

# Stima & Filtraggio: Lab 2

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## *Today's Lab*

### Wiener Filtering & Applications

- ① Stochastic processes in **MATLAB**<sup>®</sup>
- ② **MATLAB**<sup>®</sup> tools for Wiener filtering

## *Today's Lab*

### Wiener Filtering & Applications

#### ① Stochastic processes in **MATLAB**<sup>®</sup>

- Generating white noise
- Generating filtered noise
- Useful **MATLAB**<sup>®</sup> commands

*(weakly stationary)*  
**white noise processes**

$$\{e(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[e(t)] = \mu, \mathbb{E}[e(t)e(s)] = \sigma^2\delta(t-s) + \mu^2$$



*(weakly stationary)*  
**white noise processes**

$$\{e(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[e(t)] = \mu, \mathbb{E}[e(t)e(s)] = \sigma^2 \delta(t-s) + \mu^2$$

$$\bar{e}(t) := e(t) - \mu, \bar{e}(t) \perp \bar{e}(s), s \neq t$$



*(weakly stationary)*  
**white noise processes**

$$\{e(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[e(t)] = \mu, \mathbb{E}[e(t)e(s)] = \sigma^2 \delta(t-s) + \mu^2$$

100 samples of Gaussian white noise with mean  $\mu$  and var.  $\sigma^2$ :

```
>> rvE = dMu + dSigma*randn(1,100)
```

$\mu$

$\sigma$



*(weakly stationary)*  
**white noise processes**

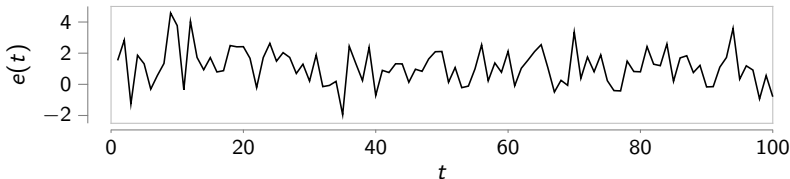
$$\{e(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[e(t)] = \mu, \mathbb{E}[e(t)e(s)] = \sigma^2\delta(t-s) + \mu^2$$

100 samples of Gaussian white noise with mean  $\mu$  and var.  $\sigma^2$ :

```
>> rvE = dMu + dSigma*randn(1,100)
```

$$\mu = 1$$

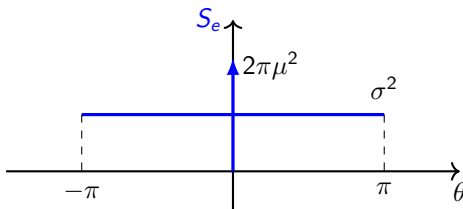
$$\sigma = 1$$



*(weakly stationary)*  
**white noise processes**

$$\{e(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[e(t)] = \mu, \mathbb{E}[e(t)e(s)] = \sigma^2 \delta(t - s) + \mu^2$$

$$\text{Spectral density: } S_e(e^{j\theta}) = 2\pi\mu^2 \delta(\theta) + \sigma^2, \theta \in [-\pi, \pi]$$



Spectral density: related to the *power of a signal*; obtained from spectrum  $S_e(z)$  evaluated on the unit circle





*(weakly stationary)*  
**white noise processes**

*– multivariate case –*

$$\{\mathbf{e}(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[\mathbf{e}(t)] = \boldsymbol{\mu}, \mathbb{E}[\mathbf{e}(t)\mathbf{e}^\top(s)] = \Sigma \delta(t-s) + \boldsymbol{\mu}\boldsymbol{\mu}^\top$$

$$\Sigma = \Sigma^\top \geq 0$$



(weakly stationary)  
**white noise processes**

– *multivariate case* –

$$\{\mathbf{e}(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[\mathbf{e}(t)] = \boldsymbol{\mu}, \mathbb{E}[\mathbf{e}(t)\mathbf{e}^\top(s)] = \Sigma \delta(t-s) + \boldsymbol{\mu}\boldsymbol{\mu}^\top$$

100 samples of 2-dim. Gaussian white noise with  
mean  $\boldsymbol{\mu} \in \mathbb{R}^2$  and cov.  $\Sigma = \Sigma^\top \in \mathbb{R}^{2 \times 2}$ ,  $\Sigma \geq 0$ :

```
>> mE = rvMu + sqrtm(dSigma)*randn(2,100)
```

