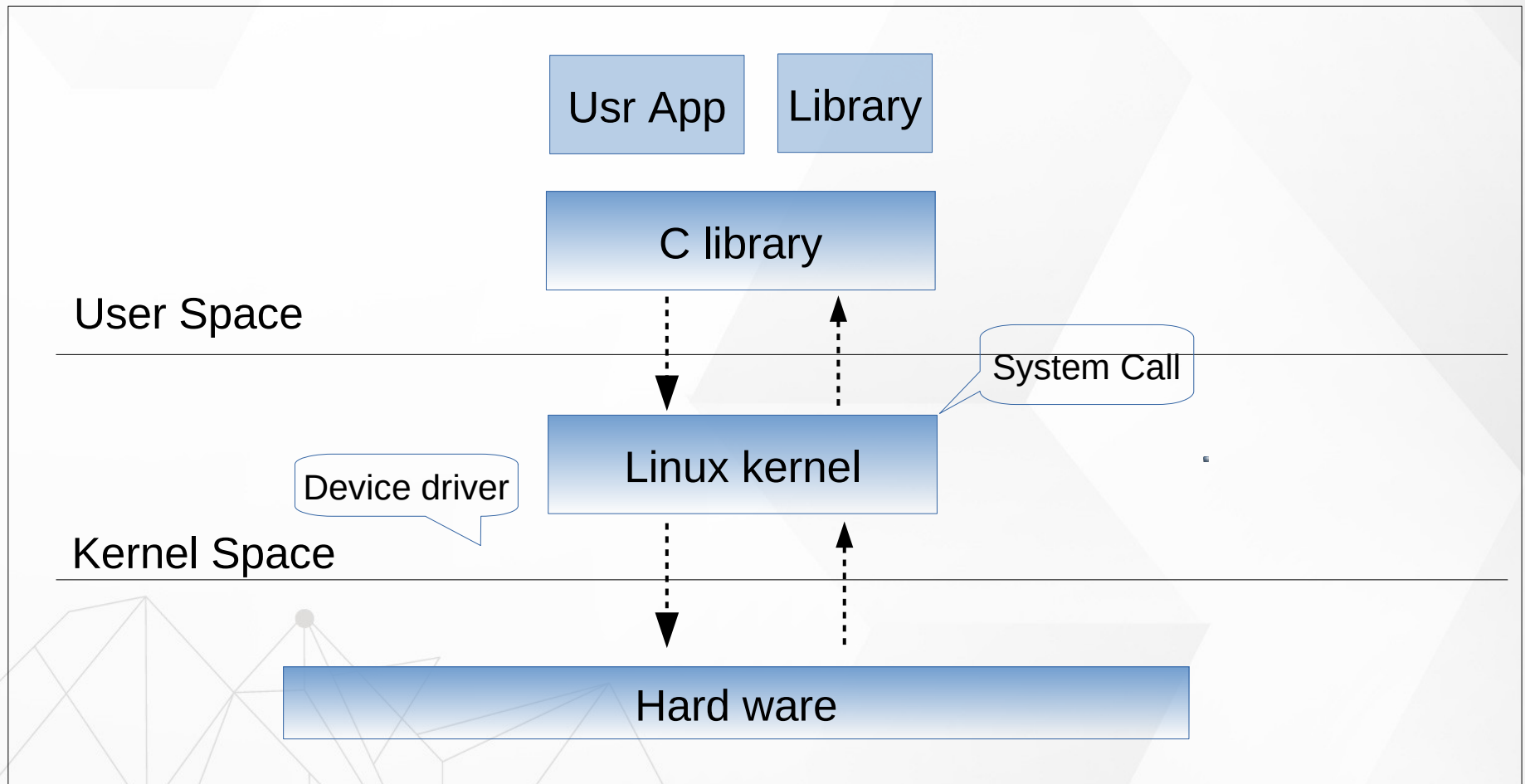


# CH9 Linux User Land

# Linux kernel





# Sys Filesystem

- Allows kernel code to export information to user processes
- SysFS is an in-memory filesystem
- It provides two components
  - A kernel programming interface for exporting these items via sysfs
  - User interface to view and manipulate these items that maps back to the kernel objects which they represent

# Sys File System

```
# tree -L 1 /sys/
```

```
/sys/  
├── block  
├── bus  
├── class  
├── dev  
├── devices  
├── firmware  
├── fs  
├── hypervisor  
├── kernel  
├── module  
└── power
```

