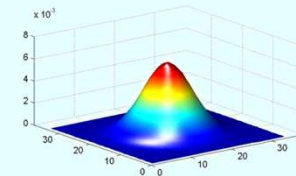


Non-parametric methods for PDF estimation

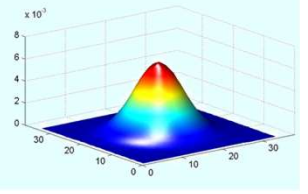


Bibliography

Density estimation for statistics & data analysis
Silverman, B.W. (1986) CRC press

See Google books

<http://books.google.es/books?vid=ISBN0412246201>

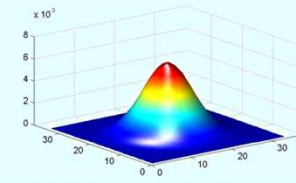


PDF estimation: goal

Obtain an estimation of the PDF from the data in the sample

Types of methods:

- **Parametric:** they start from a functional form of the PDF (e.g. a physical model) and fit its parameters using the sample (e.g. maximum likelihood)
- **Non parametric:** try to model the PDF without making any hypothesis about its functional form



For simplicity we will study the univariate case:

- Random variable

x

- PDF

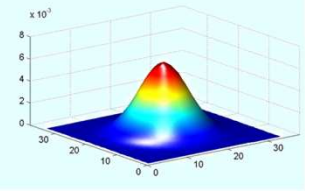
$f(x)$

- Probability

$$P(a < x < b) = \int_a^b f(x) dx$$

- Sample:

x_1, \dots, x_n

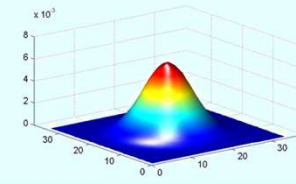


Histograms

- It's the oldest method and the most used
- Given an origin x_0 and a width h we count the objects inside each interval $[x_0+ih, x_0+(i+1)h]$ $i=0,1,2, \dots$
- We estimate the PDF as

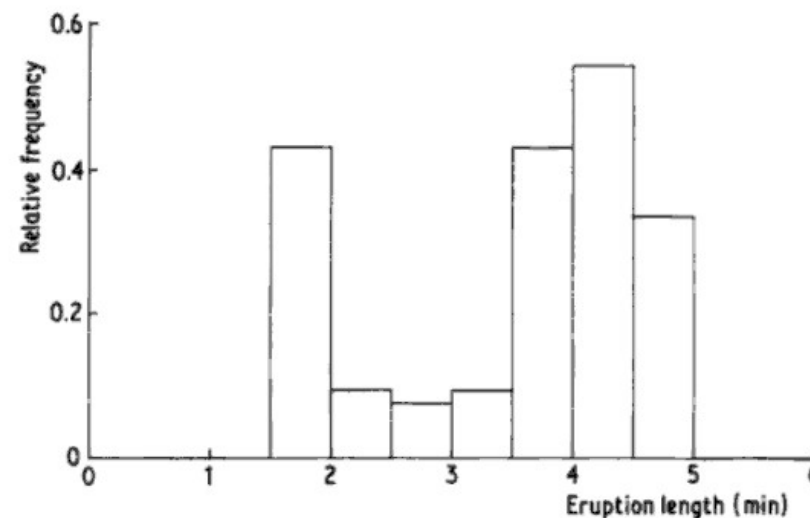
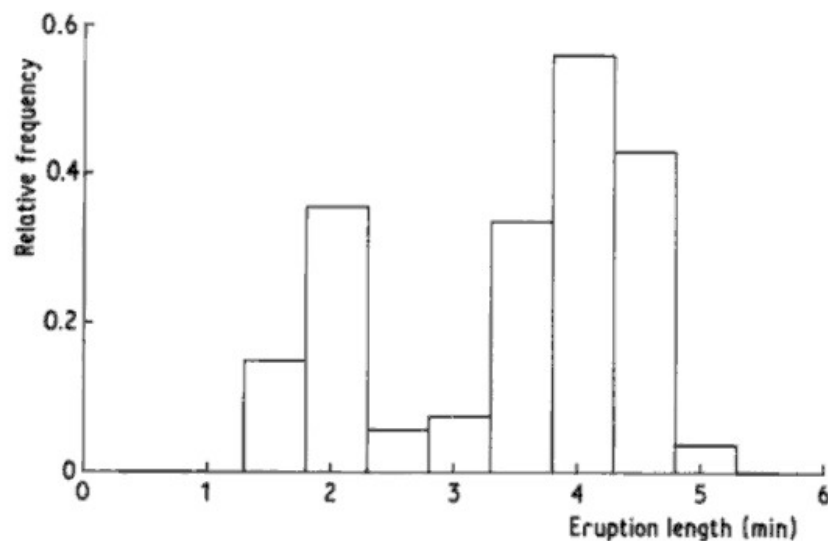
$$\hat{f}(x) = \frac{N_{obj}(x_0 + ih, x_0 + (i+1)h)}{nh}$$