$\boldsymbol{\mu}$

$\Sigma^{\frac{1}{2}}$

symmetric matrix

square root



*(weakly stationary)*  
**white noise processes**

*– multivariate case –*

$$\{\mathbf{e}(t)\}_{t \in \mathbb{Z}} \text{ s.t. } \mathbb{E}[\mathbf{e}(t)] = \boldsymbol{\mu}, \mathbb{E}[\mathbf{e}(t)\mathbf{e}^\top(s)] = \Sigma \delta(t-s) + \boldsymbol{\mu}\boldsymbol{\mu}^\top$$

100 samples of 2-dim. Gaussian white noise with  
mean  $\boldsymbol{\mu} \in \mathbb{R}^2$  and cov.  $\Sigma = \Sigma^\top \in \mathbb{R}^{2 \times 2}$ ,  $\Sigma \geq 0$ :

```
>> mE = rvMu + chol(dSigma, 'lower') * randn(2, 100)
```

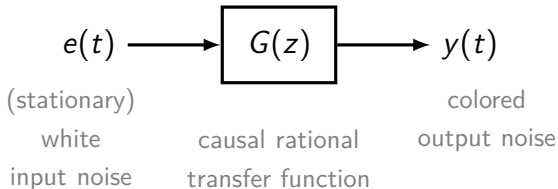
$\boldsymbol{\mu}$

$L : \Sigma = LL^\top$

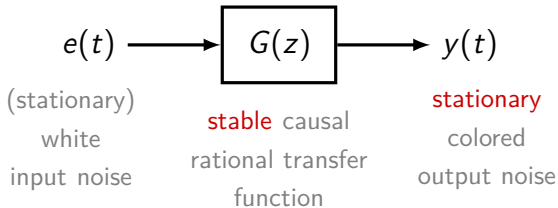
Cholesky factor  
(numerically  
convenient)



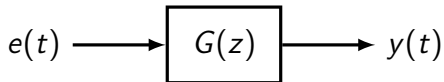
## Filtered noise processes



## Filtered noise processes



## Filtered noise processes



$$G(z) = \frac{N(z)}{D(z)}, \quad N(z), D(z) \text{ polynomials}$$

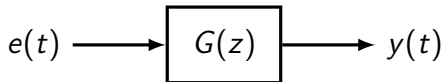


$$D^*(z^{-1})y(t) = N^*(z^{-1})e(t) \quad \left( P^*(z^{-1}) = z^{-n}P(z), n = \deg(P(z)) \right)$$

ARMA representation,  
 $z^{-1}$  = delay operator



## Filtered noise processes

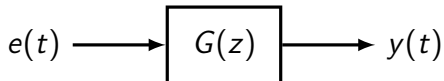


**Task.** Generate 100 samples of the process

$$y(t) = 0.1y(t-1) + e(t) - 0.2e(t-2)$$

where  $\{e(t)\}_{t \in \mathbb{Z}}$  is a Gaussian WN process ( $\mu = 0$ ,  $\sigma = 1$ )

## Filtered noise processes



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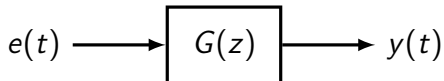
Note that  $N^*(z^{-1}) = 1 - 0.2z^{-2}$ ,  $D^*(z^{-1}) = 1 - 0.1z^{-1}$

$$\implies G(z) = \frac{z^2 - 0.2}{z^2 - 0.1z} \quad (\text{stable!})$$





## Filtered noise processes



**Task.** Generate 100 samples of the process

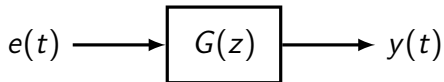
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---

<code>&gt;&gt; rvN = [1 0 -0.2]</code>	define the numerator and
<code>&gt;&gt; rvD = [1 -0.1 0]</code>	denominator polynomials in $z^{-1}$
	(does something change in $z$ ?)

## Filtered noise processes



**Task.** Generate 100 samples of the process

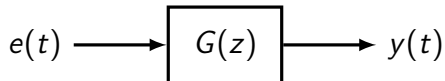
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where  $\{e(t)\}_{t \in \mathbb{Z}}$  is a Gaussian WN process ( $\mu = 0, \sigma = 1$ )

---

```
>> rvE = randn(1,100)    create white noise sequence
```

## Filtered noise processes



**Task.** Generate 100 samples of the process

$$y(t) = 0.1y(t-1) + e(t) - 0.2e(t-2)$$

where  $\{e(t)\}_{t \in \mathbb{Z}}$  is a Gaussian WN process ( $\mu = 0, \sigma = 1$ )

