d)
$$\frac{du}{dt} = \frac{\alpha}{|+v^n} - u$$
 $\frac{dv}{dt} = \frac{\alpha}{|+u^n} - v$

$$\frac{d}{dt} \left(\begin{array}{c} u \\ v \end{array} \right) = Jacobian matrix \overrightarrow{J} \left(\begin{array}{c} u \\ v \end{array} \right)$$

$$\frac{d}{dt} \left(\begin{array}{c} u \\ v \end{array} \right) = \left(\begin{array}{c} -1 & \frac{d n v^{n-1}}{c(t+v^n)^2} \\ \frac{d n v^{n-1}}{c(t+v^n)^2} & -1 \end{array} \right) \left(\begin{array}{c} u \\ v \end{array} \right)$$

At S.S.
$$\frac{du}{dt} = 0$$
 of $\frac{dw}{dt} = 0$

$$\frac{du}{dt} = \frac{\alpha}{Hv_s} - u = 0 \Rightarrow \frac{\alpha}{Hv_s} = u_s \quad (1)$$

$$\frac{dv}{dt} = \frac{\alpha}{Hu^n} - V = 0 \quad \Rightarrow \quad \frac{\alpha}{Hu^n_s} = V_s \quad (2)$$

$$\frac{d}{1+\left(\frac{\alpha}{1+u_s^2}\right)^n}=u_s$$

$$\frac{1}{J} = \left(\frac{dn v_s^{h-1}}{(1+v_s^h)^2} \right)$$

Find eigenvalues:

$$(-1-\lambda)(-1-\lambda) - \frac{dnv_s^{n-1}}{(1+v_s^n)^2} \cdot \frac{dnv_s^{n-1}}{(1+v_s^n)^2} = 0$$

$$tr(\vec{J})=-2$$
, $det(J)=(-\frac{\alpha^2 n^2 V_s \cdot w_s}{(1+V_s^n)^2(1+V_s^n)^2})$

when tr(j) <0 and det (j)>0, then system is stable

Following the criterion,
$$\text{tr}(\vec{j}) = -2 < 0$$

 $\det(j) = 1 - \frac{\alpha^2 n^2 v_s^{n-1} u_s^{n-1}}{(1 + v_s^n)^2 (1 + u_s^n)^2} > 0$

(I+ Vs") CI+ Us") >0 => (1+Vs") (1+ us") - 2 n' (Vs Us) -1 >0 => (1+1/5")2(1-26")2-22" (1/5 Us) 1-1 > 0 (It us")2 At center S.S. Vs= Us $(1 + 1)^{4} - d^{2}n^{3} \sqrt{s} > 0$ ⇒ (1+ Vsn)4 > (dn Vsn-1)2 => (I+ 1/5") > & N 1/6" For a stable system, the influence of degree of coorporativity and rate of $\lambda_{\pm} = \frac{\text{tr}(\vec{j}) \pm \sqrt{\text{tr}(\vec{j})^2 - 4\text{det}(\vec{j})}}{2}$

synthesis follow the eqn. (It is) > xn vs n-1 For example: n=1 d=1 (It V_S) $^2 > 1$ { HVs $> 1 \Rightarrow V_S > 0$ $1+V_S < 1 \Rightarrow V_S < -2$ (unrealistic)

 $tr(\vec{j})=-2$, $det(j)=(-\frac{\alpha^2 n^2 V_5 u_5^{n-1}}{(1+V_5^n)^2(1+V_5^n)^2}$

tor center steady state, x=10, n=1 us=vs $\det(J) = \left(-\frac{\alpha^2 n^2 V_s^2 v_s^{n-1}}{(1+V_s^n)^2 (1+V_s^n)^2} = \left(-\frac{(00 \times 1 \times 1 \times 1)}{(1+V_s)^2 (1+V_s^n)^2}\right)$

read from tigure $= \left[-\frac{100}{(1+1/5)^2(1+1/5)^2} \right]$ From n=1 d=10 figure, there's one point: Us=76 & 25

det (j)= 1- (00 = -7.16

$$\lambda_{\pm} = \frac{-2 \pm \sqrt{(-2)^2 + 4 \times 7.16}}{2} = \frac{-2 \pm 5.71}{2}$$

$$\lambda_{+} = 1.855$$
 $\lambda_{-} = -3.855$

Since both of them are negotive, it's stable

For center steady state, x=10 n=2 Us=Us

$$\det(J) = 1 - \frac{\alpha^2 n^2 V_s u_s}{(1 + V_s^n)^2 (1 + U_s^n)^2} = 1 - \frac{100 \times 4 \times V_s \times u_s}{(1 + V_s^2)^2 (1 + U_s^2)^2}$$

From n=2 d=10 figure. I read three point v=10,0,2

For Us \$10

$$\det(J) = 1 - \frac{400 \times 10 \times 10}{(1 + 10^{2})^{2} (1 + 10^{2})^{2}} = 1 - \frac{40000}{104060401} = 0.9996$$

$$\lambda_{\pm} = \frac{-2 \pm \sqrt{(-2)^2 - 4 \times 0.999b}}{2} = \frac{-2 \pm 0.04}{2}$$

$$\lambda_{+} = \frac{-2 + 0.04}{2} = -0.98$$
 $\lambda_{-} = \frac{-2 - 0.04}{2} = -1.02$

Since both of them are regotive, it's stable

For Us 20

$$det(J) = 1 - \frac{0}{(2+1)^2} = 1$$

$$y_{t} = \frac{2}{-5 \pm \sqrt{(-5)^{2} - 4 \times 0}} = \frac{2}{-5 \pm 5}$$

$$\lambda_{+} = \frac{2}{-2+2} = 0$$
 $\lambda_{-} = \frac{2}{-2-2} = -4$

Since there's no positive X, it's stable.

$$\det(J) = (-\frac{400 \times 2 \times 2}{(1+2^2)^2} = (-\frac{1600}{625} = -1.56)$$

$$\lambda \pm = \frac{-2 \pm \sqrt{(-2)^2 + 4 \times 1.56}}{2} = \frac{-2 \pm 3 \times 2}{2}$$

$$\lambda_{+} = \frac{2}{-2+3\cdot 2} = 0.6$$
 $\lambda_{-} = \frac{2}{-2\cdot 3\cdot 2} = -2.6$

Since there's one positive
$$\lambda$$
, it's unstable