AMS526: Numerical Analysis I (Numerical Linear Algebra for Computational and Data Sciences)

Lecture 16: QR Algorithm without Shifts (NLA§28); QR Algorithm with Shifts (NLA§29)

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Outline

QR Algorithm without Shifts

QR Algorithm with Shifts

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QR Algorithm

Most basic version of QR algorithm is remarkably simple:

Algorithm: "Pure" QR Algorithm
$$A^{(0)} = A$$
 for $k = 1, 2, \dots$
$$Q^{(k)}R^{(k)} = A^{(k-1)}$$

$$A^{(k)} = R^{(k)}Q^{(k)}$$

- With some suitable assumptions, $A^{(k)}$ converge to Schur form of A (diagonal if A is symmetric)
- Similarity transformation of A:

$$A^{(k)} = R^{(k)}Q^{(k)} = (Q^{(k)})^T A^{(k-1)}Q^{(k)}$$

• But why it works?

Unnormalized Simultaneous Iteration

- To understand QR algorithm, first consider simple algorithm
- Simultaneous iteration is power iteration applied to several vectors
- Start with linearly independent $v_1^{(0)}, \cdots, v_n^{(0)}$
- We know from power iteration that $A^k v_1^{(0)}$ converge to q_1
- With some assumptions, the space $\langle A^k v_1^{(0)}, \dots, A^k v_n^{(0)} \rangle$ should converge to $\langle q_1, \dots, q_n \rangle$
- Notation: Define initial matrix $V^{(0)}$ and matrix $V^{(k)}$ at step k:

$$V^{(0)} = \left[v_1^{(0)}|\cdots|v_n^{(0)}\right], \ V^{(k)} = A^kV^{(0)} = \left[v_1^{(k)}|\cdots|v_n^{(k)}\right]$$

Unnormalized Simultaneous Iteration

- Define orthogonal basis for column space of $V^{(k)}$ by reduced QR factorization $\hat{Q}^{(k)}\hat{R}^{(k)}=V^{(k)}$
- We assume that
 - lacktriangledown leading k+1 eigenvalues are distinct, and
 - ② all leading principal submatrices of $\hat{Q}^T V^{(0)}$ are nonsingular where $\hat{Q} = [q_1|\cdots|q_n]$
- We then have columns of $\hat{Q}^{(k)}$ converge to eigenvectors of A:

$$||q_j^{(k)} - (\pm q_j)|| = O(c^k),$$

where $c = \max_{1 \le k \le n} |\lambda_{k+1}|/|\lambda_k|$

• Proof idea: Show that subspace of any leading j columns of $V^{(k)} = A^k V^{(0)}$ converges to subspace of first j eigenvectors of A, so does the subspace of any leading j columns of $\hat{Q}^{(k)}$.

Simultaneous Iteration

- Matrices $V^{(k)} = A^k V^{(0)}$ are highly ill-conditioned
- Orthonormalize at each step rather than at the end

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Algorithm: Simultaneous Iteration Pick \hat{Q}^{(0)} \in \mathbb{R}^{n \times n} for k=1,2,\ldots Z=A\hat{Q}^{(k-1)} \hat{Q}^{(k)}\hat{R}^{(k)}=Z
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• Column spaces of $\hat{Q}^{(k)}$ and $Z^{(k)}$ are both equal to column space of $A^k \hat{Q}^{(0)}$, therefore same convergence as before

Simultaneous Iteration ← QR Algorithm

Algorithm: Simultaneous Iteration Pick $\hat{Q}^{(0)} \in \mathbb{R}^{m \times n}$ for $k=1,2,\ldots$ $Z=A\hat{Q}^{(k-1)}$ $\hat{Q}^{(k)}\hat{R}^{(k)}=Z$

Algorithm: "Pure" QR Algorithm
$$A^{(0)} = A$$
 for $k = 1, 2, ...$
$$Q^{(k)}R^{(k)} = A^{(k-1)}$$

$$A^{(k)} = R^{(k)}Q^{(k)}$$

- ullet QR algorithm is equivalent to simultaneous iteration with $\hat{Q}^{(0)}=I$
- Replace $\hat{R}^{(k)}$ by $R^{(k)}$ and $\hat{Q}^{(k)}$ by $\underline{Q}^{(k)}$, and introduce new statement $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)}$ in simultaneous iteration

