$$\begin{array}{lll} \boxed{\tau \perp \tau} & \frac{\alpha_1 \neq \alpha_2}{\alpha_1 \perp \alpha_2} \text{ Orth/Var} & \frac{\tau_1 \perp \tau_3}{\tau_1 \rightarrow \tau_2 \perp \tau_3 \rightarrow \tau_4} \text{ Orth/Fun} & \frac{\tau_1 \perp [\alpha_1/\alpha_2]\tau_2}{\forall \alpha_1.\tau_1 \perp \forall \alpha_2.\tau_2} \text{ Orth/Forall} \\ \\ \frac{\tau_1 \perp \tau_3}{\tau_1 \& \tau_2 \perp \tau_3} & \frac{\tau_2 \perp \tau_3}{\tau_1 \perp \tau_2} \text{ Orth/And1} & \frac{\tau_1 \perp \tau_2}{\tau_1 \perp \tau_2} \frac{\tau_1 \perp \tau_3}{\tau_1 \perp \tau_2} \text{ Orth/And2} & \frac{l_1 \neq l_2}{\{l_1:\tau_1\} \perp \{l_2:\tau_2\}} \text{ Orth/Reclab} \\ \\ \frac{\tau_1 \perp \tau_2}{\{l:\tau_1\} \perp \{l:\tau_2\}} & \text{ Orth/Rec} \end{array}$$

Figure 1. Orthogonality between types.

$$\frac{\alpha \in \gamma}{\gamma \vdash \alpha} \text{ wfvar } \frac{\gamma \vdash \tau_1}{\gamma \vdash \tau} \text{ wftop } \frac{\gamma \vdash \tau_1}{\gamma \vdash \tau_1 \to \tau_2} \text{ wffun } \frac{\gamma, \alpha \vdash \tau}{\gamma \vdash \forall \alpha. \tau} \text{ wfforall }$$
 
$$\frac{\gamma \vdash \tau_1}{\gamma \vdash \tau_1 \& \tau_2} \frac{\Gamma \vdash \tau_2}{\gamma \vdash \tau_1 \& \tau_2} \text{ wfand } \frac{\gamma \vdash \tau}{\gamma \vdash \{l : \tau\}} \text{ wfrec}$$

Figure 2. Well-formedness of types.

Values 
$$\nu := \top | \lambda(x:\tau).e | \Lambda \alpha.e | \nu_1, \nu_2 | \{l = e\}$$

Figure 3. Values.

$$\frac{\tau_1 <: \tau}{(\tau)(\nu : \tau_1) \hookrightarrow \nu} \text{ Cast/Base } \qquad \frac{(\tau)(\nu_1 : \tau_1) \hookrightarrow \nu}{(\tau)(\nu_1, \nu_2 : \tau_1 \ \& \ \tau_2) \hookrightarrow \nu} \text{ Cast/Left} \qquad \frac{(\tau)(\nu_2 : \tau_2) \hookrightarrow \nu}{(\tau)(\nu_1, \nu_2 : \tau_1 \ \& \ \tau_2) \hookrightarrow \nu} \text{ Cast/Right}$$

Figure 4. Casts.

$$\frac{e_1 \Downarrow \lambda(x:\tau). e \qquad e_2 \Downarrow \nu_2 \qquad (\tau)(\nu_2:\tau_2) \hookrightarrow \nu_3 \qquad [\nu_3/x]e \Downarrow \nu}{e_1 \ (e_2:\tau_2) \Downarrow \nu} \ Dyn/App$$
 
$$\frac{e_1 \Downarrow \forall \alpha. e \qquad [\tau/\alpha]e \Downarrow \nu}{e_1 \ \tau \Downarrow \nu} \ Dyn/TApp \qquad \frac{e_1 \Downarrow \nu_1 \qquad e_2 \Downarrow \nu_2}{e_1, e_2 \Downarrow \nu_1, \nu_2} \ Dyn/Merge$$

