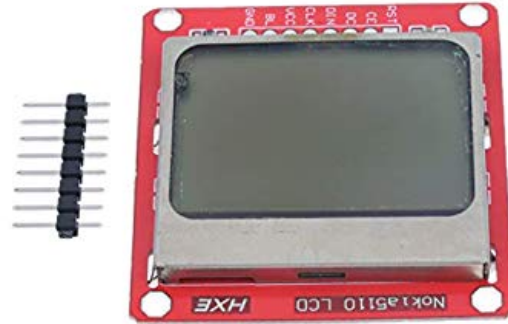


GPS module communication

BPC-DE2 Project

Created by: Jan Malucha, Richard Panáček, Michal Pernica



Modules

- GPS module PA6H (Drotek Electronics)
- Display Nokia 5110
- Microcontroller Arduino UNO (ATmega328P)

Connecting Modules

Connections between Display and Arduino

RST to PB1

SCE to PB2

DC to PB3

DIN to PB4

CLK to PB5

Power delivery with 3.3 V

Led Backlight to GND

GND to GND

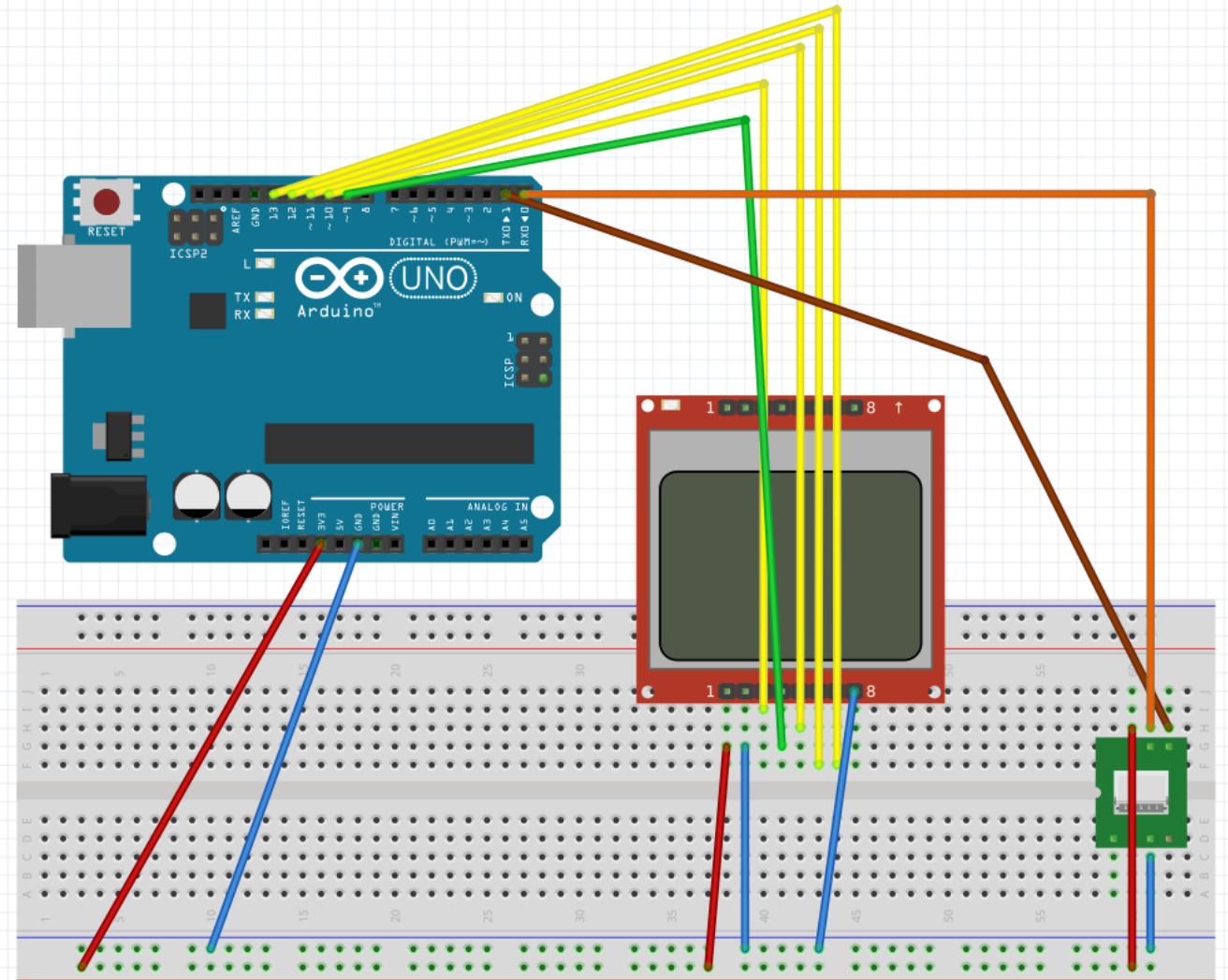
Connections between GPS and Arduino

Rx to Tx (PD1)

Tx to Rx (PD0)

Vin to 3.3 V

GND to GND



Requirements of the projects:

Communication
with GPS Data

Storage with export
to PC

Displaying data on
the Nokia 5110
display

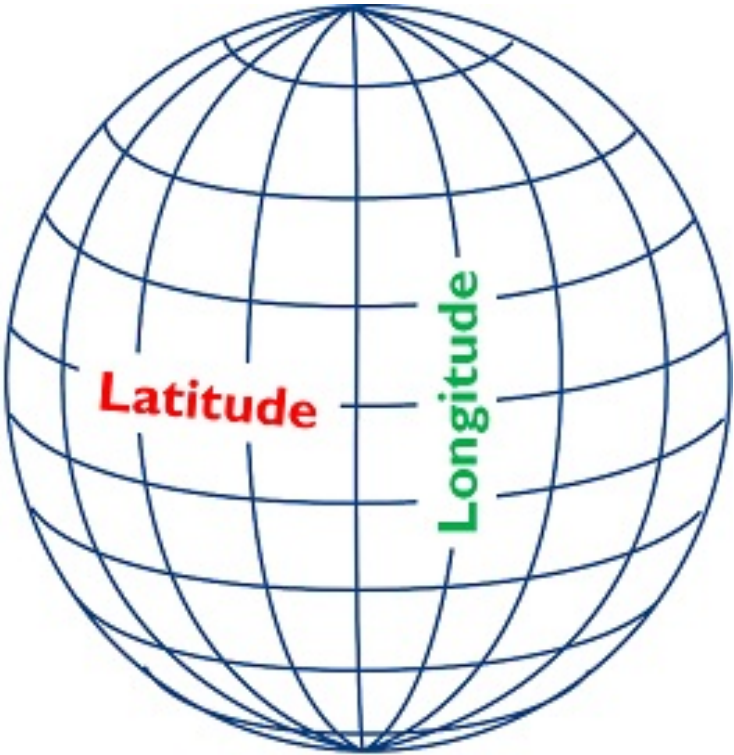
NMEA sentences

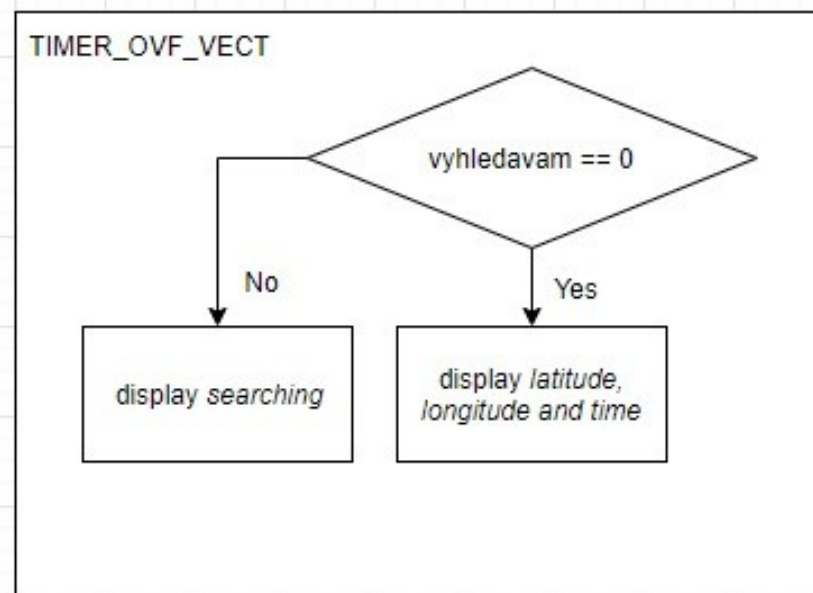
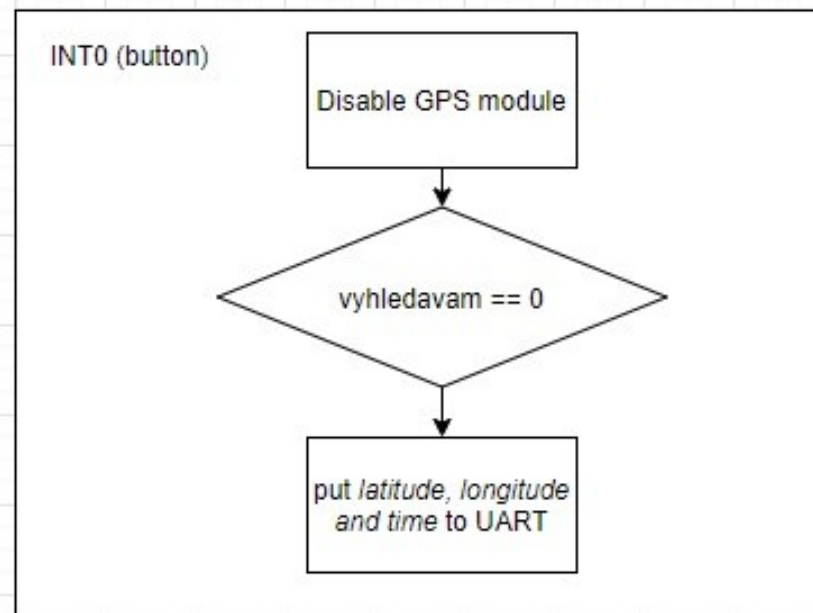
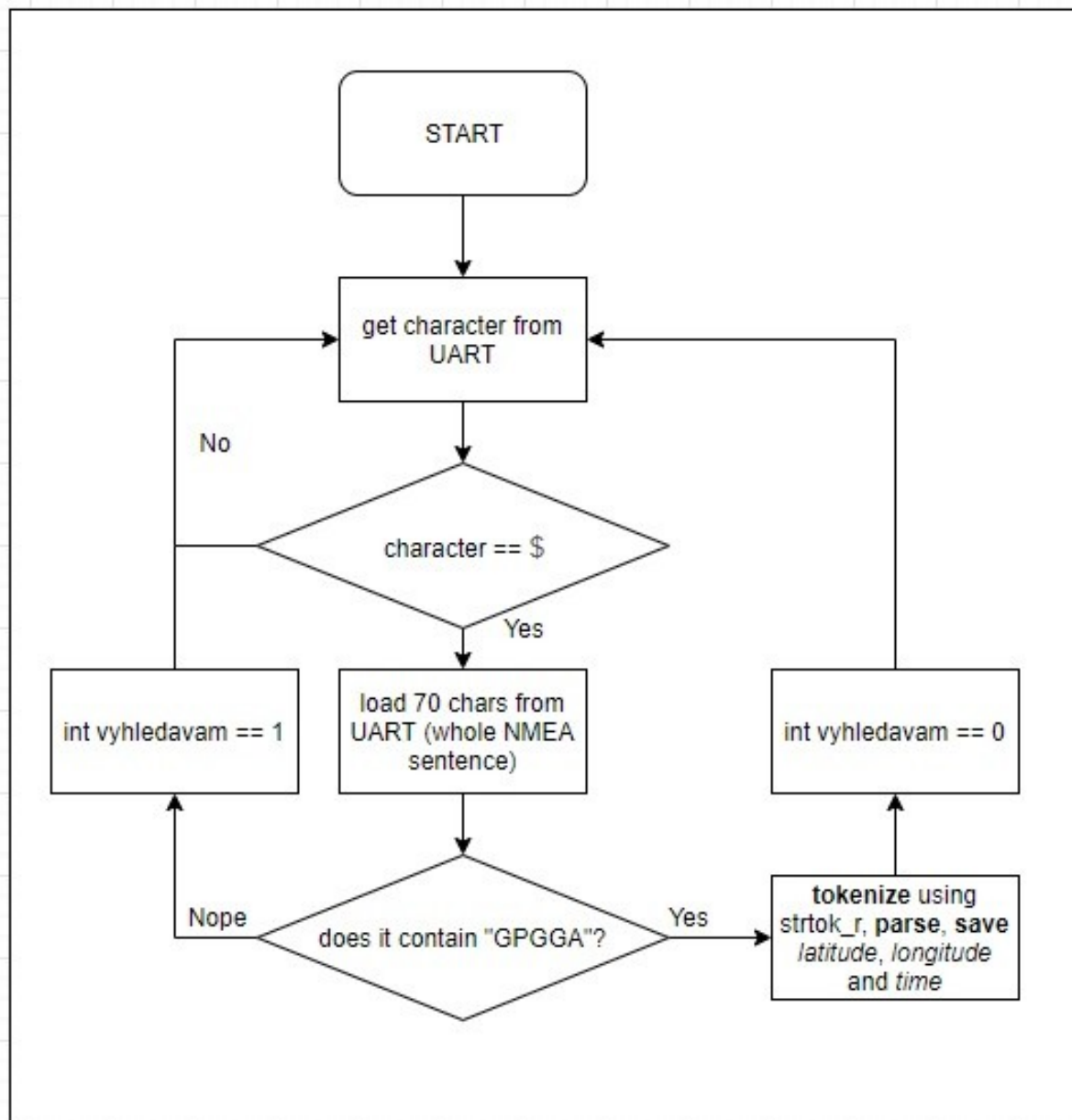
```
$GPGGA,080714.000,4913.6237,N,01634.4839,E,1,8,1.15,276.1,M,43.5,M,,*52
$GPGSA,A,3,01,22,14,03,23,11,19,17,,,,,1.45,1.15,0.88*0F
$GPGSV,3,1,12,22,85,003,12,01,73,146,12,03,65,278,13,11,53,184,13*76
$GPGSV,3,2,12,14,41,057,10,17,34,301,12,23,29,205,11,31,25,091,11*78
$GPGSV,3,3,12,19,21,319,13,32,16,046,14,09,02,214,,08,02,181,*77
$GPRMC,080714.000,A,4913.6237,N,01634.4839,E,0.61,186.44,271,119,,,A*68
$GPVTG,186.44,T,,M,0.61,N,1.14,K,A*31

$GPGGA,064951.000,2307.1256,N,12016.4438,E,1,8,0.95,39.9,M,17.8,M,,*65
```