Simultaneous iteration
$$\frac{Q^{(0)} = I}{Z = AQ^{(k-1)}}$$

$$\underline{Q^{(k)}R^{(k)}} = Z$$

$$A^{(k)} = (\underline{Q^{(k)}})^T A\underline{Q^{(k)}}$$

QR algorithm
$$A^{(0)} = A$$

$$Q^{(k)}R^{(k)} = A^{(k-1)}$$

$$A^{(k)} = R^{(k)}Q^{(k)}$$

$$\underline{Q}^{(k)} = Q^{(1)}Q^{(2)} \cdots Q^{(k)}$$

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Simultaneous Iteration ← QR Algorithm

- $Q^{(k)} = Q^{(1)}Q^{(2)}\cdots Q^{(k)}$. Let $\underline{R}^{(k)} = R^{(k)}R^{(k-1)}\cdots R^{(1)}$
- Both schemes generate QR factorization $A^k = \underline{Q}^{(k)}\underline{R}^{(k)}$ and projection $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A\underline{Q}^{(k)}$

Proof by induction. For k=0 it is trivial for both algorithms. For $k\geq 1$ with simultaneous iteration, $A^{(k)}$ is given by definition, and

$$A^k = A\underline{Q}^{(k-1)}\underline{R}^{(k-1)} = \underline{Q}^{(k)}R^{(k)}\underline{R}^{(k-1)} = \underline{Q}^{(k)}\underline{R}^{(k)}$$

For $k \geq 1$ with QR algorithm,

$$A^k = A\underline{Q}^{(k-1)}\underline{R}^{(k-1)} = \underline{Q}^{(k-1)}A^{(k-1)}\underline{R}^{(k-1)} = \underline{Q}^{(k)}\underline{R}^{(k)}$$

and

$$A^{(k)} = \left(Q^{(k)}\right)^T A^{(k-1)} Q^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)}$$

Convergence of QR Algorithm

- Since $\underline{Q}^{(k)} = \hat{Q}^{(k)}$ in simultaneous iteration, column vectors of $\underline{Q}^{(k)}$ converge linearly to eigenvectors if A has distinct eigenvalues
- From $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)}$, diagonal entries of $A^{(k)}$ are Rayleigh quotients of column vectors of $\underline{Q}^{(k)}$, so they converge linearly to eigenvalues of A
- Off-diagonal entries of $A^{(k)}$ converge to zeros, as they are generalized Rayleigh quotients involving approximations of distinct eigenvectors
- Overall, $A = \underline{Q}^{(k)}A^{(k)}\left(\underline{Q}^{(k)}\right)^T$. For a symmetric matrix, it converges to eigenvalue decomposition of A
- Convergence rate is only linear: columns of $\hat{Q}^{(k)}$ converge to eigenvectors of $A \|q_j^{(k)} (\pm q_j)\| = O(c^k)$, where $c = \max_{1 \le k \le n} |\lambda_{k+1}|/|\lambda_k|$

Outline

QR Algorithm without Shifts

QR Algorithm with Shifts

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Simultaneous Inverse Iteration ← QR Algorithm

- Similar to inverse iteration, QR algorithm can be sped-up by introducing shifts at each step
- Assume A is real and symmetric. QR algorithm is equivalent to simultaneous inverse iteration, applied to "flipped" identity matrix P

$$P = \left[\begin{array}{ccc} & & 1 \\ & 1 \\ & \vdots \\ 1 & & \end{array} \right]$$

Simultaneous inverse iteration

$$\hat{Q}^{(0)} = P$$

for $k = 1, 2, ...$
 $Z = A^{-1} \hat{Q}^{(k-1)}$
 $\hat{Q}^{(k)} \hat{R}^{(k)} = Z$

