

**Lecture 27:**

# **Rendering Challenges of VR**

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**Computer Graphics**  
**CMU 15-462/15-662, Fall 2015**

# Virtual reality (VR) vs augmented reality (AR)

**VR = virtual reality**

**User is completely immersed in virtual world (sees only light emitted by display)**



**AR = augmented reality**

**Display is an overlay that augments user's normal view of the real world (e.g., terminator)**



# VR headsets

Oculus Rift (Crescent Bay Prototype)



Sony Morpheus



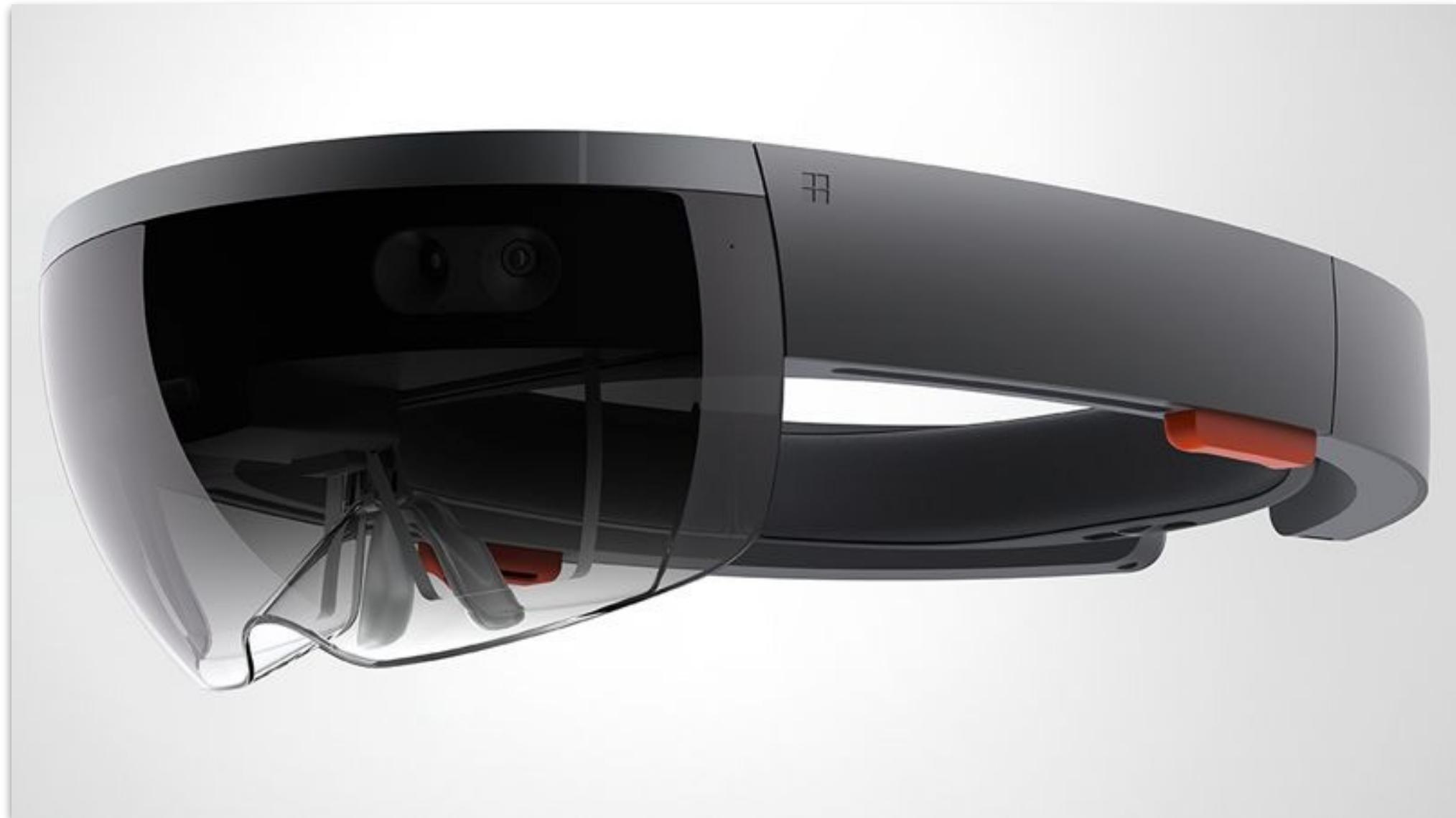
HTC Vive



Google  
Cardboard



# AR headset: Microsoft Hololens



# Today: rendering challenges of VR

- Since you are now all experts in renderings, today we will talk about the unique challenges of rendering in the context of modern VR headsets
- VR presents many other difficult technical challenges
  - display technologies
  - accurate tracking of face, head, and body position
  - haptics (simulation of touch)
  - sound synthesis
  - user interface challenges (inability of user to walk around environment, how to manipulate objects in virtual world)
  - content creation challenges
  - and on and on...

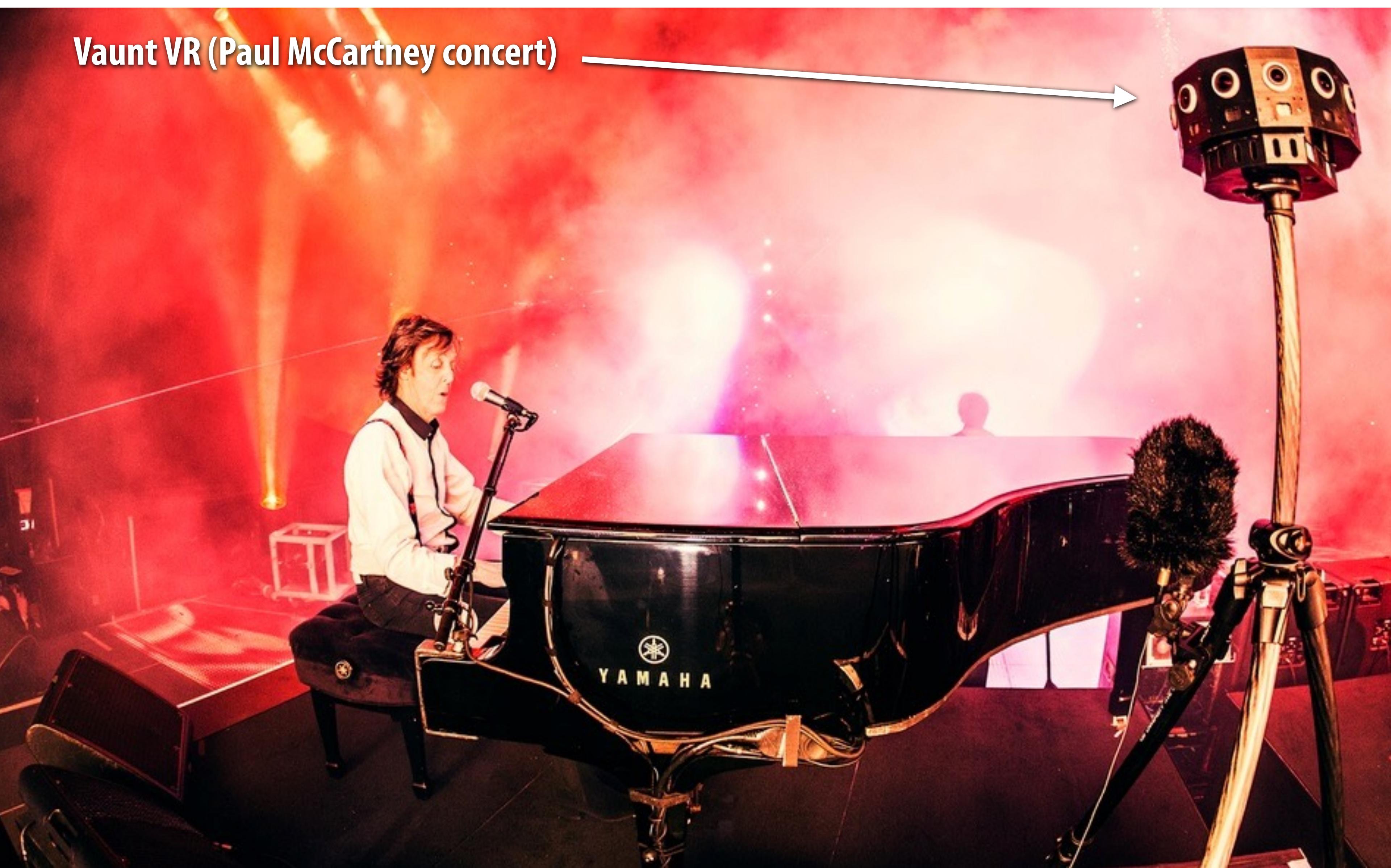
# VR gaming



Bullet Train Demo (Epic)

# VR video

Vaunt VR (Paul McCartney concert)



# VR video



# VR teleconference / video chat



trial version

# Oculus Rift DK2

Rift DK2 is best documented of modern prototypes, so I'll use it for discussion here



Oculus Rift DK2

# Oculus Rift DK2 headset



# Oculus Rift DK2 headset

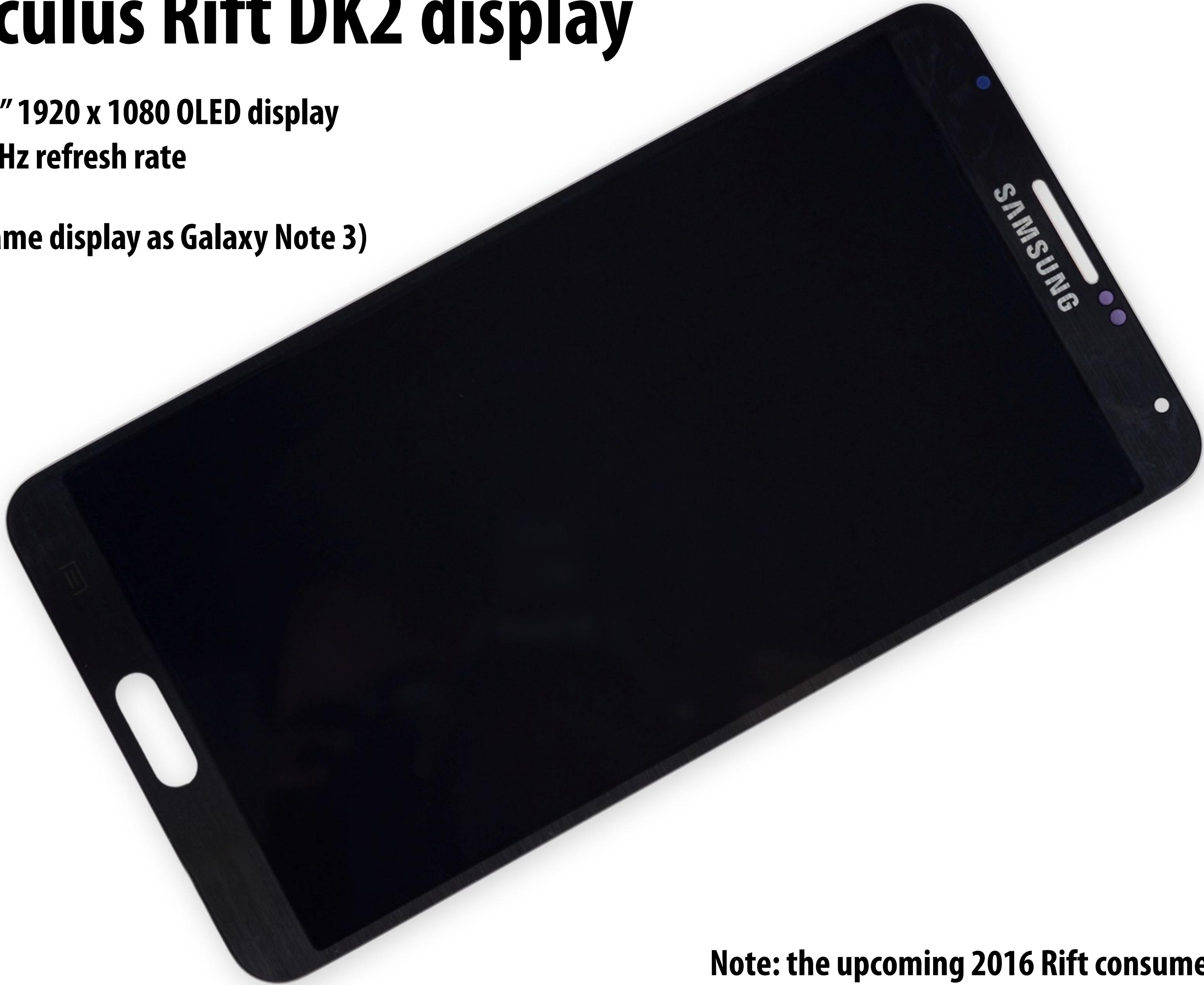


# Oculus Rift DK2 display

5.7" 1920 x 1080 OLED display

75 Hz refresh rate

(Same display as Galaxy Note 3)

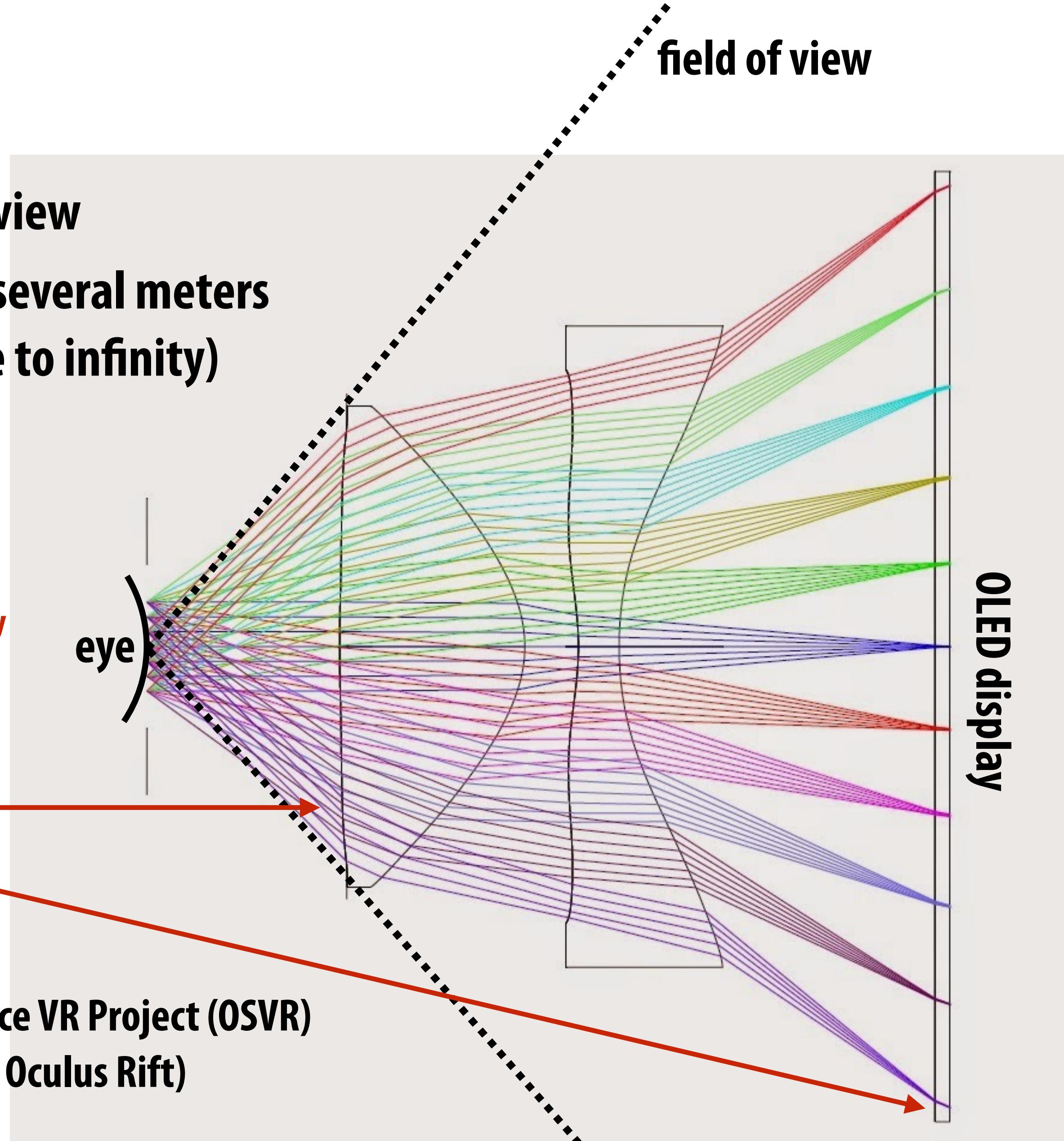


Note: the upcoming 2016 Rift consumer product features two 1080x1200 displays at 90Hz.

