# Notes on Math in Economics

### Victor Li

### October 2023

# Contents

1	LOGIC	2
2	SET	3
3	TOPOLOGY ON EUCLIDEAN SPACE	4
4	TOPOLOGY	9
5	LINEAR ALGEBRA	10
6	FIXED POINT	11
7	LATITICE AND SUPER-MODULARITY	<b>12</b>
8	STATIC OPTIMIZATION	13
9	DYNAMIC OPTIMIZATION	14

### 1 LOGIC

Proposition

is a declaration that can be either true or false, but not both. If withour further notice, P and Q is propositions as default.

Negation

 $\neg P$ 

Conjunction

 $P \wedge Q$ 

Disjunction

 $P \vee Q$ 

Implication

 $P \Rightarrow Q$ 

Equivalence

 $P \iff Q$ 

Converse

 $P \Rightarrow Q : Q \Rightarrow P$ 

Inverse

$$P \Rightarrow Q : \neg P \Rightarrow \neg Q$$

Contrapositive

$$P \Rightarrow Q : \neg Q \Rightarrow \neg P$$

Contradiction

$$(P \land \neg Q) \Rightarrow \neg P$$
 ,  
where P is a priori  $\Rightarrow Q$ 

Logically equivalence

$$P \equiv Q, (P \Rightarrow Q) \equiv (\neg Q \Rightarrow \neg P) \equiv [(P \land \neg Q) \Rightarrow \neg P]$$

Truth table

Р	Q	¬ <b>P</b>	$P \lor Q$	$P \land Q$	$P{\Rightarrow}Q$	$P \Longleftrightarrow Q$	$\mathbf{Q}{\Rightarrow}\mathbf{P}$	$\neg P \Rightarrow \neg Q$	$\neg Q \Rightarrow \neg P$
Т	Т	F	Т	Т	Т	Т	Т	Т	Т
Т	F	F	Т	F	F	F	T	Т	F
F	Т	Т	Т	F	Т	F	F	F	Т
F	F	Т	F	F	Т	T	Т	T	T

Universal quantifier

$$\forall x, P(x)$$

Existence quantifier

$$\exists x, P(x)$$

Negation of the two quantifier

$$\neg [\forall x, P(x)] \equiv [\exists x, \neg P(x)]; \tag{1}$$

$$\neg [\exists x, P(x)] \equiv [\forall x, \neg P(x)] \tag{2}$$

### 2 SET

 $\operatorname{Set}$ 

$$e.g.X = \{1, 2, 3\}$$

Element

$$\omega \in X$$

Family

$$\mathscr{X} = \{A,B,C\}$$

Union

$$A \cup B = \{\omega | (\omega \in A) \lor (\omega \in B)\} = A + B$$

Intersection

$$A \cap B : \{\omega | (\omega \in A) \land (\omega \in B)\} = AB$$

Complement

$$A \setminus B = \{\omega | (\omega \in A) \land (\omega \notin B)\} = A - B \tag{3}$$

$$A^c = \Omega \setminus A \tag{4}$$

$$A \setminus B = A \cap B^c \tag{5}$$

Disjoint

$$A \cap B = \emptyset \tag{6}$$

$$A \cap A^c = \emptyset \tag{7}$$

Subset

$$A \subset B : \omega \in A \Rightarrow \omega \in B$$

Superset

$$B \supset A$$

Equivalence

$$A = B \iff (A \subset B) \land (B \subset A)$$

Equivalent difference

$$A \triangle B = (A \setminus B) \cup (B \setminus A)$$

Algorithing rules

$$A \cap B = B \cap A, A \cup B = B \cup A \tag{8}$$

$$(A \cup B) \cap C = (A \cap C) \cup (B \cap C) \tag{9}$$

De Morgan's Rule

$$(\cup A_i)^c = \cap A_i^c, (\cap A_i)^c = \cup A_i^c$$

Cartesian products

$$\underset{i \in I}{\pi} A_i = A_1 \times A_2 \times \dots \times A_I$$

### 3 TOPOLOGY ON EUCLIDEAN SPACE

Euclidean space

the space of vectors of real numbers with n components, denoted as  $\mathbb{R}^n$ . Metric on  $\mathbb{R}^n$ 

$$(x,y) \in \mathbb{R}^n, (\mathbb{R}^n, d) : d(x,y) = \sqrt{\sum_{i=1}^n (x_i - y_i)^2}$$