Figure 5. Dynamic semantics.

$$|\tau| = T$$

$$\begin{aligned} |\alpha| &= \alpha \\ |T| &= () \\ |\tau_1| &\to |\tau_2| = |\tau_1| \to |\tau_2| \\ |\forall \alpha. \ \tau| &= \forall \alpha. \ |\tau| \\ |\tau_1 \ \& \ \tau_2| &= (|\tau_1|, |\tau_2|) \\ |\{l: \tau\}| &= |\tau| \end{aligned}$$

Figure 6. Type translation.

$$\begin{array}{c} \hline \tau <: \tau \hookrightarrow C \\ \hline \hline \alpha <: \alpha \hookrightarrow \lambda(x:|\alpha|).x \\ \hline \end{array} \begin{array}{c} \tau_3 <: \tau_1 \hookrightarrow C_1 \\ \hline \tau_2 <: \tau_4 \hookrightarrow C_2 \\ \hline \hline \tau_1 \to \tau_2 <: \tau_3 \to \tau_4 \hookrightarrow \lambda(f:|\tau_1 \to \tau_2|).\lambda(x:|\tau_3|).C_2 \ (f \ (C_1 \ x)) \\ \hline \end{array} \begin{array}{c} sub \text{fun} \\ \hline \end{array} \\ \hline \begin{array}{c} \tau_1 <: [\alpha_1/\alpha_2]\tau_2 \hookrightarrow C \\ \hline \forall \alpha_1.\tau_1 <: \forall \alpha_2.\tau_2 \hookrightarrow \lambda(f:|\forall \alpha_1.\tau_1|). \land \alpha.C \ (f \ \alpha) \\ \hline \end{array} \begin{array}{c} sub \text{for all} \\ \hline \end{array} \begin{array}{c} \tau_1 <: \tau_2 \hookrightarrow C_1 \\ \hline \tau_1 <: \tau_2 \hookrightarrow C_1 \\ \hline \end{array} \begin{array}{c} \tau_1 <: \tau_3 \hookrightarrow C_2 \\ \hline \tau_1 <: \tau_2 & \sigma_3 \hookrightarrow \lambda(x:|\tau_1|). \ (C_1 \ x, C_2 \ x) \\ \hline \end{array} \begin{array}{c} sub \text{and} \\ \hline \end{array} \\ \hline \begin{array}{c} \tau_1 <: \tau_2 \hookrightarrow C_3 \\ \hline \end{array} \begin{array}{c} \tau_1 <: \tau_3 \hookrightarrow C_2 \\ \hline \tau_1 <: \tau_2 & \sigma_3 \hookrightarrow \lambda(x:|\tau_1|). \ (C_1 \ x, C_2 \ x) \\ \hline \end{array} \begin{array}{c} sub \text{and} \\ \hline \end{array} \\ \hline \begin{array}{c} \tau_1 <: \tau_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \hline \end{array} \begin{array}{c} \tau_1 <: \tau_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow C \\ \hline \end{array} \begin{array}{c} \tau_1 & \sigma_2 \hookrightarrow \tau_3 \hookrightarrow \lambda(x:|\tau_1 \ \& \tau_2 \hookrightarrow \tau_3 \hookrightarrow \lambda(x:|\tau_1 \ \& \tau_1 \ \& \tau_2 \hookrightarrow \tau_3 \hookrightarrow \lambda(x:|\tau_1 \ \& \tau_1 \ \& \tau_2 \hookrightarrow \tau_3 \hookrightarrow \lambda(x:|\tau_1 \ \& \tau_2 \hookrightarrow \tau_3 \hookrightarrow \lambda(x:|\tau_1 \ \& \tau_1 \ \end{smallmatrix}$$

Figure 7. Elaboration subtyping.

