

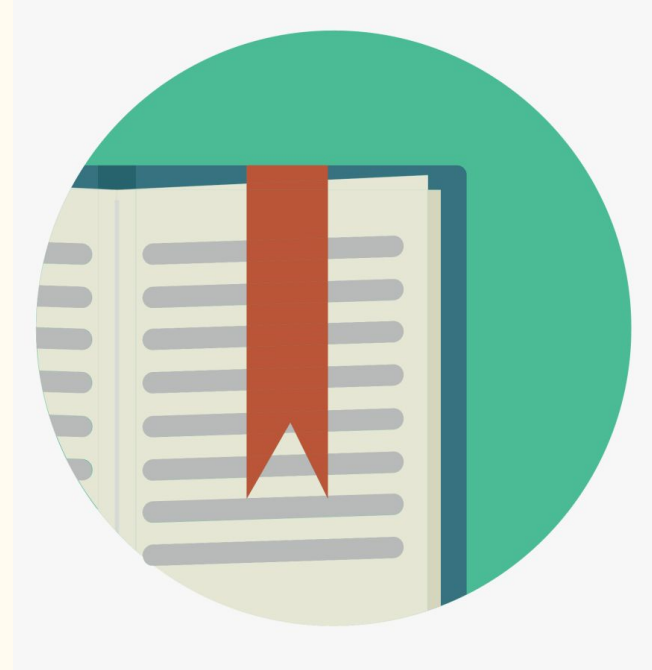
Project : "490. The Maze"

Depth-First Traversal

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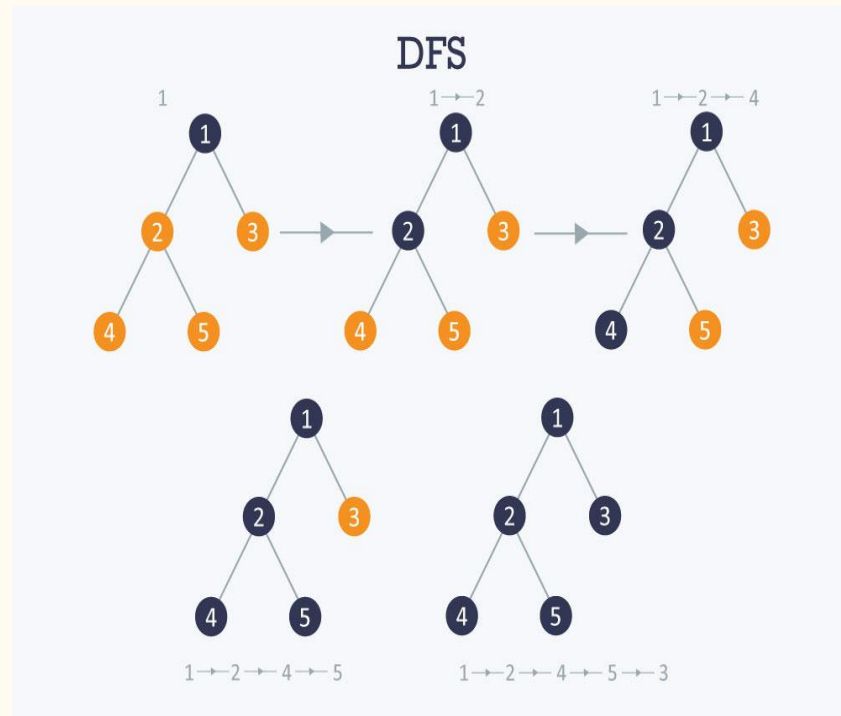
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Introduction

- ❑ Depth-First Search algorithm
- ❑ Manually solve the maze
- ❑ Python implementation

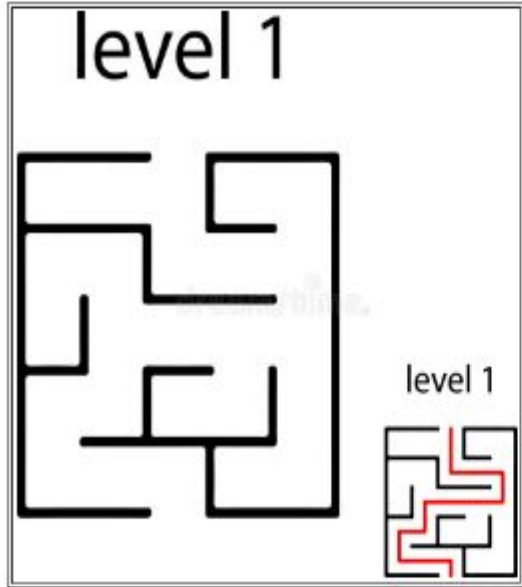


Depth-First Search Algorithm

- ❑ An algorithm for traversing or searching tree or graph data structures
- ❑ Start at the root node, mark the node, and move to the adjacent unmarked node
- ❑ Continue this loop until there is no unmarked adjacent node
- ❑ Backtrack and check for other unmarked nodes, and traverse them
- ❑ Print the nodes in the path

Design - Tree

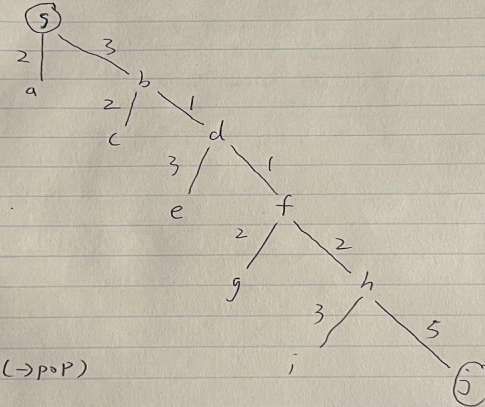
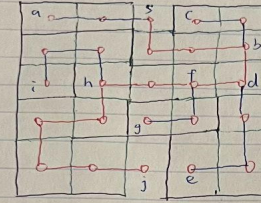
Conduct Depth First Traversal (DFT) on a maze - Level 1 Maze



