

## traffic series #2

Training a Machine Learning Model to Detect Holding Patterns from ADS-B data

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Focus on a specific method in the `traffic` library:

```
>>> flight.holding_pattern()  
>>> flight.next("holding_pattern")  
>>> flight.label("holding_pattern")
```

Contributions:

- a labelled dataset: [doi:10.4121/20411868](https://doi.org/10.4121/20411868)  
(2 months of data at EGLC, EGLL, EHAM, EIDW, LFPG, LSZH)
- a ML model (`.onnx` files: *scaler* and *classifier*)
- an implementation in `traffic`

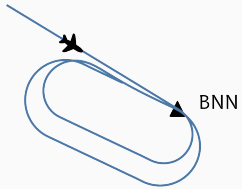
**holding pattern** (*noun*): flight manoeuvre used to keep an aircraft while awaiting further instructions. Holding patterns are typically used when air traffic congestion or adverse weather conditions prevent an aircraft from landing immediately or progressing along its intended route.

An aircraft usually follows a **racetrack-like loop**, typically flying a **straight path** for a set distance, then making a **turn to complete the loop**.

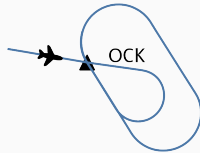
Rule-based method? ML-based method?

# Illustration

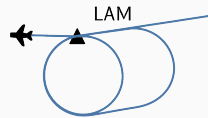
a.



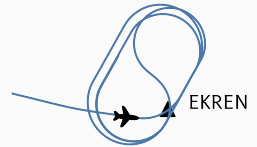
b.

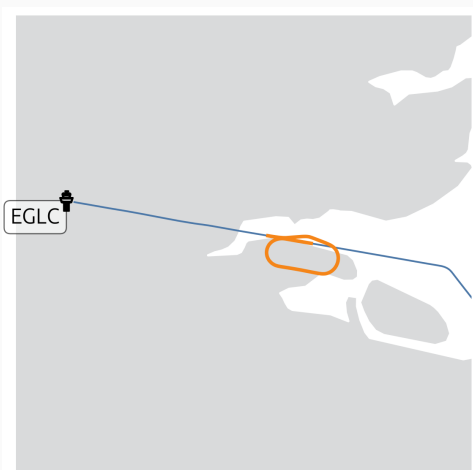
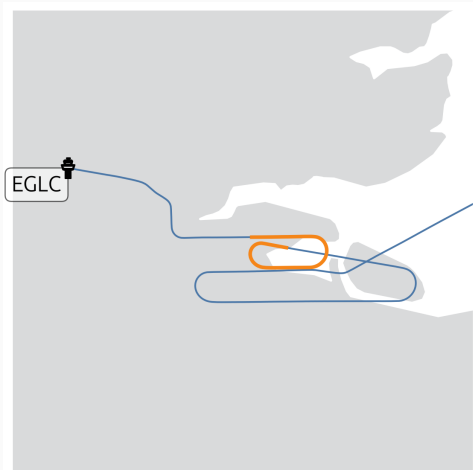


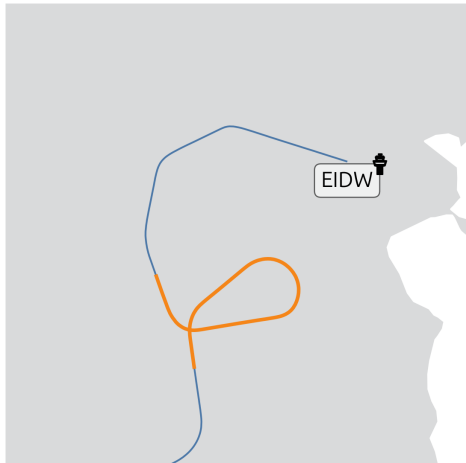
c.

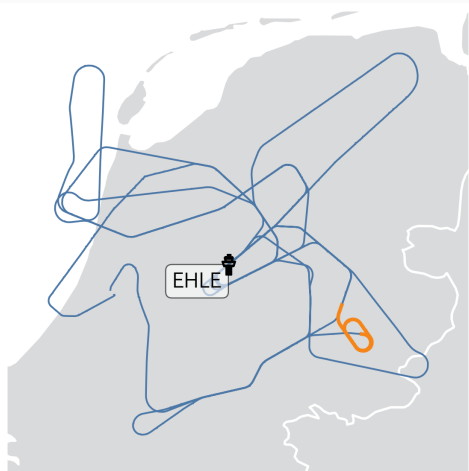


d.