Equal of vectors on  $\mathbb{R}^n$ 

$$x = y \iff \forall i, x_i = y_i$$

Greater than or equal of vectors on  $\mathbb{R}^n$ 

$$x \geqslant y \iff \forall i, x_i \geqslant y_i$$

Greater than of vectors on  $\mathbb{R}^n$ 

$$x > y \iff \forall i, x_i \geqslant y_i; \exists j, x_i > y_i$$

Much greater than of vectors on  $\mathbb{R}^n$ 

$$x \gg y \iff \forall i, x_i > y_i$$

 $\epsilon$ -open ball/  $\epsilon$ -neighborhood of x on  $\mathbb{R}^n$ 

$$B_{\epsilon}(x) = \{ y \in \mathbb{R}^n | d(x, y) < \epsilon \}$$

Max on  $\mathbb{R}$ 

$$\exists A \in \mathbb{R}, (x \in A) \land (\forall a \in A, x \geqslant a) \Rightarrow x = \max A$$

Min on  $\mathbb{R}$ 

$$\exists A \in \mathbb{R}, (x \in A) \land (\forall a \in A, x \leqslant a) \Rightarrow x = \min A$$

Upper bound on  $\mathbb{R}$ 

$$\exists A \subset \mathbb{R}, (x \in \mathbb{R}) \land (\forall a \in A, x \geqslant a) \Rightarrow x \text{ is the upper bound of } A$$

Supremum on  $\mathbb{R}$  x is the least upper bound of  $A \subset \mathbb{R} \iff x = \sup A$  Lower bound on  $\mathbb{R}$ 

$$\exists A \subset \mathbb{R}, (x \in \mathbb{R}) \land (\forall a \in A, x \leqslant a) \Rightarrow x \text{ is the lower bound of } A$$

Infimum on  $\mathbb{R}$  x is the least lower bound of  $A \subset \mathbb{R} \iff x = \inf A$ Open set on  $\mathbb{R}^n$ 

$$S \subset \mathbb{R}^n, \forall x \in S, \exists \epsilon > 0, B_{\epsilon}(x) \subset S$$

**Theorem 1.** some theorems of open set:

1. 
$$\varnothing$$
 and  $\mathbb{R}^n$  are open (10)

Topology

a system  $\tau = \{S_{\alpha}\}_{{\alpha} \in A}$  is a topology on space X if

1. 
$$\emptyset$$
 and  $X \in \tau$  (13)

2. 
$$\forall \{S_{\beta} | S_{\beta} \in \tau\}, \cup S_{\beta} \in \tau$$
 (14)

3. 
$$\forall \{S_k | S_k \in \tau, k = 1, 2...n\}, \cap S_k \in \tau$$
 (15)

Closed set

$$S \subset \mathbb{R}^n$$
 is closed if  $S^c$  is open

**Theorem 2.** Some theorems of closed set:

1. 
$$\varnothing$$
 and  $\mathbb{R}^n$  are open (16)

Sequence in  $\mathbb{R}^n$ 

$$\{x^i\}_{n=1}^{\infty} = \{x_1, x_2, ..., x_n, ...\}, x_i \in \mathbb{R}^n$$

Converge

if for a sequence  $\{x^i\}$ ,  $\forall \epsilon > 0$ ,  $\exists N, i \ge N, d(x^i, \alpha) < \epsilon \Rightarrow x$  is the limit of the sequence  $\{x^i\}$ 

Bounded

$$\exists M > 0, S \subset B_M(\cdot)$$

**Theorem 3.** A non-decreasing and bounded sequence  $\{x^i\}_{i=1}^{\infty}$  in  $\mathbb{R}$  converges.

Proof.

bounded 
$$\Rightarrow \exists M > 0, \{x_i\}_{i=1}^{\infty} \subset B_M(0) = \{y \in \mathbb{R} : \sqrt{(y-0)^2} < M\}$$
 (19)

$$\Rightarrow \sup\{x^i\}_{i=1}^{\infty} < M \tag{20}$$

$$\forall \epsilon > 0, x - \epsilon$$
 is not an upper bound of the sequence (21)

$$\Rightarrow \exists x^N \in x_i, x^N > x - \epsilon \tag{22}$$

nondecreasing 
$$\Rightarrow \forall i \geqslant N, x^i \geqslant x^N \Rightarrow x^i > x - \epsilon$$
 (23)

$$\forall i, x \geqslant x^i \Rightarrow x > x^i - \epsilon \tag{24}$$

$$\Rightarrow |x - x^i| = d(x, x^i) < \epsilon \Rightarrow \text{converge}$$
 (25)

Using convergence to define closed set

$$S \in \mathbb{R}^n, \{x^i\} \subset S, \{x^i\} \to x \in S \Rightarrow S$$
 is a closed set

Non-empty closed cell in  $\mathbb{R}^n$ 

$$I = \{x = (x_1, x_2, ..., x_n) : a_1 \le x_1 \le b_1, a_2 \le x_2 \le b_2, ..., a_n \le x_n \le b_n, \}$$
 (26)

$$= [a_1, b_1] \times [a_2, b_2] \times \dots \times [a_n, b_n]$$
 (27)

Theorem 4 (Nested cells theorem).