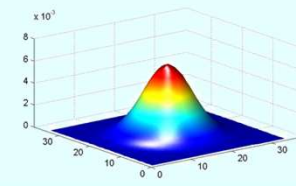
where n is the total number of objects



Disadvantages:

- Very convenient for 1D data, but unpractical for multidimensional data
- The estimation of the PDF is discontinuous
- Is very dependent of the origin and width chosen





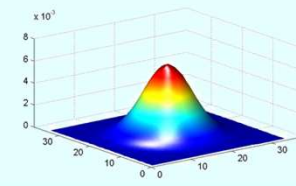
Simple estimator

- Starting from the definition of the PDF

$$f(x) = \lim_{h \rightarrow 0} \left(\frac{1}{2h} P(x - h < X < x + h) \right)$$

- We fix a small width h and define a “natural” estimator of the PDF

$$\hat{f}(x) = \frac{N_{obj}(x - h, x + h)}{2nh}$$



- It is usually expressed in the following way:

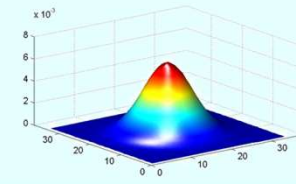
Weight function

$$w(\alpha) = \begin{cases} 1/2 & |\alpha| < 1 \\ 0 & \text{otherwise} \end{cases}$$

Estimator

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n w\left(\frac{x - x_i}{h}\right)$$

It is the sum over the sample of “boxes” centered in each one of the observations; is a kind of histogram where each point is the center of a sampling interval.