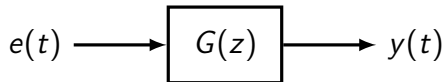
---

```
>> rvY = filter(rvN,rvD,rvE)    generate the process!
```

**N.B.** Initial conditions set to 0



## Filtered noise processes



**Task.** Generate 100 samples of the process

$$y(t) = 0.1y(t-1) + e(t) - 0.2e(t-2)$$

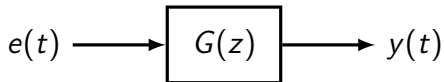
where  $\{e(t)\}_{t \in \mathbb{Z}}$  is a Gaussian WN process ( $\mu = 0$ ,  $\sigma = 1$ )

---

*an alternative procedure...*



## Filtered noise processes



**Task.** Generate 100 samples of the process

$$y(t) = 0.1y(t-1) + e(t) - 0.2e(t-2)$$

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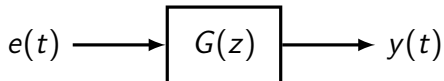
---

`>> z = tf('z')` define the transfer function

`>> tfG = (z^2-0.2)/(z^2-0.1*z)`



## Filtered noise processes



**Task.** Generate 100 samples of the process

$$y(t) = 0.1y(t-1) + e(t) - 0.2e(t-2)$$

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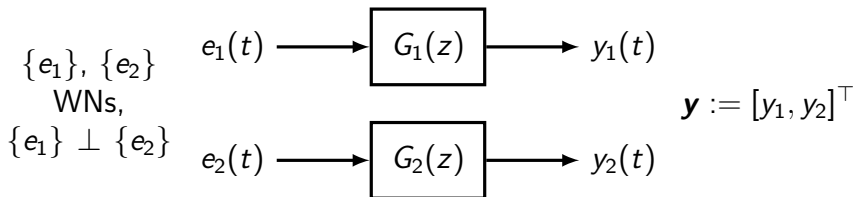
```
>> cvY = lsim(tfG,rvE)           generate the process!
```

**N.B.** Initial conditions set to 0

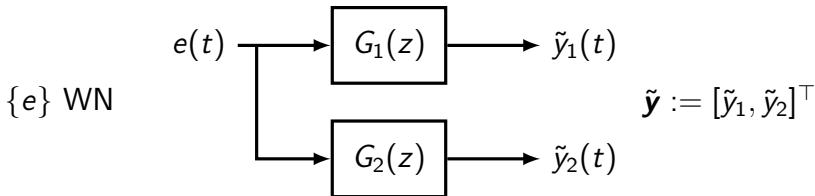


## Filtered noise processes

– *an important remark* –

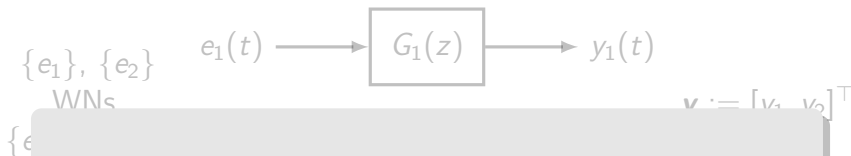


$\{e_1\}, \{e_2\}, \{e\}$  same mean and variance

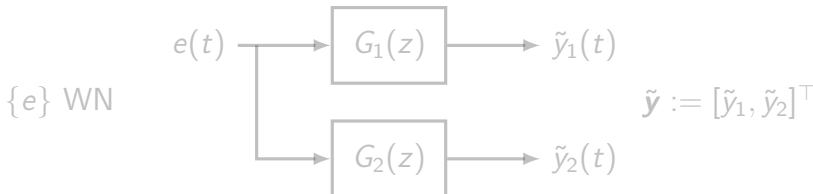


## Filtered noise processes

– *an important remark* –

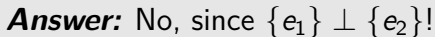


**Question:** Do  $\mathbf{y}$  and  $\tilde{\mathbf{y}}$  define the same process?





**– an important remark –**





## Useful MATLAB® commands

(Pay attention on  $z$  and  $z^{-1}$ !)

