

Robust Winner Determination and Simultaneous Elicitation of Scoring Rules and Preferences

November 26, 2018

Social choice deals with the problem of determining a consensus choice from the preferences of different agents (voters). In the classical setting, the social choice rule is fixed beforehand; indeed many works analyze the properties of different rules (including axiomatic treatments) in order to justify the choice of specific social choice functions. Moreover, it is usually assumed that the preferences of the voters are completely known.

In this draft we depart from the classic view by considering that both preferences and the social choice rule can be only partially specified. We note that previous works have considered either partial preferences or a partially specified aggregation, but we do not know of any work considering both sources of uncertainty at the same time. We provide a method for approximate winner determination and an incremental elicitation protocol based on minimax regret.

Background

We assume that there is a set A of m alternatives and n agents (voters); each agent is associated to a preference order. The preferences of the agents are supposed to be linear orders (connected, transitive, asymmetric relations) involving the alternatives; \succ_i denotes the “real” preference relation of agent i . The set $(\succ_1, \dots, \succ_n)$ is known in the social choice literature as the *preference profile*. The profile is equivalently represented by $\mathbf{v} = (v_1, \dots, v_n)$ where $v_i(j)$ denotes the rank (position) of alternative j in the preference order \succ_i . With a little abuse of notation, we will use the term profile to refer to either \mathbf{v} or to the preference relations, depending on the context. Let V the set of possible preference profiles (the cartesian product of n linear orders).

A social choice function $f : V \rightarrow A$ associates a profile with one winner (or multiple winners in some cases). Among the many possible social choice functions, we consider those rules that are based on a numerical score that is decomposable voter-wise. In particular positional scoring rules attach weights to positions; an alternative obtains a score that depends on the rank obtained in each of the preference orders:

$$s(x) = \sum_{i=1}^n w_{v_i(x)}.$$

where the vector (w_1, \dots, w_m) is called the scoring vector; it is usually assumed that the weights constitute a monotonic sequence: $w_1 \geq w_2 \geq \dots \geq w_m$.

We want to reason about partial preference information. A partial preference is encoded by a partial order \succ_k^p of voter k ; we assume that preference information is truthful, i.e. $a \succ_k^p b \implies a \succ_k b$.

A completion of \succ_k^p is any linear order \succ_k that extends \succ_k^p . Let $C(\succ_k^p)$ be the set of completions of \succ_k^p , that is the set of all complete rankings that extend \succ_k^p . An incomplete profile is a set of partial votes $\mathbf{p} = (\succ_1^p, \dots, \succ_n^p)$.

We let $C(\mathbf{p}) = C(\succ_1^{\mathbf{p}}) \times \dots \times C(\succ_n^{\mathbf{p}})$ be the set of complete profiles extending p .

We also assume that the weights of the scoring rules are only partially specified. We use W to denote the set of feasible weight vector. Without loss of generality, we assume $w_1 = 0$ and $w_m = 0$. The preferences of the chair are encoded with linear constraints, for instance one may state that $w_2 > 0.5$. A specific kind of preference may require the sequence of the weights to be convex, that means that the difference of between the weight of the first position and the weight of the second position is at least as much as the difference between the weights of the second and third position, etc.

$$\forall i \in \{1, \dots, n\} \quad w_i - w_{i+1} \geq w_{i+1} - w_{i+2} \iff w_i - 2w_{i+1} + w_{i+2} \geq 0$$

This is a constraint often used when aggregating rankings in sport competitions.

Related works

Uncertain scoring rules A number of works have dealt with the problem of reasoning with incompletely specified aggregation functions. In particular, when considering positional scoring rules, it is possible to derive dominance relations (akin to stochastic dominance) that allow to eliminate some alternatives since they will be less preferred than another one for any instantiation of the weights [3]. More recently the characterization of methods for aggregating the uncertainty over the scoring vectors has been studied in [4]. We also note that the elicitation methods based on minimax regret described in [1] (and in many other recent papers), while not specifically targeted to scoring rules, can be easily adapted (from a technical point of view) to elicit the scoring vector from a committee.

Incomplete profiles Lu and Boutilier [2] assume that the preferences of the voters are only partially known (while the social choice function is known and fixed in advance; it is assumed to be decomposable) and propose to use minimax regret to produce a robust approximation. Each alternative is associated with a max regret value that measures how far from optimal it could be in the worst case given any completion of the partial profile. The computation of max regret is facilitated by the fact the score is decomposable.

Incomplete profiles and partial information about the scoring rule

Perhaps it could be made more general considering not only scoring rules, but all rules based on a score (as in Boutilier's paper)

In this draft, we consider a setting where both the voters' preferences and the preferences of the chair about the voting rule are incomplete. We write the score as $s(x; v, w)$ to underline the dependency of the score on the preference profile and on the weight vector. Let $s(x; v, w)$ denote the score of alternative x in profile \mathbf{v} with weights \mathbf{w} :

$$s(x; \mathbf{v}, \mathbf{w}) = \sum_{i=1}^m w_{v_i(x)}$$

The quality of an alternative can be quantified by considering the maximum regret with respect to an adversary that can choose the instantiation of both a complete profile (extending the known preferences of the agents) and of the scoring vectors (associated to the preferences of the committee).