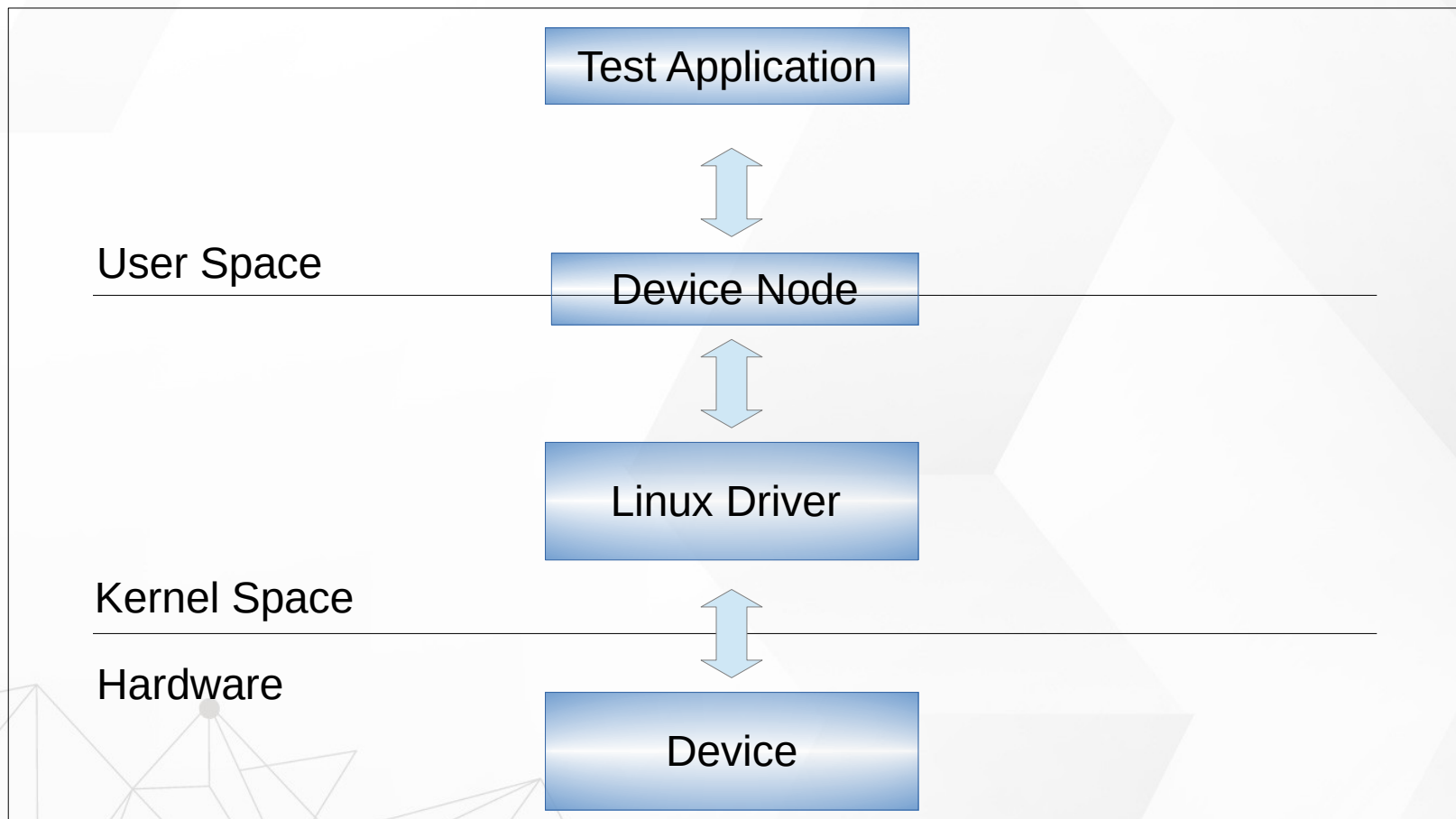
```
# tree -L 1 /sys/class/i2c-dev/i2c-0/
```

```
/sys/class/i2c-dev/i2c-0/  
├── dev  
├── device -> ../../../../i2c-0  
├── name  
├── power  
├── subsystem -> ../../../../../../class/i2c-dev  
└── uevent
```

```
# tree -L 1 /sys/class/i2c-dev
```

```
/sys/class/i2c-dev/  
├── i2c-0 -> ../../devices/pci0000:00/0000:00:02.0/i2c-0/i2c-dev/i2c-0  
├── i2c-1 -> ../../devices/pci0000:00/0000:00:02.0/i2c-1/i2c-dev/i2c-1  
├── i2c-2 -> ../../devices/pci0000:00/0000:00:02.0/i2c-2/i2c-dev/i2c-2  
├── i2c-3 -> ../../devices/pci0000:00/0000:00:02.0/i2c-3/i2c-dev/i2c-3  
├── i2c-4 -> ../../devices/pci0000:00/0000:00:02.0/i2c-4/i2c-dev/i2c-4  
├── i2c-5 -> ../../devices/pci0000:00/0000:00:02.0/i2c-5/i2c-dev/i2c-5  
├── i2c-6 -> ../../devices/pci0000:00/0000:00:02.0/drm/card0/card0-DP-1/i2c-6/i2c-dev/i2c-6  
├── i2c-7 -> ../../devices/pci0000:00/0000:00:02.0/drm/card0/card0-DP-2/i2c-7/i2c-dev/i2c-7  
└── i2c-8 -> ../../devices/pci0000:00/0000:00:02.0/drm/card0/card0-DP-3/i2c-8/i2c-dev/i2c-8
```

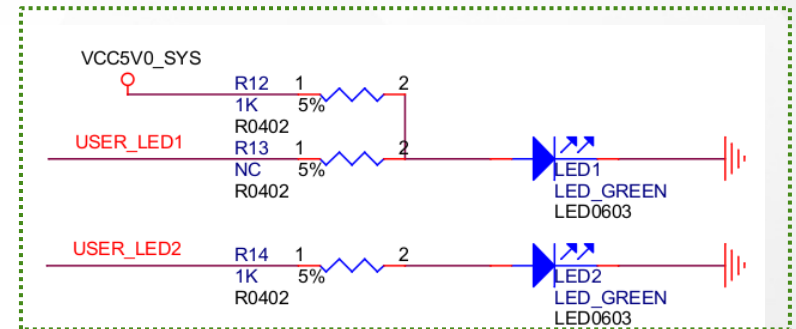
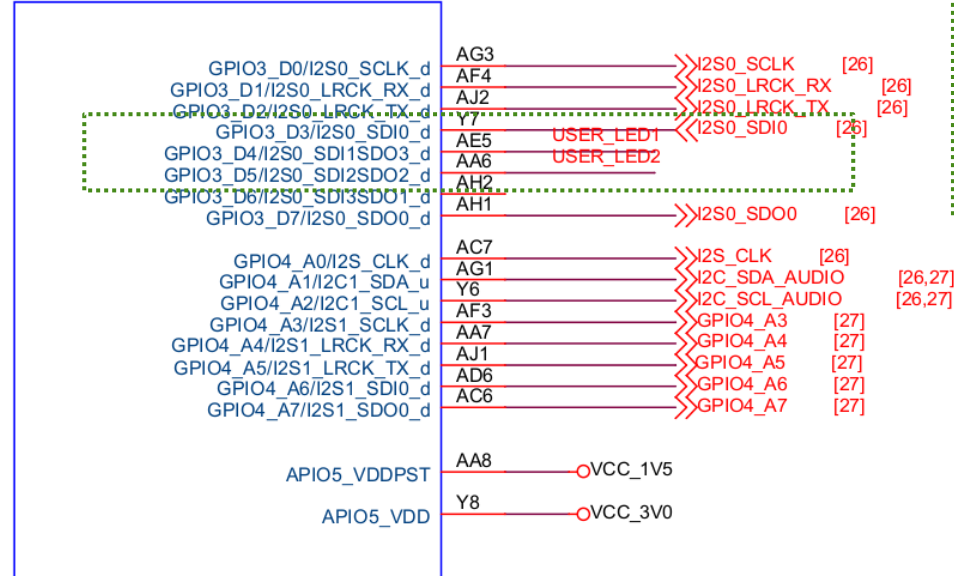
# User land and Driver



# LED Drivers

# LED Schematic

U1J RK3399 Note:RK3399 part J is 1.8V/3.0V mode



GPIO3\_D4/I2S0\_SDI1SDO3\_d → LED1

GPIO3\_D5/I2S0\_SDI2SDO2\_d → LED2



# LED Subsystem

## ➤ Control LED convenient with SysFS

### ➤ For example

- `echo 1 > /sys/class/leds/user-led2/shot`

## ➤ Switch different LED trigger type in SysFS

### ➤ For example

- `echo "gpio" > /sys/class/leds/user-led2/trigger`
- `echo "1" > /sys/class/leds/user-led2/brightness`
- `echo "0" > /sys/class/leds/user-led2/brightness`