# Role of optics

1. Create wide field of view
2. Place focal plane at several meters away from eye (close to infinity)

Note: parallel lines reaching eye converge to a single point on display  
(eye accommodates to plane near infinity)

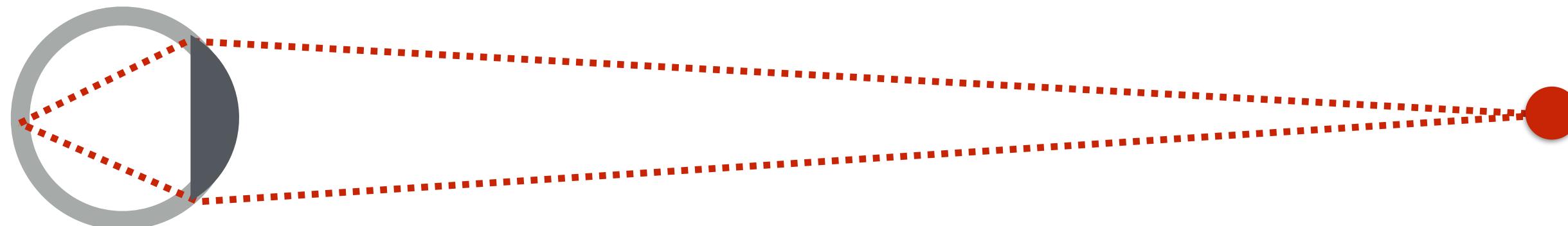


Lens diagram from Open Source VR Project (OSVR)  
(Not the lens system from the Oculus Rift)  
<http://www.osvr.org/>

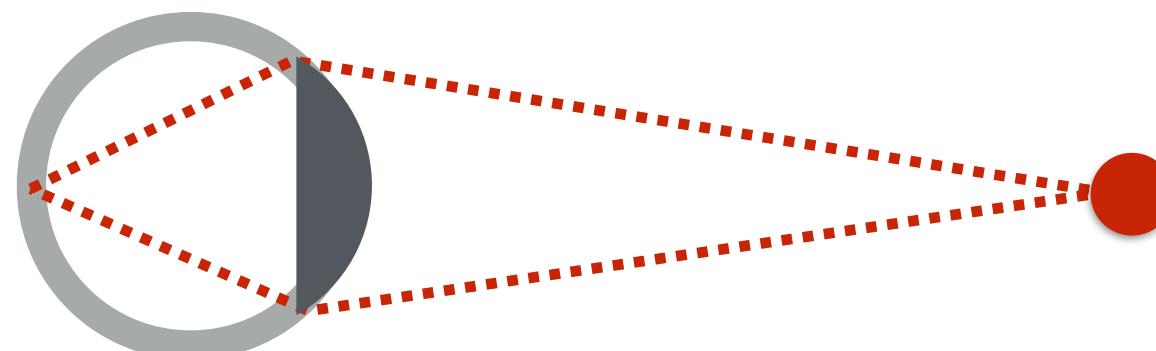
# Accommodation and vergence

**Accommodation: changing the optical power of the eye to focus at different distances**

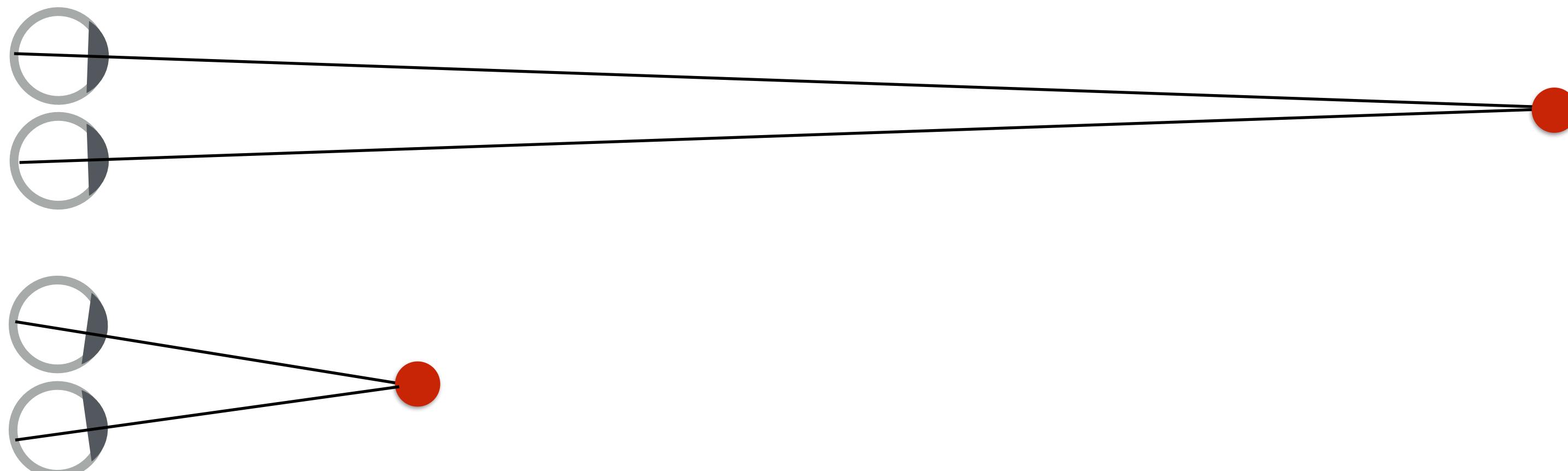
**Eye accommodated  
at far distance**



**Eye accommodated  
at near distance**

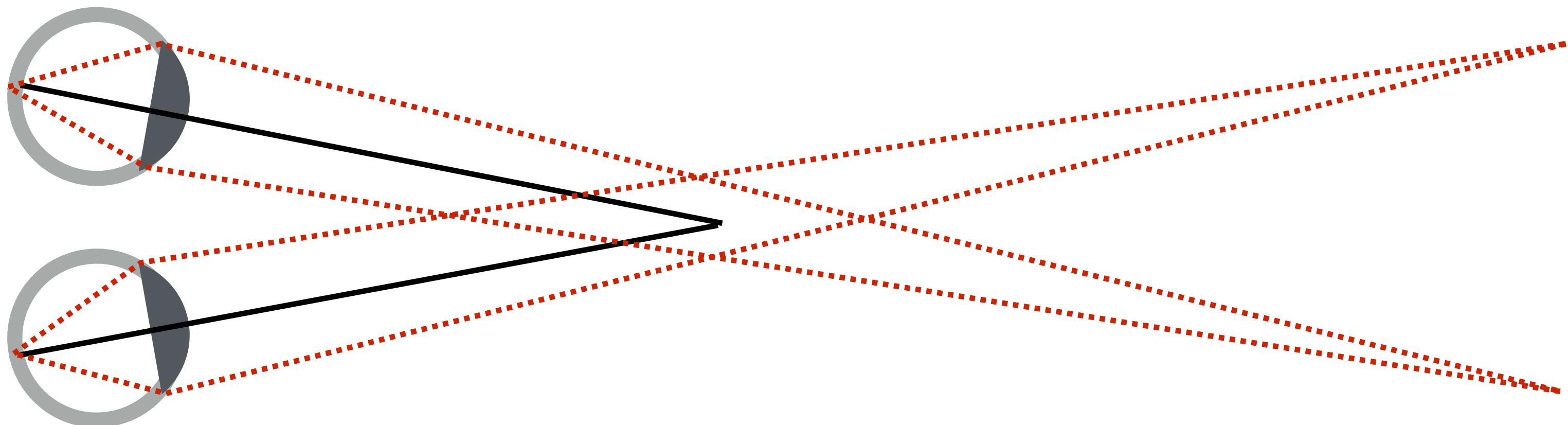


**Vergence: rotation of eye to ensure projection of object falls in center of retina**



# Accommodation - vergence conflict

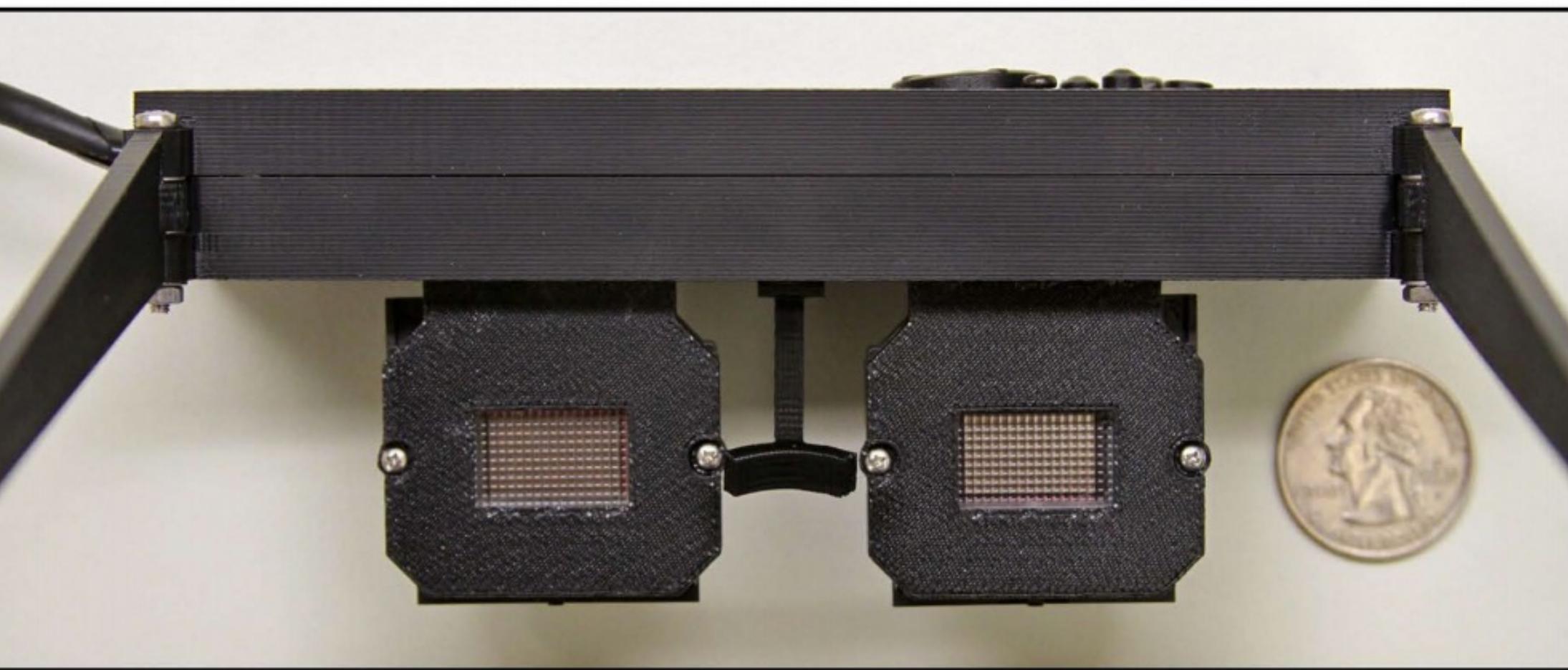
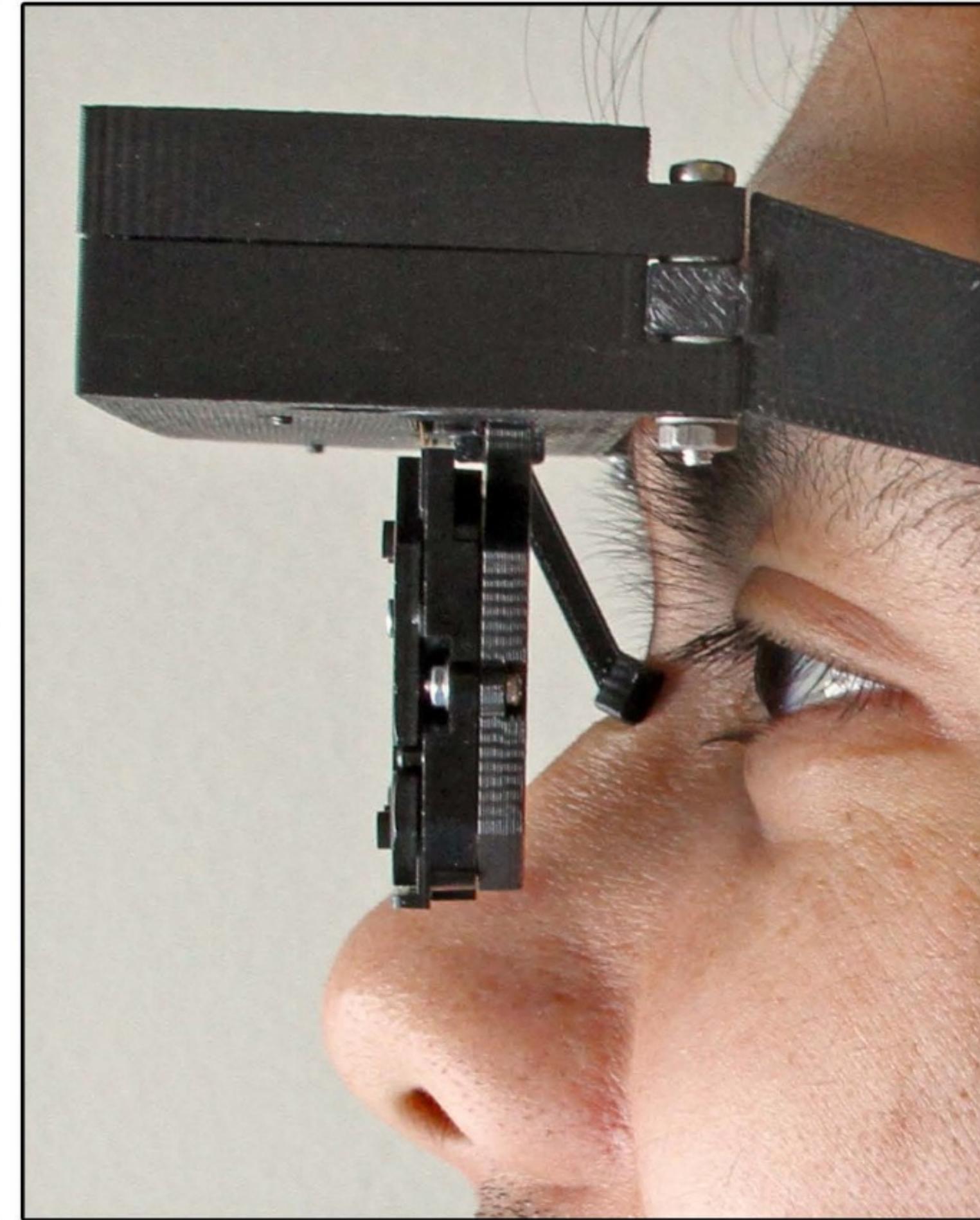
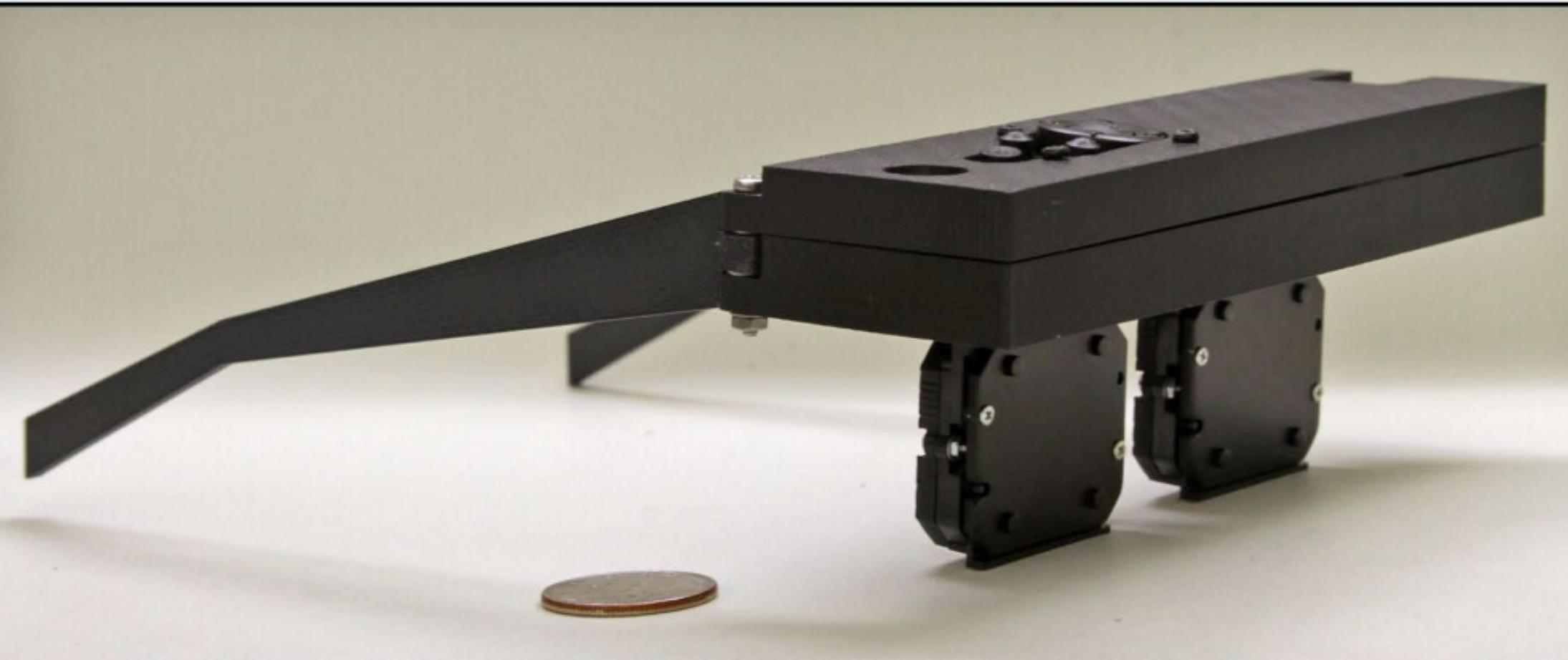
- Given design of current VR displays, consider what happens when objects are up-close to eye in virtual scene
  - Eyes must remain accommodated to near infinity (otherwise image on screen won't be in focus)
  - But eyes must converge in attempt to fuse stereoscopic images of object up close
  - Brain receives conflicting depth clues... (discomfort, fatigue, nausea)



