

HEV Motor Comparison of IPMSM With Nd Sintered Magnet and Heavy Rare-Earth Free Injection Magnet in the Same Size

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Abstract—In the near future, usage of heavy rare-earth element needs to be reduced, due to resource risk and rising price with vehicle electrification. This paper compared two hybrid electric vehicle traction motors of the same size using Nd sintered magnet and heavy rare-earth free magnet. We designed two interior permanent magnet synchronous motors varying only the rotor design and material. A new motor was developed using heavy rare-earth free magnet with performance and size equal to Nd sintered motor. The rotor shape was designed as the one of a synchronous reluctance motor to overcome the lack of heavy rare-earth free motor torque. The motor performance was verified with a series of experiments.

Index Terms—Traction motor, EV, HEV, heavy rare-earth free, Dy free, IPMSM.

I. INTRODUCTION

THE current generation of home electric appliances and electric vehicles/hybrid electric vehicles (EVs/HEVs) uses interior permanent magnet synchronous motors (IPMSMs) that contain rare-earth permanent magnets [1].

The IPMSM has high efficiency, a high power factor, and a high power density. However, rare-earth permanent magnets containing dysprosium (Dy) and terbium (Tb) are expensive and there is concern regarding the stable supply of rare earth materials. On the other hand, a synchronous reluctance motor (SynRM) is driven by reluctance torque [2]. The SynRM does not use permanent magnets, and so sacrifices torque density, power factor, and efficiency compared to the PMSM. However, by adding a proper quantity of PM to the SynRM, the torque density and power factor of the SynRM can be improved. Such motors are referred to as permanent magnet assisted synchronous reluctance motors (PMASynRMs) [3].

The leading rare-earth magnet deposits are not distributed evenly, however, with production in recent years limited to the countries [4]. Further, heavy rare-earth elements usage needs

TABLE I
SPECIFICATIONS OF THE ND SINTERED IPMSM AND TARGET OF THE
HEAVY RARE-EARTH FREE MOTOR

Division	Target
Number of poles	10
Number of slots	60
Max power [kW]	31
Max torque [Nm]	200
Stator internal diameter [mm]	113
Stator external diameter [mm]	160
Stack length [mm]	120
Air gap [mm]	0.6
Max input current [A _{pk}]	340
Torque ripple @Max torque [%]	5↓
Torque ripple @Max rpm [%]	10↓

to be reduced because of the risks and cost of working with such a scarce resource. Without heavy rare earth added, Nd magnet will have reduced H_{cj}, B_r. Therefore, to use heavy rare-earth free magnet, engineers need to find ways to overcome this problem. In this paper, we designed IPMSM with heavy rare-earth free magnet by using PMASynRM shape. In this study, Aichi Steel Co. Mag-Fine (MF) heavy rare-earth free bonded injection magnets was used as the magnets of the IPMSM. This study investigated the rotor structure on the performance of the IPMSM with heavy rare-earth free magnets. Generally Nd sintered magnet use Dy, Tb, Ga for diffusion treatment. However Mag-Fine Magnet use Cu, Al for diffusion instead of Dy, Tb, Ga. This is a characteristic of Mag-Fine Magnet.

II. DESIGN OF THE IPMSM ROTOR STRUCTURE WITH HEAVY RARE-EARTH FREE MAGNET

A. Nd Sintered IPMSM Model and Specifications

In this paper, motors have same stator but different rotor structure and magnet. Table I shows specifications of the Nd sintered IPMSM. Heavy rare-earth free magnet motor target is same as IPMSM with the Nd sintered magnet.

Fig. 1 is IPMSM rotor core model and real motor sample with Nd sintered magnet.

B. Heavy Rare-Earth Free IPMSM Concept Design

Table II shows B_r and H_{cb} of the Nd sintered magnet and heavy rare-earth free magnet.

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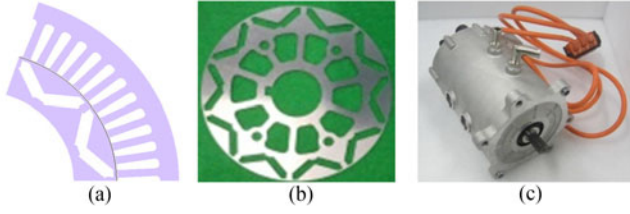


Fig. 1. IPMSM motor with Nd sintered magnet. (a) Rotor core model. (b) Rotor core sheet. (c) IPMSM ASM.

TABLE II
COMPARISON OF THE MAGNETS

Division	Nd Sintered magnet	Heavy rare-earth free magnet
Magnet Br [T]	1.31	0.67
Magnet Hcb [kA/m]	987	478

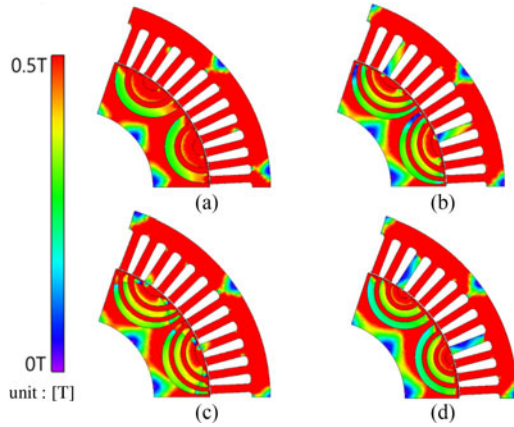


Fig. 2. Concept rotor models for heavy rare-earth free motor. (a) 2-layer. (b) 3-layer of different thickness. (c) 3-layer of different thickness and barrier. (d) 3-layer of same thickness.