# LED SysFS

```
root@rockpi4b:/sys/class/leds/user-led2# ls -l
```

```
brightness
device -> ../../../../gpio-leds
max_brightness
power
subsystem -> ../../../../../../class/leds
trigger
uevent
```

Check trigger type

```
root@rockpi4b:/sys/class/leds/user-led2# cat trigger
none rc-feedback kbd-scrolllock kbd-numlock kbd-capslock
kbd-kanalock kbd-shiftlock kbd-altgrlock kbd-ctrllock kbd-altlock
kbd-shiftllock kbd-shiftrlock kbd-ctrlllock kbd-ctrlrlock m
timer oneshot heartbeat backlight [gpio] cpu0 cpu1 cpu2 cpu
```

Switch trigger type

```
root@rockpi4b:/sys/class/leds/user-led2# echo heartbeat > trigger
```

```
root@rockpi4b:/sys/class/leds/user-led2# cat trigger
none rc-feedback kbd-scrolllock kbd-numlock kbd-capslock
kbd-kanalock kbd-shiftlock kbd-altgrlock kbd-ctrllock kbd-altlock
kbd-shiftllock kbd-shiftrlock kbd-ctrlllock kbd-ctrlrlock mmc0 mmc1
timer oneshot [heartbeat] backlight gpio| cpu0 cpu1 cpu2 cpu3 cpu4 cpu5
```

# GPIO Control

# Driver LED in User Space

## ➤ Paths in Sysfs

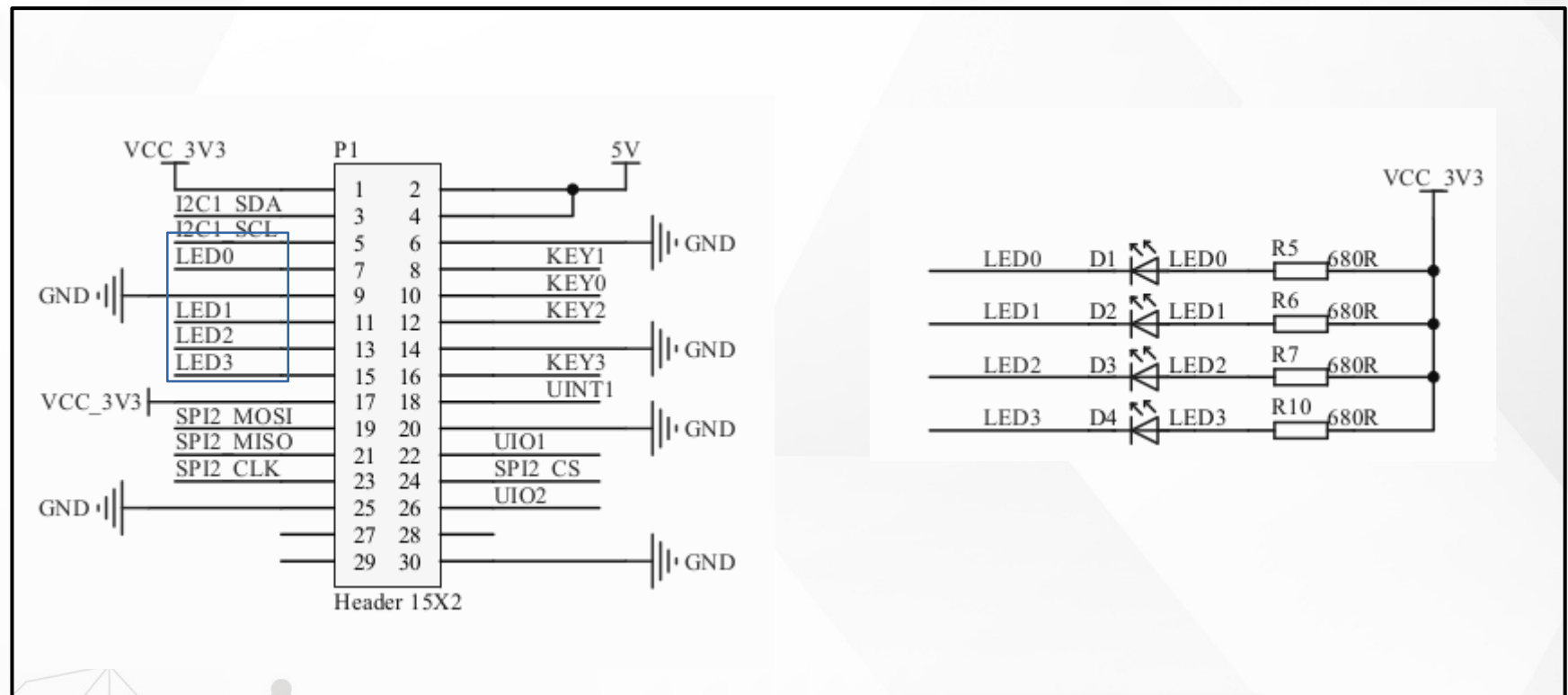
### ➤ /sys/class/gpio:

- Control interfaces used to get userspace control over GPIOs;
- GPIOs themselves
- GPIO controllers("gpio\_chip" instances)

### ➤ /sys/class/gpio/

- "export" : ask the kernel to export GPIO to userspace by writing
  - "echo 19 > export"
  - create a "gpio19" node in /sys/class/gpio
- "unexport" : Reverses the effect of exporting to userspace
  - "echo 19 > unexport"
  - remove "gpio19" node from /sys/class/gpio

# Cadtc Ext Board LED



# RockPi4B HEAD

## Rock Pi 4 A/B/C general purpose input-output (GPIO) connector

ROCK Pi 4 has a 40-pin expansion header. Each pin is distinguished by color.