"Pure" QR Algorithm
$$A^{(0)} = A$$
for $k = 1, 2, ...$
 $Q^{(k)}R^{(k)} = A^{(k-1)}$
 $A^{(k)} = R^{(k)}Q^{(k)}$

Simultaneous Inverse Iteration ← QR Algorithm

- Let $\underline{Q}^{(k)} = Q^{(1)}Q^{(2)}\cdots Q^{(k)}$ and $\underline{R}^{(k)} = R^{(k)}R^{(k-1)}\cdots R^{(1)}$. Then $A^k = Q^{(k)}\underline{R}^{(k)}$
- Inverting A^k , we have $A^{-k} = \left(\underline{R}^{(k)}\right)^{-1} \left(\underline{Q}^{(k)}\right)^T$
- Because A^{-k} is symmetric, $A^{-k} = \underline{Q}^{(k)} \left(\underline{R}^{(k)}\right)^{-T}$
- Use "flipped" permutation matrix P and write that last expression as

$$A^{-k}P = \left[\underline{Q}^{(k)}P\right]\left[P\left(\underline{R}^{(k)}\right)^{-T}P\right],$$

which is QR factorization of $A^{-k}P$

• Therefore, simultaneous inverse iteration applied to $\hat{Q}^{(0)}=P$ is "equivalent" to QR algorithm, in that it produces

$$\hat{Q}^{(k)} = \underline{Q}^{(k)}P$$
 and $\hat{R}^{(k)}\hat{R}^{(k-1)}\cdots\hat{R}^{(1)} = P\left(\underline{R}^{(k)}\right)^{-T}P$

• Question: How to obtain $A^{(k)}$ in simultaneous inverse iteration?

Simultaneous Inverse Iteration ← QR Algorithm

- Let $\underline{Q}^{(k)} = Q^{(1)}Q^{(2)}\cdots Q^{(k)}$ and $\underline{R}^{(k)} = R^{(k)}R^{(k-1)}\cdots R^{(1)}$. Then $A^k = Q^{(k)}\underline{R}^{(k)}$
- Inverting A^k , we have $A^{-k} = \left(\underline{R}^{(k)}\right)^{-1} \left(\underline{Q}^{(k)}\right)^T$
- Because A^{-k} is symmetric, $A^{-k} = \underline{Q}^{(k)} \left(\underline{R}^{(k)}\right)^{-T}$
- Use "flipped" permutation matrix P and write that last expression as

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which is QR factorization of $A^{-k}P$

• Therefore, simultaneous inverse iteration applied to $\hat{Q}^{(0)} = P$ is "equivalent" to QR algorithm, in that it produces

$$\hat{Q}^{(k)} = \underline{Q}^{(k)}P$$
 and $\hat{R}^{(k)}\hat{R}^{(k-1)}\cdots\hat{R}^{(1)} = P\left(\underline{R}^{(k)}\right)^{-T}P$

• Question: How to obtain $A^{(k)}$ in simultaneous inverse iteration? Answer: $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)} = P\left(\hat{Q}^{(k)}\right)^T A \hat{Q}^{(k)} P$

QR Algorithm with Shifts

• Similar to inverse iteration, we can introduce shifts $\mu^{(k)}$ to accelerate convergence

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Algorithm: QR Algorithm with Shifts A^{(0)} = A for k = 1, 2, ... Pick a shift \mu^{(k)} Q^{(k)}R^{(k)} = A^{(k-1)} - \mu^{(k)}I A^{(k)} = R^{(k)}Q^{(k)} + \mu^{(k)}I
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Properties of QR Algorithm with Shift

• From $Q^{(k)}R^{(k)} = A^{(k-1)} - \mu^{(k)}I$ and $A^{(k)} = R^{(k)}Q^{(k)} + \mu^{(k)}I$, we have

$$A^{(k)} = \left(Q^{(k)}\right)^T A^{(k-1)} Q^{(k)}$$

- Then by induction, $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)}$
- However, instead of $A^k = \underline{Q}^{(k)}\underline{R}^{(k)}$, we now have

$$\left(A - \mu^{(k)}I\right)\left(A - \mu^{(k-1)}I\right)\cdots\left(A - \mu^{(1)}I\right) = \underline{Q}^{(k)}\underline{R}^{(k)},$$

which can be shown by induction

- In other words, $\underline{Q}^{(k)}$ is orthogonalization of $\prod_{i=k}^{1} (A \mu^{(k)}I)$
- If $\mu^{(k)}$ are good estimates of eigenvalues, then last column of $\underline{Q}^{(k)}$ converges to corresponding eigenvector