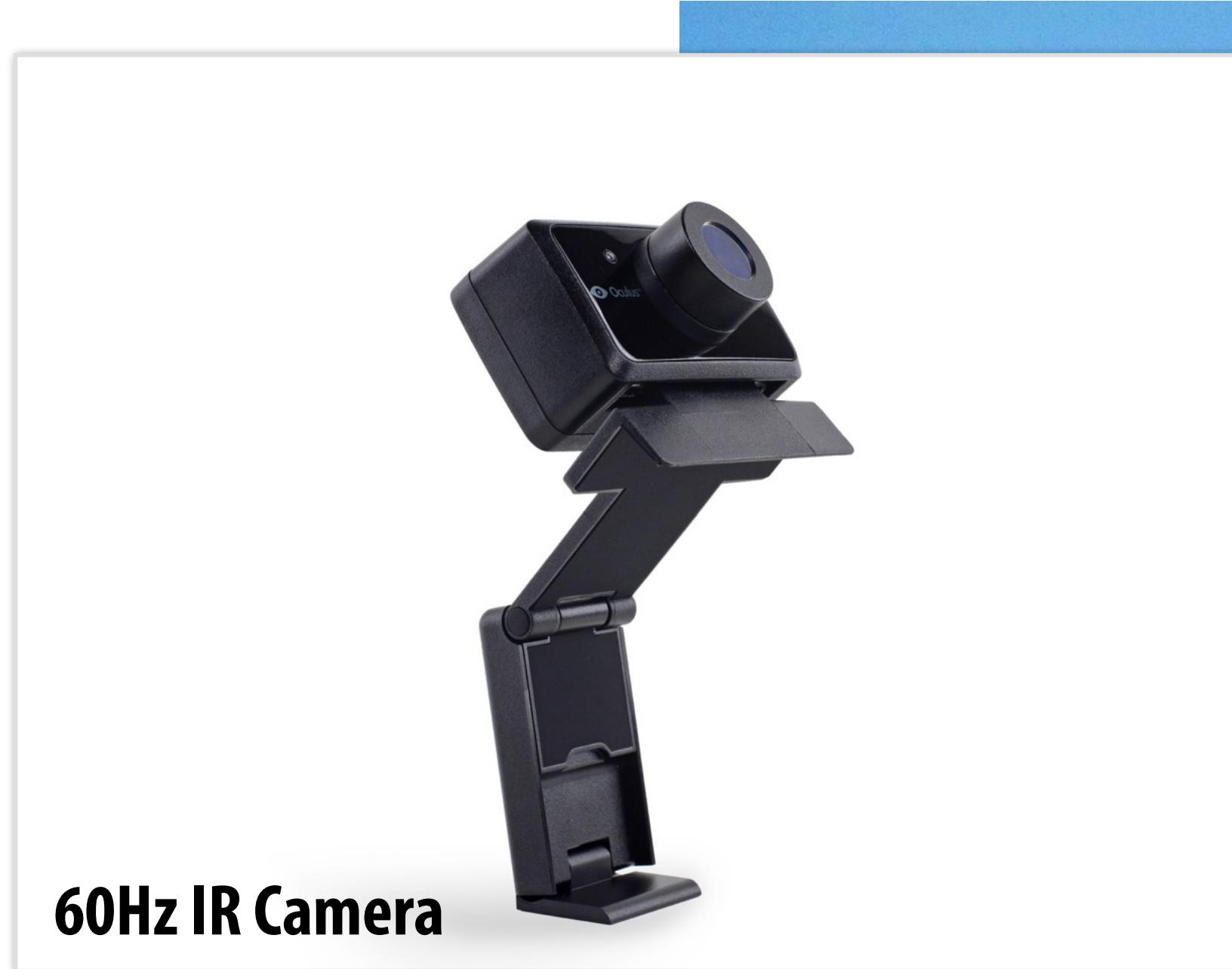
This problem stems from nature of display design. If you could just make a display that emits the light field that would be produced by a virtual scene, then you could avoid the accommodation - vergence conflict...

# Aside: near-eye light field displays

Recreate light field in front of eye



# Oculus DK2 IR camera and IR LEDs



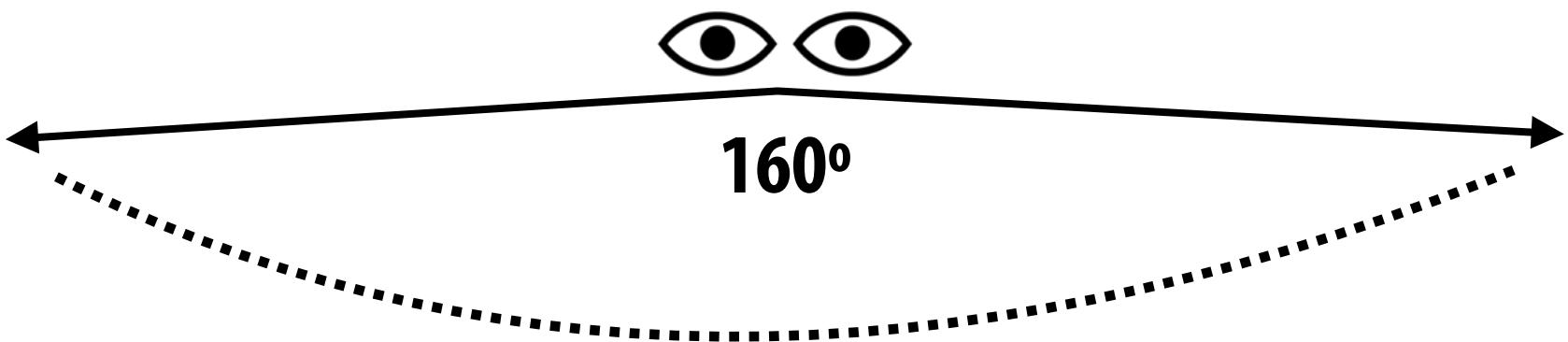
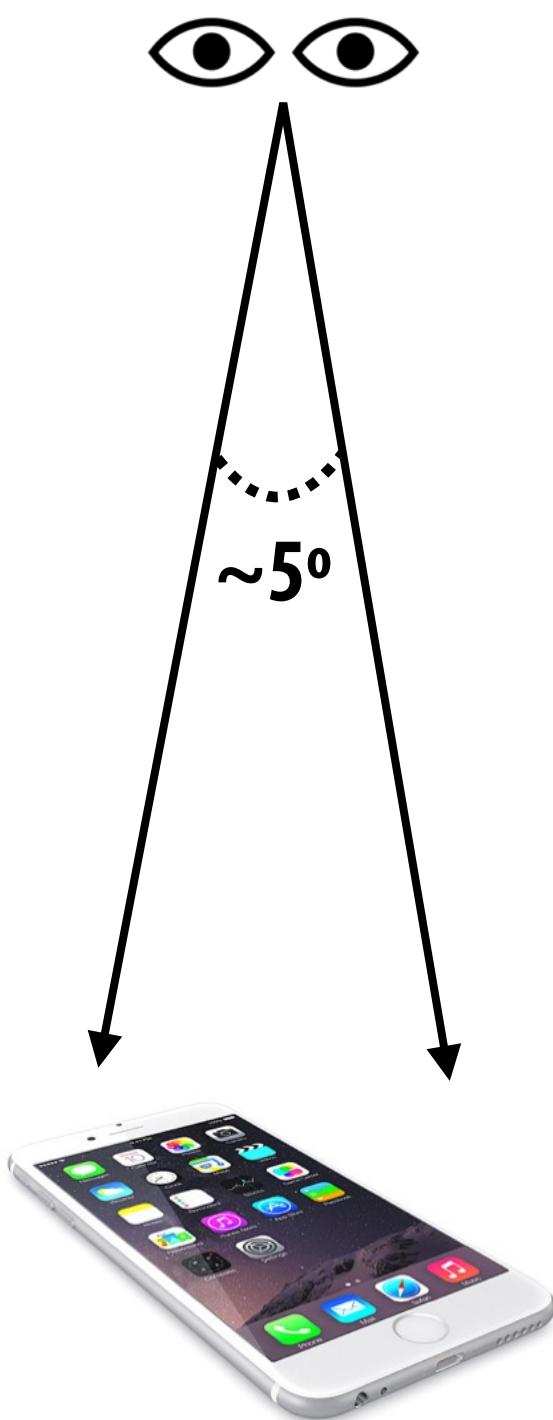
# Name of the game, part 1: low latency

- The goal of a VR graphics system is to achieve “presence”, tricking the brain into thinking what it is seeing is real
- Achieving presence requires an exceptional low-latency system
  - What you see must change when you move your head!
  - End-to-end latency: time from moving your head to the time new photons hit your eyes
    - Measure user's head movement
    - Update scene/camera position
    - Render new image
    - Transfer image to headset, then to transfer to display in headset
    - Actually emit light from display (photons hit user's eyes)
  - Latency goal of VR: 10-25 ms
    - Requires exceptionally low-latency head tracking
    - Requires exceptionally low-latency rendering and display

# Thought experiment: effect of latency

- Consider a 1,000 x 1,000 display spanning 100° field of view
  - 10 pixels per degree
- Assume:
  - You move your head 90° in 1 second (only modest speed)
  - End-to-end latency of system is 50 ms (1/20 sec)
- Therefore:
  - Displayed pixels are off by 4.5° ~ 45 pixels from where they would be in an ideal system with 0 latency

# Name of the game, part 2: high resolution



**Human:  $\sim 160^\circ$  view of field per eye ( $\sim 200^\circ$  overall)**  
**(Note: this does not account for eye's ability to rotate in socket)**

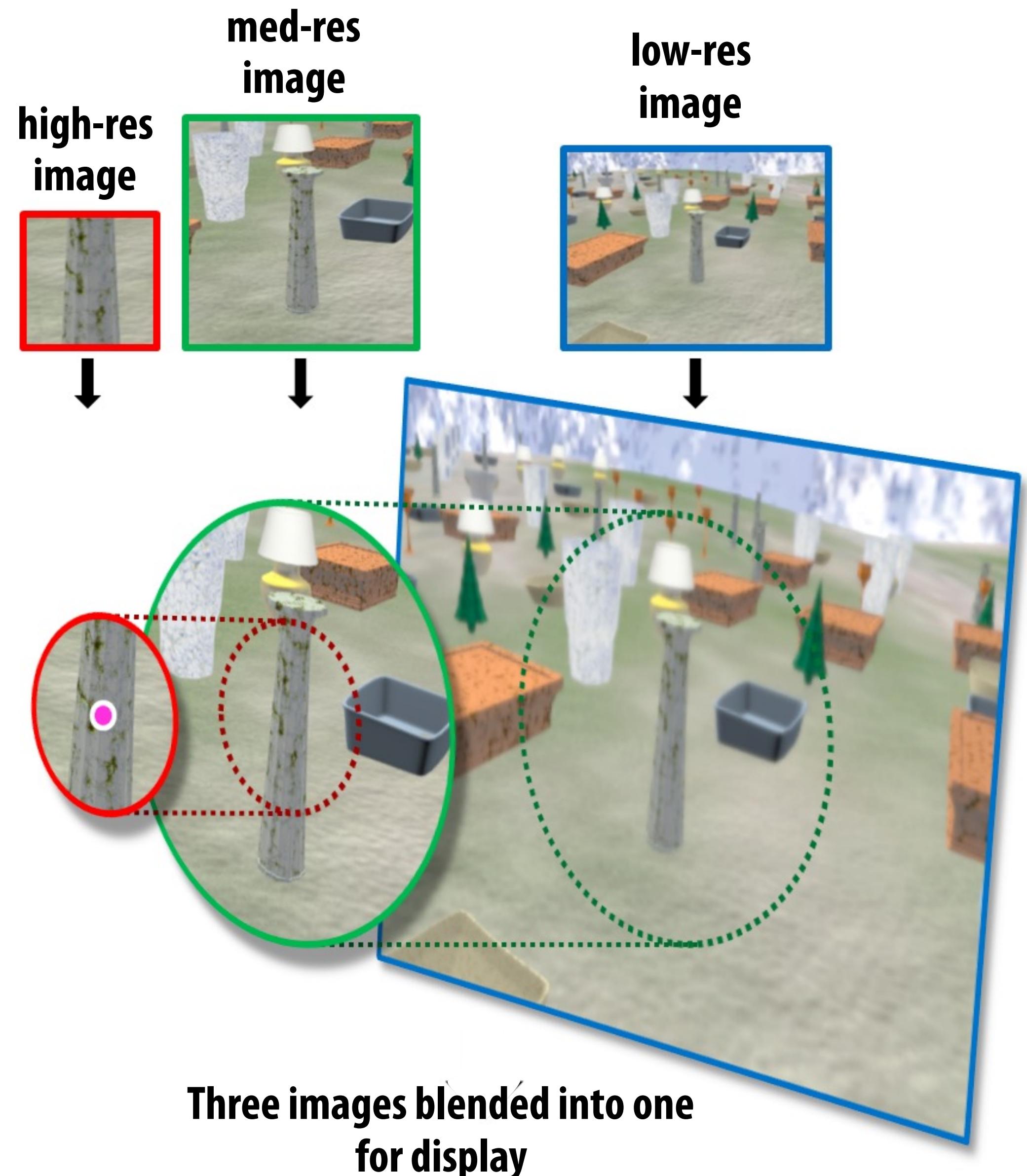
**Future “retina” VR display:**  
**57 ppd covering 200°**  
**= 11K x 11K display per eye**  
**= 220 MPixel**

**iPhone 6: 4.7 in “retina” display:**  
**1.3 MPixel**  
**326 ppi → 57 ppd**

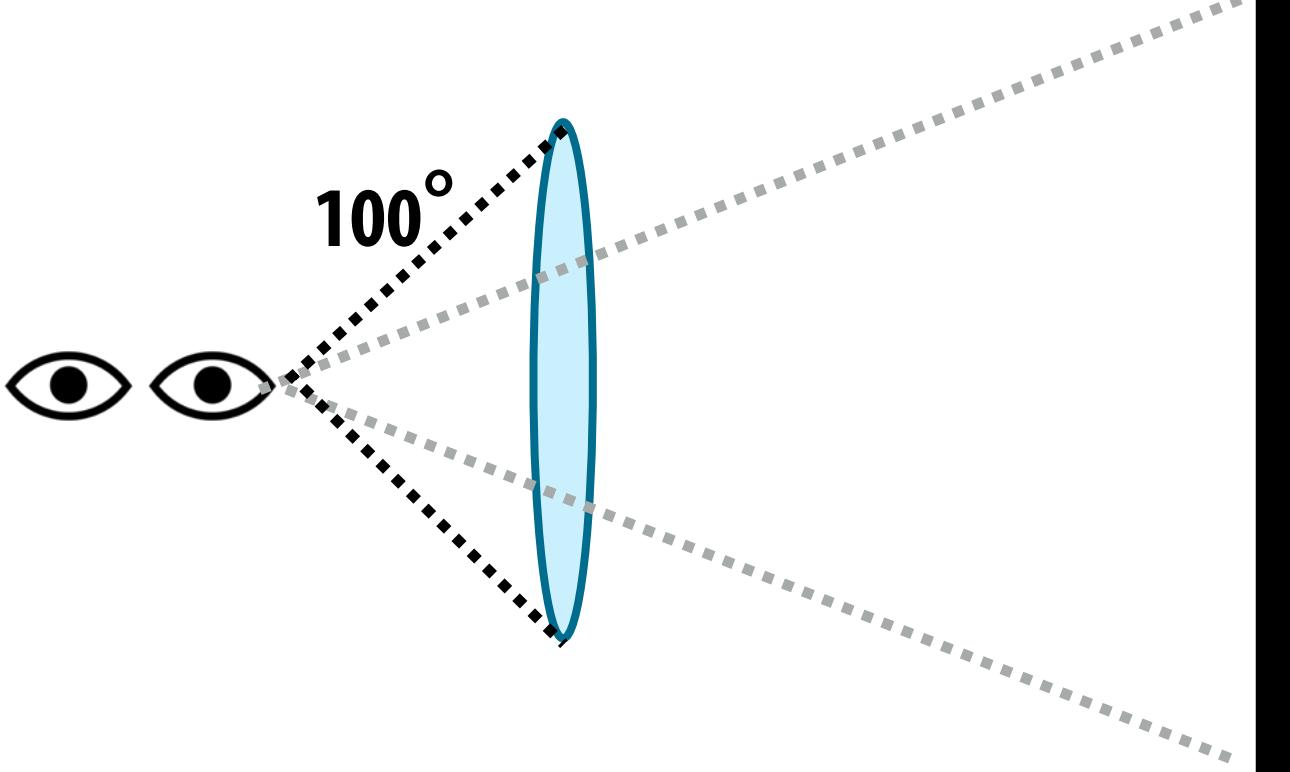
**Strongly suggests need for eye tracking and  
foveated rendering (eye can only perceive  
detail in 5° region about gaze point)**