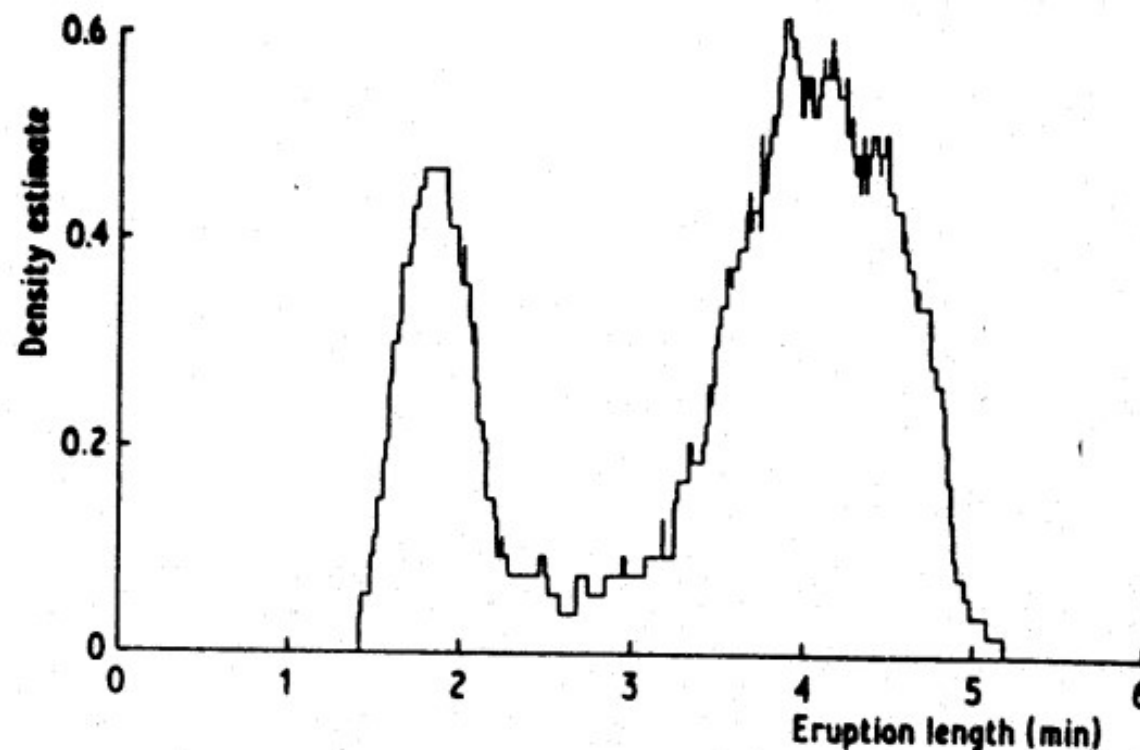


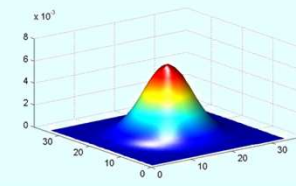
Advantages:

- It does not depend on any origin

Disadvantages:

- Depends of the chosen width h
- The estimation of the PDF is discontinuous





Kernel estimator

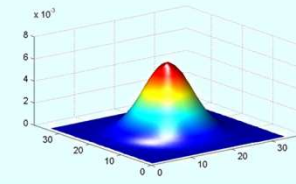
- Starting from the simple estimator, the weight function is substituted by a *kernel function* $\kappa(x)$ such that

$$\int_{-\infty}^{\infty} \kappa(x) dx = 1 \quad (\text{normalized})$$

and the estimator of the PDF is

$$\hat{f}(x) = \frac{1}{nh} \sum_{i=1}^n \kappa\left(\frac{x - x_i}{h}\right)$$

where h is the window width or smoothing parameter

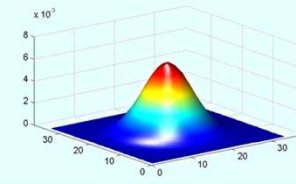


Advantages:

- This PDF estimator has all the continuity and differentiability properties of the kernel function

