

Computational Intelligence

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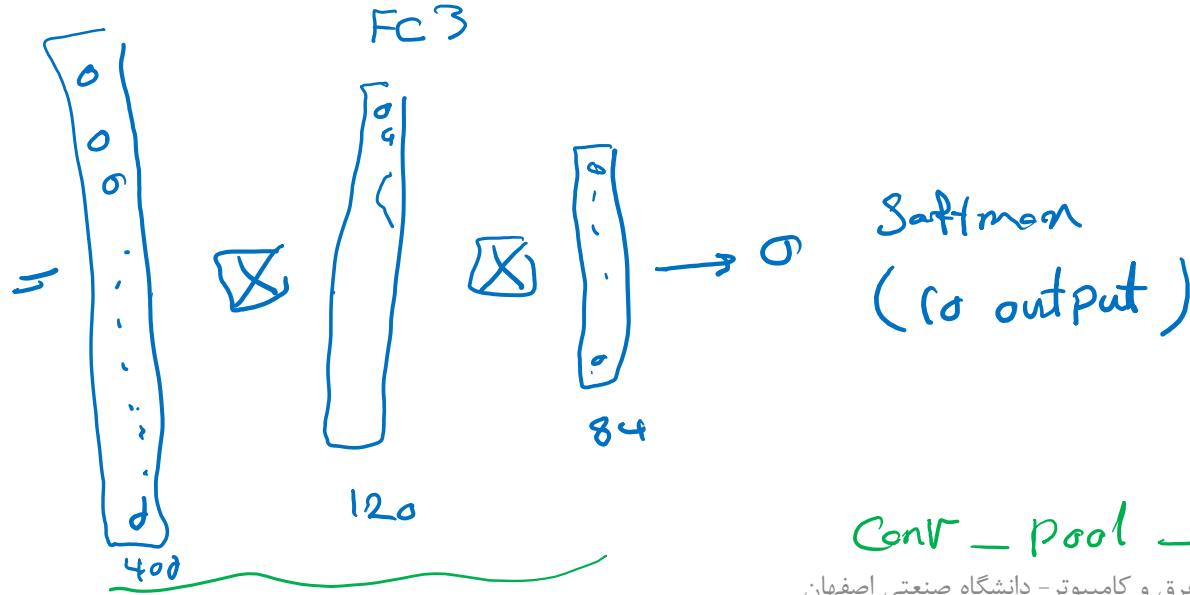
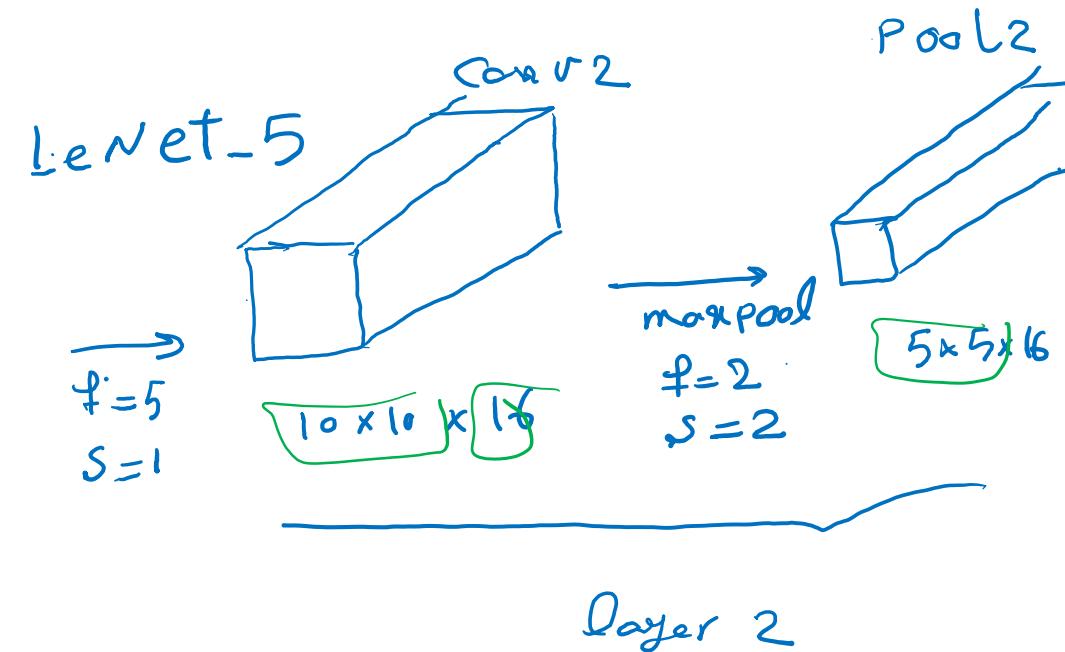
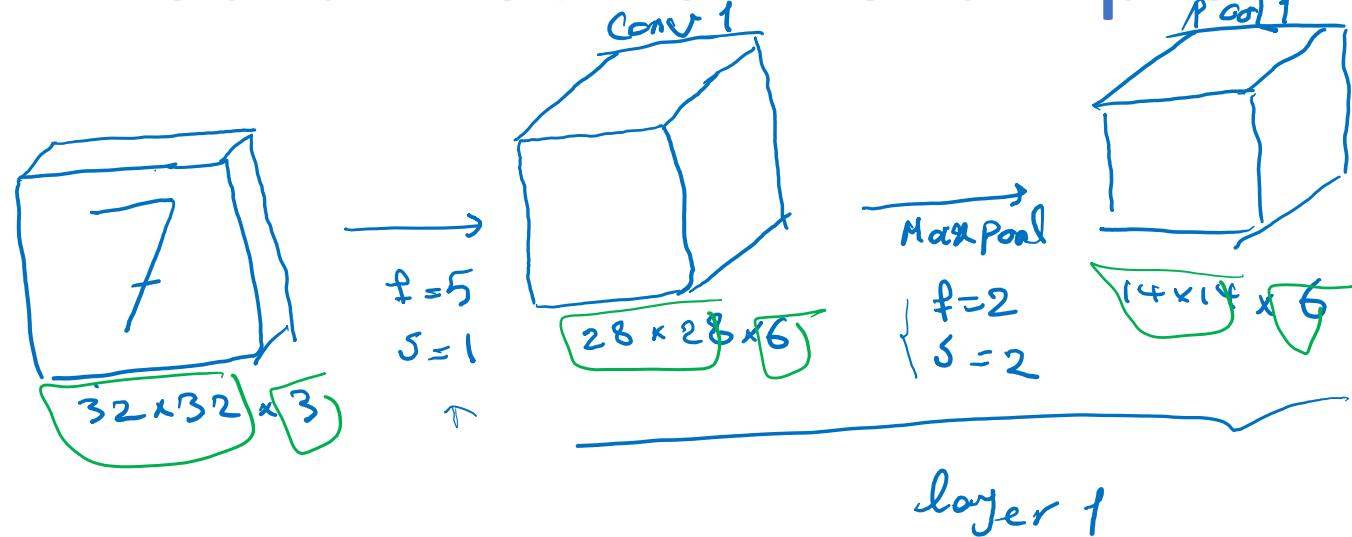
Isfahan University of Technology