# Foveated rendering

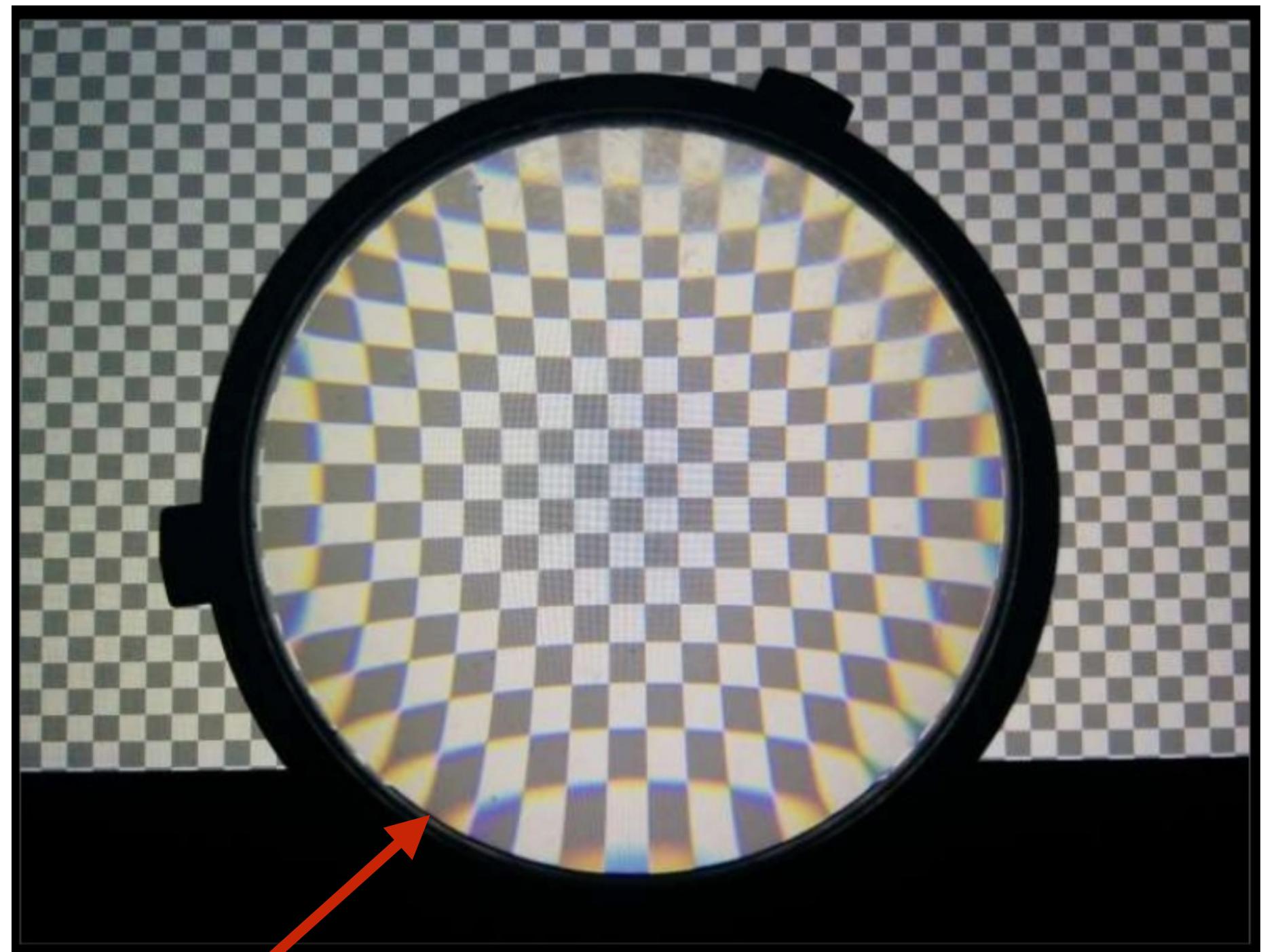
Idea: track user's gaze, render with increasingly lower resolution farther away from gaze point



# Requirement: wide field of view



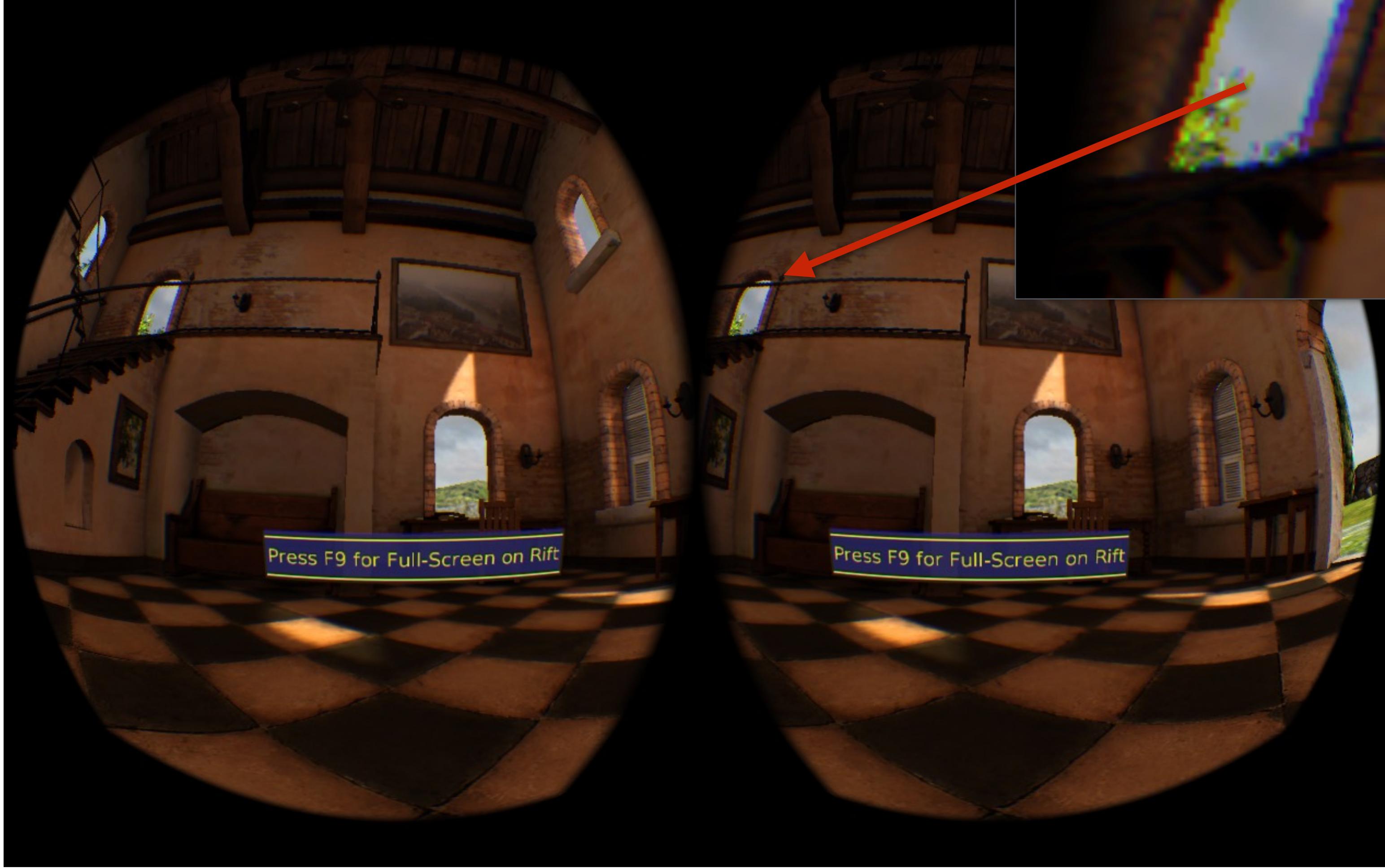
View of checkerboard through Oculus Rift lens



## Lens introduces distortion

- **Pincushion distortion**
- **Chromatic aberration (different wavelengths of light refract by different amount)**

# Rendered output must compensate for distortion of lens in front of display



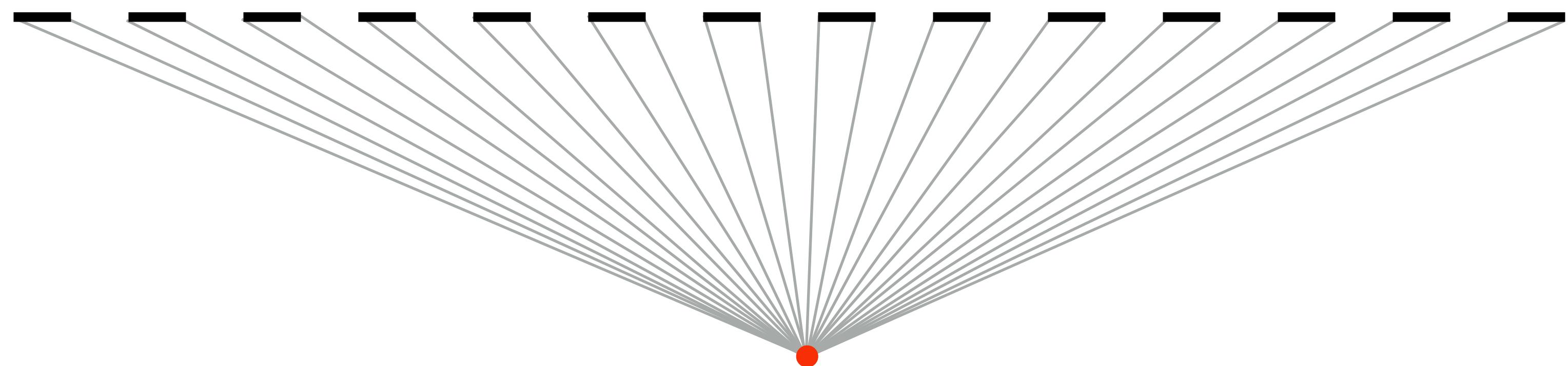
**Step 1: render scene using traditional graphics pipeline at full resolution for each eye**

**Step 2: warp images and composite into frame rendering is viewed correctly after lens distortion  
(Can apply unique distortion to R, G, B to approximate correction for chromatic aberration)**

# Challenge: rendering via planar projection

Recall: rasterization-based graphics is based on perspective projection to plane

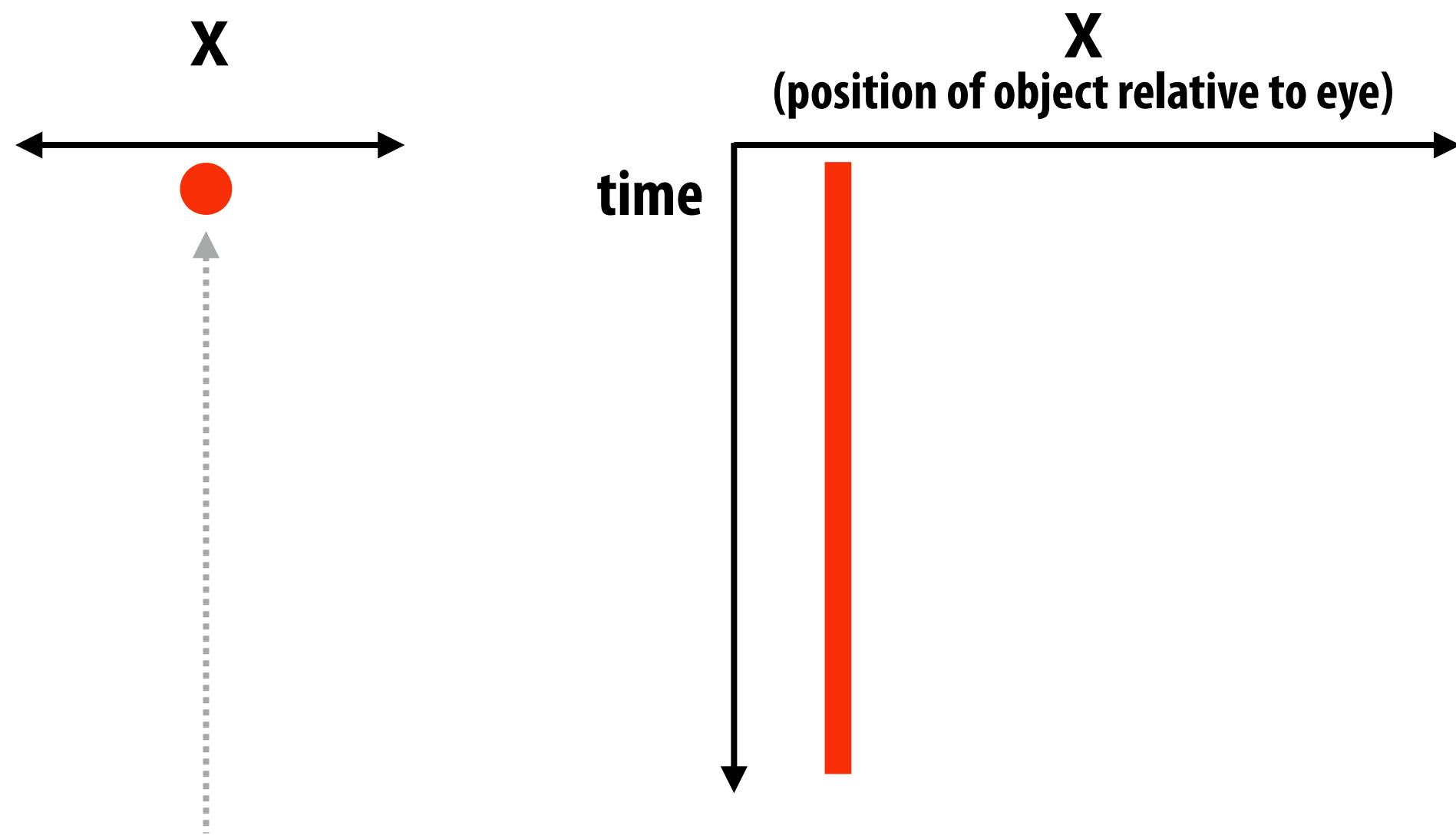
- Reasonable for modest FOV, but distorts image under high FOV
- Recall: VR rendering spans wide FOV



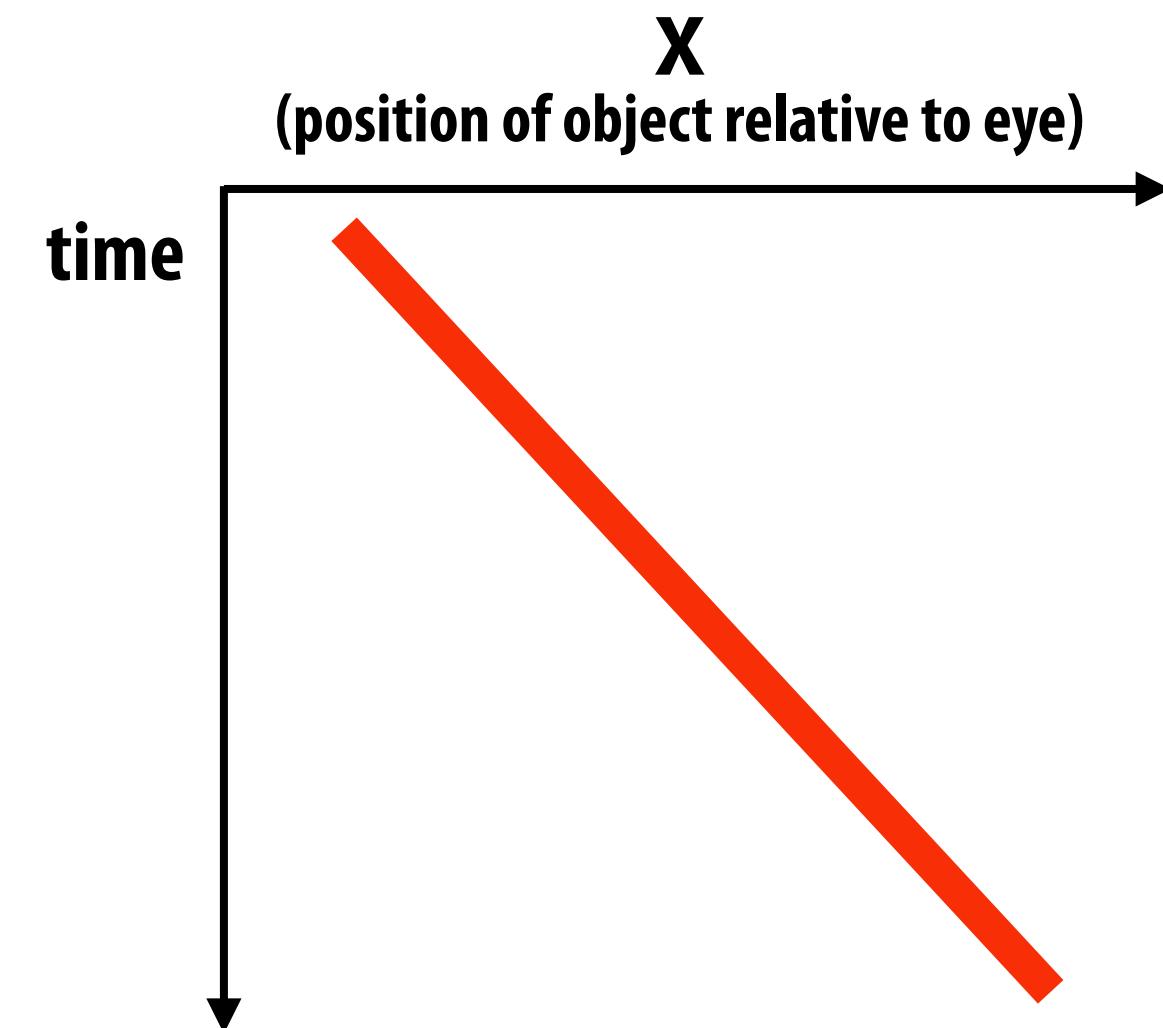
Pixels span larger angle in center of image  
(lowest angular resolution in center)