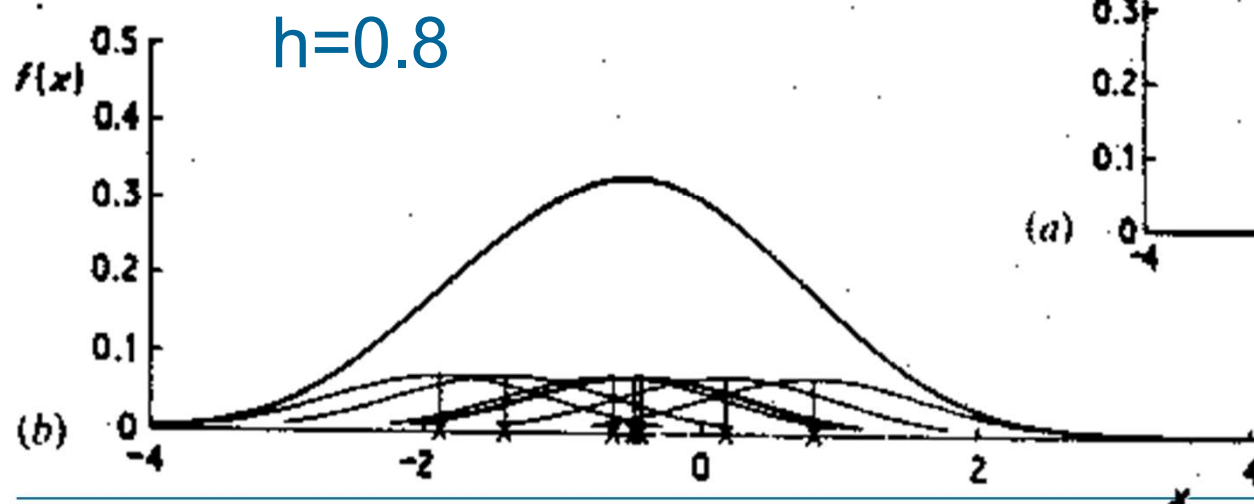
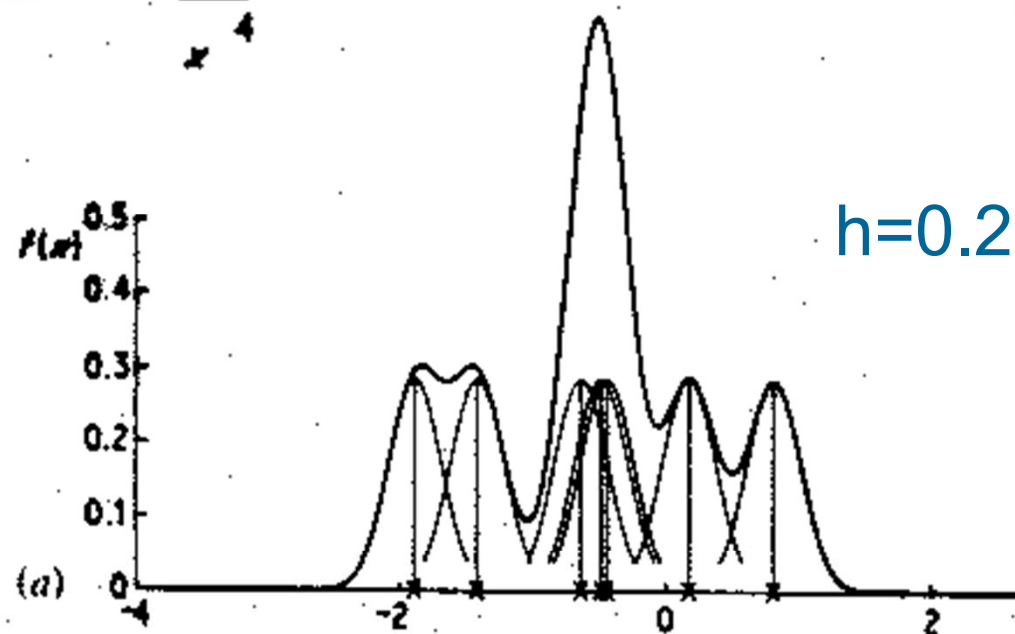
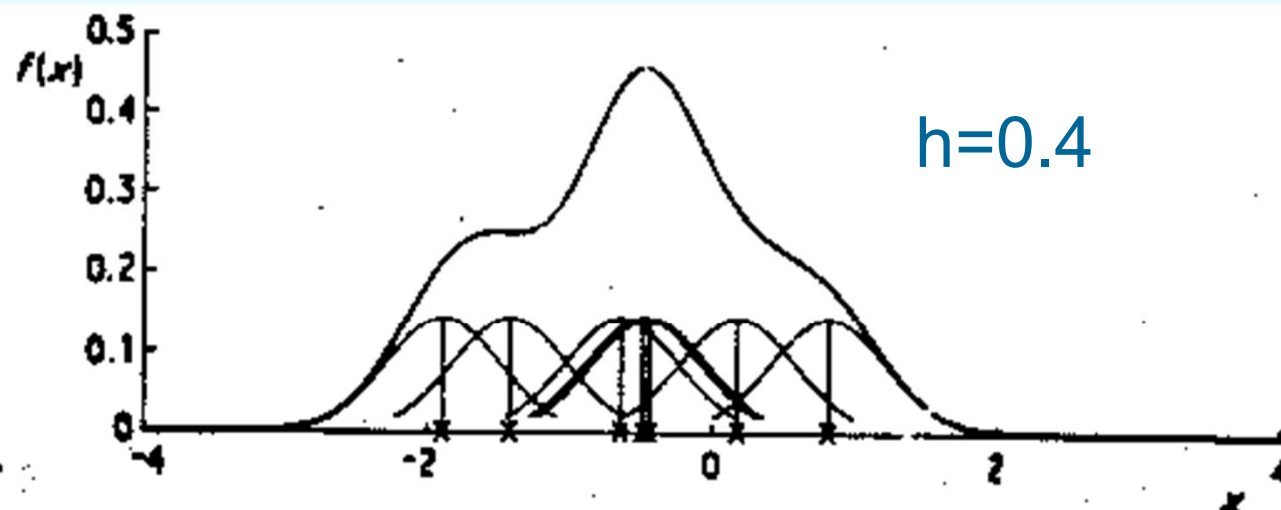
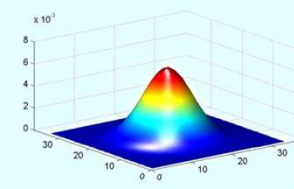
Disadvantages:

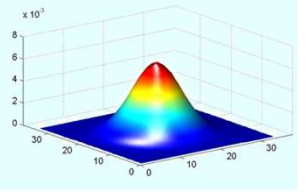
- Depends of the chosen width h
 - For sparse samples small values of h tend to produce spurious spikes
 - For large values of h the details of the PDF are lost (smoothed out)



Example:

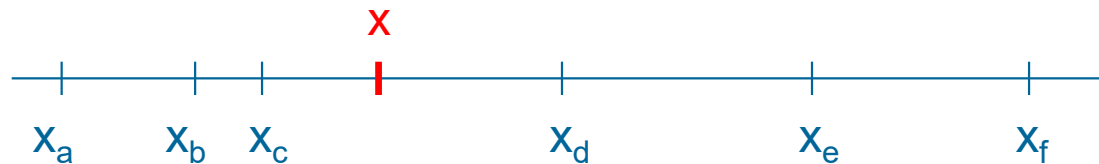
A gaussian kernel function: we are representing the PDF as a sum of gaussians centered in each one of the observations and a width determined by the h parameter





Nearest Neighbor estimator

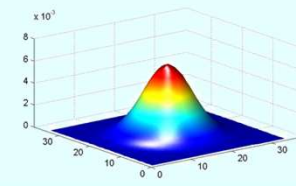
- Aims to adapt the smoothing to the local density of the data
- For each point x of the possible range of values calculate and sort the distances to the points in the sample



$$d_1 \leq d_2 \leq \dots \leq d_k \leq d_{k+1} \dots$$

- Choose the smoothing factor k , a small integer, typically

$$k \cong n^{1/2}$$



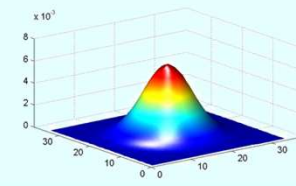
- Define the PDF estimator as

$$\hat{f}(x) = \frac{k}{2n d_k(x)}$$

The idea is that with this definition the density of observations in an interval $2d_k(x)$ around x is just k :

$$k = n 2d_k(x) f(x)$$

It's like defining a simple estimator where the “box” is variable and chosen so that there are k observations in it.