TABLE III
COMPARISON OF THE CONCEPT MODELS

Division	(a)	(b)	(c)	(d)
Torque [Nm]	182.2	183.5	166.2	182.4
Magnet Volume [mm ³]	288,350	295,680	247,370	290,660
Ripple [%]	4.45	9.98	8.13	6.96

There are models of concept design for IPMSM with Heavy rare-earth free magnet in the Fig. 2. SynRM rotor shape was used to overcome the lack of heavy rare-earth free motor torque. Table III shows performance and magnet volume of concept models.

We selected model (a) concept among the concept models, because (a) model's torque and ripple is better than others, have lowest magnet volume. In the case of 3-layer structure, it was hard to satisfy the target performance due to the given rotor size is small. And magnets have demagnetization points.

Table IV and Fig. 3 Shows the correlation between design variables. As the results, torque is not dependent on magnet volume. Model M1, M5, M6 has high torque, among them M1 model magnet volume is small.

TABLE IV
CORRELATION BETWEEN DESIGN VARIABLES

Division	Layer	Magnet volume [mm ³]	Torque [Nm]	Ripple [%]
M1(a)	2	288,350	182.2	4.45
M2	2	317,340	178.5	3.24
M3	2	340,400	175.1	4.48
M4	2	337,070	175.3	5.70
M5	2	316,500	184.2	3.30
M6(d)	3	290,660	182.4	6.96

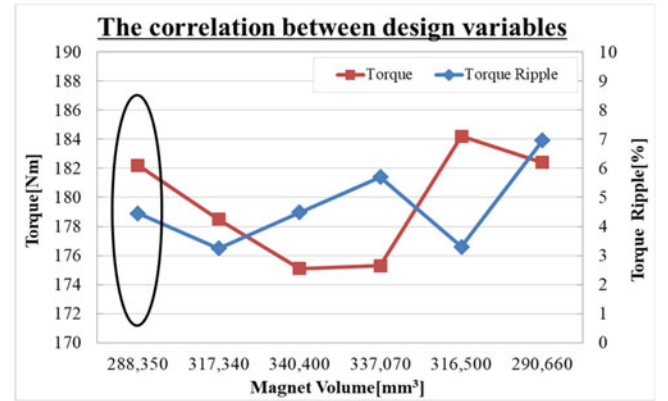


Fig. 3. The correlation between design variables.

Variables		Final Model
a. Magnet shape	f. Magnet barrier	
b. Magnet layer	g. Second layer magnet thickness offset	
c. Magnet volume	h. Rotor external diameter offset	
d. Air gap	i. Thickness between layers	
e. Rib thickness		

Fig. 4. Design variables and final heavy rare-earth free IPMSM.

In Table IV, M1 is the concept model (a) and M6 is the concept model (d) of Fig. 2.

C. Heavy Rare-Earth Free IPMSM Detail Design

We conducted the detail design with 9 variables to satisfy target specifications for the IPMSM with heavy rare-earth free magnet. Fig. 4 shows design variables and final model. 9 variables are related to the rotor. These are factors that affect motor power, demagnetization and torque ripple. We can derive these variables from concept models and design experience.

In this design review, the impact of the demagnetization was larger on the second layer. So the thickness of the second layer magnet was thicker than first layer.

Fig. 5 shows demagnetization region of rotor magnet on the 150 °C, max current and current angle. Table V is design results of the IPMSM with heavy rare-earth free magnet. As the results, heavy rare-earth free IPMSM meet the target. The selection of magnet amount considered the characteristic of the heavy rare-earth free magnet and material cost. Upon reviewing the

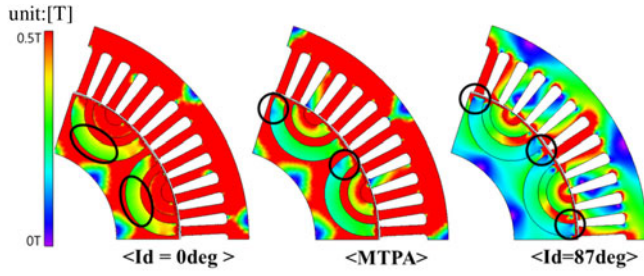


Fig. 5. Demagnetization weak region of rotor magnet.