Future investigations may consider: curved displays, ray casting to achieve uniform angular resolution, rendering with piecewise linear projection plane (different plane per tile of screen)

# Consider object position relative to eye



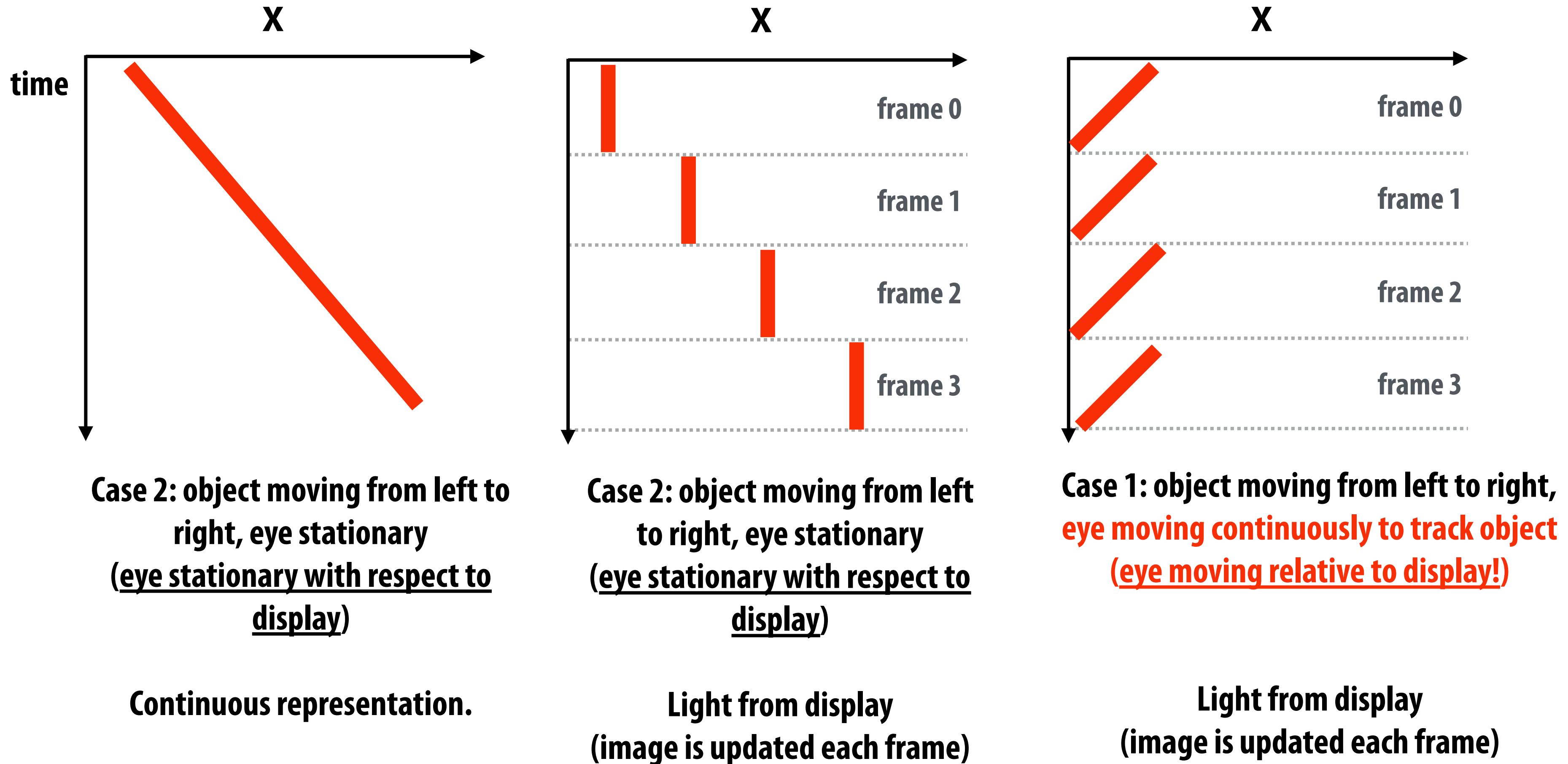
**Case 1: object stationary relative to eye:**  
(eye still and red object still  
OR  
red object moving left-to-right and  
eye moving to track object  
OR  
red object stationary in world but head moving  
and eye moving to track object)



**Case 2: object moving relative to eye:**  
(red object moving from left to right but  
eye stationary, i.e., it's focused on a different  
stationary point in world)

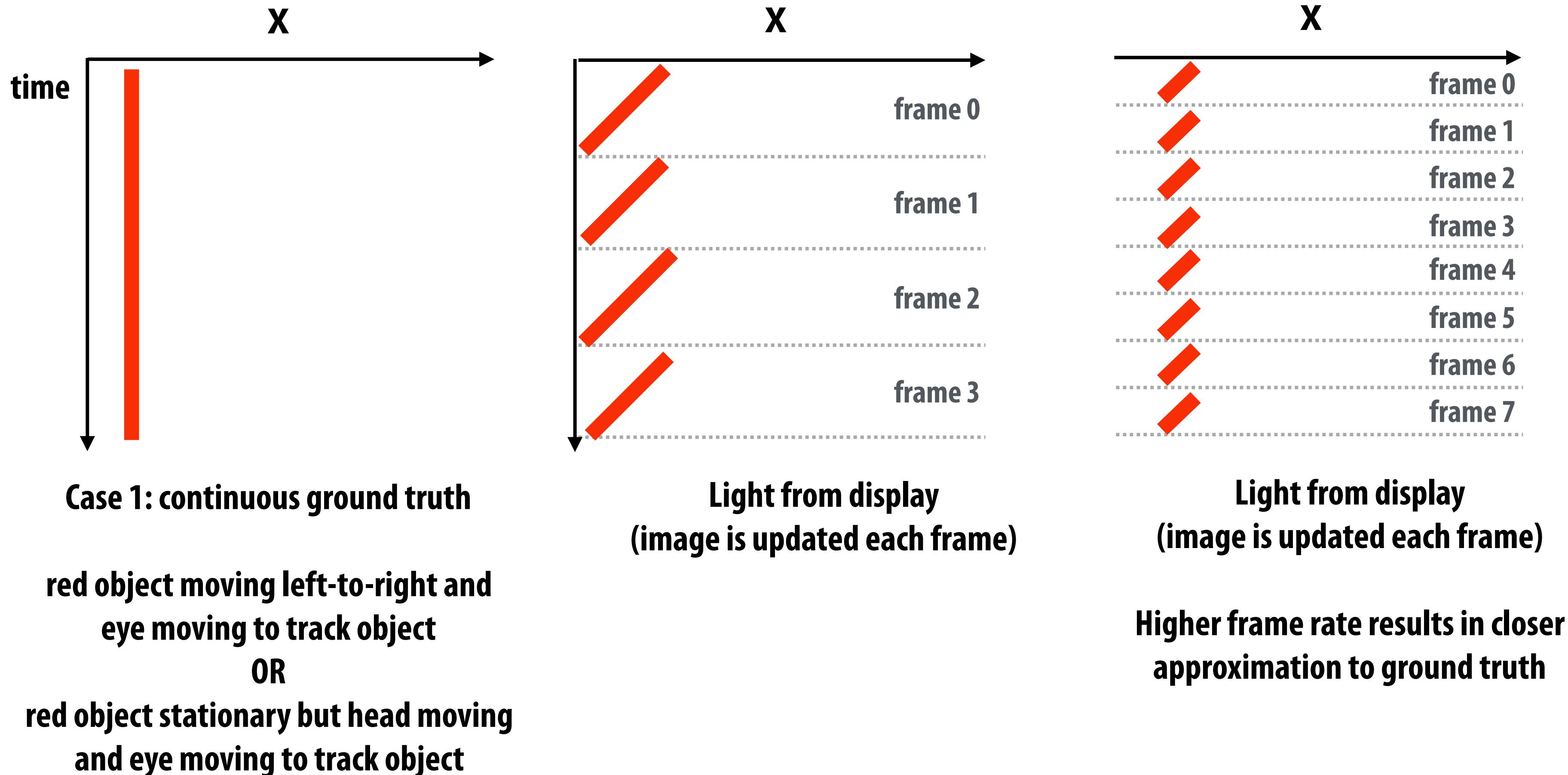
**NOTE: THESE GRAPHS PLOT OBJECT POSITION RELATIVE TO EYE  
RAPID HEAD MOTION WITH EYES TRACK A MOVING OBJECT IS A FORM OF CASE 1!!!**

# Effect of latency: judder

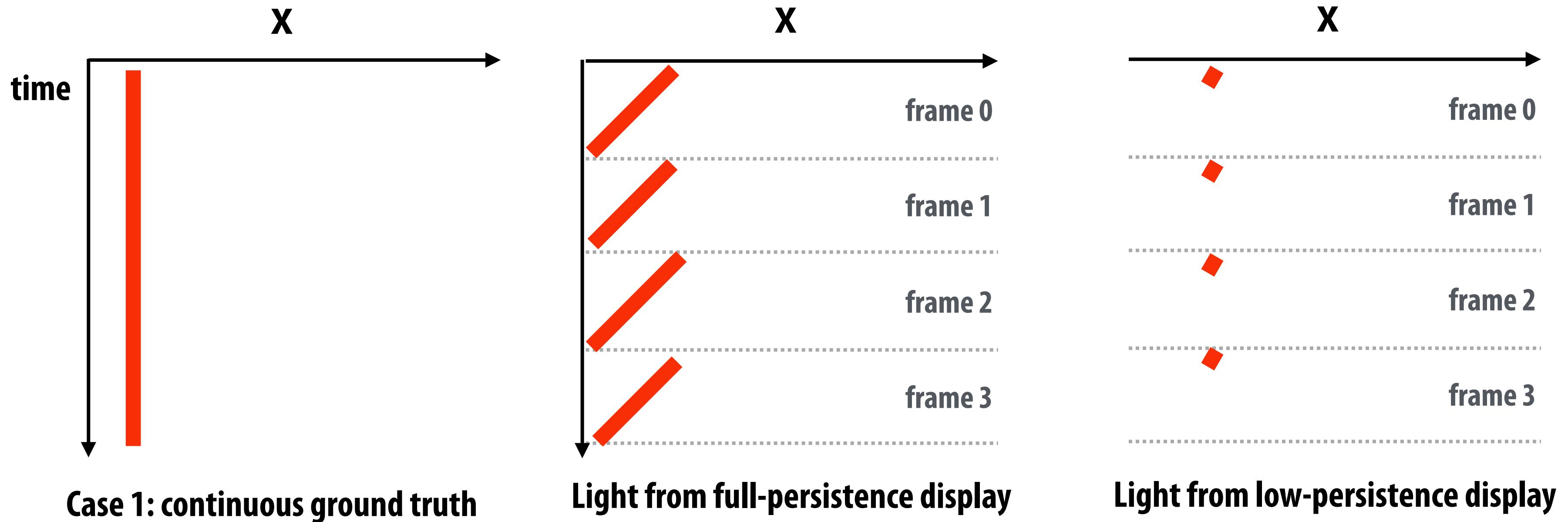


Explanation: since eye is moving, object's position is relatively constant relative to eye (as it should be, eye is tracking it). But due discrete frame rate, object falls behind eye, causing a smearing/strobing effect ("choppy" motion blur). Recall from earlier slide: 90 degree motion, with 50 ms latency results in 4.5 degree smear

# Reducing judder: increase frame rate



# Reducing judder: low persistence display



red object moving left-to-right and  
eye moving to track object

OR

red object stationary but head moving  
and eye moving to track object

Full-persistence display: pixels emit light for entire frame

Low-persistence display: pixels emit light for small fraction of frame

Oculus DK2 OLED low-persistence display

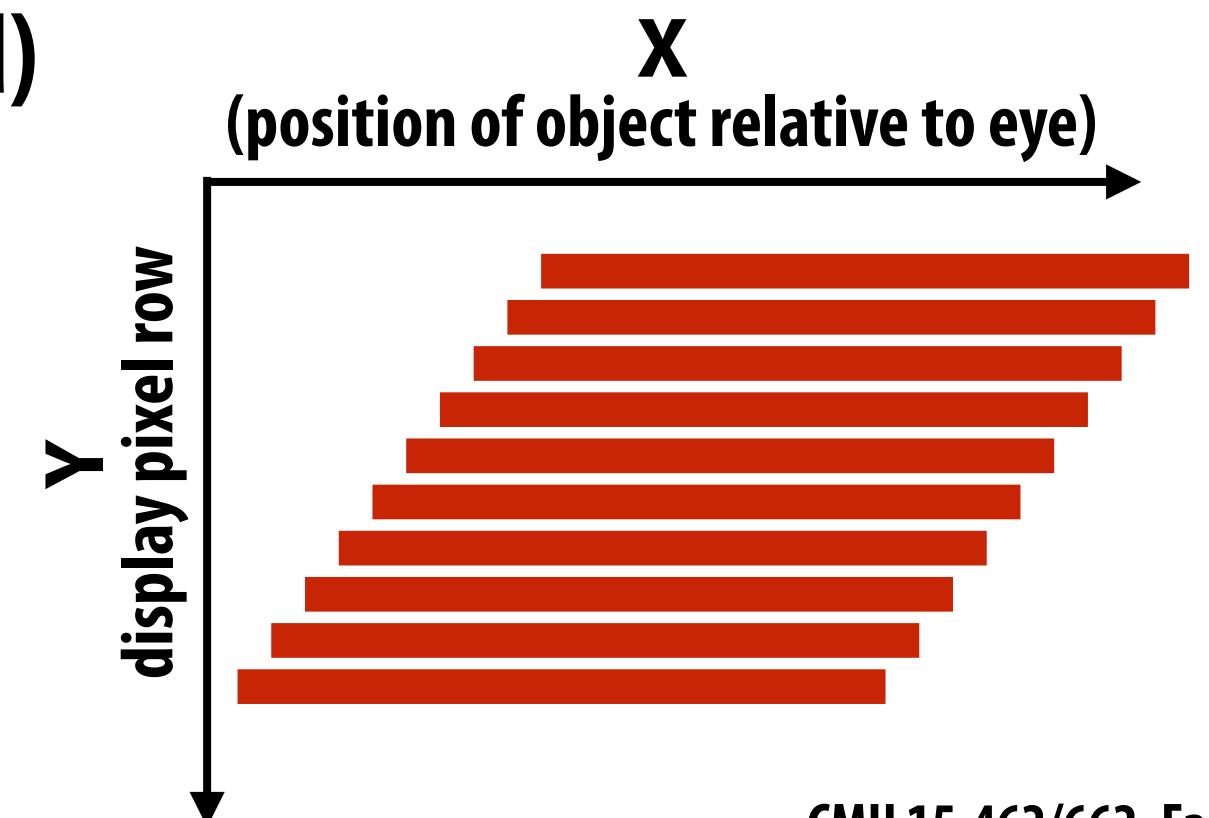
- 75 Hz frame rate (~13 ms per frame)
- Pixel persistence = 2-3ms

# Artifacts due to rolling OLED backlight

- Image rendered based on scene state at time  $t_0$
- Image sent to display, ready for output at time  $t_0 + \Delta t$
- “Rolling backlight” OLED display lights up rows of pixels in sequence
  - Let  $r$  be amount of time to “scan out” a row
  - Row 0 photons hit eye at  $t_0 + \Delta t$
  - Row 1 photons hit eye at  $t_0 + \Delta t + r$
  - Row 2 photons hit eye at  $t_0 + \Delta t + 2r$
- Implication: photons emitted from bottom rows of display are “more stale” than photons from the top!
- Consider eye moving horizontally relative to display (e.g., due to head movement while tracking square object that is stationary in world)