Create TF $\frac{N(z)}{D(z)}$	<code>&gt;&gt; tfG = tf(rvN,rvD,-1)</code>
Filter $\{e(t)\}_t$ by $\frac{N^*(z^{-1})}{D^*(z^{-1})}$	<code>&gt;&gt; rvY = filter(rvN,rvD,rvE)</code>
Filter $\{e(t)\}_t$ by $G(z)$	<code>&gt;&gt; cvY = lsim(tfG,rvE)</code>
Recover $N(z)$ , $D(z)$	<code>&gt;&gt; [rvN,rvD] = tfdata(tfG,'v')</code>
From TF to SS	<code>&gt;&gt; ssG = ss(tfG)</code>
From TF to ZPK	<code>&gt;&gt; zpkG = zpk(tfG)</code>



## *Practice time 1!*

**Ex 1.1.** Create a function

```
[bS,bMP] = checkTFStability(tfG)
```

that has as input a causal scalar discrete-time transfer function object `tfG`. The function returns

- boolean `bS` = `true` if any coprime representation of `tfG` is (strictly) **stable**, and `bS` = `false` otherwise,
- boolean `bMP` = `true` if any coprime representation of `tfG` is **minimum phase**, i.e. it is stable with marginally stable inverse, and `bMP` = `false` otherwise.

Then, test the function on the following TFs:

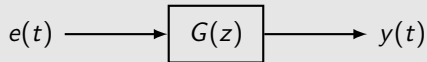
$$G_1(z) = \frac{z+2}{z^2+0.4z-0.45}, \quad G_2(z) = \frac{z^2-0.7z+1}{z^2+0.4z-0.45}, \quad G_3(z) = \frac{z(z+1)}{z^2+2.5z+1}.$$

## Practice time 1!

**Ex 1.2.** Create a function

`plotSpectrum(tfG)`

that has as input a causal scalar discrete-time transfer function `tfG`. The function plots the **spectral density** in the frequency interval  $\theta \in [-\pi, \pi]$  of the process generated by filtering a Gaussian WN process ( $\mu = 0$ ,  $\sigma = 1$ ) through `tfG`. If `tfG` has poles on the unit circle, the function throws an error and displays an error message.



Then, test the function on the TFs of Ex. 1.1.

**Extra question.** What happens if  $\sigma \neq 1$ ?

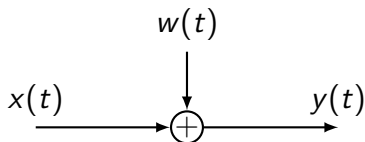
## *Today's Lab*

### Wiener Filtering & Applications

- ② Wiener filtering in **MATLAB**<sup>®</sup>
  - Quick recap
  - Computing integrals via residues
  - Computing causal and anticausal parts
  - Perform spectral factorization

# Wiener filtering

## Setup



$\{x(t)\}_{t \in \mathbb{Z}}$ : stationary input process

$\{w(t)\}_{t \in \mathbb{Z}}$ : stationary external noise

$\{y(t)\}_{t \in \mathbb{Z}}$ : stationary output process

$$\begin{bmatrix} S_x & S_{xy} \\ S_{xy}^* & S_y \end{bmatrix}$$

Joint spectrum

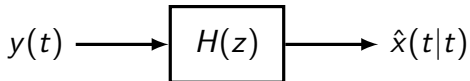


# Wiener filtering

## *Wiener estimate*

$$H(z) := \left[ \frac{S_{xy}(z)}{L(z^{-1})} \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$



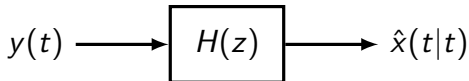


# Wiener filtering

## *Wiener estimate*

$$H(z) := [S_{x\epsilon}(z)]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$

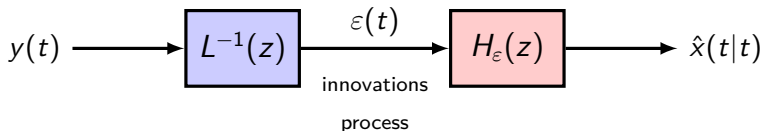


# Wiener filtering

## Wiener estimate

$$H(z) := \left[ \frac{S_{xy}(z)}{L(z^{-1})} \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$



# Wiener filtering

## *Wiener estimate*

$$H(z) := \left[ \frac{S_{xy}(z)}{L(z^{-1})} \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$

$$\text{Var } \tilde{x}(t|t) = \int_{-\pi}^{\pi} \left( S_x(e^{j\theta}) - H_\varepsilon(e^{j\theta})H_\varepsilon(e^{-j\theta}) \right) \frac{d\theta}{2\pi}$$

estimation error variance



## Wiener filtering *in practice*

How to compute the integral of a rational function upon the unit circle?

How to compute the causal and (strictly) anticausal part of a rational function?

How to perform spectral factorization?



## Wiener filtering *in practice*

How to compute the integral of a rational function upon the unit circle?

How to compute the causal and (strictly) anticausal part of a rational function?

