

AMICI

Generated by Doxygen 1.8.10

Wed May 4 2016 14:08:03

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## 1 AMICI 0.1 General Documentation

### 1.1 Introduction

AMICI is a MATLAB interface for the [SUNDIALS](#) solvers CVODES (for ordinary differential equations) and IDAS (for algebraic differential equations). AMICI allows the user to specify differential equation models in terms of symbolic variables in MATLAB and automatically compiles such models as .mex simulation files. In contrast to the SUNDIALSTB interface, all necessary functions are transformed into native C code, which allows for a significantly faster numerical integration. Beyond forward integration, the compiled simulation file also allows for first and second order forward sensitivity analysis, steady state sensitivity analysis and adjoint sensitivity analysis for likelihood based output functions.

The interface was designed to provide routines for efficient gradient computation in parameter estimation of biochemical reaction models but is also applicable to a wider range of differential equation constrained optimization problems.

### 1.2 Availability

The sources for AMICI are accessible as

- Source [tarball](#)
- Source [zipball](#)
- GIT repository on [github](#)

Once you've obtained your copy check out the [Installation](#)

### 1.2.1 Obtaining AMICI via the GIT versioning system

In order to always stay up-to-date with the latest AMICI versions, simply pull it from our GIT repository and recompile it when a new release is available. For more information about GIT checkout their [website](#)

The GIT repository can currently be found at <https://github.com/FFroehlich/AMICI> and a direct clone is possible via

```
git clone https://github.com/FFroehlich/AMICI.git AMICI
```

### 1.2.2 License Conditions

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## 1.3 Installation

If AMICI was downloaded as a zip, it needs to be unpacked in a convenient directory. If AMICI was obtained via cloning of the git repository, no further unpacking is necessary.

To use AMICI, start MATLAB and add the AMICI directory to the MATLAB path. To add all toolbox directories to the MATLAB path, execute the matlab script

```
installToolbox.m
```

To store the installation for further MATLAB session, the path can be saved via

```
savepath
```

For the compilation of .mex files, MATLAB needs to be configured with a working C compiler. The C compiler needs to be installed and configured via:

```
mex -setup c
```

For a list of supported compilers we refer to the mathworks documentation: [mathworks.de](http://mathworks.de)

The tools SUNDIALS and SuiteSparse shipped with AMICI do **not** require further installation.

AMICI uses the following packages from SUNDIALS:

**CVODES:** the sensitivity-enabled ODE solver in SUNDIALS. Radu Serban and Alan C. Hindmarsh. *ASME 2005 International Design Engineering Technical Conferences and Computers and Information in Engineering Conference*. American Society of Mechanical Engineers, 2005. [PDF](#)

## IDAS

AMICI uses the following packages from SuiteSparse:

**Algorithm 907: KLU**, A Direct Sparse Solver for Circuit Simulation Problems. Timothy A. Davis, Ekanathan Palamadai Natarajan, *ACM Transactions on Mathematical Software*, Vol 37, Issue 6, 2010, pp 36:1 - 36:17. [PDF](#)

**Algorithm 837: AMD**, an approximate minimum degree ordering algorithm, Patrick R. Amestoy, Timothy A. Davis, Iain S. Duff, *ACM Transactions on Mathematical Software*, Vol 30, Issue 3, 2004, pp 381 - 388. [PDF](#)

**Algorithm 836: COLAMD**, a column approximate minimum degree ordering algorithm, Timothy A. Davis, John R. Gilbert, Stefan I. Larimore, Esmond G. Ng *ACM Transactions on Mathematical Software*, Vol 30, Issue 3, 2004, pp 377 - 380. [PDF](#)

## 2 Model Definition & Simulation

In the following we will give a detailed overview how to specify models in AMIWRAP and how to call the generated simulation files.

### 2.1 Model Definition

This guide will guide the user on how to specify models in MATLAB. For example implementations see the examples in the example directory.