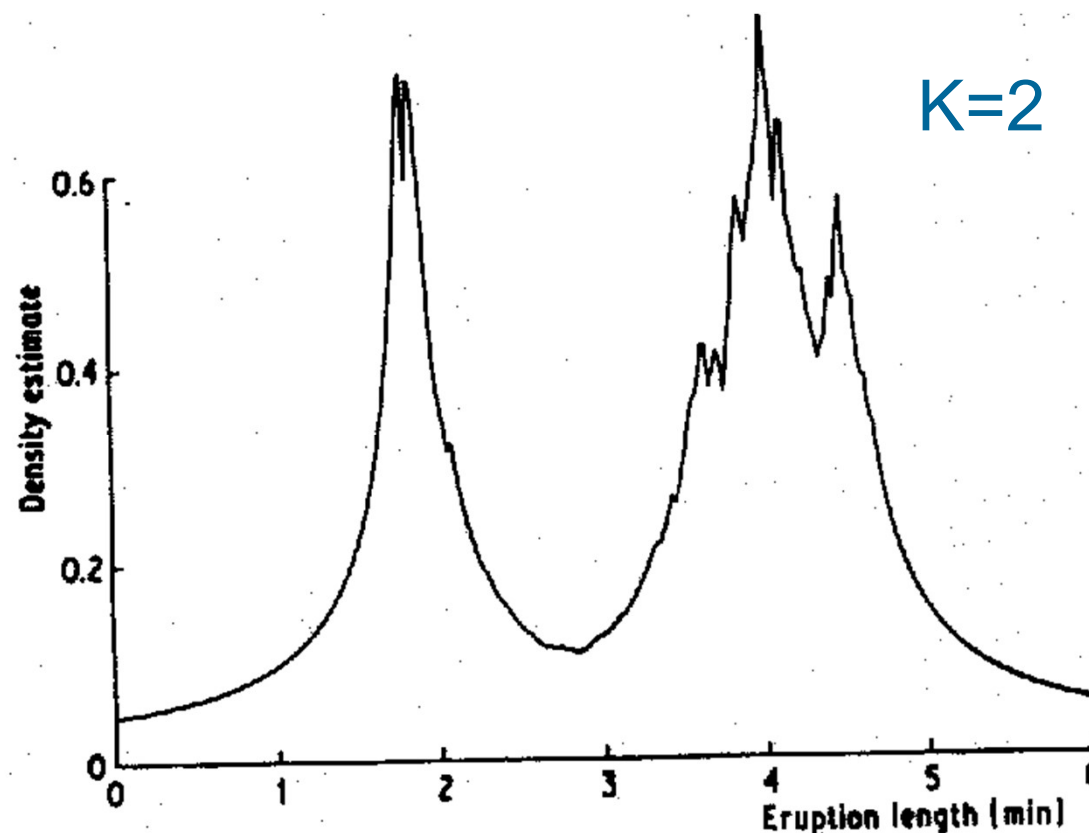


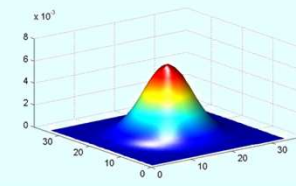
Advantages:

- It does not depend on the origin and k can be determined in a “natural” way as $n^{1/2}$

Disadvantages:

- It's continuous, but it
- may not be derivable



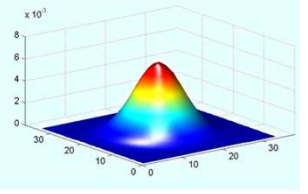


NN estimator with kernel

- We use the kernel functions in the NN method

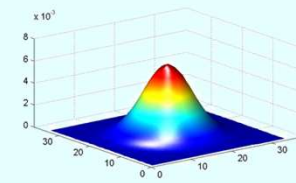
$$\hat{f}(x) = \frac{1}{n d_k(x)} \sum_{i=1}^n K\left(\frac{x - x_i}{d_k(x)}\right)$$

It's like the kernel estimator but with a variable h parameter that is self-adapted to each point.