- We do not have a labelled dataset
- We want more than a yes/no answer: classification ➤ detection
- We know few things about *deep clustering*: build a latent space so that two resembling trajectories will be neighbours on a low dimension space

**Step 1:** Label a dataset (*unsupervised* learning, then manual labour)

**Step 2:** Train a model (*supervised* learning)



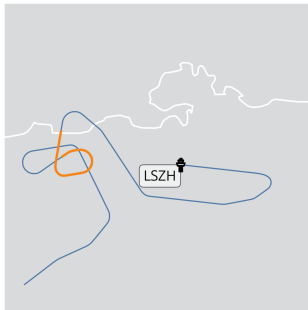
## Step 1: Label a dataset

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# Sliding windows

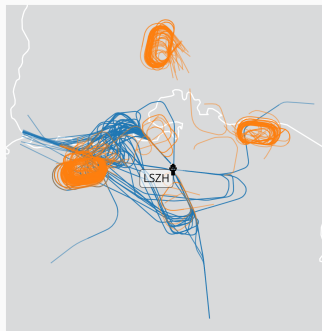
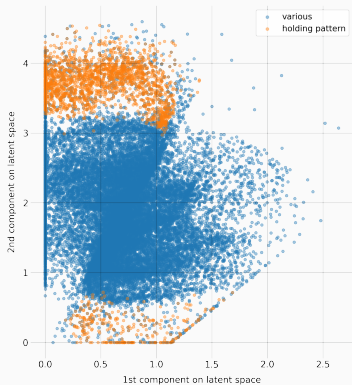
We need to identify parts of trajectories, so we will proceed with *sliding windows*:  
(classification vs. detection)

```
flight.sliding_windows("6 min", "2 min")
```



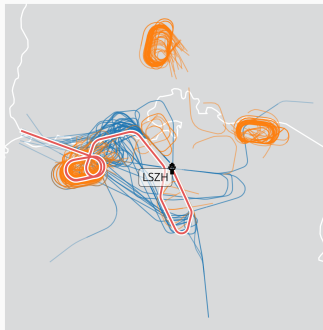
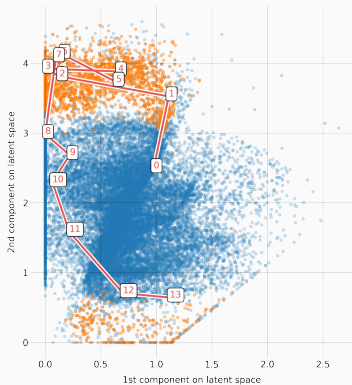
# Structuration of the latent space

After training a basic autoencoder 30-8-2-8-30 to create a latent space, we note that holding patterns tend to cluster:



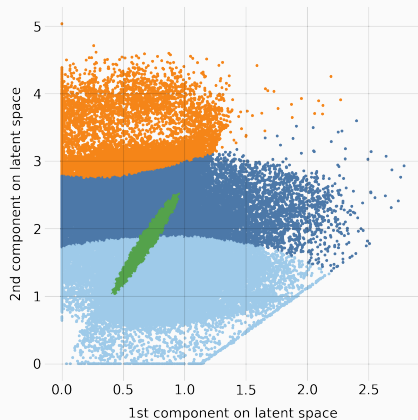
# Trajectory in the latent space

We can identify the holding pattern part of the trajectory in the latent space:



## Clustering of the latent space

Now, we need to identify those “holding pattern” areas for a pre-labelling:  
**clustering the latent space** (Gaussian Mixture for instance)



## From a pre-labelling to a labelling

- Now we can mark all segments in the proper cluster as *“holding pattern”*
- But in fact, it was quite average (imagine *Google Translate level*)

We adjusted all the labels manually with a visual tool:

- left plot (*“holding patterns”*):  
click to mark as **“not** holding pattern”
- right plot (**“not** holding pattern”):  
click to mask as *“holding pattern”*

# GET THE SHIT

☒ DONE

97,700 flights    784,177 segments (49,822 positive)

# GET THE SHIT



97,700 flights    784,177 segments (49,822 positive)

*The biggest, most horrendous, terribly monstrous part of the work—the absolute pinnacle of frustration and despair, the unparalleled abyss of toil and tedium, the most impossibly dreadful and gruelling segment of it all.*



## Step 2: Train a classifier

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## Supervised learning with a NN classifier

- `flight.sliding_window("6 min", "2 min")` if `segment.duration >= "5 min"`
- Feature: *unwrapped track angle* | `MinMaxScaling()`
- **Convolutional architecture** (significantly better than flattened):

```
Linear(30, 8) | Reshape(-1, 1, 8) | Conv1d(1, 10, 3) | ReLU()  
| MaxPool1d(2) | Flatten() | Linear(30, 8) | ReLU()  
| Linear(8, 4) | ReLU() | Linear(4, 1) | Sigmoid()'
```

- train/test splitting (~ 80%)
- Metrics: accuracy, precision, recall, f1-score, IoU

*Best results with EIDW as testing set (precision: 0.85, recall: 0.75, f1: 0.76, IoU: ~0.6 but...)*

## Conclusion

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## Key take-aways

- Unsupervised learning helps to bootstrap a labelling
- Now, we have a labelled dataset for holding patterns (cost: *blood and tears*)
- Models exported in .onnx format: usable in any programming language

```
from traffic.data.datasets import landing_heathrow_2019
```

```
subset = landing_heathrow_2019.has('holding_pattern').eval().sample(600)
```

```
subset.plot(color="#bab0ac") # gray
```

```
for hp in subset.holding_pattern():
```

```
    hp.plot(color="#f58518") # orange
```