Outline

- Convolutional Neural Networks
 - CNN Example
 - Why Convolutions?
- Case Studies
 - Why look at case studies?
 - Classic Networks
 - LeNet-5
 - AlexNet
 - VGG

Convolutional Neural Networks: CNN Example

Neural network example



Conv - Pool - Conv - Pool - FC - FC
سمانه حسینی سمنانی - دانشکده برق و کامپیوتر - دانشگاه صنعتی اصفهان

$n_H, n_W \downarrow$
 $n_C \uparrow$
FC - Softmax

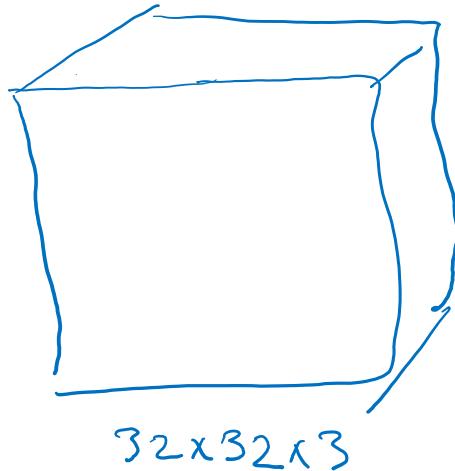
Neural network example

SL.No		Activation Shape	Activation Size	# Parameters
1.	Input Layer:	(32, 32, 3)	3072	0
2.	CONV1 ($f=5, s=1$)	(28, 28, 8)	6272	608
3.	POOL1	(14, 14, 8)	1568	0
4.	CONV2 ($f=5, s=1$)	(10, 10, 16)	1600	3216
5.	POOL2	(5, 5, 16)	400	0
6.	FC3	(120, 1)	120	48120
7.	FC4	(84, 1)	84	10164
8.	Softmax	(10, 1)	10	850