Table-2: GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Time	064951.000		hhmmss.sss
Latitude	2307.1256		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12016.4438		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Indicator	Fix 1		See Table-3
Satellites Used	8		Range 0 to 14
HDOP	0.95		Horizontal Dilution of Precision
MSL Altitude	39.9	meters	Antenna Altitude above/below mean-sea-level
Units	M	meters	Units of antenna altitude
Geoidal Separation	17.8	meters	
Units	M	meters	Units of geoids separation
Age of Diff. Corr.		second	Null fields when DGPS is not used
Checksum	*65		
<CR> <LF>			End of message termination





Video presentation

https://www.youtube.com/watch?v=jfIPIAEUn_A&feature=youtu.be

Extensions

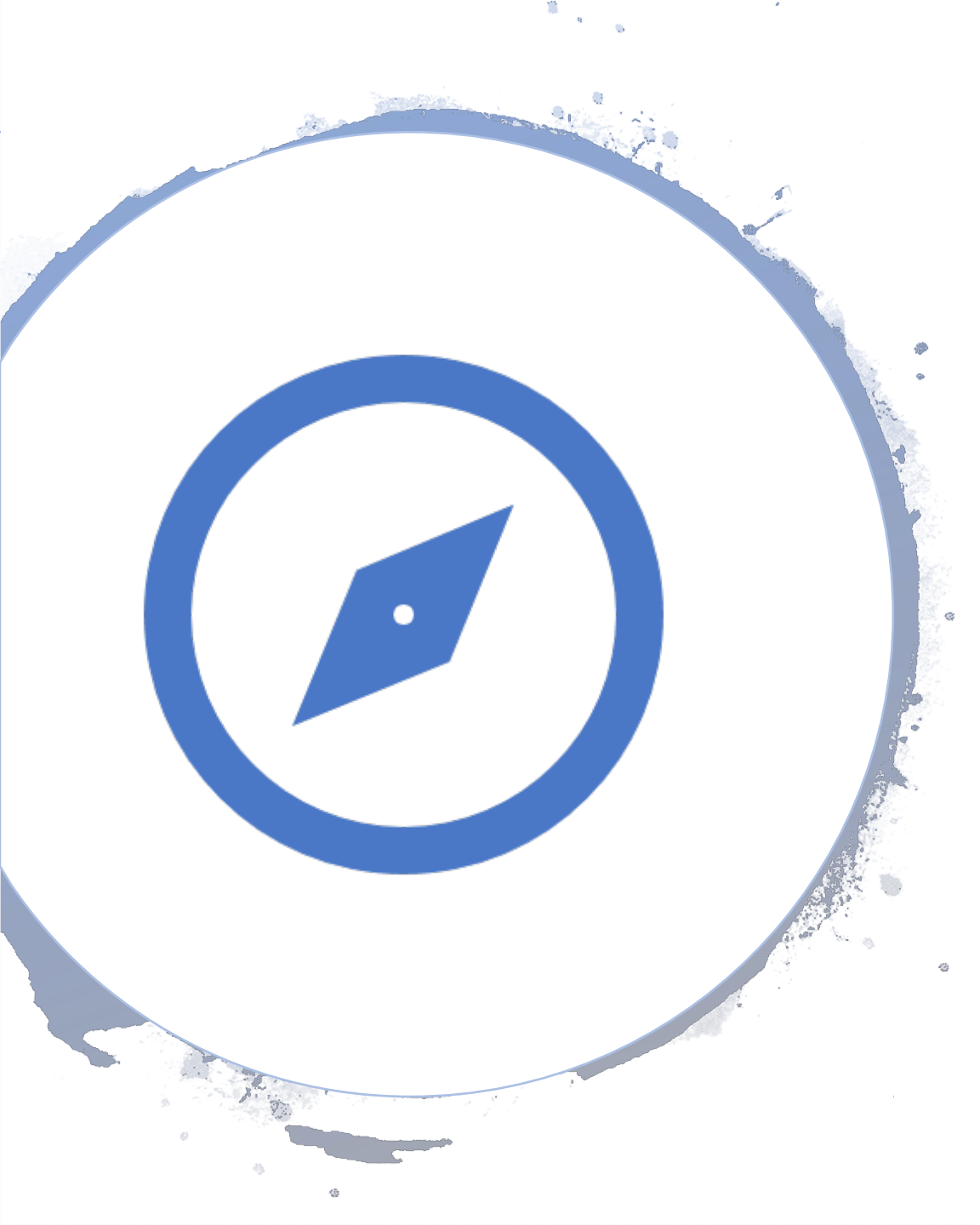


Application "Where is Česká":

- **Module:** Arduino compass HMC5883L
- **Direction towards Česká tram stop should be displayed instead of north on the compass**
- **Calculation of angle to Česká from your position and orientation towards magnetic north**

