

# M.S STUDENT · SEJONG UNIVERSITY

# Daeyang Al Center, 05006, Seoul, Repulic of Korea

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Education	
Sejong University  M.S IN DEPARTMENT OF AI ROBOTICS  • Advisor: Prof. Yukyung Choi	Seoul, South Korea Mar.2024 -
Sejong University  B.S IN DEPARTMENT OF INTELLIGENT MECHATRONICS ENGINEERING  • Hornors: Cum Laude (Overall GPA: 3.94/4.5, Major GPA: 4.24/4.5)  • Undergrad advisor: Prof. Yukyung Choi	Seoul, South Korea Mar.2018 - Feb.2024
Publications	
[C3] Boosting Cross-spectral Unsupervised Domain Adaptation for Thermal Semantic Segmentation  SEOKJUN KWON*, JEONGMIN SHIN*, NAMIL KIM, SOONMIN HWANG, AND YUKYUNG CHOI  International Conference on Robotics and Automation (ICRA)	May, 2025
<ul> <li>Acceptance Rate: 38.7%</li> <li>[C2] A Two-Stage Framework for Small Character Detection in the Manufacturing Industry</li> <li>YUNSEO JEONG*, <u>SEOKJUN KWON*</u>, JEONGMIN SHIN AND YUKYUNG CHOI</li> </ul>	Nov, 2024
<ul> <li>International Conference on Control, Automation and Systems (ICCAS)</li> <li>[J1] UMHE: Unsupervised Multispectral Homography Estimation</li> <li>JEONGMIN SHIN, JIWON KIM, SEOKJUN KWON, NAMIL KIM, SOONMIN HWANG, AND YUKYUNG</li> <li>CHOI</li> <li>IEEE Sensors Journal</li> <li>Impact Factor: 4.3 (SCIE, Q1)</li> </ul>	Apr, 2024
[C1] Unsupervised Domain Adaptation with Mutual Learning for Semantic Segmentation for Thermal Images  SEOKJUN KWON, JEONGMIN SHIN, DAECHAN HAN, AND YUKYUNG CHOI  Image Processing and Image Understanding (IPIU)  Bronze Prize, Best Paper Award	Feb, 2023
Research Experience	
Research on Autonomous eVTOL Core Convergence Technology for Urban Air Mobility (UAM).  FUNDED BY THE MINISTRY OF SCIENCE AND ICT (MSIT)  Developed an open-vocabulary object detection algorithm for autonomous eVTOL driving and landing.	Sejong Univ Jul. 2024 - Current
Development of an AI-Based High Resolution Low Power Smart Camera and Machine Vision Integrated Solution for Defect Detection in Manufacturing FUNDED BY MINISTRY OF TRADE, INDUSTRY AND ENERGY (MOTIE)  • Developed a real-time small character detection algorithm for machine vision camera. [C2]	Sejong Univ Apr. 2023 - Current

## **ICT Challenge and Advanced Network of HRD**

FUNDED BY THE MINISTRY OF SCIENCE AND ICT (MSIT)

Sejong Univ Jul. 2022 - Current

• Developed a model for estimating the homography matrix between RGB and Thermal Images. [J1]

# Development of AI Camera Technology to Support Battlefield Environmental Awareness and Weapon System Performance

Sejong Univ

FUNDED BY THE MINISTRY OF SCIENCE AND ICT (MSIT)

Mar. 2022 - Feb. 2023

Developed a domain adaptation algorithm for a thermal sensor-based semantic segmentation task. [C3, C1]

# Awards \_\_\_\_\_

### MSIT 1ST AUTONOMOUS DRIVING AI CHALLENGE

Nov, 2024

3rd Prize

• Developed object detection and instance segmentation algorithms for autonomous driving car.

### THE 35TH WORKSHOP ON IMAGE PROCESSING AND IMAGE UNDERSTANDING (IPIU)

Feb, 2023

• Bronze Prize, **Best Paper Award** 

## Patents \_\_\_\_\_

#### METHOD FOR DETECTING DEFECTS IN MANUFACTURING INDUSTRIAL PRODUCTS AND APPARATUS

Sep, 2024

• Korea patent (applied) No. 10-2023-0118908

## CROSS SPECTRAL UNSUPERVISED DOMAIN ADAPTATION METHOD AND APPARATUS

Aug, 2024

• Korea patent (applied) No. 10-2024-0113714

#### MULTISPECTRAL HOMOGRAPHY ESTIMATION METHOD AND APPARATUS

Apr, 2023

Korea patent (applied) No. 10-2023-0054572

# Teaching Experience \_\_\_\_\_

# Deep Learning System

Spring, 2024

Instructor: Prof. Yukyung Choi

• Role: Head Teaching Assistant

## **Artificial Intelligence**

Fall, 2023

INSTRUCTOR: PROF. YUKYUNG CHOI

• Role: Teaching Assistant

# Machine Learning

Spring, 2023

**INSTRUCTOR: PROF. YUKYUNG CHOI**• Role: Teaching Assistant