How to perform spectral factorization?



## Computing integrals via residues

Let  $G(z) = N(z)/D(z)$  be a scalar rational function. We can decompose  $G(z)$  using partial fraction expansion

$$G(z) = \sum_{i=1}^{n_p} \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j} + k_{n_\infty} z^{n_\infty} + \cdots + k_1 z + k_0$$

- $\{p_i\}_{i=1}^{n_p}$  are the poles of  $G(z)$  and  $\{\mu_i\}_{i=1}^{n_p}$  the corresponding multiplicities
- $R_{ij}$  are (in general, complex) coefficients corresponding to the term of multiplicity  $\mu_j$  of the pole  $p_i$
- $n_\infty = \max\{\deg N(z) - \deg D(z), 0\}$



## Computing integrals via residues

The coefficients  $R_{ij}$  are called *residues*<sup>\*</sup> and are of crucial importance in complex analysis.

If  $p_i$  has multiplicity  $\mu_i = 1$ , then

$$R_{i1} = \lim_{z \rightarrow p_i} G(z)(z - p_i)$$

If  $p_i$  has multiplicity  $\mu_i > 1$ , then

$$R_{ij} = \frac{1}{(\mu_i - j)!} \lim_{z \rightarrow p_i} \left[ \frac{d^{\mu_i - j}}{dz^{\mu_i - j}} G(z)(z - p_i)^{\mu_i} \right], \quad j = 1, \dots, \mu_i$$

<sup>\*</sup>Formally, the residues are only the coefficients  $R_{i1}$ 's.

## Computing integrals via residues

Let  $F(z)$  be a rational function analytic on the unit circle. The computation of the integral of  $F(z)$  upon the unit circle boils down to

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} F(e^{j\theta}) d\theta = \frac{1}{2\pi j} \oint_{|z|=1} \frac{F(z)}{z} dz = \sum_{i: |p_i| < 1} R_{i1}$$

Hence, it suffices to

- 1 Compute the partial fraction expansion of  $G(z) = F(z)/z$
- 2 Sum the (one-multiplicity) residues  $R_{i1}$  of poles  $p_i$  s.t.  $|p_i| < 1$





# Computing integrals via residues

*...in MATLAB<sup>®</sup>*

```
>> [cvR, cvP, rvK] = residue(rvN, rvD)
```

- $\text{cvR} = [R_{11} \ R_{12} \ \dots \ R_{1\mu_1} \ R_{21} \ \dots]^\top$
- $\text{cvP} = [p_1 \ p_1 \ \dots \ p_1 \ p_2 \ \dots]^\top$  (every  $p_i$  is repeated  $\mu_i$  times!)
- $\text{rvK} = [k_{n_\infty} \ \dots \ k_1 \ k_0]$



# Computing integrals via residues

...in MATLAB®

```
>> [cvR, cvP, rvK] = residue(rvN, rvD)
```

```
>> [rvN, rvD] = residue(cvR, cvP, rvK)
```

- $\text{cvR} = [R_{11} \ R_{12} \ \dots \ R_{1\mu_1} \ R_{21} \ \dots]^\top$

Inverse operation!

- $\text{cvP} = [p_1 \ p_1 \ \dots \ p_1 \ p_2 \ \dots]^\top$  (every  $p_i$  is repeated  $\mu_i$  times!)

- $\text{rvK} = [k_{n_\infty} \ \dots \ k_1 \ k_0]$



## Wiener filtering *in practice*

How to compute the integral of a rational function upon the unit circle?

How to compute the causal and (strictly) anticausal part of a rational function?

How to perform spectral factorization?



## Computing causal and (strictly) anticausal parts

Let  $G(z) = N(z)/D(z)$  be a scalar rational function analytic on the unit circle. We can decompose  $G(z)$  as

$$\begin{aligned} G(z) &= \sum_{i=1}^{n_p} \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j} + k_{n_\infty} z^{n_\infty} + \cdots + k_1 z + k_0 \\ &= \sum_{i: |p_i| < 1} \text{Res}_i(z) + k_0^+ + k_0^- + \sum_{i: |p_i| > 1} \text{Res}_i(z) + \sum_{i=1}^{n_\infty} k_i z^i \end{aligned}$$

where  $\text{Res}_i(z) := \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j}$ ,  $k_0 = k_0^+ + k_0^-$  with

$$k_0^- := - \sum_{|p_i| > 1} \text{Res}_i(0)$$



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where  $\text{Res}_i(z) := \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j}$ ,  $k_0 = k_0^+ + k_0^-$  with