#### 2.1.1 Header

The model definition needs to be defined as a function which returns a struct with all symbolic definitions and options.

```
function [model] = example_model_syms()
```

#### 2.1.2 Options

Set the options by specifying the respective field of the modelstruct

```
model.(fieldname) = (value)
```

The options specify default options for simulation, parametrisation and compilation. All of these options are optional.

field	description	default
.param	parametrisation 'log'/'log10'/'lin'	'lin'
.debug	flag to compile with debug symbols	false
.forward	flag to activate forward sensitivities	true
.adjoint	flag to activate adjoint sensitivities	true

When set to true, the fields 'noforward' and 'noadjoint' will speed up the time required to compile the model but also disable the respective sensitivity computation.

#### 2.1.3 States

Create the respective symbolic variables. The name of the symbolic variable can be chosen arbitrarily.

```
syms state1 state2 state3
```

Create the state vector containing all states:

```
x = [ state1 state2 state3 ];
```

#### 2.1.4 Parameters

Create the respective symbolic variables. The name of the symbolic variable can be chosen arbitrarily. Sensitivities **will be derived** for all parameters.

```
syms param1 param2 param3 param4 param5 param6
```

Create the parameters vector

```
p = [ param1 param2 param3 param4 param5 param6 ];
```

#### 2.1.5 Constants

Create the respective symbolic variables. The name of the symbolic variable can be chosen arbitrarily. Sensitivities with respect to constants **will not be derived**.

```
syms const1 const2
```

Create the parameters vector

```
k = [ const1 const2 ];
```

#### 2.1.6 Differential Equation

For time-dependent differential equations you can specify a symbolic variable for time. This **needs** to be denoted by t.

```
syms t
```

Specify the right hand side of the differential equation f or xdot

```
xdot(1) = [ const1 - param1*state1 ];
xdot(2) = [ +param2*state1 + dirac(t-param3) - const2*state2 ];
xdot(3) = [ param4*state2 ];
```

or

```
f(1) = [ const1 - param1*state1 ];
f(2) = [ +param2*state1 + dirac(t-param3) - const2*state2 ];
f(3) = [ param4*state2 ];
```

The specification of f or xdot may depend on [States](#), [Parameters](#) and [Constants](#).

For DAEs also specify the mass matrix.

```
M = [1, 0, 0;...
     0, 1, 0;...
     0, 0, 0];
```

The specification of M may depend on parameters and constants.

For ODEs the integrator will solve the equation  $\dot{x} = f$  and for DAEs the equations  $M \cdot \dot{x} = f$ . AMICI will decide whether to use CVODES (for ODEs) or IDAS (for DAEs) based on whether the mass matrix is defined or not.

In the definition of the differential equation you can use certain symbolic functions. For a full list of available functions see [symbolic\\_functions.c](#).

Dirac functions can be used to cause a jump in the respective states at the specified time-point. This is typically used to model injections, or other external stimuli. Spline functions can be used to model time/state dependent response with unknown time/state dependence.

### 2.1.7 Initial Conditions

Specify the initial conditions. These may depend on [Parameters](#) or [Constants](#) and must have the same size as `x`.

```
x0 = [ param4, 0, 0 ];
```

### 2.1.8 Observables

Specify the observables. These may depend on [Parameters](#) and [Constants](#).

```
y(1) = state1 + state2;
y(2) = state3 - state2;
```

In the definition of the observable you can use certain symbolic functions. For a full list of available functions see [symbolic\\_functions.c](#). Dirac functions in observables will have no effect.

### 2.1.9 Events

Specifying events is optional. Events are specified in terms of a trigger function, a bolus function and an output function. The roots of the trigger function defines the occurrences of the event. The bolus function defines the change in the state on event occurrences. The output function defines the expression which is evaluated and reported by the simulation routine on every event occurrence. The user can create events by constructing a vector of objects of the class [amievent](#).

```
event(1) = amievent(state1 - state2, 0, []);
```

Events may depend on [States](#), [Parameters](#) and [Constants](#) but **not** on [Observables](#)

### 2.1.10 Standard Deviation

Specifying of standard deviations is optional. It only has an effect when computing adjoint sensitivities. It allows the user to specify standard deviations of experimental data for [Observables](#) and [Events](#).