Generator of XML coordinate string:

- **Export and use in Google Earth**




```
<?xml version="1.0" encoding="UTF-8"?>
<kml xmlns="http://www.opengis.net/kml/2.2">
  <Placemark>
    <name>Simple placemark</name>
    <description>Attached to the ground. Intelligently places itself
      at the height of the underlying terrain.</description>
    <Point>
      <coordinates>-122.0822035425683,37.42228990140251,0</coordinates>
    </Point>
  </Placemark>
</kml>
```

C = Magnetic North
[-114.04 82.7]

A = VUT FEKT
[16.5732 49.226]

B = Česká
[16.6051 49.1974]

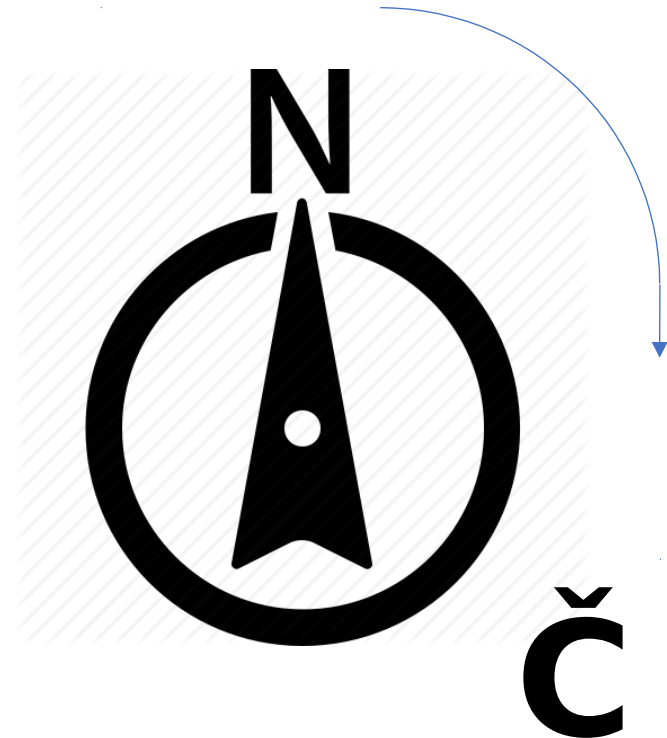
$$v1 = \overrightarrow{AC} = (-114.04 - 16.5732; 82.7 - 49.226) = (-130.6132; 33.474)$$