- ❑ Legged Robot moves on streets:
DFS

Solution - Tree

- ❑ Mase
- ❑ Tree
- ❑ DFT



j
 i ($\rightarrow pop$)
 h
 g ($\rightarrow pop$)
 f
 e ($\rightarrow pop$)
 d
 c ($\rightarrow pop$)
 b
 a ($\rightarrow pop$)
 s

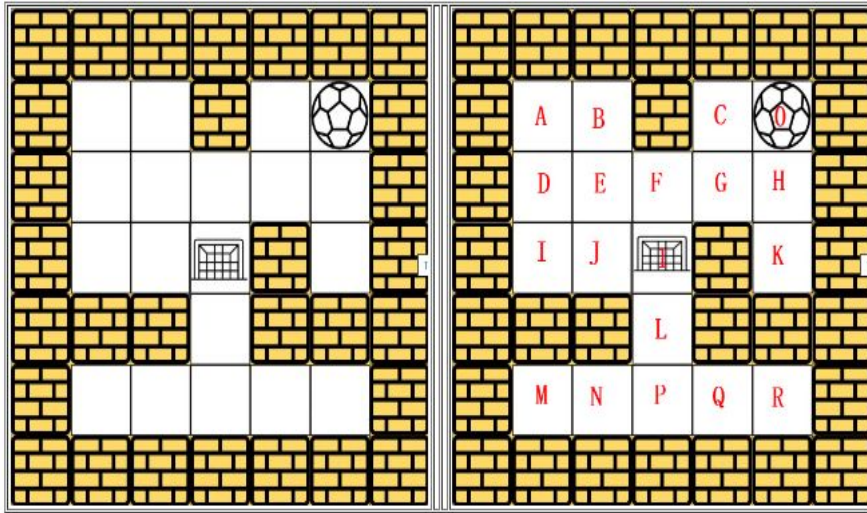
\Rightarrow

j
 h
 f
 d
 b
 s

Design - Mase Matrix

Depth-First Traversal for matrix maze

- Please refer the concepts shown on [Maze](#) to draw the detailed steps on using [Depth-First Traversal](#) to find the path.



- ❑ Wheeled robots moves in a hotel: DFS

[illegible]

Right \rightarrow Left \rightarrow Top \rightarrow Bottom

Implementation

- ❑ There is only one ball and one destination in the maze
- ❑ Both the ball and the destination exist on an empty space, and they will not be at the same position initially
- ❑ The given maze does not contain border but the border of the maze are all walls
- ❑ The maze contains at least 2 empty spaces, and both the width and height of the maze won't exceed 100

```

class Solution(object):
    def hasPath(self, maze, start, destination):
        """
        :type maze: List[List[int]]
        :type start: List[int]
        :type destination: List[int]
        :rtype: bool
        """
        start = tuple(start)
        destination = tuple(destination)
        if start == destination:
            return True
        directions = [(0, 1), (0, -1), (1, 0), (-1, 0)]
        width = len(maze)
        height = len(maze[0])
        if 1 <= destination[0] < width-1 and 1 <= destination[1] < height-1:
            if not any([maze[destination[0]+direction[0]][destination[1]+direction[1]] for
direction in directions]):
                return False
        positions = [start]
        visited = set()
        while positions:
            position = positions.pop(0)
            for direction in directions:
                if (position + direction) in visited: continue
                nextPosition = position
                while (nextPosition+direction) not in visited:
                    visited.add(nextPosition+direction)
                    prevPosition = nextPosition
                    nextPosition = (nextPosition[0]+direction[0],

```

Python implementation continued...

```
        nextPosition = (nextPosition[0]+direction[0],
nextPosition[1]+direction[1])
        if not 0 <= nextPosition[0] < width or not 0 <= nextPosition[1] < height
or maze[nextPosition[0]][nextPosition[1]] == 1:
            if prevPosition == destination:
                return True
            positions.append(prevPosition)
            break
    return False
```

Test cases

Accepted

Runtime: 25 ms



Your input

```
[[0,0,1,0,0],[0,0,0,0,0],[0,0,0,1,0],[1,1,0,1,1],[0,0,0,0,0]]  
[0,4]  
[2,2]
```

Output

true

☐ Diff

Expected

true

Accepted

Runtime: 15 ms



Your input

```
[[0,0,1,0,0],[0,0,0,0,0],[0,0,0,1,0],[1,1,0,1,1],[0,0,0,0,0]]  
[0,4]  
[3,2]
```

Output

false

☐ Diff

Expected

false

Enhancement ideas

- ❑ Time complexity
- ❑ Auxiliary Space



Conclusion

- ❑ We introduced the depth-first search algorithm
- ❑ DFT problems can be solved manually
- ❑ We implemented and tested its python implementation

thank
you



References

❏ GeeksforGeeks. (2019, February 4). *Depth First Search or DFS for a Graph - GeeksforGeeks*.

GeeksforGeeks. <https://www.geeksforgeeks.org/depth-first-search-or-dfs-for-a-graph/>

❏ Jeffrey. (2020, March 22). *leetcode 490. The Maze (Python)*. (Jeffrey's Blog).

<https://zhenyu0519.github.io/2020/03/22/lc490/>