Let 
$$\{I_i\}$$
 be a sequence of non-empty closed cells in  $\mathbb{R}^n$  that are nested, (28)

$$i.e.I_1 \supset I_2 \supset \cdots \supset I_k \supset I_{k+1} \supset \dots$$
 (29)

$$then \bigcap_{i=1}^{\infty} I_i \neq \emptyset \tag{30}$$

Subsequence

$$\exists \{x^i\} \in \mathbb{R}^n, \{x^{i_k}\} \text{ where } i_k < i_{k+1}$$

$$\tag{31}$$

$$e.g. (32)$$

$$\{x^i\} = \{x_1, x_2, x_3, x_4, x_5, \dots\}$$
(33)

$$\{x^{i_k}\} = \{x_1, x_3, x_5, \dots\} \tag{34}$$

**Theorem 5** (Bolzano-Weierstrass theorem). The theorem states that each infinite bounded sequence in  $\mathbb{R}^n$  has a convergent subsequence. An equivalent formulation is that a subset of  $\mathbb{R}^n$  is sequentially compact if and only if it is closed and bounded. The theorem is sometimes called the sequential compactness theorem.

#### Open cover

a family  $\{T_{\alpha}\}_{\alpha \in A} \in \mathbb{R}^n$  is said to be an open cover of  $S \subset \mathbb{R}^n$  if  $T_{\alpha}$  is open for each  $\alpha \in A$  and  $S \subset \cup_{\alpha} T_{\alpha}$ 

Finite open subcover

given an open cover  $\{T_{\alpha}\}_{\alpha \in A} \in \mathbb{R}^n$ ,  $\{T_{\alpha_k}\}_{k=1}^N$  is said to be a finite subcover if for each  $\alpha_k \in A, S \subset \bigcup_{\alpha_k} T_{\alpha_k}$ .

Compact

a set  $S \subset \mathbb{R}^n$  is compact if for any open cover of S, there exists a finite open subcover

**Theorem 6** (Heine-Borel theorem).  $S \subset \mathbb{R}^n$  is compact  $\iff S$  is closed and bounded

Function

$$f: X \to Y = \{ y \in Y | \exists x \in X, f(x) \in Y \}; \tag{35}$$

$$\exists S \subset X, f(S) = \{ y \in Y | \exists x \in S, f(x) = y \}$$
 (36)

One-to-one or Injection

$$f(x_1) \neq f(x_2), x_1 \neq x_2$$

Continuent function

$$\exists f: \mathbb{R}^n \to \mathbb{R}^m, \forall x \in \mathbb{R}^n, \exists \delta > 0, \forall x' \in B_{\delta}(x), f(x') \in B_{\delta}[f(x)]$$
 (37)

$$or$$
 (38)

$$\forall \text{ open } T \subset \mathbb{R}^n, f^{-1}(T) \text{ is open}$$
 (39)

Theorem 7 (Weierstrass theorem).

$$D \subset X$$
 is a nonempty compact set (40)

$$f: X \to Y \text{ is a continuent function}$$
 (41)

$$\Rightarrow f(D) \subset Y \text{ is compact}$$
 (42)

Lemma 1 (Corollary of Weierstrauss theorem on real Number space).

$$D \subset X$$
 is a nonempty compact set (43)

$$f: X \to \mathbb{R} \text{ is a continuent function}$$
 (44)

$$\Rightarrow \exists x_1, x_2 \in D, \forall x \in D, f(x_1) \leqslant f(x) \leqslant f(x_2) \tag{45}$$

Distance between point and closed set

using Weierstrauss theorem to make sure there is a shortest distance between a point and a closed set

Vector/a point in Euclidean space

$$x = (x_1, x_2, ..., x_n) \in \mathbb{R}^n$$

Convex

 $C \subset \mathbb{R}^n$  is convex if and only if  $\forall x, y \in C$  and  $\lambda \in [0,1], \lambda x + (1-\lambda)y \in C$ 