Advantages:

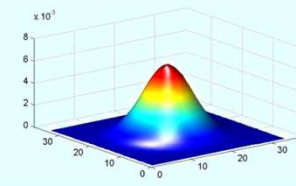
- Does not depend of any origin and k can be determined in a “natural” way as $n^{1/2}$
- Continuous and derivable



Question: which kernel function should we use?

Table 3.1. Some kernels and their efficiencies

Kernel	$K(t)$	Efficiency (exact and to 4 d.p.)
Epanechnikov	$\frac{3}{4}(1 - \frac{1}{3}t^2)\sqrt{5}$ for $ t < \sqrt{5}$, 0 otherwise	1
Biweight	$\frac{15}{8}(1 - t^2)^2$ for $ t < 1$, 0 otherwise	$\left(\frac{3087}{3125}\right)^{1/2} \approx 0.9939$
Triangular	$1 - t $ for $ t < 1$, 0 otherwise	$\left(\frac{243}{250}\right)^{1/2} \approx 0.9859$
Gaussian	$\frac{1}{\sqrt{2\pi}} e^{-(1/2)t^2}$	$\left(\frac{36\pi}{125}\right)^{1/2} \approx 0.9512$
Rectangular	$\frac{1}{2}$ for $ t < 1$, 0 otherwise	$\left(\frac{108}{125}\right)^{1/2} \approx 0.9295$

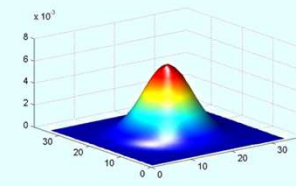


The properties of the kernel methods are well known:

- Biases
- Error of the estimator
- Optimisation techniques to choose the best smoothing factor

See Silverman (1986) for a discussion. Specifically see the **discrepancy measures between an estimator and the PDF**

$$MSE_x(\hat{f}) = E \left\{ \left(\hat{f}(x) - f(x) \right)^2 \right\}$$

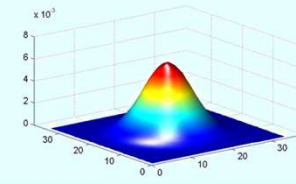


Extension of the kernel methods to multivariate data

$$\int_{\mathbb{R}^n} \kappa(\vec{x}) d\vec{x} = 1$$

$$\hat{f}(\vec{x}) = \frac{1}{n h^d} \sum_{i=1}^n \kappa\left(\frac{\vec{x} - \vec{x}_i}{h}\right)$$