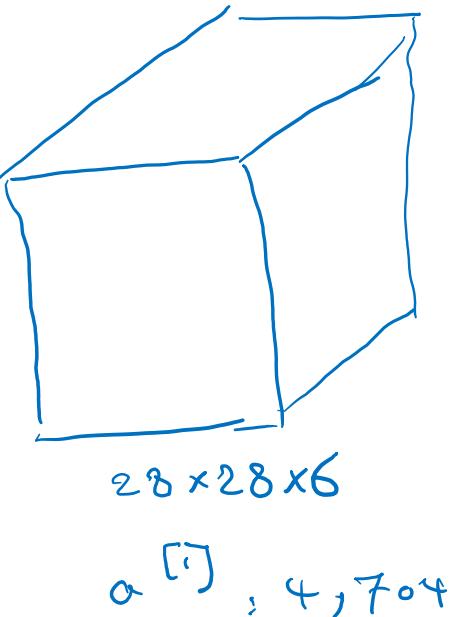
Convolutional Neural Networks: Why convolutions?

Why convolutions

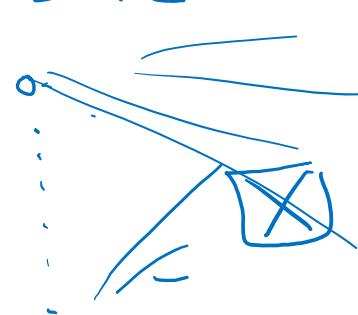
Conv:



$f=5$
6 filter



FC:



3072
0

$$\frac{5 \times 5 - 25}{1} + 1 = 26$$

$$6 \times 26 = \underline{156} \text{ Parameters}$$

$$3072 \times 4704 \approx \underline{14M}$$

Why convolutions

translation invariance

The diagram illustrates a convolution operation. On the left is a 6x6 input matrix with all values set to 10, except for the bottom-right corner which is 0. A 3x3 kernel matrix is shown next, with values 1, 0, -1 in each row. Below the kernel is the dimension 3×3 . The multiplication symbol (*) is placed between the input and kernel matrices. To the right of the multiplication is an equals sign (=). The result is a 4x4 output matrix where every value is 30, except for the top-left corner which is 0. This 0 is circled in red, and a blue wavy line points from it to the bottom-right corner of the input matrix, demonstrating that the output unit is only activated by the input feature at that specific position.

10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0

*

1	0	-1
1	0	-1
1	0	-1

3×3

=

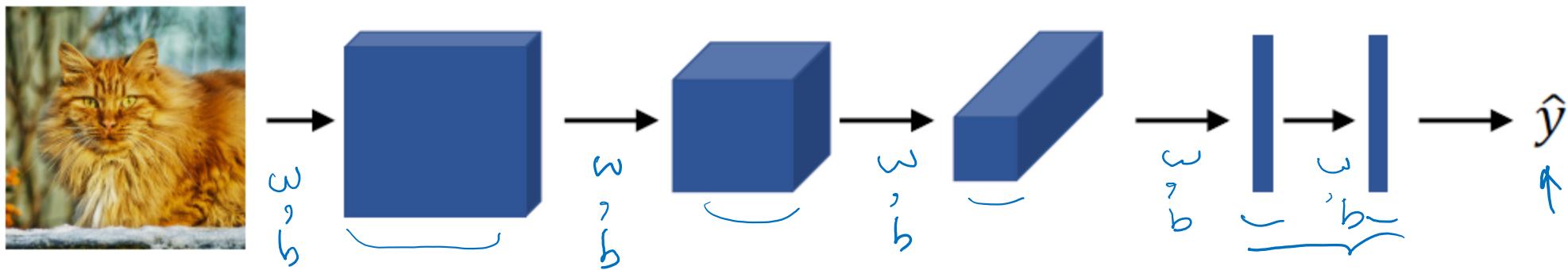
0	30	30	0
0	30	30	0
0	30	30	0
0	30	30	0

- **Parameter sharing:** A feature detector (such as a vertical edge detector) that's useful in one part of the image is probably useful in another part of the image.
- **Sparsity of connections:** In each layer, each output value depends only on a small number of inputs.