Standard deviation for observable data is denoted by `sigma_y`

```
sigma_y(1) = param5;
```

Standard deviation for event data is denoted by `sigma_t`

```
sigma_t(1) = param6;
```

Both `sigma_y` and `sigma_t` can either be a scalar or of the same dimension as the [Observables](#) / [Events](#) function. They can depend on time and [Parameters](#) but must not depend on the [States](#) or [Observables](#). The values provided in `sigma_y` and `sigma_t` will only be used if the value in `Sigma_Y` or `Sigma_T` in the user-provided data struct is NaN. See [Model Simulation](#) for details.

### 2.1.11 Attach to Model Struct

Eventually all symbolic expressions need to be attached to the model struct.

```
model.sym.x = x;
model.sym.k = k;
model.sym.event = event;
model.sym.xdot = xdot;
% or
model.sym.f = f;
model.sym.M = M; %only for DAEs
model.sym.p = p;
model.sym.x0 = x0;
model.sym.y = y;
model.sym.sigma_y = sigma_y;
model.sym.sigma_t = sigma_t;
```

## 2.2 Model Compilation

The model can then be compiled by calling `amiwrap`:

```
amiwrap(modelname, 'example_model_syms', dir, o2flag)
```

Here `modelname` should be a string defining the modelname, `dir` should be a string containing the path to the directory in which simulation files should be placed and `o2flag` is a flag indicating whether second order sensitivities should also be compiled. The user should make sure that the previously defined function 'example\_model\_syms' is in the user path. Alternatively, the user can also call the function 'example\_model\_syms'

```
[model] = example_model_syms()
```

and subsequently provide the generated struct to `amiwrap()`, instead of providing the symbolic function:

```
amiwrap(modelname, model, dir, o2flag)
```

In a similar fashion, the user could also generate multiple model and pass them directly to `amiwrap()` without generating respective model definition scripts.

See also

[amiwrap\(\)](#)

## 2.3 Model Simulation

After the call to `amiwrap()` two files will be placed in the specified directory. One is a `am_modelname.mex` and the other is `simulate_modelname.m`. The mex file should never be called directly. Instead the MATLAB script, which acts as a wrapper around the .mex simulation file should be used.

The `simulate_modelname.m` itself carries extensive documentation on how to call the function, what it returns and what additional options can be specified. In the following we will give a short overview of possible function calls.

### 2.3.1 Integration

Define a time vector:

```
t = linspace(0,10,100)
```

Generate a parameter vector:

```
theta = ones(6,1);
```

Generate a constants vector:

```
kappa = ones(2,1);
```

Integrate:

```
sol = simulate_modelname(t, theta, kappa, [], options)
```

The integration status will be indicated by the `sol.status` flag. Negative values indicated failed integration. The states will then be available as `sol.x`. The observables will then be available as `sol.y`. The events will then be available as `sol.root`. If no event occurred there will be an event at the end of the considered interval with the final value of the root function stored in `sol.rval`.

Alternatively the integration call also be called via

```
[status,t,x,y] = simulate_modelname(t, theta, kappa, [], options)
```

The integration status will be indicated by the status flag. Negative values indicated failed integration. The states will then be available as `x`. The observables will then be available as `y`. No event output will be given.



### 2.3.2 Forward Sensitivities

Define a time vector:

```
t = linspace(0,10,100)
```

Generate a parameter vector:

```
theta = ones(6,1);
```

Generate a constants vector:

```
kappa = ones(2,1);
```

Set the sensitivity computation to forward sensitivities and Integrate:

```
options.sensi = 1;
options.forward = true;
sol = simulate_modelname(t,theta,kappa,[],options)
```