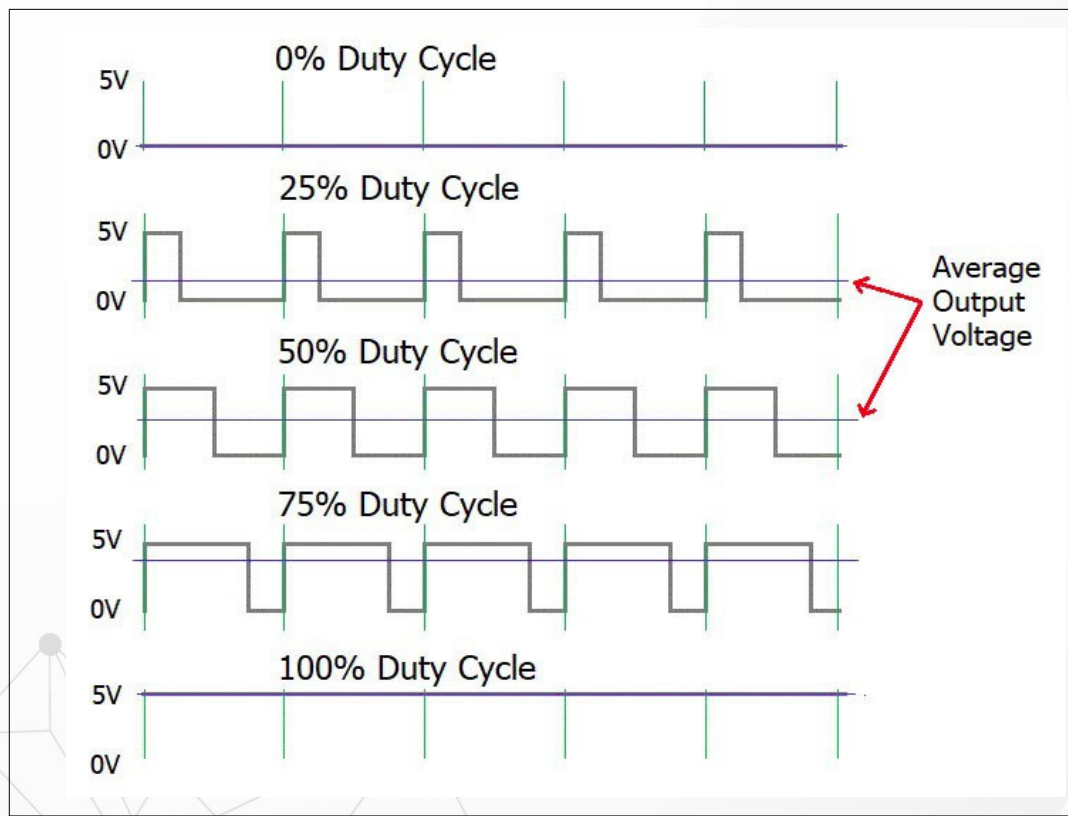
GPIO number	Function2	Function1	GPIO	Pin#	Pin#	GPIO	Function1	Function2	GPIO number
		+3.3V		1	2		+5.0V		
71		I2C7_SDA	GPIO2_A7	3	4		+5.0V		
72		I2C7_SCL	GPIO2_B0	5	6		GND		
75		SPI2_CLK	GPIO2_B3	7	8	GPIO4_C4	UART2_TXD		148
		GND		9	10	GPIO4_C3	UART2_RXD		147
146		PWM0	GPIO4_C2	11	12	GPIO4_A3	I2S1_SCLK		131
150		PWM1	GPIO4_C6	13	14		GND		
149		SPDIF_TX	GPIO4_C5	15	16	GPIO4_D2			154
		+3.3V		17	18	GPIO4_D4			156
40	UART4_TXD	SPI1_TXD	GPIO1_B0	19	20		GND		
39	UART4_RXD	SPI1_RXD	GPIO1_A7	21	22	GPIO4_D5			157
41		SPI1_CLK	GPIO1_B1	23	24	GPIO1_B2	SPI1_CS <sub>n</sub>		42
		GND		25	26		ADC_IN0		
64		I2C2_SDA	GPIO2_A0	27	28	GPIO2_A1	I2C2_CLK		65
74	I2C6_SCL	SPI2_TXD	GPIO2_B2	29	30		GND		
73	I2C6_SDA	SPI2_RXD	GPIO2_B1	31	32	GPIO3_C0	SPDIF_TX	UART3_CTS <sub>n</sub>	112
76		SPI2_CS <sub>n</sub>	GPIO2_B4	33	34		GND		
133		I2S1_LRCK_TX	GPIO4_A5	35	36	GPIO4_A4	I2S1_LRCK_RX		132
158			GPIO4_D6	37	38	GPIO4_A6	I2S1_SDI		134
		GND		39	40	GPIO4_A7	I2S1_SDO		135

# PWM Sub System



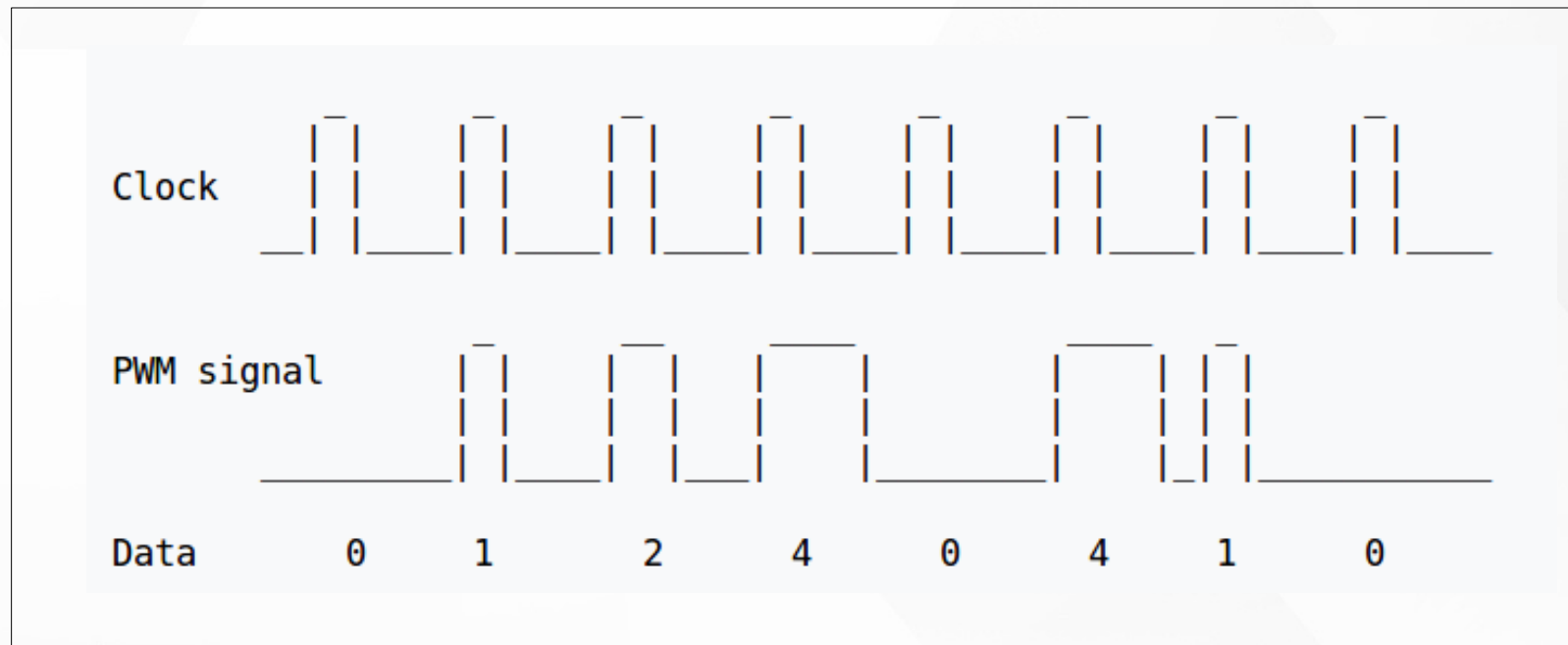
# PWM

## PWM : Pulse Width Modulation





# PWM



[https://en.wikipedia.org/wiki/Pulse-width\\_modulation](https://en.wikipedia.org/wiki/Pulse-width_modulation)



# PWM Parameter in Linux



## ▶ Period

- The total period of the PWM signal
- Value is in nanoseconds
- sum of the active and inactive time of the PWM

## ▶ duty\_cycle

- The active time of the PWM signal
- Value is in nanoseconds
- must be less than the period.