Choosing $\mu^{(k)}$: Rayleigh Quotient Shift

• Natural choice of $\mu^{(k)}$ is Rayleigh quotient for last column of $Q^{(k)}$

$$\mu^{(k)} = r(q_m^{(k)}) = (q_m^{(k)})^T A q_m^{(k)}$$

- ullet As in Rayleigh quotient iteration, last column $q_m^{(k)}$ converges cubically
- This Rayleigh quotient appears as (m, m) entry of $A^{(k)}$ since $A^{(k)} = \left(\underline{Q}^{(k)}\right)^T A \underline{Q}^{(k)}$
- Rayleigh quotient shift corresponds to setting $\mu^{(k)} = A_{mm}^{(k)}$

Choosing $\mu^{(k)}$: Wilkinson Shift

- QR algorithm with Rayleigh quotient shift might fail sometimes, e.g., $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$, for which $A^{(k)} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ and μ is always 0
- Wilkinson breaks symmetry by considering lower-rightmost 2×2 submatrix of $A^{(k)}$: $B = \begin{bmatrix} a_{n-1} & b_{n-1} \\ b_{n-1} & a_m \end{bmatrix}$
- Choose eigenvalue of B closer to a_n , with arbitrary tie-breaking:

$$\mu = a_n - \operatorname{sign}(\delta)b_{n-1}^2 / \left(|\delta| + \sqrt{\delta^2 + b_{n-1}^2} \right)$$

where $\delta = (a_{n-1} - a_n)/2$; if $\delta = 0$, set sign(δ) to 1 (or -1)

 QR algorithm always converges with this shift; quadratically in worst case, and cubically in general

"Practical" QR Algorithm

- Practical QR algorithm involves two additional components:
 - ▶ tridiagonalization of A at the beginning. The tridiagonal structure is preserved by $A^{(k)}$ (Exercise 28.2)
 - deflation of A into submatrices when $A^{(k)}$ is separable

Algorithm: "Practical" QR Algorithm
$$\begin{pmatrix} Q^{(0)} \end{pmatrix}^T A^{(0)} Q^{(0)} = A \text{ {tridiagnolization of } A \text{}}$$
 for $k=1,2,\ldots$ Pick a shift $\mu^{(k)}$
$$Q^{(k)} R^{(k)} = A^{(k-1)} - \mu^{(k)} I$$

$$A^{(k)} = R^{(k)} Q^{(k)} + \mu^{(k)} I$$
 If any off-diagonal element $a_{j,j+1}^{(k)}$ is sufficiently close to zero set $a_{j,j+1} = a_{j+1,j} = 0$ to obtain
$$\begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = A^{(k)} \text{ and apply QR algorithm to } A_1 \text{ and } A_2$$

Stability and Accuracy

Theorem

QR algorithm is backward stable

$$\tilde{Q}\tilde{\Lambda}\tilde{Q} = A + \delta A, \quad \frac{\|\delta A\|}{\|A\|} = O(\epsilon_{machine})$$

where $\tilde{\Lambda}$ is computed Λ and \tilde{Q} is exactly orthogonal matrix

- Its combination with Hessenberg reduction is also backward stable
- Furthermore, eigenvalues are always well conditioned for **normal** matrices: it can be show that $|\tilde{\lambda}_j \lambda_j| \leq \|\delta A\|_2$, and therefore,

$$\frac{|\tilde{\lambda}_j - \lambda_j|}{\|A\|} = O(\epsilon_{\mathsf{machine}})$$

where $\tilde{\lambda}_i$ are the computed eigenvalues

 However, sensitivity of eigenvectors depends on distances between adjacent eigenvalues, so error in eigenvectors may be arbitrarily large