$$k_0^- := - \sum_{|p_i| > 1} \text{Res}_i(0)$$

**Why  $k_0^-$ ?** At  $z = 0$ , the strictly anticausal part must be 0



## Computing causal and (strictly) anticausal parts

Let  $G(z) = N(z)/D(z)$  be a scalar rational function analytic on the unit circle. We can decompose  $G(z)$  as

$$\begin{aligned} G(z) &= \sum_{i=1}^{n_p} \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j} + k_{n_\infty} z^{n_\infty} + \cdots + k_1 z + k_0 \\ &= \underbrace{\sum_{i: |p_i| < 1} \text{Res}_i(z) + k_0^+}_{\substack{[G(z)]_+ \\ \text{causal part}}} + \underbrace{k_0^- + \sum_{i: |p_i| > 1} \text{Res}_i(z) + \sum_{i=1}^{n_\infty} k_i z^i}_{\substack{[[G(z)]]_- \\ \text{strictly anticausal part}}} \end{aligned}$$



## Computing causal and (strictly) anticausal parts

Let  $G(z) = N(z)/D(z)$  be a scalar rational function analytic on the unit circle. We can decompose  $G(z)$  as

$$\begin{aligned} G(z) &= \sum_{i=1}^{n_p} \sum_{j=1}^{\mu_i} \frac{R_{ij}}{(z - p_i)^j} + k_{n_\infty} z^{n_\infty} + \cdots + k_1 z + k_0 \\ &= \underbrace{\sum_{i: |p_i| < 1} \text{Res}_i(z) + k_0^+}_{[G(z)]_+ \text{ causal part}} + \underbrace{k_0^- + \sum_{i: |p_i| > 1} \text{Res}_i(z) + \sum_{i=1}^{n_\infty} k_i z^i}_{[[G(z)]]_- \text{ strictly anticausal part}} \end{aligned}$$

**Moral:**  $[G(z)]_+$  and  $[[G(z)]]_-$  can be computed using residues!



## *Practice time 2!*

**Ex 2.1.** Create a function

```
dInt = resIntegral(tfF)
```

that has as input a rational transfer function object `tfF`. The function returns the integral `dInt` upon the unit circle of `tfF` computed via the residue method.

---

Recall:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} F(e^{j\theta}) d\theta = \frac{1}{2\pi j} \oint_{|z|=1} \frac{F(z)}{z} dz = \sum_{i: |p_i| < 1} R_{i1}$$



## *Practice time 2!*

**Ex 2.2.** Create a function

```
[tfCaus,tfACaus] = causalPart(tfG)
```

that has as input a rational transfer function object `tfG`. The function returns the causal part `tfCaus` and the strictly anticausal part `tfACaus` of `tfG`.

---

Recall:

$$G(z) = \underbrace{\sum_{i: |p_i| < 1} \text{Res}_i(z) + k_0^+ + k_0^-}_{[G(z)]_+} + \underbrace{\sum_{i: |p_i| > 1} \text{Res}_i(z) + \sum_{i=1}^{n_\infty} k_i z^i}_{[[G(z)]]_-}$$

## Wiener filtering *in practice*

How to compute the integral of a rational function upon the unit circle?

How to compute the causal and (strictly) anticausal part of a rational function?

How to perform spectral factorization?



## Scalar rational spectral factorization

### *the procedure*

Let  $\{p_i\}_{i=1}^n$  be the *strictly stable* (finite) poles of  $S(z)$  different from zero, counted with multiplicity. Let  $\{z_i\}_{i=1}^m$  be the *marginally stable* (finite) zeros of  $S(z)$  different from zero, counted with multiplicity for the strictly stable zeros and with *half-multiplicity* for the marginally stable zeros.



## Scalar rational spectral factorization

### *the procedure*

Let  $\{p_i\}_{i=1}^n$  be the strictly stable (finite) poles of  $S(z)$  different from zero, counted with multiplicity. Let  $\{z_i\}_{i=1}^m$  be the marginally stable (finite) zeros of  $S(z)$  different from zero, counted with multiplicity for the strictly stable zeros and with half-multiplicity for the marginally stable zeros.

$$1. S(z) = cz^r \frac{\prod_{i=1}^m (z - z_i)(z - 1/\bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z - 1/\bar{p}_i)}, \quad r = n - m \text{ (by symmetry)}$$