**Result: perceived shear!**

**Recall rolling shutter effects on modern digital cameras.**



# Compensating for rolling backlight

- Perform post-process shear on rendered image
  - Similar to previously discussed barrel distortion and chromatic warps
  - Predict head motion, assume fixation on static object in scene
    - Only compensates for shear due to head motion, not object motion
- Render each row of image at a different time (the predicted time photons will hit eye)
  - Suggests exploration of different rendering algorithms that are more amenable to fine-grained temporal sampling, e.g., ray caster? (each row of camera rays samples scene at a different time)

# Increasing frame rate using re-projection

- **Goal: maintain as high a frame rate as possible under challenging rendering conditions:**
  - Stereo rendering: both left and right eye views
  - High-resolution outputs
  - Must render extra pixels due to barrel distortion warp
  - Many “rendering hacks” (bump mapping, billboards, etc.) are less effective in VR so rendering must use more expensive techniques
- **Researchers experimenting with reprojection-based approaches to improve frame rate (e.g., Oculus’ “Time Warp”)**
  - Render using conventional techniques at 30 fps, reproject (warp) image to synthesize new frames based on predicted head movement at 75 fps
  - Potential for image processing hardware on future VR headsets to perform high frame-rate reprojection based on gyro/accelerometer

# Near-future VR system components

**Low-latency image processing  
for subject tracking**



**Massive parallel computation for  
high-resolution rendering**



**Exceptionally high bandwidth connection  
between renderer and display:  
e.g., 4K x 4K per eye at 90 fps!**

**High-resolution, high-frame rate,  
wide-field of view display**



**In headset motion/accel  
sensors + **eye tracker****



**On headset graphics  
processor for sensor  
processing and re-  
projection**

# Interest in acquiring VR content



**Google's JumpVR video:  
16 4K GoPro cameras**

**Consider challenge of:  
Registering/3D align video stream (on site)  
Broadcast encoded video stream across the  
country to 50 million viewers**

**Lytro Immerge**  
**(leveraging light field camera  
technology to acquire VR content)**



# **Summary: virtual reality presents many new challenges for graphics systems developers**

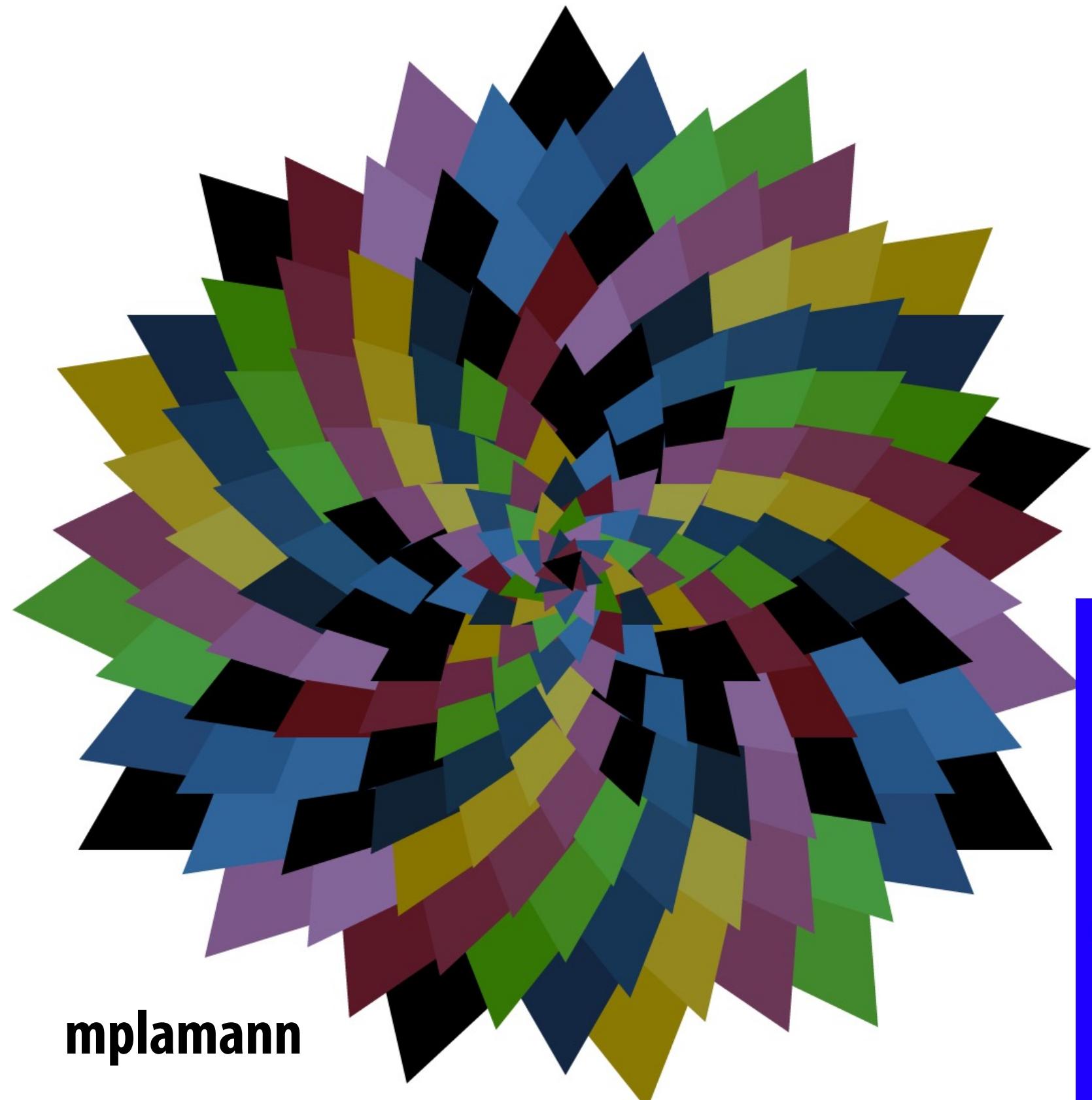
- **Major goal: minimize latency of head movement to photons**

- Requires low latency tracking (not discussed today)
  - Combination of external camera image processing (vision) and high rate headset sensors
  - Heavy use of prediction
- Requires high-performance rendering
  - High-resolution, wide field-of-view output
  - High frame-rate
  - Rendering must compensate for constraints of display system:
    - Optical distortion (geometric, chromatic)
    - Temporal offsets in rows of pixels

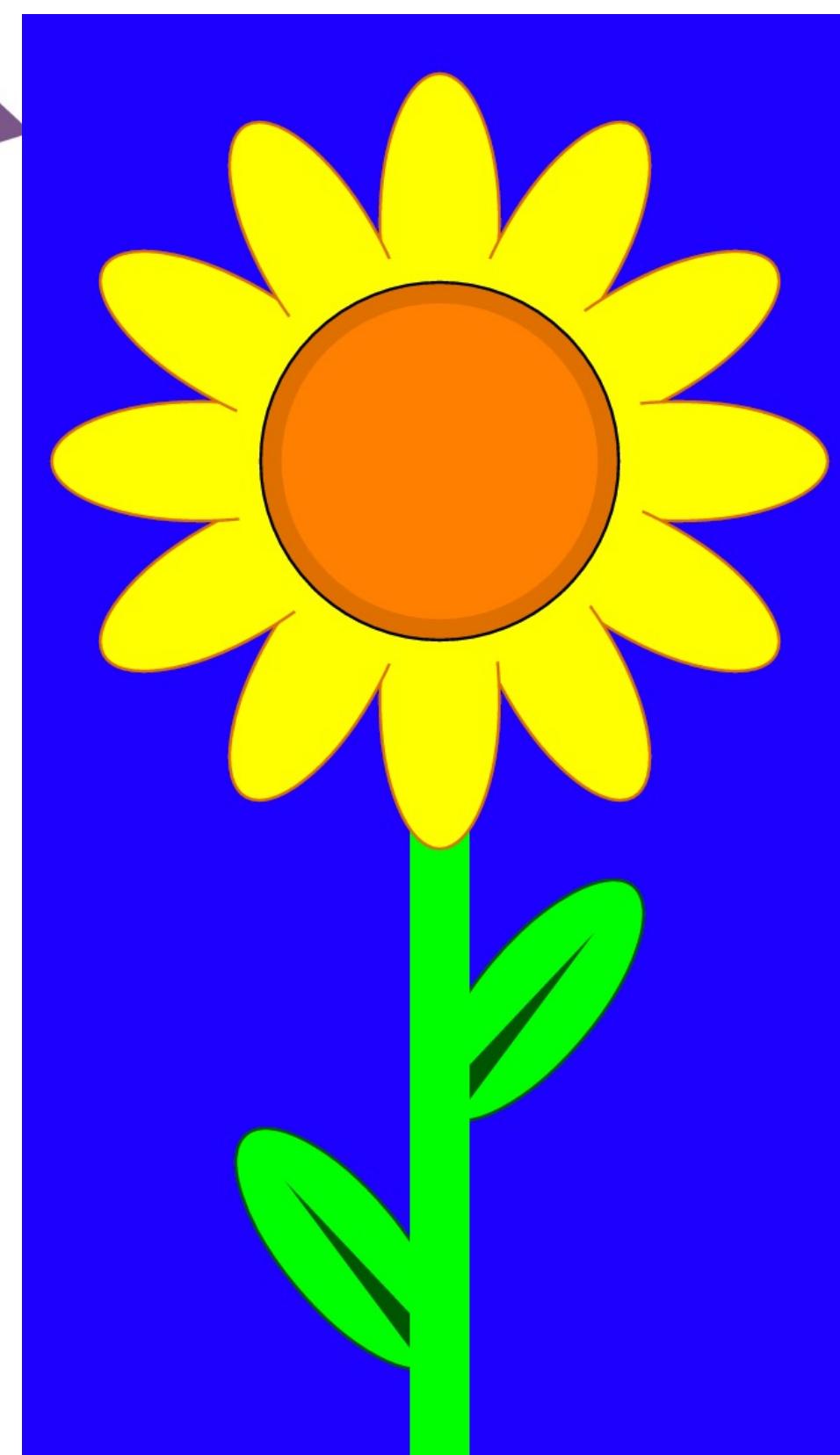
- **Significant research interest in display technologies that are alternatives to flat screens with lenses in front of them**

# **Course wrap up**

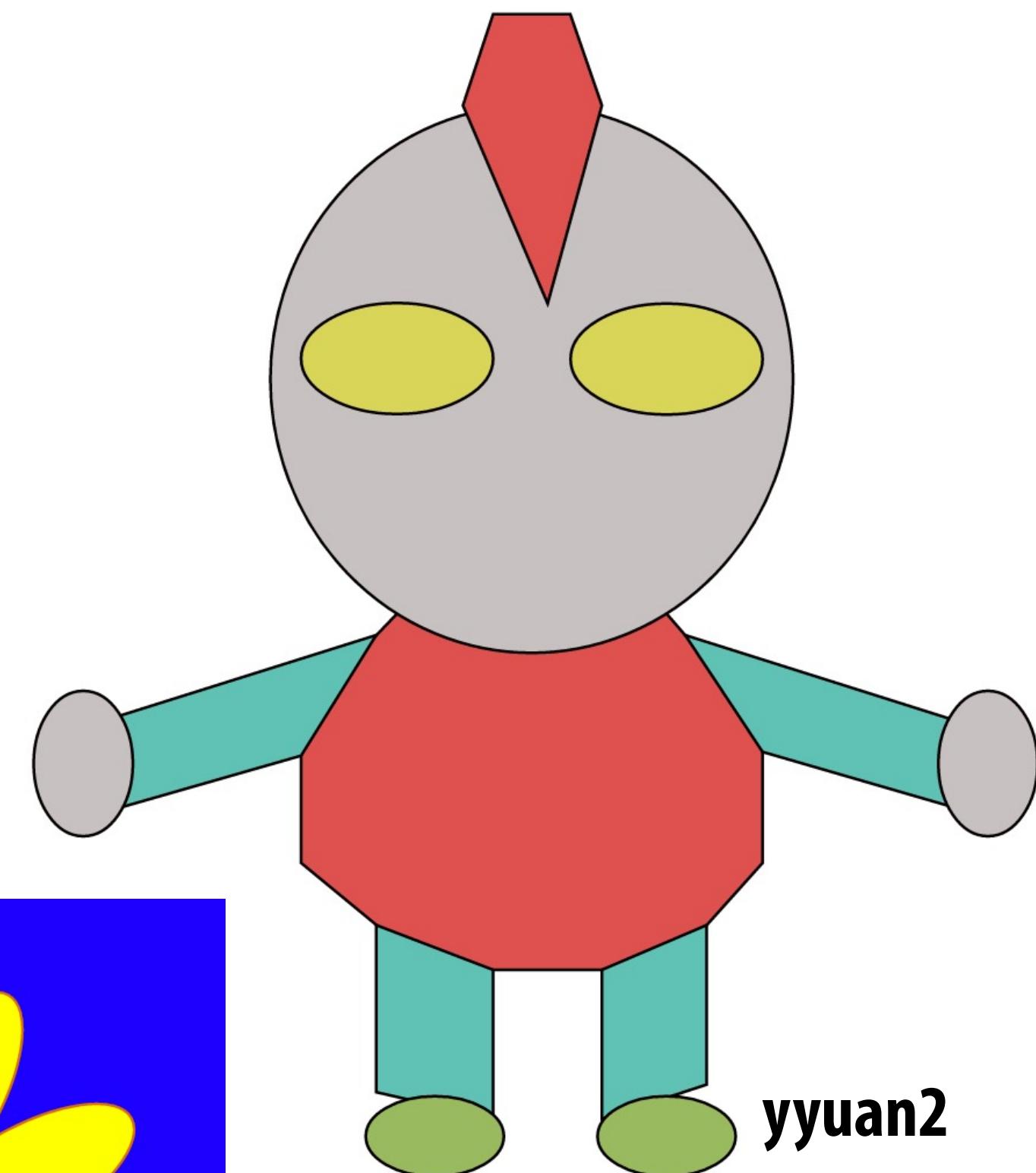
# Student project demo reel!



