## 1 Introduction

The programms contained in 'dstpy3' package can be used to calculate the direct scattering transform for the nonlinear Schrödinger equation. For extensive description, see the papers

- G. Boffetta and A. R. Osborne: Computation of the Direct Scattering Transform for the Nonlineare Schroedinger Equation, Journal of Comp. Phys. **102**, p 252-264, (1992)
  - http://personalpages.to.infn.it/~boffetta/Papers/bo92.pdf
- Mansoor I. Yousefi, Frank R. Kschischang:
  - Information Transmission using the Nonlinear Fourier Transform,
    Part I https://arxiv.org/abs/1202.3653
  - Information Transmission using the Nonlinear Fourier Transform, Part II https://arxiv.org/abs/1204.0830
  - Information Transmission using the Nonlinear Fourier Transform,
    Part III https://arxiv.org/abs/1302.2875

## 2 What the algorithms should do

For a given field, the direct scattering transform shall be calculated. The problem can be formulated as eigenvalue problem

$$v_t = \left( \begin{array}{cc} -j\lambda & q(x) \\ -q^*(x) & j\lambda \end{array} \right) v$$

with the eigenvalue  $\lambda$ . Assuming the normalized time and field vectors q(x) and x are present in discretized form. For an eigenvalue candidate  $\zeta$ , v can be calculated by integration:

$$v[k+1] = v[k] + \mathrm{d}x \cdot P[k]v[k] \tag{1}$$

with

$$P[k] = \begin{pmatrix} -j\zeta & q[k] \\ -q^*[k] & j\zeta \end{pmatrix}$$
 (2)

and the starting value

$$v[0] = \begin{pmatrix} \exp(j\zeta x_{\text{max}}) \\ 0 \end{pmatrix} . \tag{3}$$

The scattering coefficients  $a(\zeta)$  and  $b(\zeta)$  then can be calculated from v:

$$a(\zeta) = v_1(x_{\text{max}}) \exp(j\zeta \cdot x_{\text{max}}) \tag{4}$$

$$b(\zeta) = v_2(x_{\text{max}}) \exp(-j\zeta \cdot x_{\text{max}}) \tag{5}$$

The candidate  $\zeta$  can is an eigenvalue, when  $a(\zeta) = 0$  (or very small, when performing the integration numerically).

For root finding, it is desirable to have the derivative of a. To do this, one needs to calculate

$$\frac{\mathrm{d}a}{\mathrm{d}\zeta} = -jx_{\mathrm{max}} \exp(-j\zeta \cdot x_{\mathrm{max}}) \cdot v_1'(\zeta) \quad . \tag{6}$$

The derivative of v with respect to  $\zeta$  is v', which can be integrated with

$$v'[k+1] = v'[k] + dx \left(P'[k]v[k] + P[k]v'[k]\right) \tag{7}$$

and the initial value

$$v'[0] = \begin{pmatrix} jx_{\text{max}} \exp(j\zeta \cdot x_{\text{max}}) \\ 0 \end{pmatrix} . \tag{8}$$

From this, one gets

$$a'(\zeta) = (v_1'(x_{\text{max}}) + jx_{\text{max}} \cdot v_1(x_{\text{max}})) \exp(j\zeta \cdot x_{\text{max}}) . \tag{9}$$

To simultaneously integrate v and v', one can solve

$$\begin{pmatrix} v[k+1] \\ v'[k+1] \end{pmatrix} = \begin{pmatrix} v[k] \\ v'[k] \end{pmatrix} + dx \cdot \begin{pmatrix} P[k] & 0 \\ P'[k] & P[k] \end{pmatrix} \begin{pmatrix} v[k] \\ v'[k] \end{pmatrix} . \tag{10}$$

To find some eigenvalue with  $a(\lambda) = 0$  from a starting value  $\zeta$ , one can follow the root-finding procedure:

$$\zeta_{k+1} = \zeta_k - \frac{a(\zeta_k)}{a'(\zeta_k)} \tag{11}$$