TABLE V
DESIGN RESULTS OF THE IPMSM WITH HEAVY RARE-EARTH FREE

Division	Nd Sintered	Final design	Proto model
Number of poles	10	←	←
Max Power [kW]	31	←	26.8
Air gap [mm]	0.6	←	←
Stator diameter [mm]	160	←	←
Stack length [mm]	120	←	←
Max. torque [Nm]	200	←	173
Base Speed [RPM]	1480	←	←
Max. input current [Apk]	340	←	←
Torque ripple @Max torque [%]	3.8	2.5	2.3
Torque ripple @9000 rpm [%]	9.8	9.6	5.5
Max current density [Apk/mm ³]	40	←	←
Magnet amount [mm ³]	164,400	330,360	254,300

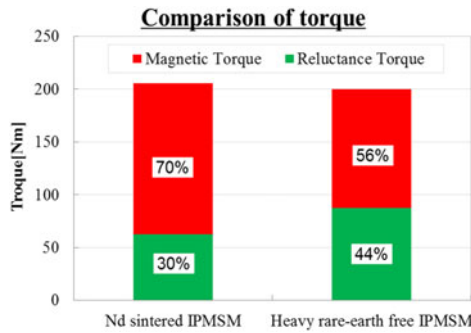


Fig. 6. Comparison of torque components of IPMSM models.

material costs, the target magnet amount can reduce the cost of material by 5% less than Nd sintered IPMSM.

Fig. 6 shows the torque components according to IPMSM models. To compensate for insufficient torque, reluctance torque has been increased. But torque ripple level was satisfied the target.

III. PROTOTYPE PRODUCTION AND TEST RESULTS

A. Prototype Product

A review of prototype for design verification was conducted. The applied magnet of the final model is the injection radial magnetizing type but prototype is made as a split processing axial magnetizing type to reduce the proto costs. Because magnet injection mold is expensive. Fig. 7 shows the results of a magnetic field according to the magnetizing method and segmentation. The flux linkage rms value of condition (a) is

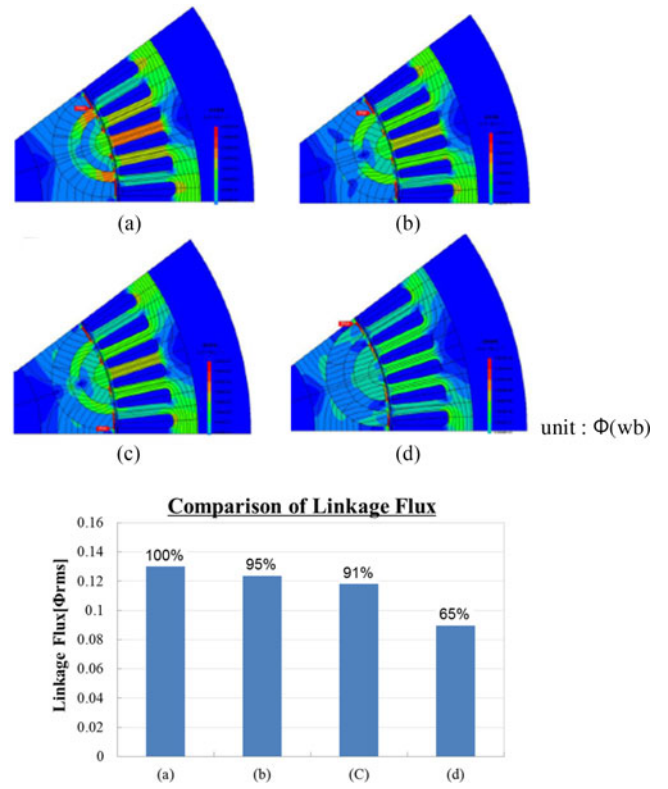


Fig. 7. The results according to the magnetizing and segment. (a) Radial/Injection. (b) Axial/5Segments. (c) Axial/4Segments. (d) Axial/2Segments.

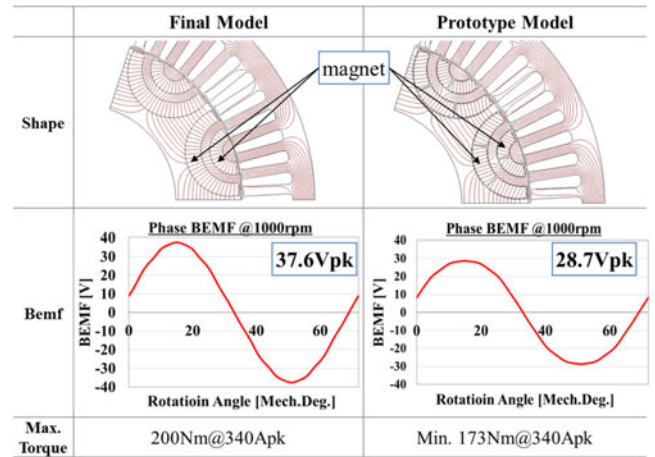


Fig. 8. Comparison of final model and prototype model.

0.129 Φ (rms). Assuming that condition (a) value is 100%, the rms value of flux linkage of the other conditions is shown in the graph of Fig. 7 below. As a result, condition (b) is selected for prototype production. The flux linkage value of the condition (b) is better than others except condition (a). Since there is a difference between final model and prototype, the representative performance of prototype has been reviewed.

Fig. 8 is the 5 segment magnet shape and torque result of prototype review. In the prototype model, the torque is higher than the lowered bEMF ratio, because reluctance torque ratio

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