We propose to use minimax regret to identify the alternative to declare as the approximate winner, extending the work of [2] to the simultaneous presence of uncertainty in the agents' preferences and uncertainty in the weights. The maximum regret is considered by assuming an adversary can choose both 1) to extend the partial profile into a complete profile 2) can instantiate the weights choosing among any feasible weight vector in W .

$$\begin{aligned}\text{PMR}(x, y; \mathbf{p}, W) &= \max_{\mathbf{w} \in W} \max_{\mathbf{v} \in C(\mathbf{p})} s(y; \mathbf{v}, \mathbf{w}) - s(x; \mathbf{v}, \mathbf{w}) \\ \text{MR}(x; \mathbf{p}, W) &= \max_{y \in A} \text{PMR}(x, y; \mathbf{p}, W) \\ \text{MMR}(\mathbf{p}, W) &= \min_{x \in A} \text{MR}(x; \mathbf{p}, W) \\ x^*(\mathbf{p}, W) &\in \arg \min_{x \in A} \text{MR}(x; \mathbf{p}, W)\end{aligned}$$

- $\text{PMR}(x, y; \mathbf{p}, W)$ denotes the pairwise max regret of x relative to y given partial profile \mathbf{p} and the space of weights W , that is the worst-case loss under all possible realizations of the full profile *and* all possible instantiations of the weights.
- Max regret $\text{MR}(x; \mathbf{p}, W)$ is the worst-case loss of x . It is the loss occurred by an adversarial selection of a complete profile \mathbf{v} extending \mathbf{p} and a selection of $\mathbf{w} \in W$ to maximize the loss between x and the true winner under \mathbf{v} and w .
- Minimax regret $\text{MMR}(\mathbf{p}, W)$ is the minimum of max regret obtained when choosing x^*

By recommending the alternative associated with minimax regret, we can provide a recommendation that gives worst-case guarantees, giving some robustness in face of uncertainty (due to both not knowing the agents' preferences and the weights used in the aggregation).

Computation of minimax regret We will adapt the reasoning from [2] combined with linear programming optimization.

Exploiting the decomposition of the score in terms of votes we can rewrite PMR as follows:

$$\begin{aligned}\text{PMR}(x, y; \mathbf{p}, W) &= \max_{\mathbf{w} \in W} \max_{\mathbf{v} \in C(\mathbf{p})} [s(y; \mathbf{v}, \mathbf{w}) - s(x; \mathbf{v}, \mathbf{w})] = \\ &= \max_{\mathbf{w} \in W} \sum_{j=1}^n \max_{v_j \in C(\succ_j^{\mathbf{p}})} [s(y; v_j, \mathbf{w}) - s(x; v_j, \mathbf{w})] = \\ &= \max_{\mathbf{w} \in W} \sum_{j=1}^n \max_{v_j \in C(\succ_j^{\mathbf{p}})} [w_{v_j(y)} - w_{v_j(x)}]\end{aligned}$$

This is just sketchy TODO: reason about the optimization and complete section

In many cases the inner maximization can be made regardless of the outer max. Part of the optimization can be made voter-wise: for each of the agent,s we compute the extend the partial preference into a linear order that makes the gap between y and x as wide as possible. However, in some cases the choice of how to complete the profiles may depend on the choice of weights, therefore it may be quite complicated... (need to use integer variables???) *Explain why convex sequences do not pose any problem* In the case of convex sequences, the optimization

can be done without integer variables. Let \hat{v}_k be the linear order extending p_k according to the procedure described in [2].

$$\max_{\mathbf{w} \in W} \sum_{j=1}^n [w_{\hat{v}_j(y)} - w_{\hat{v}_j(x)}]$$

Therefore the pairwise maximum regret can be computed with a linear program.

Interactive Elicitation Starting from some initial partial knowledge, our goal is to learn both the scoring rule function and the agents’ preferences. While this is of course possible by doing one elicitation after another one, we propose an interleaved approach. We adopt an interactive protocol for simultaneously eliciting the preferences of the chair about the voting rule and the voters’ preferences about the alternatives. Indeed, it can be beneficial to interleave questions asked to the committee and questions asked to voters, depending on which is estimated to be more informative.

Answers given by the committee about the scoring rule refines our knowledge of the weights w_1, \dots, w_n . Answers given by one of the agents refine our knowledge about the agent’s preferences

- At each step we need to decide whether we want to ask a question to the committee or to one of the agents (and to which agent in particular).
- We can consider different types of questions: asking to compare a pair of alternatives, asking about top-k alternatives.

Type of questions that we can ask to the chair: bound queries, comparison queries.

- In the experiments we want to compare the interleaved approach with a baseline challenger, a method that elicits the preferences of the voters first and then the voting rule (or the other way around)

Some ideas: decompose the regret into two components, one due to \mathbf{w} and one due to \mathbf{p} , and ask a question to the chair / or to one of the agents depending on which is highest

References

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