# PWM Parameter in Linux

## ➤ Polarity

- The polarity of the PWM signal

## ➤ Enable



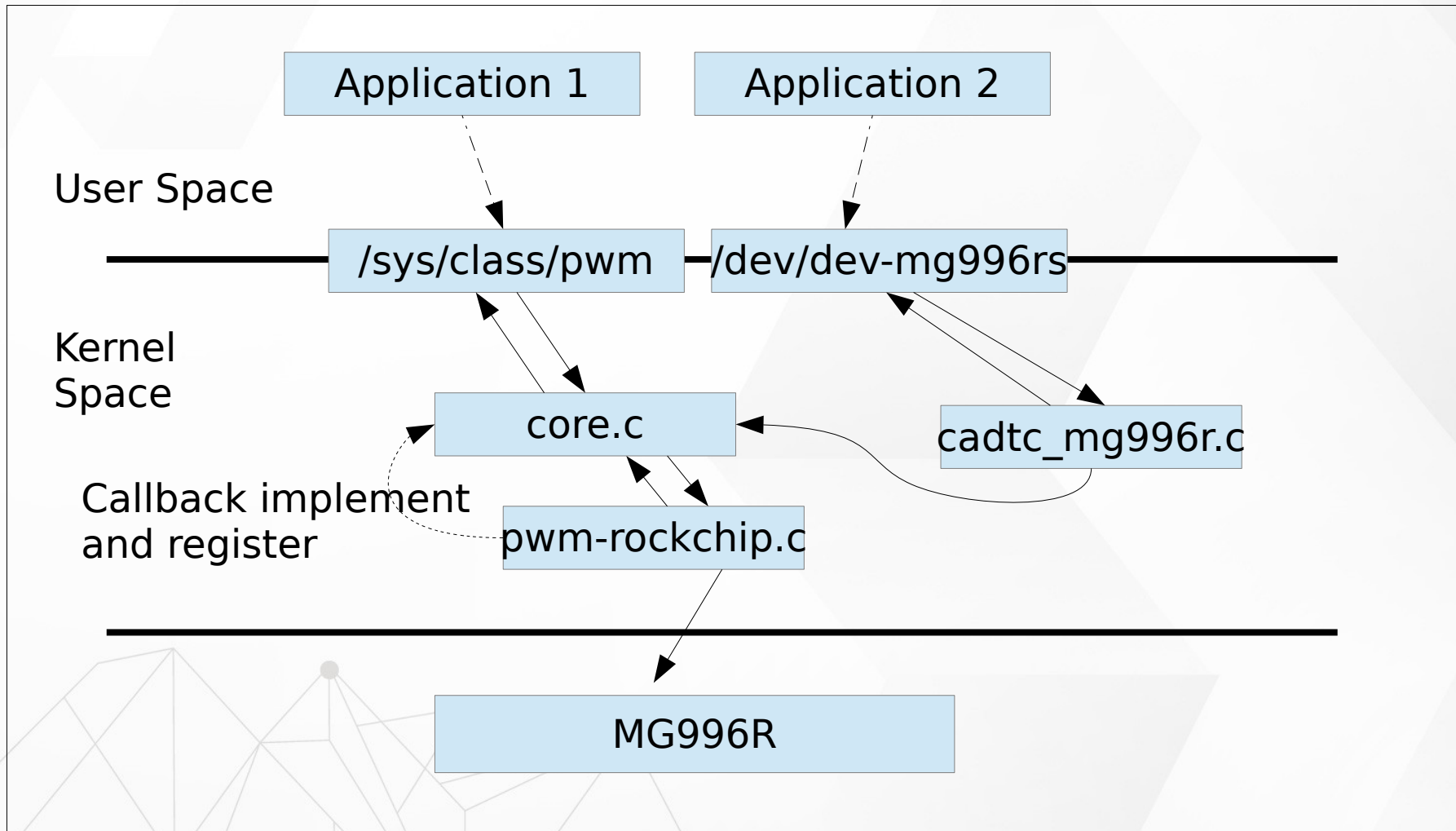
# PWM Driver

➤ \$(KERNEL\_SRC)/Documentation/pwm.txt

➤ Platform Driver

- drivers/pwm/
- drivers/pwm/core.c
- drivers/pwm/pwm-rockchip.c

# PWM Subsystem



# RockPi4B HEAD

## Rock Pi 4 A/B/C general purpose input-output (GPIO) connector

ROCK Pi 4 has a 40-pin expansion header. Each pin is distinguished by color.

GPIO number	Function2	Function1	GPIO	Pin#	Pin#	GPIO	Function1	Function2	GPIO number
		+3.3V		1	2		+5.0V		
71		I2C7_SDA	GPIO2_A7	3	4		+5.0V		
72		I2C7_SCL	GPIO2_B0	5	6		GND		
75		SPI2_CLK	GPIO2_B3	7	8	GPIO4_C4	UART2_TXD		148
		GND		9	10	GPIO4_C3	UART2_RXD		147
146		PWM0	GPIO4_C2	11	12	GPIO4_A3	I2S1_SCLK		131
150		PWM1	GPIO4_C6	13	14		GND		
149		SPDIF_TX	GPIO4_C5	15	16	GPIO4_D2			154
		+3.3V		17	18	GPIO4_D4			156
40	UART4_TXD	SPI1_TXD	GPIO1_B0	19	20		GND		
39	UART4_RXD	SPI1_RXD	GPIO1_A7	21	22	GPIO4_D5			157
41		SPI1_CLK	GPIO1_B1	23	24	GPIO1_B2	SPI1_CS <sub>n</sub>		42
		GND		25	26		ADC_IN0		
64		I2C2_SDA	GPIO2_A0	27	28	GPIO2_A1	I2C2_CLK		65
74	I2C6_SCL	SPI2_TXD	GPIO2_B2	29	30		GND		
73	I2C6_SDA	SPI2_RXD	GPIO2_B1	31	32	GPIO3_C0	SPDIF_TX	UART3_CTS <sub>n</sub>	112
76		SPI2_CS <sub>n</sub>	GPIO2_B4	33	34		GND		
133		I2S1_LRCK_TX	GPIO4_A5	35	36	GPIO4_A4	I2S1_LRCK_RX		132
158			GPIO4_D6	37	38	GPIO4_A6	I2S1_SDI		134
		GND		39	40	GPIO4_A7	I2S1_SDO		135