*(zero-pole-gain decomposition)*



## Scalar rational spectral factorization

### *the procedure*

Let  $\{p_i\}_{i=1}^n$  be the strictly stable (finite) poles of  $S(z)$  different from zero, counted with multiplicity. Let  $\{z_i\}_{i=1}^m$  be the marginally stable (finite) zeros of  $S(z)$  different from zero, counted with multiplicity for the strictly stable zeros and with half-multiplicity for the marginally stable zeros.

$$1. S(z) = cz^r \frac{\prod_{i=1}^m (z - z_i)(z - 1/\bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z - 1/\bar{p}_i)}, \quad r = n - m$$

$$2. S(z) = \lambda^2 \frac{\prod_{i=1}^m (z - z_i)(z^{-1} - \bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z^{-1} - \bar{p}_i)}, \quad \lambda^2 := c \frac{\prod_{i=1}^m -\frac{1}{\bar{z}_i}}{\prod_{i=1}^n -\frac{1}{\bar{p}_i}} > 0$$

*(“symmetrizing” the equation)*



## Scalar rational spectral factorization

### *the procedure*

Let  $\{p_i\}_{i=1}^n$  be the strictly stable (finite) poles of  $S(z)$  different from zero, counted with multiplicity. Let  $\{z_i\}_{i=1}^m$  be the marginally stable (finite) zeros of  $S(z)$  different from zero, counted with multiplicity for the strictly stable zeros and with half-multiplicity for the marginally stable zeros.

1. 
$$S(z) = cz^r \frac{\prod_{i=1}^m (z - z_i)(z - 1/\bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z - 1/\bar{p}_i)}, \quad r = n - m$$
2. 
$$S(z) = \lambda^2 \frac{\prod_{i=1}^m (z - z_i)(z^{-1} - \bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z^{-1} - \bar{p}_i)}, \quad \lambda^2 := c \frac{\prod_{i=1}^m -\frac{1}{\bar{z}_i}}{\prod_{i=1}^n -\frac{1}{\bar{p}_i}} > 0$$
3. 
$$L(z) = \textcolor{red}{z}^{n-m} \lambda \frac{\prod_{i=1}^m (z - z_i)}{\prod_{i=1}^n (z - p_i)} \quad (\text{"balancing" relative degree})$$



## Scalar rational spectral factorization

### *the procedure*

Let  $\{p_i\}_{i=1}^n$  be the strictly stable (finite) poles of  $S(z)$  different from zero, counted with multiplicity. Let  $\{z_i\}_{i=1}^m$  be the marginally stable (finite) zeros of  $S(z)$  different from zero, counted with multiplicity for the strictly stable zeros and with half-multiplicity for the marginally stable zeros.

$$1. S(z) = cz^r \frac{\prod_{i=1}^m (z - z_i)(z - 1/\bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z - 1/\bar{p}_i)}, \quad r = n - m$$

$$2. S(z) = \lambda^2 \frac{\prod_{i=1}^m (z - z_i)(z^{-1} - \bar{z}_i)}{\prod_{i=1}^n (z - p_i)(z^{-1} - \bar{p}_i)}, \quad \lambda^2 := c \frac{\prod_{i=1}^m -\frac{1}{\bar{z}_i}}{\prod_{i=1}^n -\frac{1}{\bar{p}_i}} > 0$$

$$3. L(z) = z^{n-m} \lambda \frac{\prod_{i=1}^m (z - z_i)}{\prod_{i=1}^n (z - p_i)} \quad (\lambda > 0 \Rightarrow \text{canonical } L(z))$$



# Scalar rational spectral factorization

## ...in MATLAB®

```
>> [cvZ,cvP,dK] = zpndata(tfS,'v');
```

- cvZ: column vector containing the zeros of  $S(z)$ , counted with multiplicity
- cvP: column containing the poles of  $S(z)$ , counted with multiplicity
- dK = c, gain of  $S(z)$

Pay attention on the term  $z^{n-m}!$





## Application: the Wiener predictor

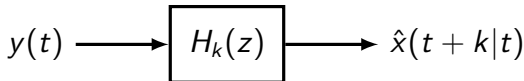


## Wiener prediction

*k-step ahead Wiener predictor*

$$H_k(z) := \left[ z^k \frac{S_{xy}(z)}{L(z^{-1})} \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$



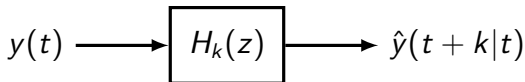
## Wiener prediction

*k*-step ahead Wiener predictor

**Case**  $\{x(t)\}_{t \in \mathbb{Z}} = \{y(t)\}_{t \in \mathbb{Z}}$

$$H_k(z) := \left[ z^k L(z) \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$