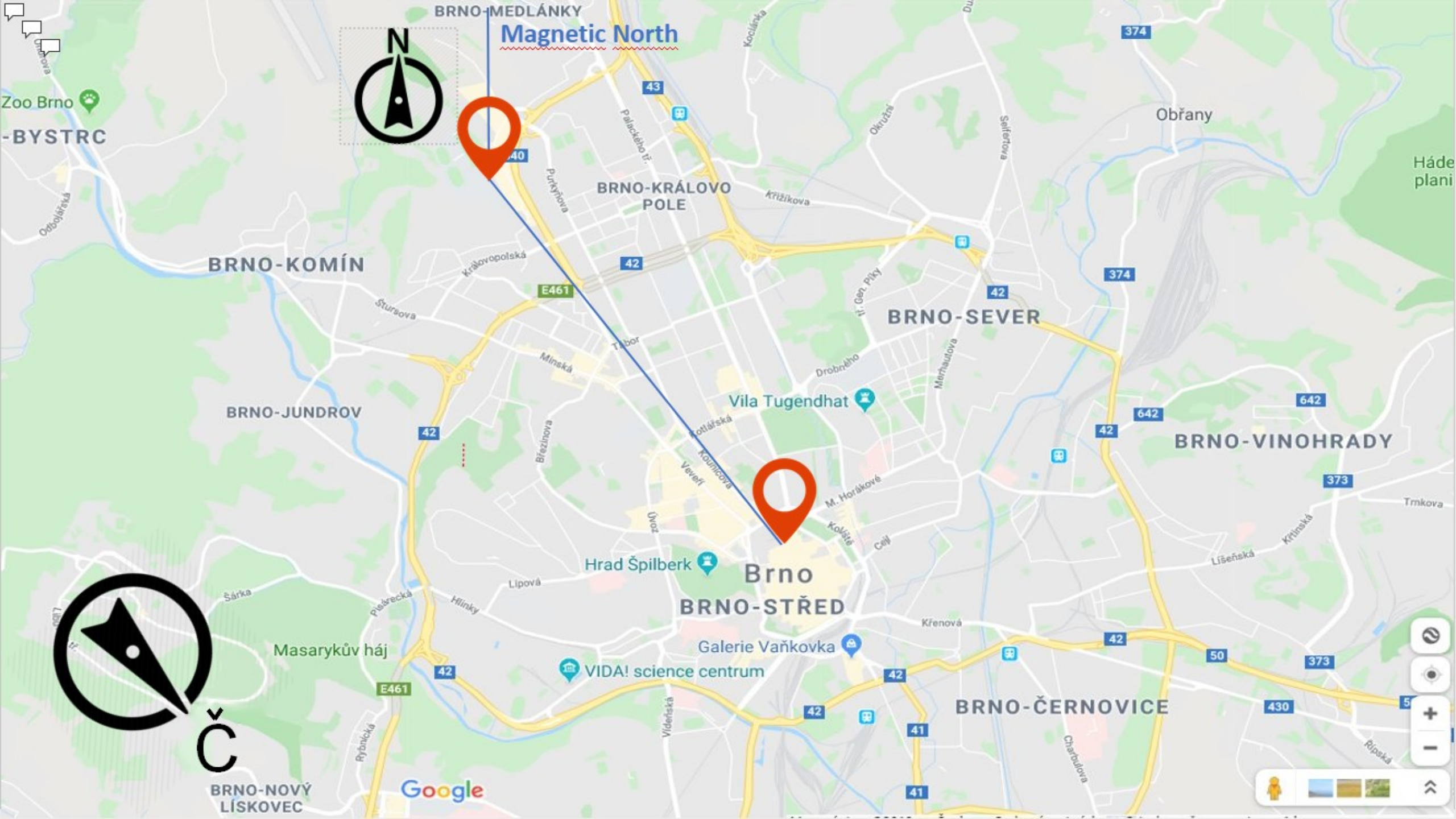
$$v2 = \overrightarrow{AB} = (16.6051 - 16.5732; 49.1974 - 49.226) = (0.0319; -0.0286)$$

$$\alpha = \arccos \frac{v1v2}{|v1||v2|} = \arccos \frac{-4.1666 - 0.9574}{134.8344 * 0.0428} = \arccos(-0.8879) = 2.6636 \text{ rad}$$

$$\alpha = \arccos \frac{v1v2}{|v1||v2|} = \arccos \frac{-4.1666 - 0.9574}{134.8344 * 0.0428} = \arccos(-0.8879) = 2.6636 \text{ rad}$$