Theorem 8 (Two theorems about convexity).

$$\exists C, D \in \mathbb{R}^n \ are \ convex \Rightarrow$$
 (46)

$$C + D = \{x + y | x \in C, y \in D\} \text{ is convex}; \tag{47}$$

$$\forall \alpha \in \mathbb{R}, \alpha C \text{ is also convex} \tag{48}$$

Hyperplane

$$\exists h \in \mathbb{R}^n, \lambda \in \mathbb{R}, \{x \in \mathbb{R}^n | hx = \lambda\} \text{ is a hyperplane}$$

Half-space

$$\exists h \in \mathbb{R}^n, \lambda \in \mathbb{R}, \{x \in \mathbb{R}^n | hx \leq \lambda\} \text{ or } \{x \in \mathbb{R}^n | hx \geq \lambda\} \text{ is a half-space}$$

**Theorem 9** (seperating hyperplane theorem).

Suppose that a set 
$$C \neq \emptyset \subset \mathbb{R}^n$$
 is closed and convex, and a point  $b \notin C$  (49)

$$\Rightarrow \exists h \in \mathbb{R}^n, \exists \lambda \in \mathbb{R}, \forall x \in C, h \cdot b < \lambda < h \cdot x \tag{50}$$

Using hyperplane to seperate two convex sets

Suppose that two nonempty sets  $C, D \subset \mathbb{R}^n$  are closed and convex, and  $C \cap D = \emptyset$  (51)

if at least one of the two sets is bounded, then  $\exists h \neq 0 \in \mathbb{R}^n, \exists \lambda \in \mathbb{R},$  (52)

$$\forall x \in C, \forall y \in D, h \cdot x < \lambda < h \cdot y \tag{53}$$

Corrospondance

$$F: X \Rightarrow Y \iff \forall x \in X, F(x) \subset Y$$

- F(x) is assumed non-empty from now on if without furthur notice Compact-valued correspondence

$$\forall x \in X, F(x) \subset Y \text{ is compact}$$

Convex-valued correspondance

$$\forall x \in X, F(x) \subset Y \text{ is convex}$$

Closed-valued correspondance

$$\forall x \in X, F(x) \subset Y \text{ is closed}$$

Singleton-valued correspondance

$$\forall x \in X, F(x) \subset Y$$
 is a singleton set  $\iff F(x)$  is a function  $f(x)$ 

Continuous function

A function f is continuous if and only if for any open  $\forall x \in X$ 

Upper hemi-continuous correspondance Lower hemi-continuous correspondance

#### Theorem 10.

F is continuous if and only if F is both upper hemi-continuous and lower hemi-continuous.

### 4 TOPOLOGY

a topology  $\tau$  on X is a family of subsets of X satisfying

$$\begin{cases} \varnothing, X \in \tau \\ \tau \text{ is closed under finite intersections} \\ \tau \text{ is closed under unions} \end{cases}$$

Topological space

$$(X,\tau)$$

Open set

a member of  $\tau$  is an open set

Closed set

the complement of an open set is a closed set

Interior and Closure

let  $(x,\tau)$  be a topological space and  $A\subset X$ , interior is the largest open set included by A

and closure is the smallest closed set including A

Dense

If 
$$D \in (X, \tau)$$
,  $Cl(D) = X \Rightarrow D$  is dense

Seperable

$$\exists D \in (X, \tau), Cl(D) = X \Rightarrow X \text{ is seperable}$$

Continuous function

In  $(X,\tau), f:X\to Y$  is continuous if  $f^{-1}(U)\subset X$  is open whenever  $U\subset Y$  is open

Hemeomorphic

 $\exists (X,\tau), (Y,\tau)$ , if a one-to-one continuous function  $f: X \to Y$  such that  $f^{-1}$  is continuous Compact

 $\exists K \subset (X, \tau), \forall$  open cover K includes a finite subcover  $\iff K$  is compact

**Theorem 11** (Weierstrass theorem). Every continuous function from topological space to another carries compact sets to compact sets.

## 5 LINEAR ALGEBRA

## 6 FIXED POINT

## 7 LATITICE AND SUPER-MODULARITY

## 8 STATIC OPTIMIZATION

 $\begin{array}{c} {\rm Lagrangian~method} \\ {\rm KKT~method} \end{array}$ 

## 9 DYNAMIC OPTIMIZATION

Hamiltonian method Bellman method Discrete time optimization