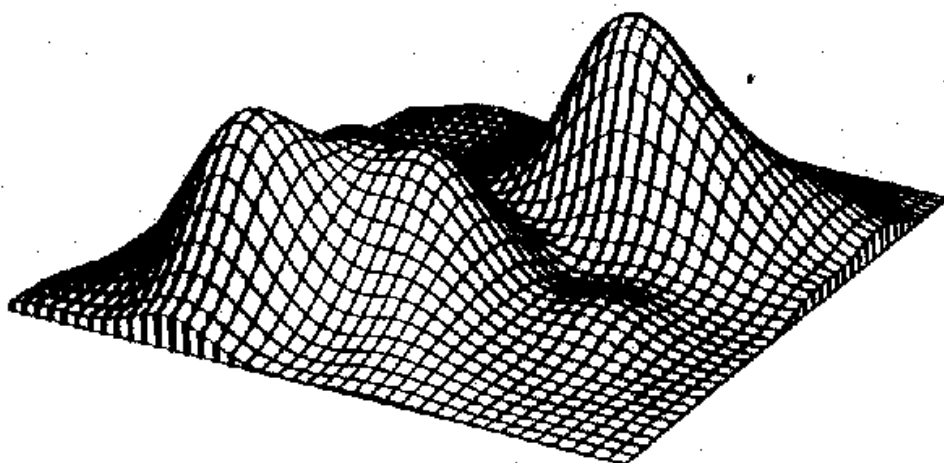
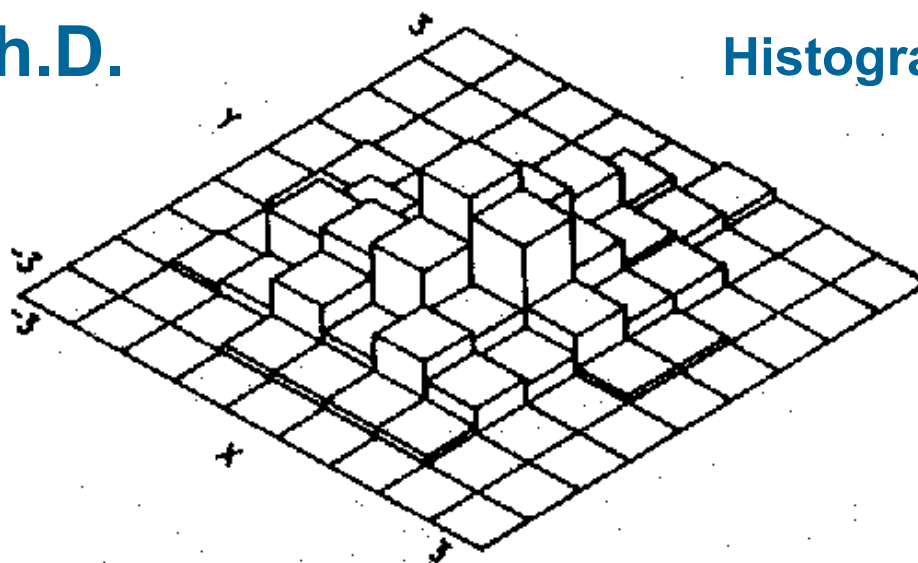
The use of a single smoothing coefficient is
 usually enough if the data have been
 standardized



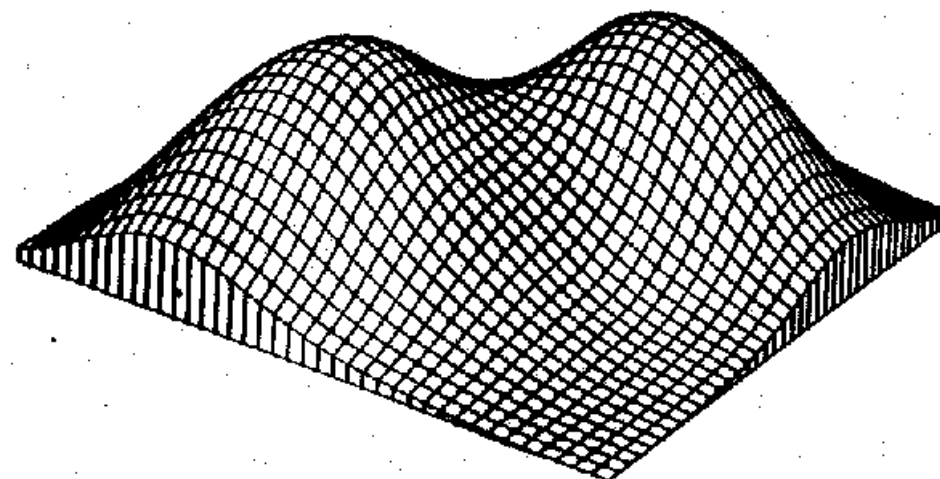
Example from R. Asiain Ph.D.

Bivariate normal distributions

Histogram



Kernel estimation $h=1.2$



Kernel estimation $h=2.2$