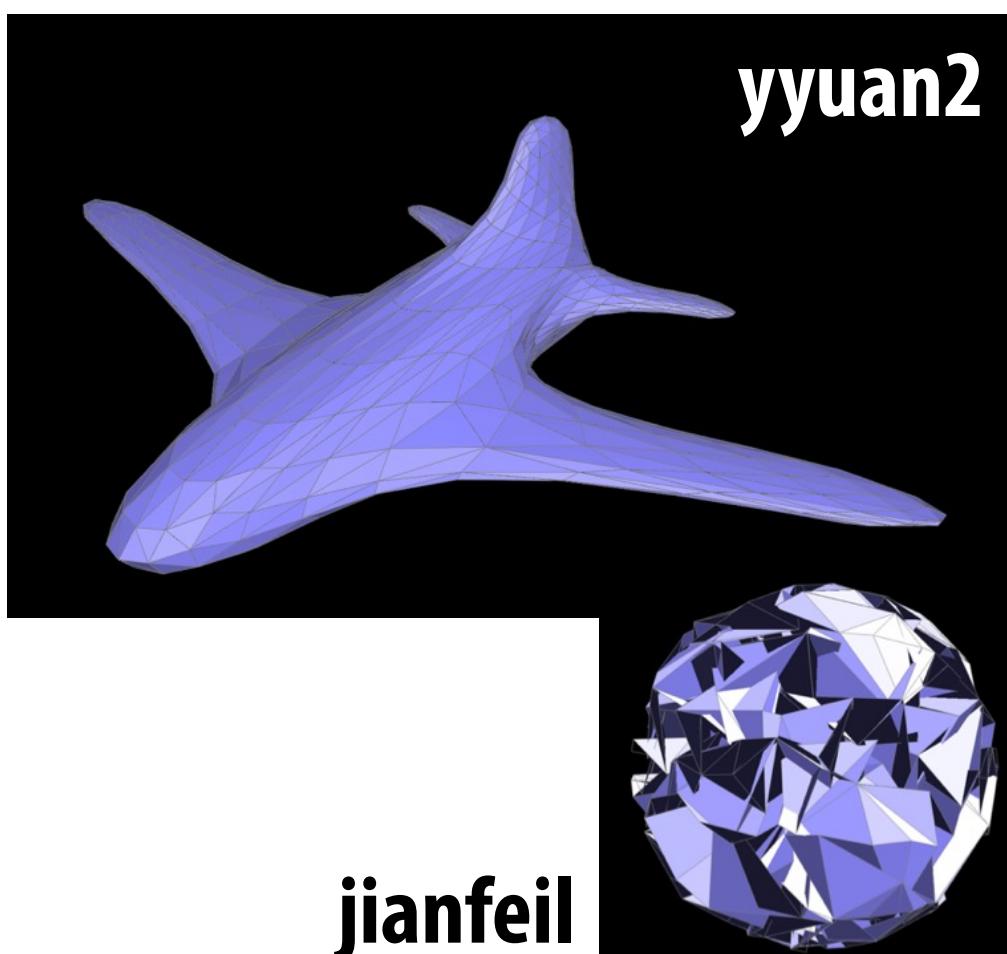
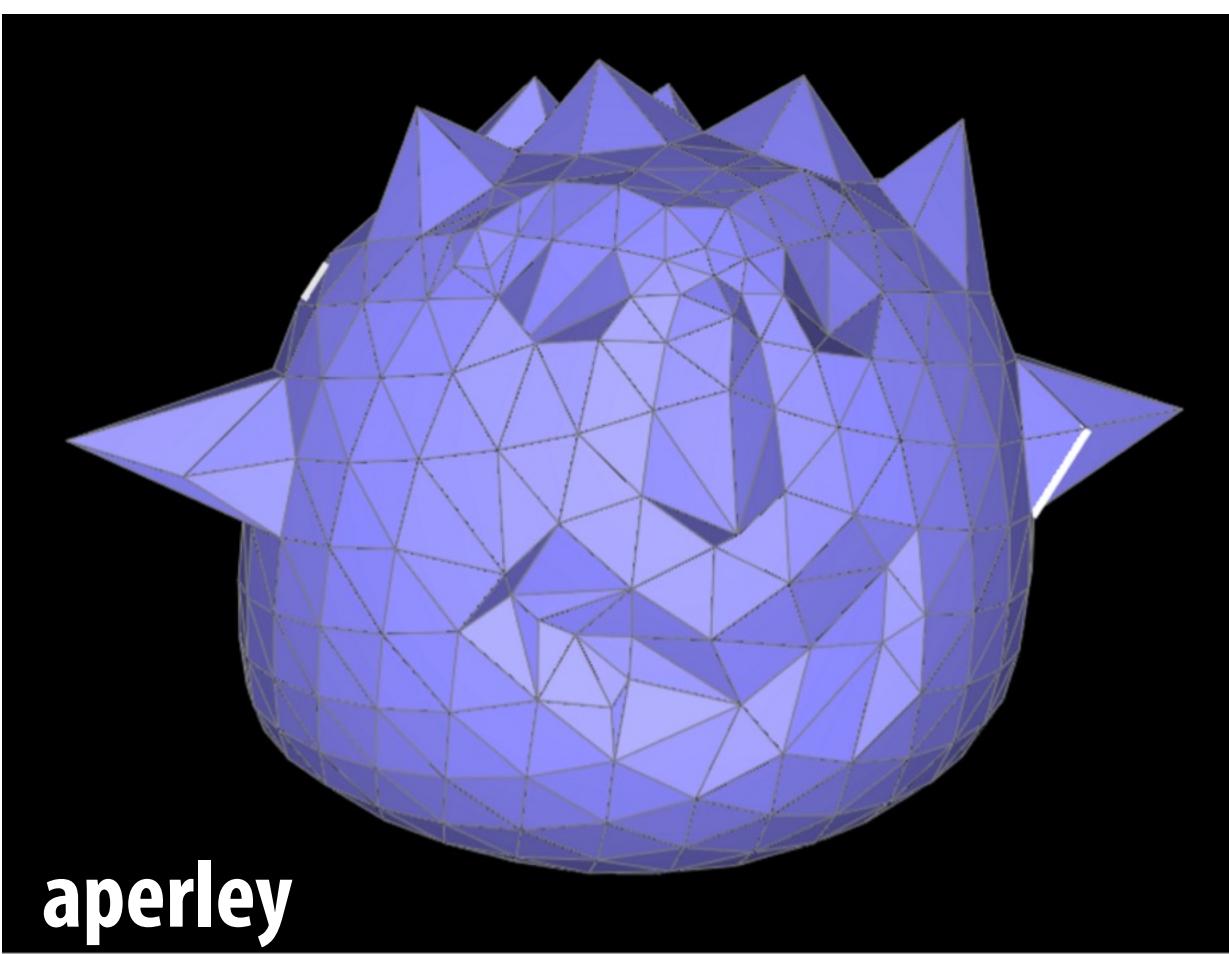
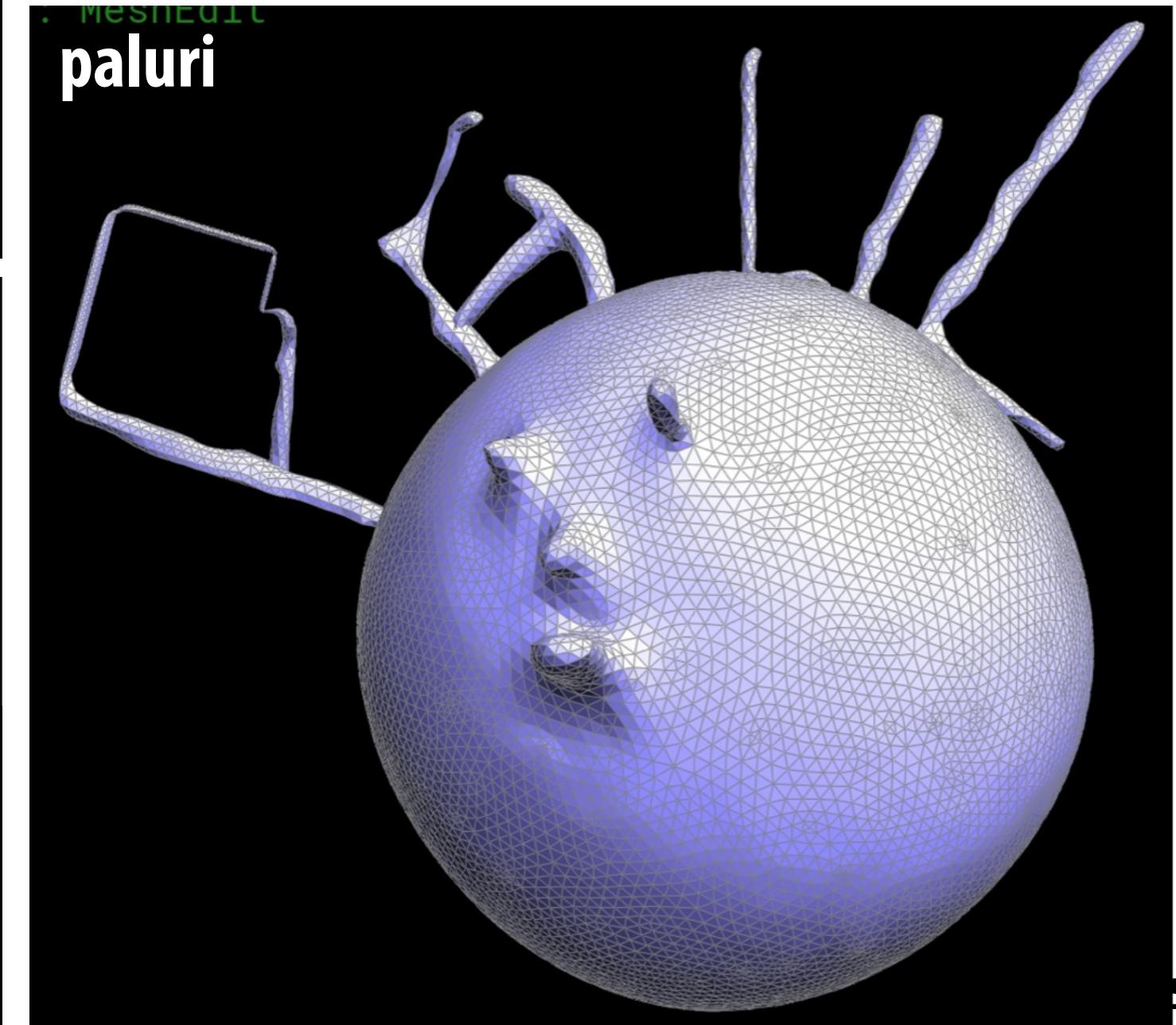
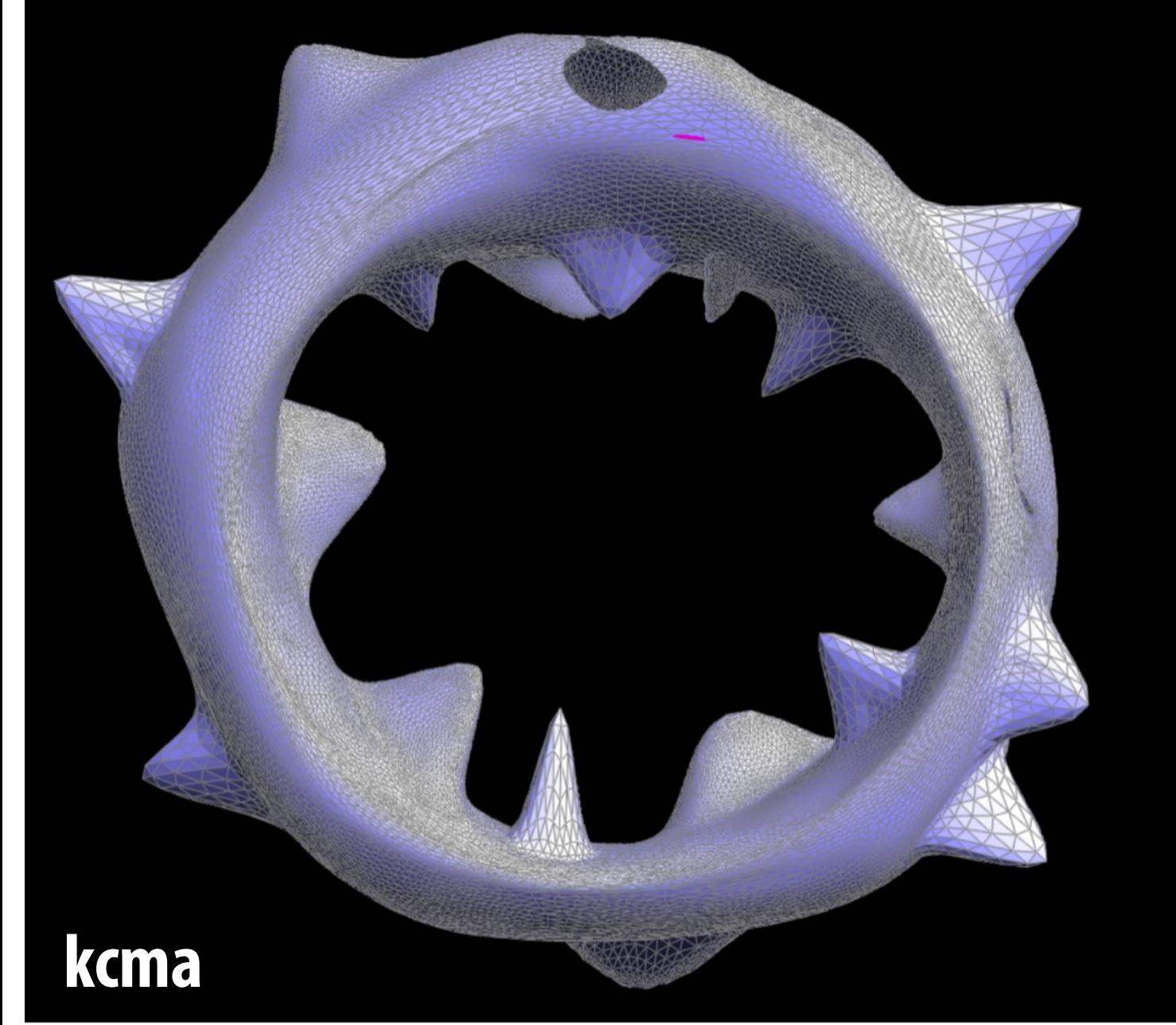
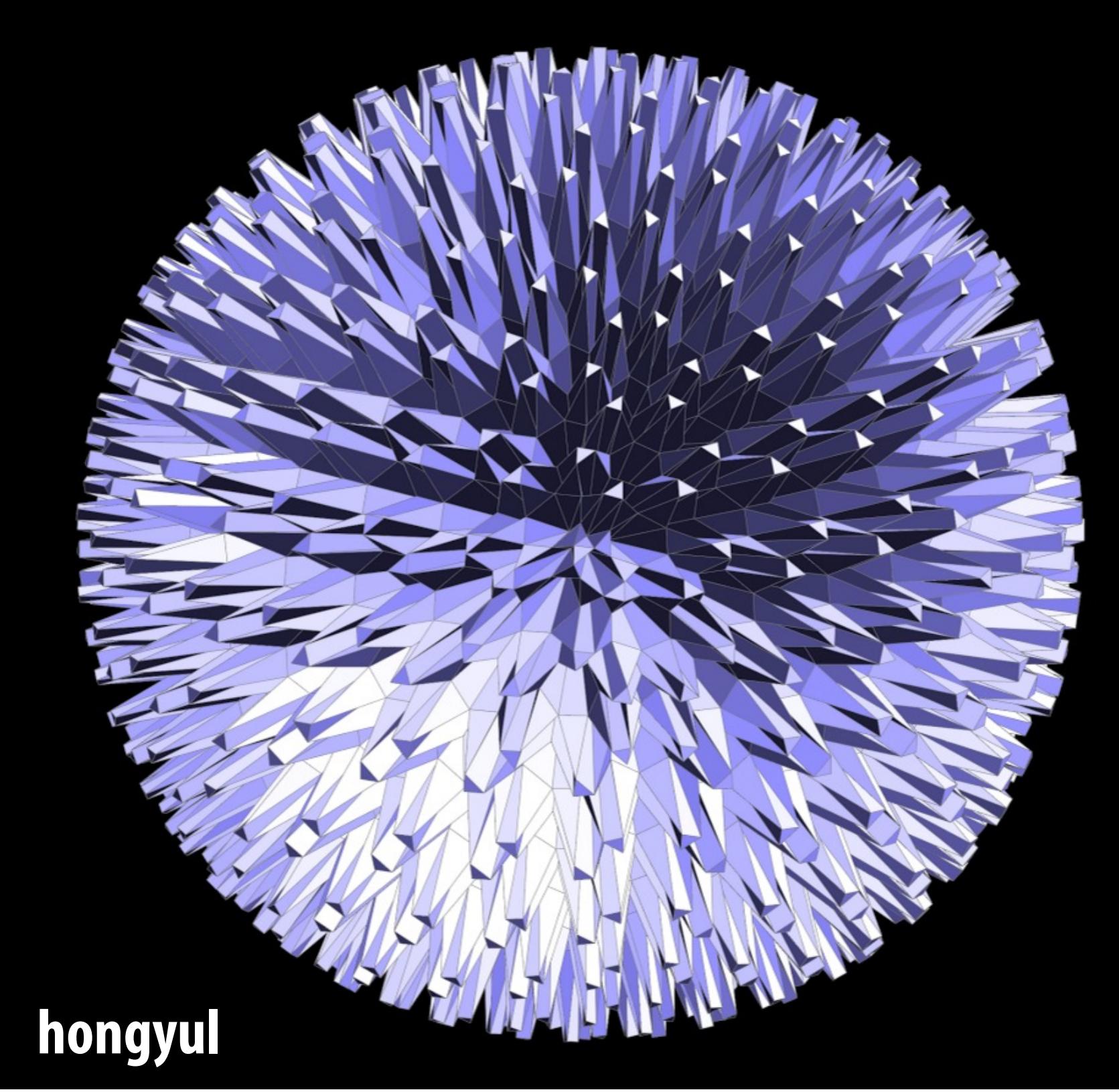
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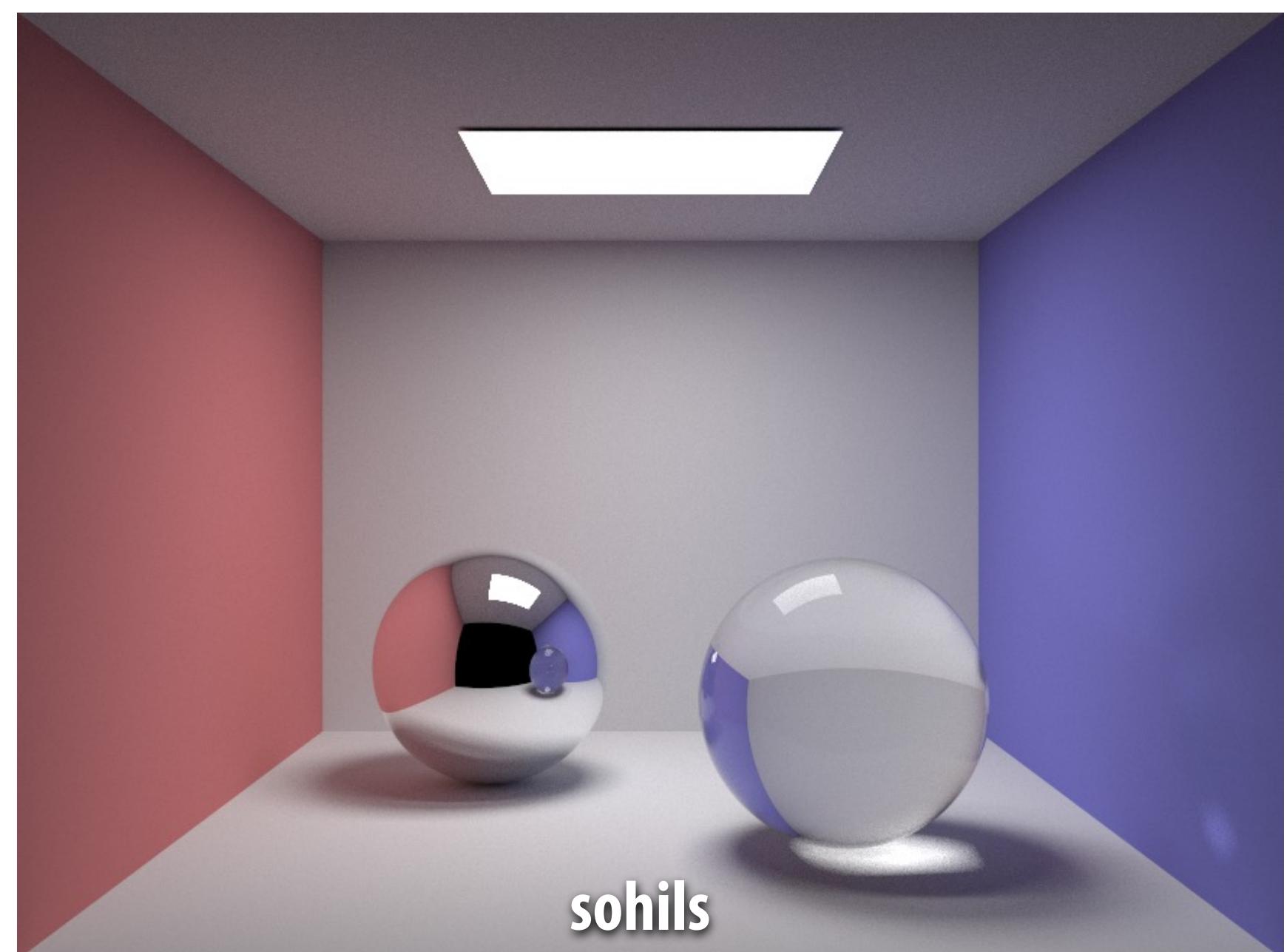
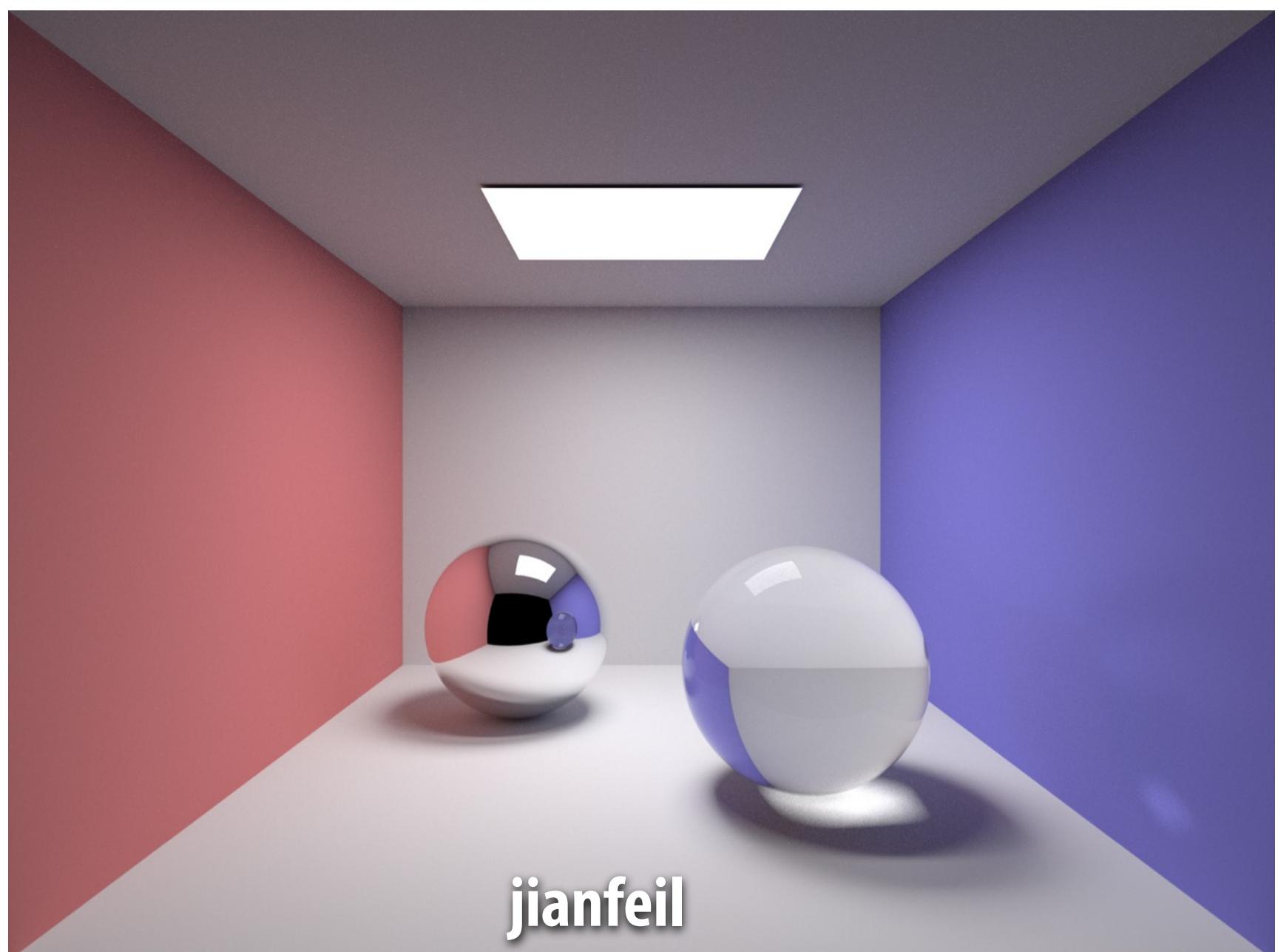
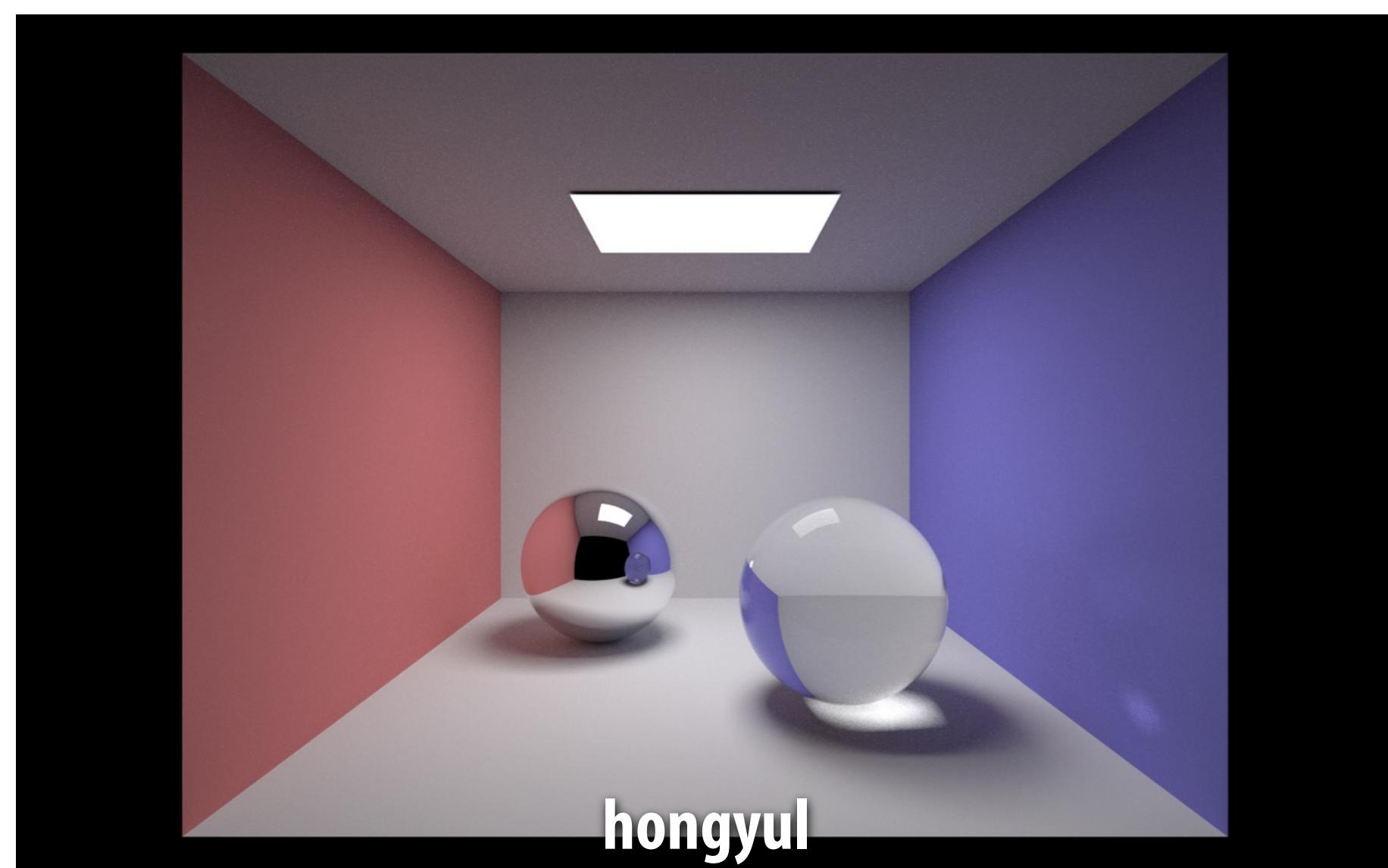
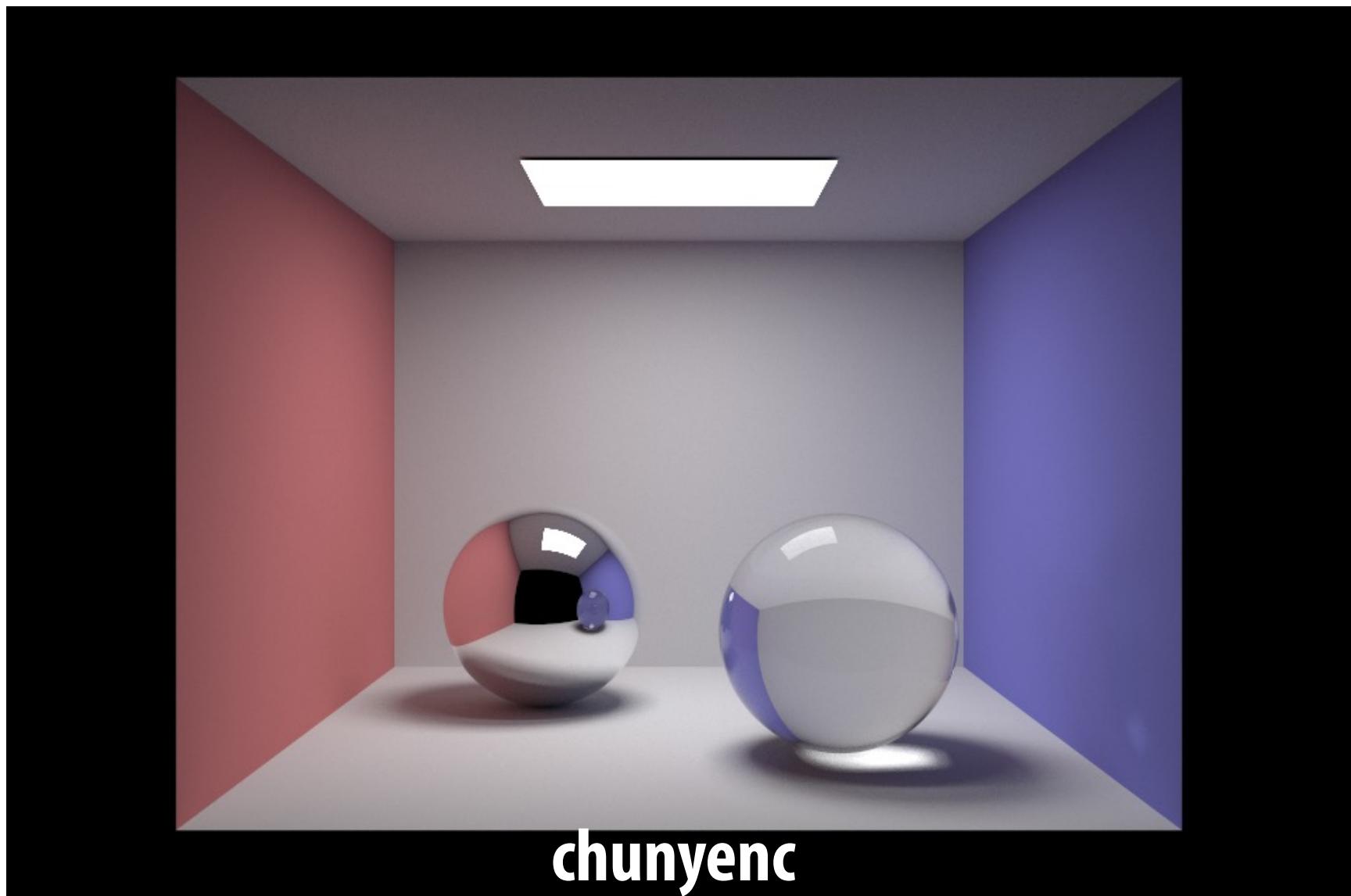
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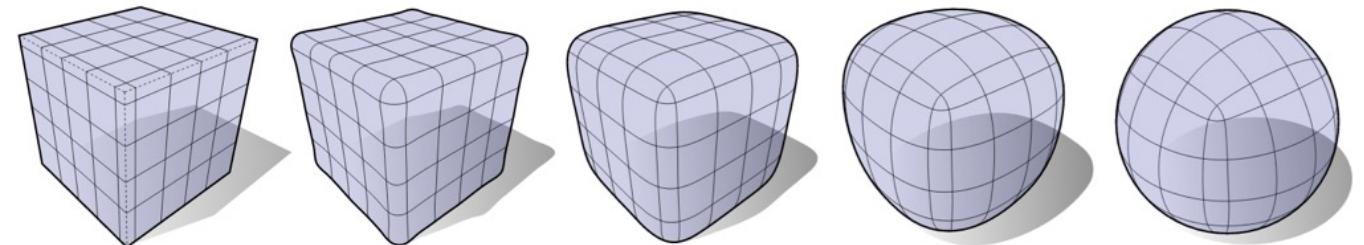