Putting it together

Training set $(\underline{x}^{(1)}, \underline{y}^{(1)}) \dots (\underline{x}^{(m)}, \underline{y}^{(m)})$.

w, b → random



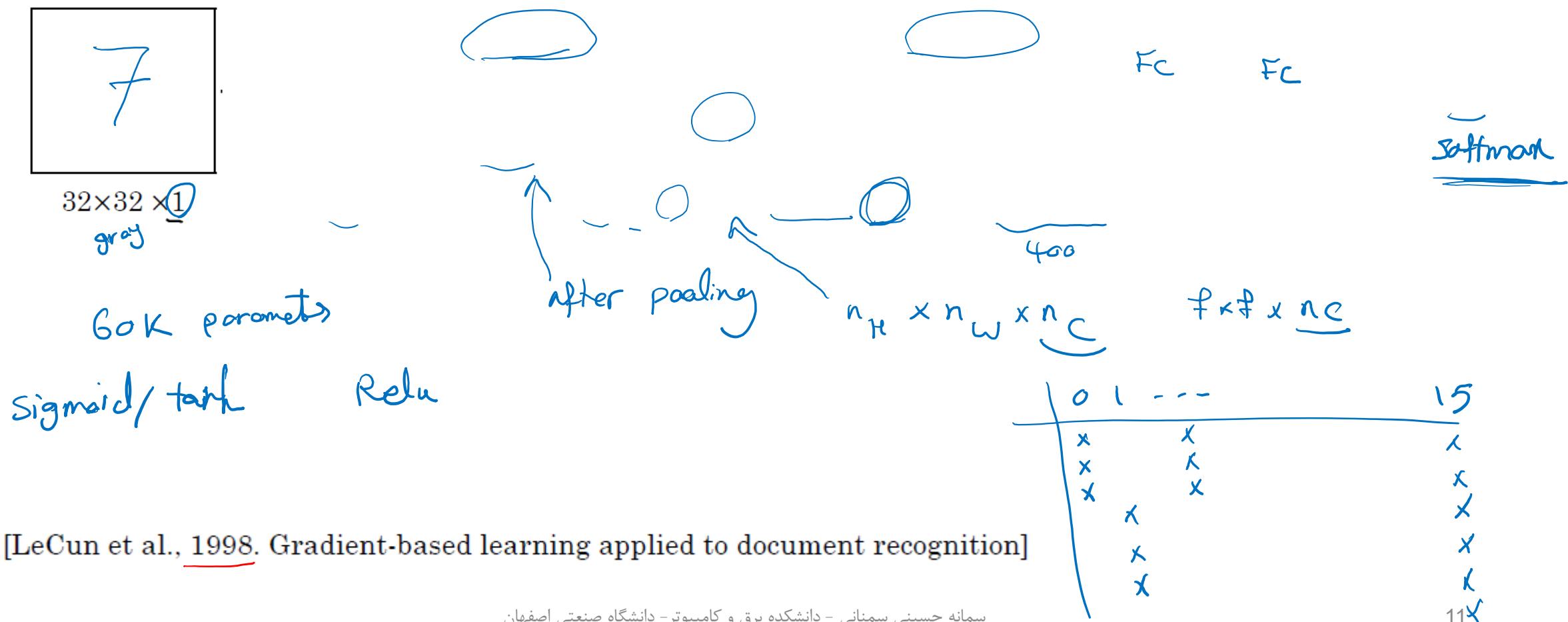
$$\text{Cost } J = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}^{(i)}, y^{(i)})$$