$$\frac{(x,\tau) \in \gamma}{\gamma \vdash x : \tau \hookrightarrow x} \; \text{EVAR} \quad \frac{\gamma}{\gamma \vdash T : T \hookrightarrow ()} \; \text{ETOP} \quad \frac{\gamma, x : \tau \vdash e : \tau_1 \hookrightarrow E}{\gamma \vdash \lambda(x : \tau) \hookrightarrow t_1 \hookrightarrow \lambda(x : |\tau|) \cdot E} \; \text{ELAM}$$
 
$$\frac{\gamma \vdash e_1 : \tau_1 \to \tau_2 \hookrightarrow E_1 \quad \gamma \vdash e_2 : \tau_3 \hookrightarrow E_2 \quad \tau_3 \lhd \tau_1 \hookrightarrow C}{\gamma \vdash e_1 e_2 : \tau_2 \hookrightarrow E_1 \; (C \; E_2)} \; \text{EAPP} \quad \frac{\gamma, \alpha \vdash e : \tau \hookrightarrow E}{\gamma \vdash \Lambda \alpha. e : \forall \alpha. \tau \hookrightarrow \Lambda \alpha. E} \; \text{EBLAM}$$
 
$$\frac{\gamma \vdash e : \forall \alpha. \tau_1 \hookrightarrow E}{\gamma \vdash e \tau : [\tau/\alpha]\tau_1 \hookrightarrow E \; |\tau|} \; \text{ETAPP} \quad \frac{\gamma \vdash e_1 : \tau_1 \hookrightarrow E_1 \quad \gamma \vdash e_2 : \tau_2 \hookrightarrow E_2 \quad \tau_1 \perp \tau_2}{\gamma \vdash e_1, , e_2 : \tau_1 \& \tau_2 \hookrightarrow (E_1, E_2)} \; \text{EMERGE}$$
 
$$\frac{\gamma \vdash e : \tau \hookrightarrow E}{\gamma \vdash \{l = e\} : \{l : \tau\} \hookrightarrow E} \; \text{EREC-CONSTRUCT} \quad \frac{\gamma \vdash e : \tau \hookrightarrow E}{\gamma \vdash e \mid \tau_1 \hookrightarrow C} \; \text{EREC-RESTRICT}$$
 
$$\frac{\gamma \vdash e : \tau \hookrightarrow E}{\gamma \vdash e \mid \tau_1 \hookrightarrow C} \; \text{ENEC-RESTRICT}$$
 
$$\frac{\gamma \vdash e : \tau \hookrightarrow E}{\gamma \vdash e \mid \tau_1 \hookrightarrow C} \; \text{ENEC-RESTRICT}$$
 
$$\frac{\tau_1 \bullet l = \tau_2 \hookrightarrow C}{\tau_1 \& \tau_2 \bullet l = \tau \hookrightarrow \lambda(x : |\tau_1 \& \tau_2|) . \; C \; (\text{proj}_2 x)} \; \text{select}$$
 
$$\frac{\tau_1 \bullet l = \tau \hookrightarrow C}{\tau_1 \& \tau_2 \bullet l = \tau \hookrightarrow \lambda(x : |\tau_1 \& \tau_2|) . \; C \; (\text{proj}_2 x)} \; \text{select}$$
 
$$\frac{\tau_1 \land t = \tau \hookrightarrow C}{\tau_1 \& \tau_2 \lor l = \tau \hookrightarrow \lambda(x : |\tau_1 \& \tau_2|) . \; C \; (\text{proj}_2 x)} \; \text{restrict}$$
 
$$\frac{\tau_1 \land t = \tau \hookrightarrow C}{\tau_1 \& \tau_2 \land l = \tau \Leftrightarrow \lambda(x : |\tau_1 \& \tau_2|) . \; (C \; (\text{proj}_1 x), \text{proj}_2 x)} \; \text{restrict}_1$$
 
$$\frac{\tau_2 \land l = \tau \hookrightarrow C}{\tau_1 \& \tau_2 \land l = \tau \hookrightarrow C} \; \text{restrict}_2$$

**Figure 8.** Elaboration typing.