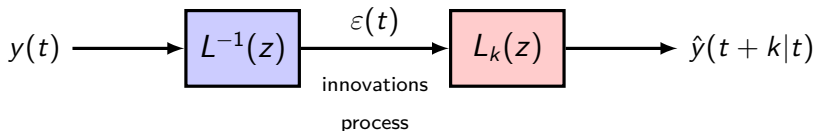
# Wiener prediction

## *k*-step ahead Wiener predictor

**Case**  $\{x(t)\}_{t \in \mathbb{Z}} = \{y(t)\}_{t \in \mathbb{Z}}$

$$H_k(z) := \left[ z^k L(z) \right]_+ \frac{1}{L(z)}$$

$$S_y(e^{j\theta}) = L(e^{j\theta})L(e^{-j\theta})$$



## How to compute $[z^k L(z)]_+$ ?

Suppose  $S_y(z)$  rational:

$$L(z) = \frac{C(z)}{A(z)} = \ell_0 + \ell_1 z^{-1} + \ell_2 z^{-2} + \dots$$

$$z^k L(z) = [z^k L(z)]_+ + [[z^k L(z)]]_-$$





## How to compute $[z^k L(z)]_+$ ?

Suppose  $S_y(z)$  rational:

$$L(z) = \frac{C(z)}{A(z)} = \ell_0 + \ell_1 z^{-1} + \ell_2 z^{-2} + \dots$$

$$z^k L(z) = [z^k L(z)]_+ + [[z^k L(z)]]_-$$


$$\frac{C_k(z)}{A(z)}$$


$$\ell_0 z^k + \ell_1 z^{k-1} + \dots + \ell_{k-1} z$$

## How to compute $[z^k L(z)]_+$ ?

Suppose  $S_y(z)$  rational:

$$L(z) = \frac{C(z)}{A(z)} = \ell_0 + \ell_1 z^{-1} + \ell_2 z^{-2} + \dots$$

$$z^k \frac{C(z)}{A(z)} = \frac{C_k(z)}{A(z)} + \sum_{i=0}^{k-1} \ell_i z^{k-i}$$



## How to compute $\left[z^k L(z)\right]_+$ ?

Suppose  $S_y(z)$  rational:

$$L(z) = \frac{C(z)}{A(z)} = \ell_0 + \ell_1 z^{-1} + \ell_2 z^{-2} + \dots$$

$$z^k C(z) = A(z) \sum_{i=0}^{k-1} \ell_i z^{k-i} + C_k(z)$$

$z^k C(z)/zA(z) \rightarrow$  polynomial division

$Q(z) := \sum_{i=0}^{k-1} \ell_i z^{k-1-i} \rightarrow$  quotient

$R(z) := C_k(z) \rightarrow$  remainder





## How to compute $[z^k L(z)]_+$ ?

Suppose  $S_y(z)$  rational:

$$L(z) = \frac{C(z)}{A(z)} = \ell_0 + \ell_1 z^{-1} + \ell_2 z^{-2} + \dots$$

$$z^k C(z) = zA(z)Q(z) + R(z)$$

*...in MATLAB®*

```
>> [rvQ,rvR] = deconv([rvC 0 .. 0], [rvA 0])  
                        k zeros
```

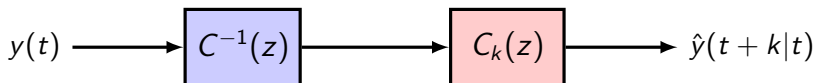


## Wiener prediction: rational case

$$H(z) := \left[ z^k L(z) \right]_+ \frac{1}{L(z)} = \frac{C_k(z)}{C(z)}$$

$$\text{Var } \tilde{y}(t+k|t) = \sum_{i=0}^{k-1} \ell_i^2$$

prediction error variance



### *Practice time 3!*

**Ex 3.1.** Create a function

```
tfW = spectralFactor(tfS)
```

that has as input a transfer function object `tfS` corresponding to a rational scalar discrete-time spectral density. The function returns the canonical minimum-phase spectral factor of `tfS`.

**Ex 3.2.** Create a function

```
[cvYhat,dVar] = WienerPredictor(tfS,cvY,iK)
```

that has as input a rational scalar spectral density `tfS` of the process  $\{y(t)\}_{t \in \mathbb{Z}}$ , a trajectory `cvY` of the latter process, and a positive integer `iK = k`. The function returns the Wiener predictions  $\hat{y}(t+k|t)$  in the vector `cvYhat` and the prediction error variance  $\text{Var } \tilde{y}(t+k|t)$  in the variable `dVar`.