# PWM SYSFS

/sys/class/pwm/pwmchip0

device    **export**    npwm    power    subsystem uevent    unexport

echo 0 > export

capture    enable    polarity    uevent    duty\_cycle period    power

echo "20000000" > period    //20ms, 50 Hz

echo "2000000" > duty\_cycle    //2ms

echo 1 > enable    //Enable

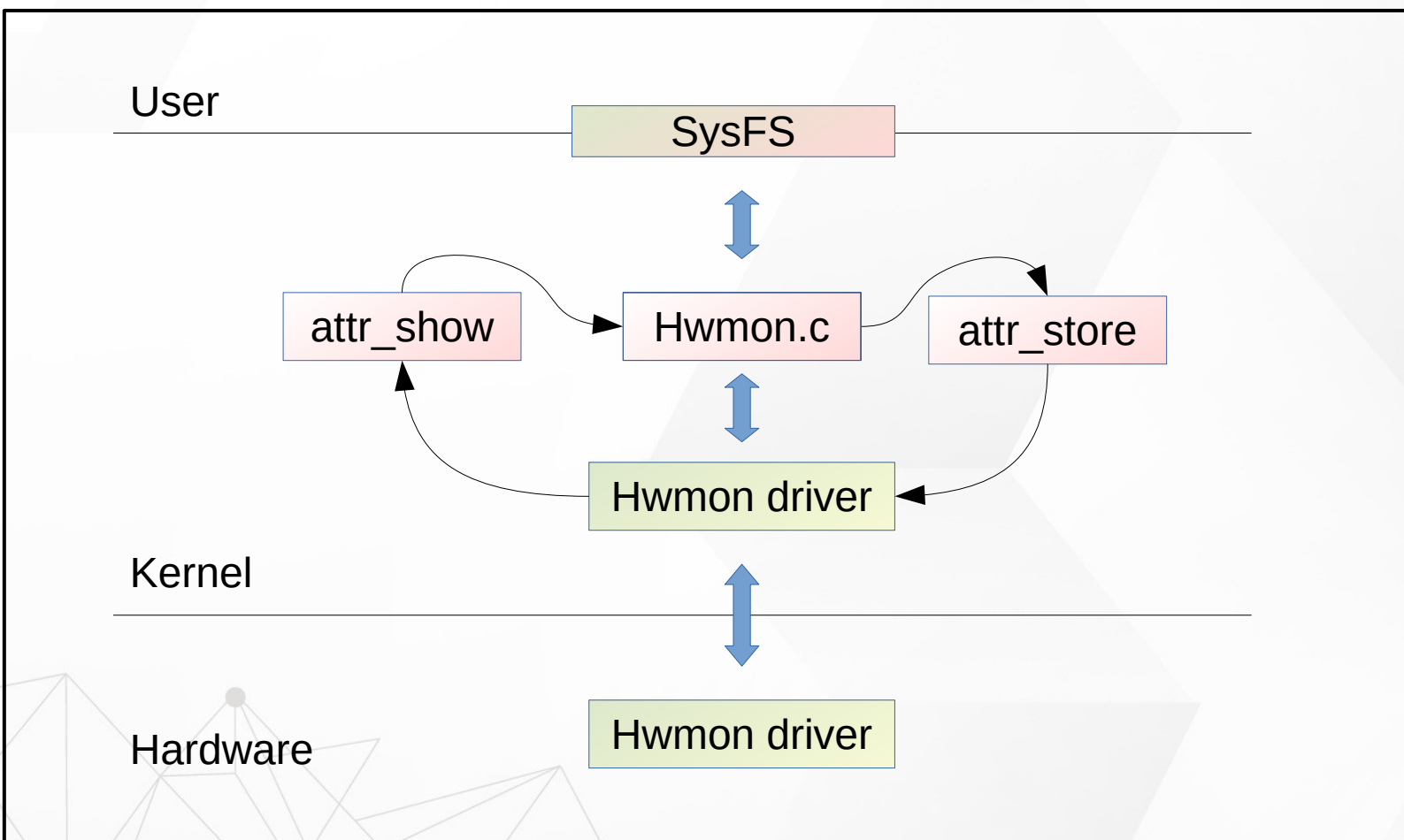


# PWM DoReMi

	Frequency (Hz)
C4	261.63
C4#	277.18
D4	293.66
D4#	311.13
E4	329.63
F4	349.23
F4#	369.99
G4	392.00
G4#	415.30
A4	440.00
A4#	466.16
B4	493.88
C5	523.25

# Hwmon Subsystem

# Hwmon Subsystem



# SHT21

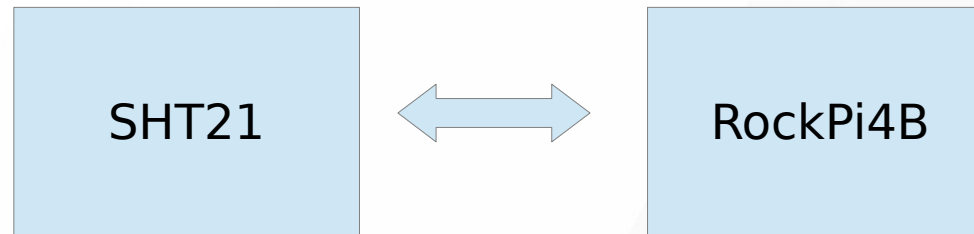
 Simple interface Bus interface

- I2C, GPIO, SPI

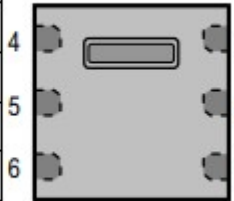
 Sensors

- Temperature
- Voltage
- Humidity
- Fan speed
- PWM control

# SHT21



Pin	Name	Comment
1	SDA	Serial Data, bidirectional
2	VSS	Ground
5	VDD	Supply Voltage
6	SCL	Serial Clock, bidirectional
3,4	NC	Not Connected