forward pass
backward pass

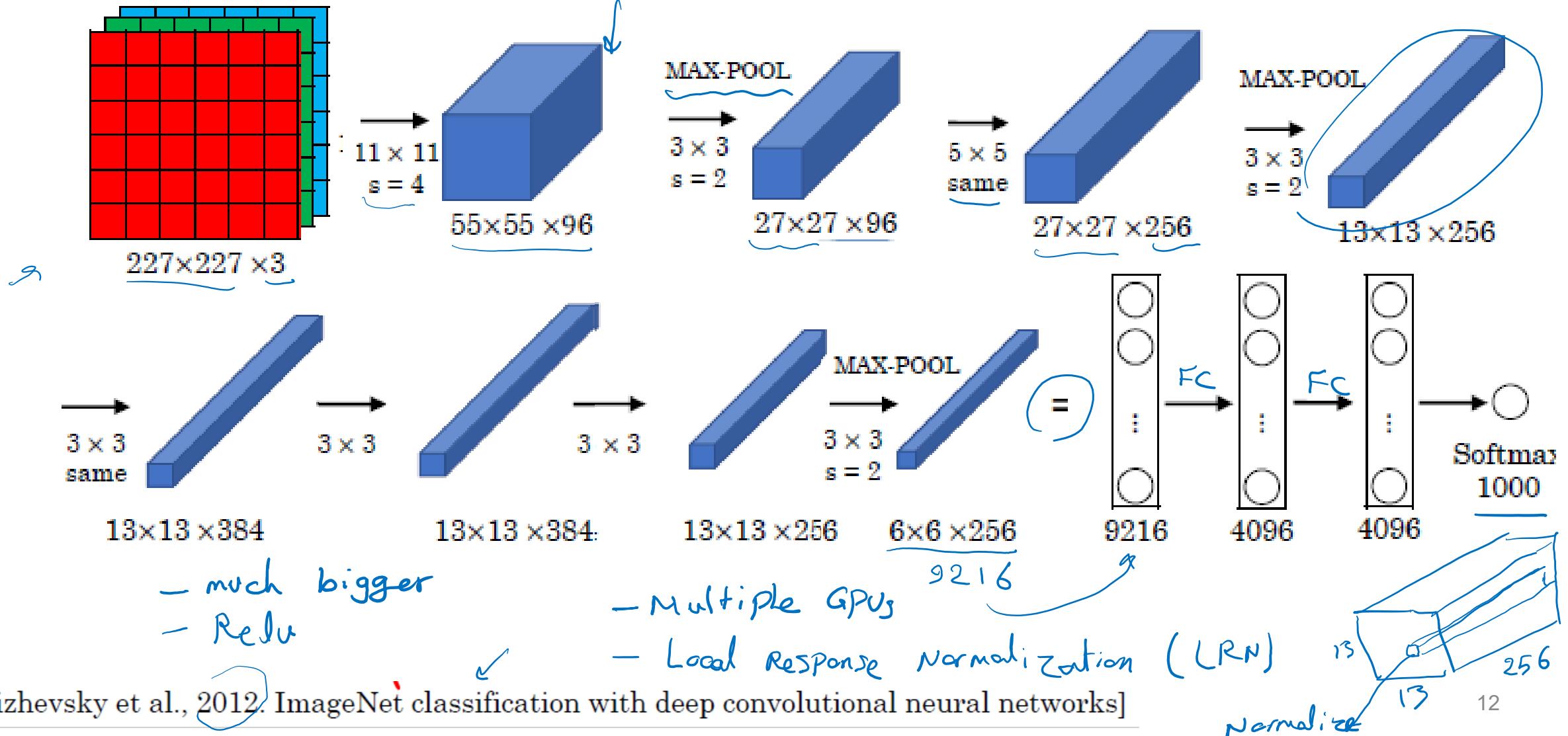
Use gradient descent to optimize parameters to reduce J

