view frames Result Recorded at time: 1542024203.957 map Broadcaster: /amcl Average rate: 6.335 Hz Most recent transform: 1542024204.664 (-0.706 sec old) Buffer length: 4.736 sec odom Broadcaster: /arduino Average rate: 9.072 Hz Most recent transform: 1542024203.954 (0.003 sec old) Buffer length: 4.960 sec base_footprint Broadcaster: /robot_state_publisher Average rate: 20.202 Hz Most recent transform: 1542024204.431 (-0.474 sec old) Buffer length: 4.950 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /base_link_to_laser4 Average rate: 12.525 Hz Average rate: 12.525 Hz Average rate: 20.202 Hz Average rate: 25.139 Hz Most recent transform: 1542024203.911 (0.046 sec old) Most recent transform: 1542024203.911 (0.046 sec old) Most recent transform: 1542024204.431 (-0.474 sec old) Most recent transform: 1542024203.967 (-0.009 sec old) Buffer length: 4.950 sec Buffer length: 4.950 sec Buffer length: 4.950 sec Buffer length: 4.933 sec base_l_wheel_link base_r_wheel_link front_flag laser_frame