A Mathematical Introduction to Data Science

October 21, 2014

Homework 4. ISOMAP & LLE

Instructor: Yuan Yao Due: Tuesday October 28, 2014

The problem below marked by * is optional with bonus credits.

1. Order the faces: The following dataset contains 33 faces of the same person $(Y \in \mathbb{R}^{112 \times 92 \times 33})$ in different angles,

http://www.math.pku.edu.cn/teachers/yaoy/data/face.mat

You may create a data matrix $X \in \mathbb{R}^{n \times p}$ where $n = 33, p = 112 \times 92 = 10304$ (e.g. X=reshape(Y,[10304,33])'; in matlab).

- (a) Explore the MDS-embedding of the 33 faces on top two eigenvectors: order the faces according to the top 1st eigenvector and visualize your results with figures.
- (b) Explore the ISOMAP-embedding of the 33 faces on the k=5 nearest neighbor graph and compare it against the MDS results. Note: you may try Tenenbaum's Matlab code http://www.math.pku.edu.cn/teachers/yaoy/Spring2011/matlab/isomapII.m
- (c) Explore the LLE-embedding of the 33 faces on the k=5 nearest neighbor graph and compare it against ISOMAP. Note: you may try the following Matlab code http://www.math.pku.edu.cn/teachers/yaoy/Spring2011/matlab/lle.m
- 2. Nyström method: In class, we have shown that every manifold learning algorithm can be regarded as Kernel PCA on graphs: (1) given N data points, define a neighborhood graph with N nodes for data points; (2) construct a positive semidefinite kernel K; (3) pursue spectral decomposition of K to find the embedding (using top or bottom eigenvectors). However, this approach might suffer from the expensive computational cost in spectral decomposition of K if N is large and K is non-sparse, e.g. ISOMAP and MDS.

To overcome this hurdle, Nyström method leads us to a scalable approach to compute eigenvectors of low rank matrices. Suppose that an N-by-N positive semidefinite matrix $K \succeq 0$ admits the following block partition

$$K = \left[\begin{array}{cc} A & B \\ B^T & C \end{array} \right]. \tag{1}$$

where A is an n-by-n block. Assume that A has the spectral decomposition $A = U\Lambda U^T$, $\Lambda = \operatorname{diag}(\lambda_i)$ ($\lambda_1 \geq \lambda_2 \geq \ldots \lambda_k > \lambda_{k+1} = \ldots = 0$) and $U = [u_1, \ldots, u_n]$ satisfies $U^T U = I$.

(a) Assume that $K = XX^T$ for some $X = [X_1; X_2] \in \mathbb{R}^{N \times k}$ with the block $X_1 \in \mathbb{R}^{n \times k}$. Show that X_1 and X_2 can be decided by:

$$X_1 = U_k \Lambda_k^{1/2},\tag{2}$$

$$X_2 = B^T U_k \Lambda_k^{-1/2},\tag{3}$$

where $U_k = [u_1, \ldots, u_k]$ consists of those k columns of U corresponding to top k eigenvalues λ_i $(i = 1, \ldots, k)$.

(b) Show that for general $K \succeq 0$, one can construct an approximation from (??) and (??),

$$\hat{K} = \begin{bmatrix} A & B \\ B^T & \hat{C} \end{bmatrix}. \tag{4}$$

where $A = X_1 X_1^T$, $B = X_1 X_2^T$, and $\hat{C} = X_2 X_2^T = B^T A^{\dagger} B$, A^{\dagger} denoting the Moore-Penrose (pseudo-) inverse of A. Therefore $\|\hat{K} - K\|_F = \|C - B^T A^{\dagger} B\|_F$. Here the matrix $C - B^T A^{\dagger} B =: K/A$ is called the (generalized) Schur Complement of A in K.

(c) Explore Nyström method on the Swiss-Roll dataset (http://www.math.pku.edu.cn/teachers/yaoy/data/swiss_roll_data.mat contains 3D-data X) with ISOMAP. To construct the block A, you may choose either of the following:

n random data points;

*n landmarks as minimax k-centers (http://www.math.pku.edu.cn/teachers/yaoy/Spring2011/matlab/kcenter.m);

Some references can be found at:

[dVT04] Vin de Silva and J. B. Tenenbaum, "Sparse multidimensional scaling using landmark points", 2004, downloadable at http://pages.pomona.edu/~vds04747/public/papers/landmarks.pdf;

[P05] John C. Platt, "FastMap, MetricMap, and Landmark MDS are all Nyström Algorithms", 2005, downloadable at http://research.microsoft.com/en-us/um/people/jplatt/nystrom2.pdf.

(d) *Assume that A is invertible, show that

$$det(K) = det(A) \cdot det(K/A),$$

(e) *Assume that A is invertible, show that

$$rank(K) = rank(A) + rank(K/A).$$

(f) *Can you extend the identities in (c) and (d) to the case of noninvertible A? A good reference can be found at,

[Q81] Diane V. Quellette, "Schur Complements and Statistics", Linear Algebra and Its Applications, 36:187-295, 1981. http://www.sciencedirect.com/science/article/pii/0024379581902329