Case Studies: Classic networks

LeNet - 5

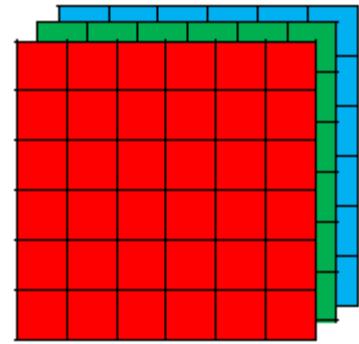


AlexNet

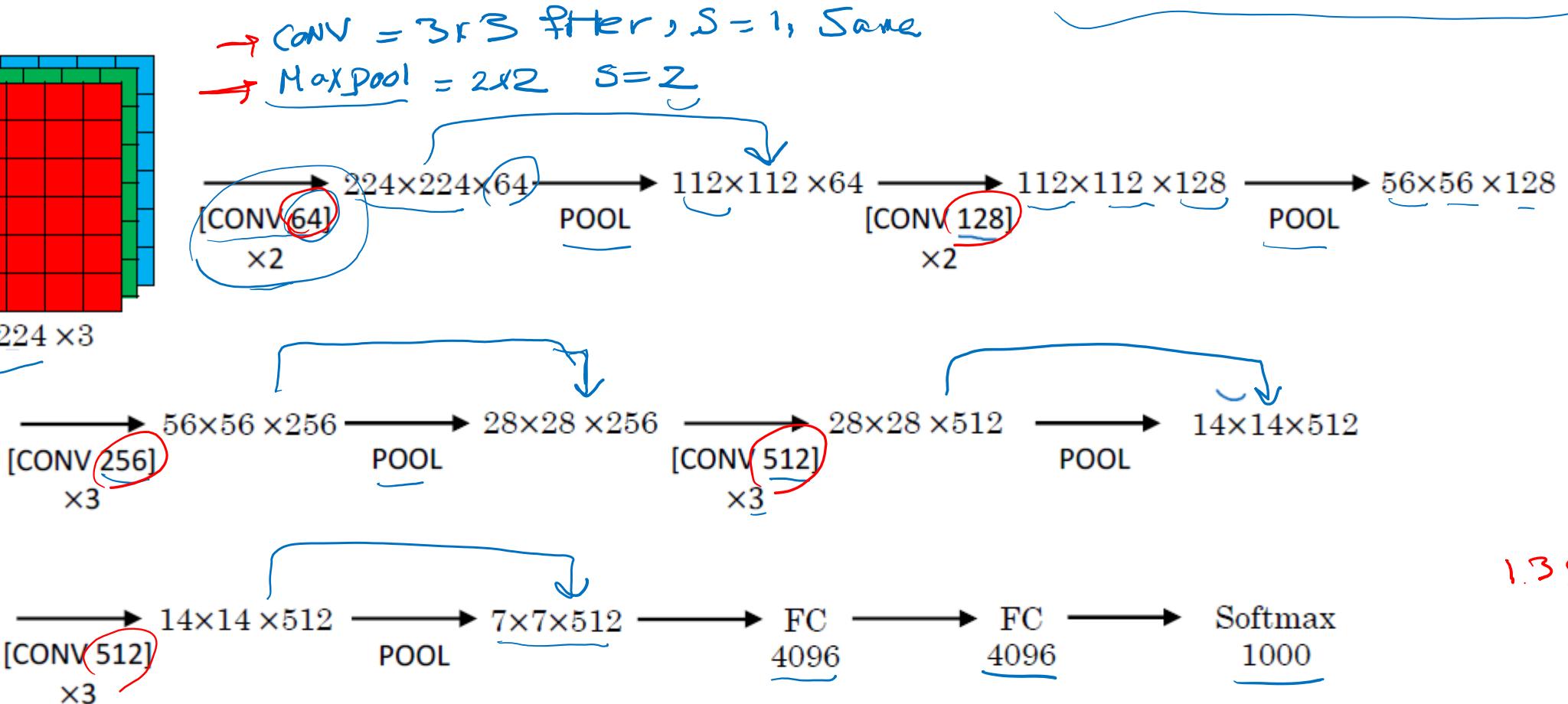


VGG - 16

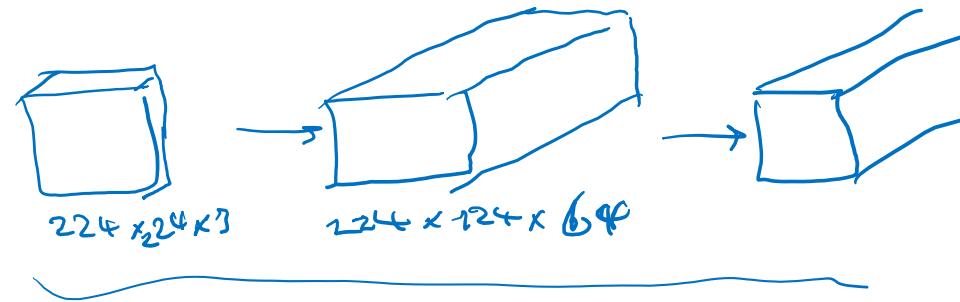
VGG 19



$224 \times 224 \times 3$



[Simonyan & Zisserman 2015. Very deep convolutional networks for large-scale image recognition]



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