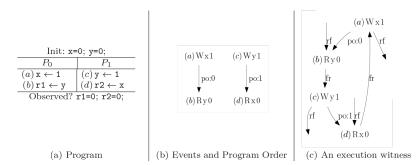
on every access to x is added assert that its x_write_flag is low

```
1 atomic{
2    assert(x_write_flag == 0);
3    y = x;
4 }
```

on assignment to dereference of pointer p flag is raised to all possible variables which p might point to

Weak Memory Models Introduction





- po program order
- rf read from:

$$(w,r) \in rf \iff r \text{ reads value written by } w$$

- ws write serialization total order on writes to the same location
- fr from read:

$$(r, w) \in fr \iff \exists w'.(w', r) \in rf \land (w', w) \in ws$$

Weak Memory Models Witness



Init: x=0; y=0;	
P_0	P_1
$(a) x \leftarrow 1$	$(b) x \leftarrow 2$
Allowed $x=1 \lor x=2$	

(a) Program



(b) An execution witness for the final state x=1



(c) An execution witness for the final state x=2

CBMC Weak Memory Models



- modern architectures modeled by relaxer relations
 - rfi internal read from, corresponds to read from the store buffer (TSO)
 - ppo program order pairs (e.g., write-read pairs on x86)
 - rfe external read from, when two processors can communicate privately via a cache (Power, ARM)
 - lacksquare ab_A relation induced by fences of architecture A
 - *dp* − dependencies between instructions
- execution is valid on A when following holds:
 - **1** SC holds per address = $acyclic(ws \cup rf \cup fr \cup po-loc)$
 - 2 Values do not come out of thin air = $acyclic(rf \cup dp)$
 - 3 ...
- symbolic event structure

Thank you.