$$\alpha = 152.4967^\circ$$





Magnetic North



BRNO-KOMÍN

BRNO-KRÁLOVO
POLE

BRNO-SEVER

BRNO-JUNDOV

BRNO-VINOHRADY

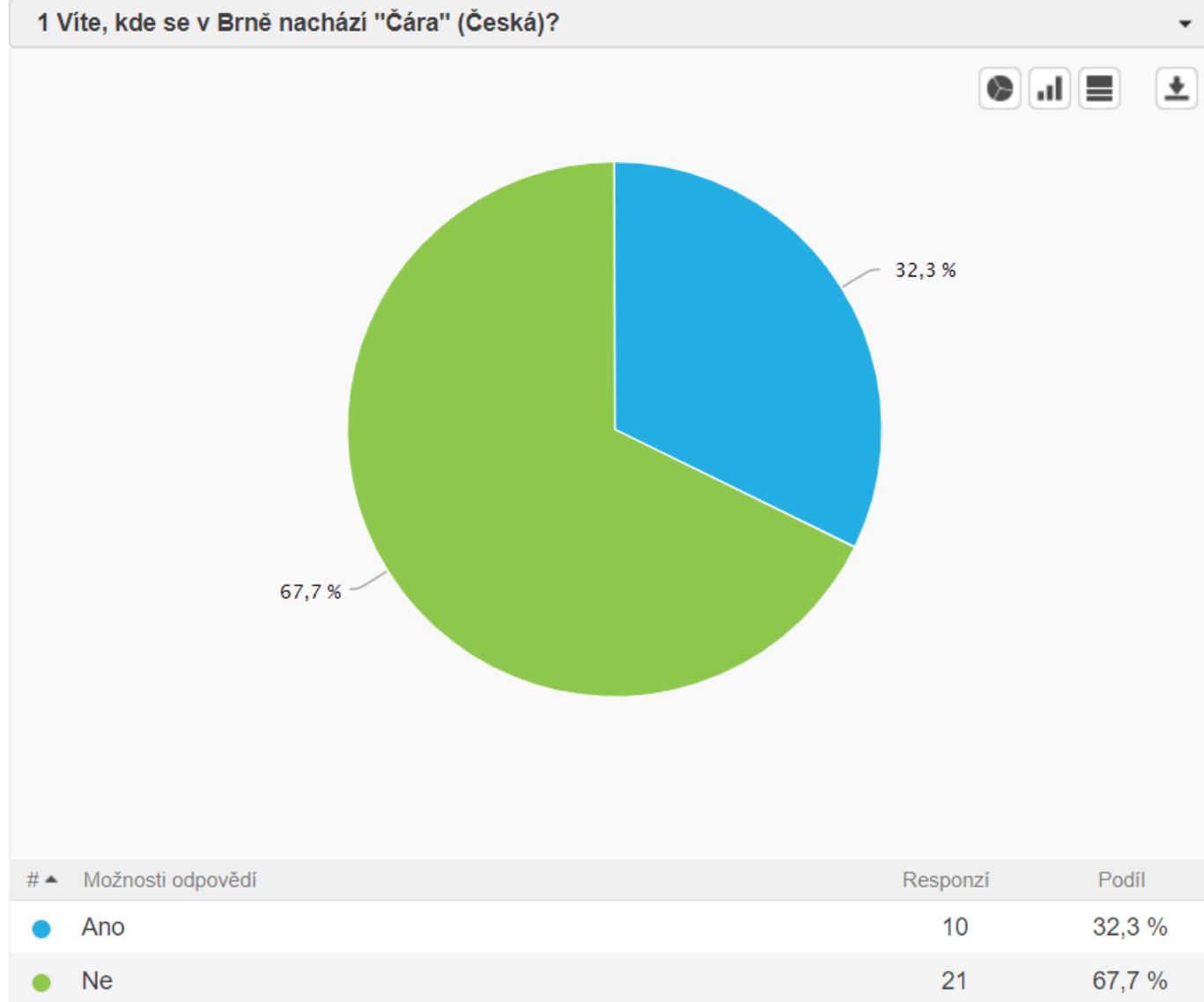
Brno
BRNO-STŘED

BRNO-ČERNOVICE

BRNO-NOVÝ
LÍSKOVEC

Google

Results of our survey:



Sources

➤ **Sergey Denisov's library: avr-nokia 5110:**

- <https://github.com/LittleBuster/avr-nokia5110>

➤ **Connecting Nokia 5110 to Arduino:**

- <https://navody.arduino-shop.cz/navody-k-produktum/lcd-displej-nokia-5110.html>

➤ **GPS:**

- <http://yopero-tech.blogspot.com/>
- <http://www.tajned.cz/>

➤ **Video:**

- https://www.youtube.com/watch?v=jfIPIAEUn_A&feature=youtu.be

➤ **KML exaple:**

- https://developers.google.com/kml/documentation/kml_tut



Thank you
for your
attention