# Student project demo reel!



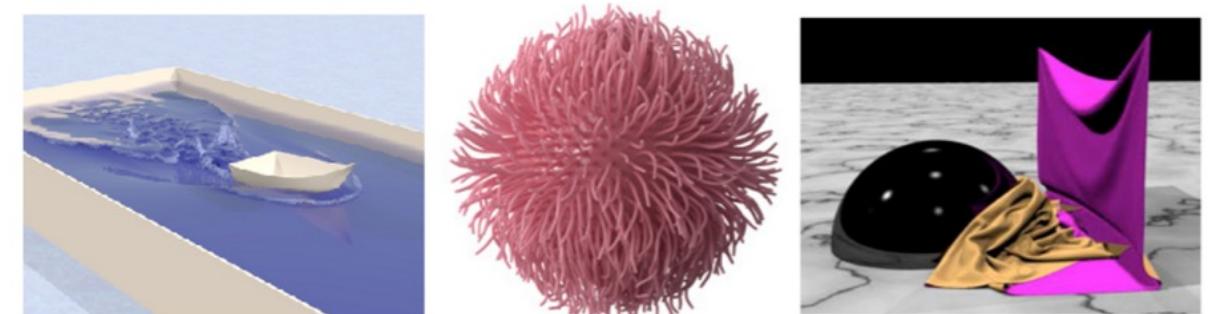
# Other cool graphics-related courses

- **15-869: Discrete Differential Geometry (Keenan Crane)**



- **15-463: Computational Photography**

- **15-467: Simulation Methods for Animation and Digital Fabrication (Stelian Coros)**



- **15-465: Animation Art and Technology (Hodgins/Duesing)**

- **15-661: Interaction and Expression using the Pausch Bridge Lighting**

- **15-418/618: Parallel Computer Architecture and Programming (Kayvon Fatahalian)**

# TAs and independent study!

- **15-462 next semester is looking for TAs!**
  - Email us if interested, and we'll direct you to Prof. Pollard
- **Students that did well in 462 have a great foundation for moving on to independent study or research in graphics**
  - Come talk to Keenan and I!

# Beyond assignments and exams

- Come talk to Keenan or I (or other professors) about participating in research!
- Consider a senior thesis!
- Pitch a seed idea to Project Olympus
- Get involved with organizations like Hackathon or ScottyLabs

**Thanks for being a great class!**

**See you on Monday! (study hard, but don't stress too much)**