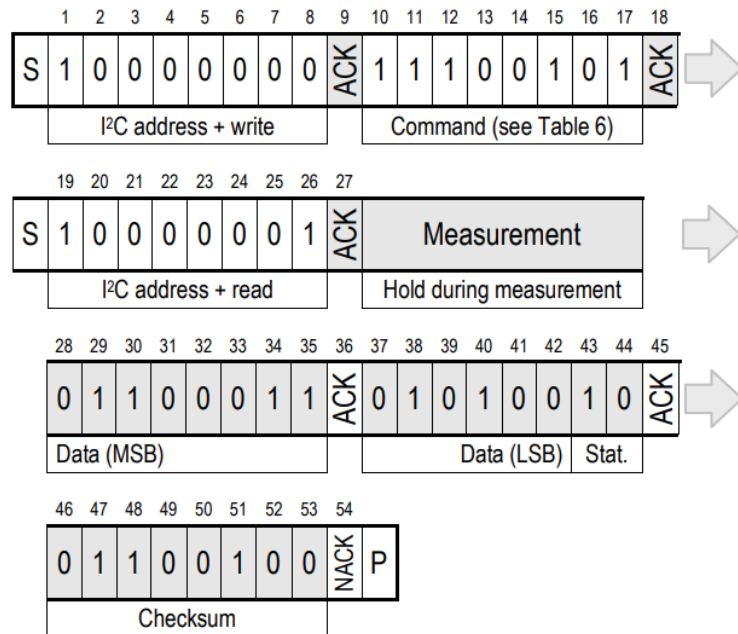


A small diagram of the SHT21 sensor package is shown to the right of the table. It is a square package with pins numbered 1 through 6. Pin 1 is at the bottom right, pin 2 is at the top right, pin 3 is at the top left, pin 4 is at the bottom left, pin 5 is at the top center, and pin 6 is at the bottom center.

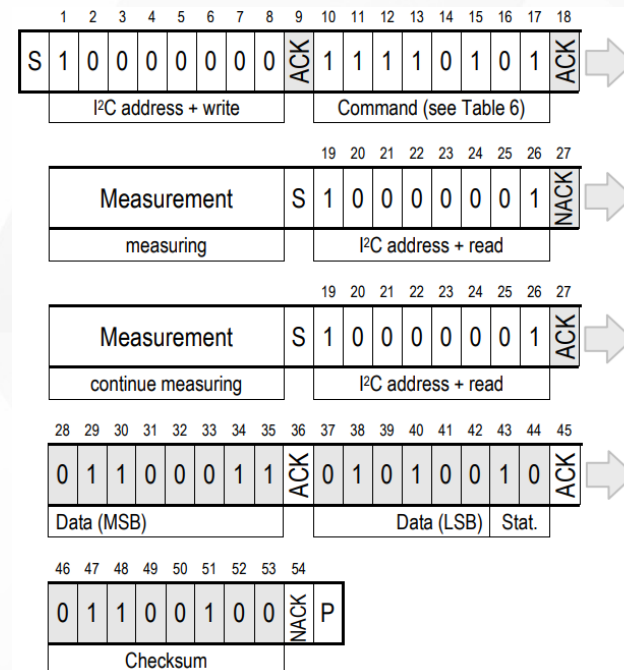
Command	Comment	Code
Trigger T measurement	hold master	1110'0011
Trigger RH measurement	hold master	1110'0101
Trigger T measurement	no hold master	1111'0011
Trigger RH measurement	no hold master	1111'0101
Write user register		1110'0110
Read user register		1110'0111
Soft reset		1111'1110

# SHT21

Hold master communication sequence

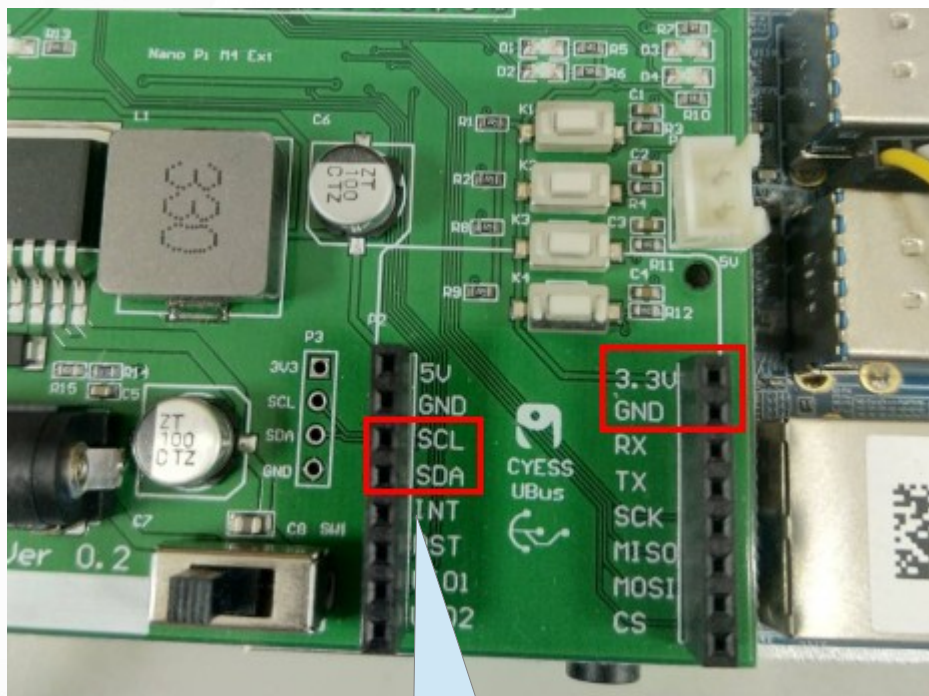


No Hold master communication sequence

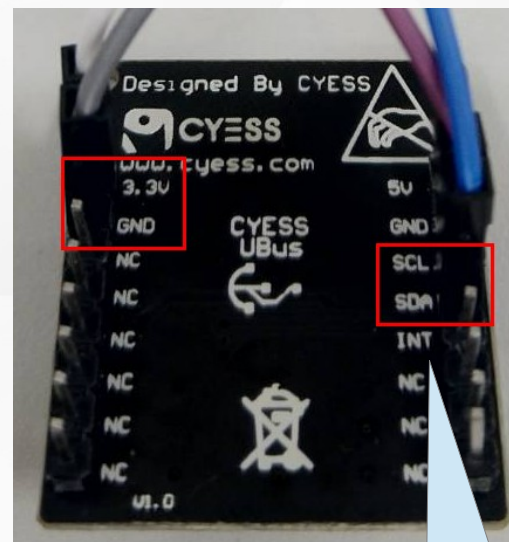




# SHT21



I2C



I2C



# SHT21

## Hwmon Sysfs

```
# ls /sys/class/hwmon/hwmon0
device          name    subsystem  uevent
humidity1_input power   temp1_input
```

## temperature

```
# cat /sys/class/hwmon/hwmon0/temp1_input
32279
```

## humidity

```
# cat /sys/class/hwmon/hwmon0/humidity1_input
34512
```

# IIO Subsystem

# IIO Introduction

## ➤ IIO - The Industrial I/O

## ➤ support for devices that in some sense

- analog to digital (ADC)
- digital to analog converters (DAC)

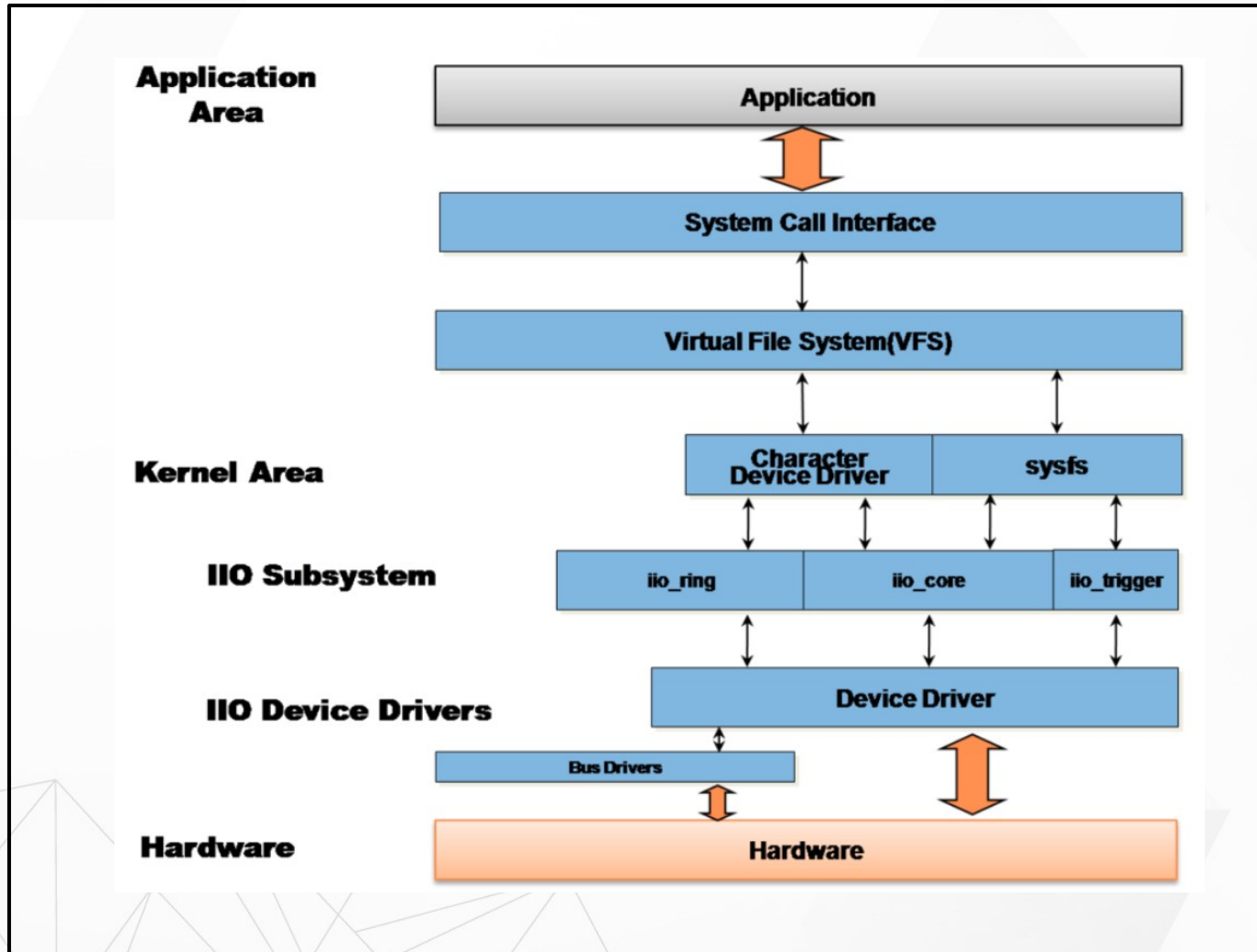
## ➤ Devices that fall into this category are

- ADCs
- Accelerometers
- Gyros
- DAC
- Pressure Sensors

# IIO Introduction

- Fill the gap between the somewhat similar hwmon and input subsystems
- Hwmon is very much directed at low sample rate sensors used in applications
  - fan speed control
  - temperature measurement.
- Input is, as it's name suggests focused on human interaction input devices

# IIO Introduction



# IIO Interface

➤ There are 2 ways for a user space application to interact with an IIO driver

➤ **/sys/bus/iio/iio:deviceX/**

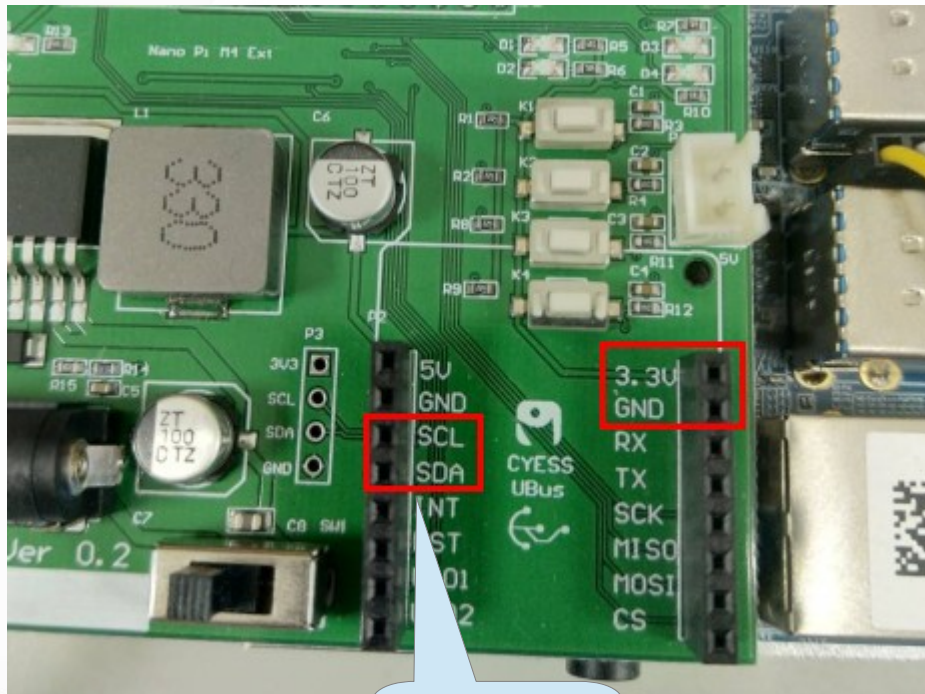
- data channels

➤ **/dev/iio:deviceX**

- buffered data transfer
- events information



# ISL29023



I2C