The integration status will be indicated by the sol.status flag. Negative values indicated failed integration. The states will then be available as sol.x, with the derivative with respect to the parameters in sol.sx. The observables will then be available as sol.y, with the derivative with respect to the parameters in sol.sy. The events will then be available as sol.root, with the derivative with respect to the parameters in sol.sroot. If no event occurred there will be an event at the end of the considered interval with the final value of the root function stored in sol.rootval, with the derivative with respect to the parameters in sol.srootval

Alternatively the integration call also be called via

```
[status,t,x,y,sx,sy] = simulate_modelname(t,theta,kappa,[],options)
```

The integration status will be indicated by the status flag. Negative values indicated failed integration. The states will then be available as x, with derivative with respect to the parameters in sx. The observables will then be available as y, with derivative with respect to the parameters in sy. No event output will be given.

### 2.3.3 Adjoint Sensitivities

Define a time vector:

```
t = linspace(0,10,100)
```

Generate a parameter vector:

```
theta = ones(6,1);
```

Set the sensitivity computation to adjoint sensitivities:

```
options.sensi = 1;
options.adjoint = true;
```

Define Experimental Data:

```
D.Y = [NaN(1,2)],ones(length(t)-1,2)];
D.Sigma_Y = [0.1*ones(length(t)-1,2),NaN(1,2)];
D.T = ones(1,1);
D.Sigma_T = NaN;
```

The NaN values in Sigma\_Y and Sigma\_T will be replaced by the specification in [Standard Deviation](#). Data points with NaN value will be completely ignored.

Generate a constants vector:

```
kappa = ones(2,1);
```

Integrate:

```
sol = simulate_modelname(t,theta,kappa,D,options)
```

The integration status will be indicated by the sol.status flag. Negative values indicated failed integration. The log-likelihood will then be available as sol.llh and the derivative with respect to the parameters in sol.sllh. Notice that for adjoint sensitivities no state, observable and event sensitivities will be available. Yet this approach can be expected to be significantly faster for systems with a large number of parameters.

### 2.3.4 Steady State Sensitivities

This will compute state sensitivities according to the formula  $s_k^x = - \left( \frac{\partial f}{\partial x} \right)^{-1} \frac{\partial f}{\partial \theta_k}$

In the current implementation this formulation does not allow for conservation laws as this would result in a singular Jacobian.

Define a final timepoint t:

```
t = 100
```

Generate a parameter vector:

```
theta = ones(6,1);
```

Generate a constants vector:

```
kappa = ones(2,1);
```

Set the sensitivity computation to steady state sensitivities:

```
options.sensi = 1;
options.ss = 1;
```

Integrate:

```
sol = simulate_modelname(t,theta,kappa,D,options)
```

The states will then be available as sol.x, with the derivative with respect to the parameters in sol.sx. The observables will then be available as sol.y, with the derivative with respect to the parameters in sol.sy. Notice that for steady state sensitivities no event sensitivities will be available. For the accuracy of the computed derivatives it is essential that the system is sufficiently close to a steady state. This can be checked by examining the right hand side of the system at the final time-point via sol.xdot.

## 3 Examples

In this section we include multiple examples on defining and simulating models.

[Example Events](#) : Forward Sensitivities for model with events and discontinuities.

[Example Dirac](#) : Forward Sensitivities for mRNA transfection model with bolus injection.

[Example Steady State](#) : Steady State Sensitivities.

[Example JAK/STAT Adjoint](#) : Adjoint Sensitivities for JAK/STAT model with parametric standard deviation.

[Example Dirac Adjoint](#) : Adjoint Sensitivities for mRNA transfection model with bolus injection.

[Example Dirac Second Order Forward](#) : Second order forward sensitivities for mRNA transfection model with bolus injection.

[Example Dirac Directional Second Order Forward](#) : Directional second order forward sensitivities for mRNA transfection model with bolus injection.

[Example Adjoint](#) : Adjoint Sensitivities for simple model with analytic solution.

## 3.1 Example Events

### 3.1.1 Model Definition

```
function [model] = model_events_syms()

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

#### STATES

```
% create state syms
syms x1 x2 x3

% create state vector
model.sym.x = [
x1 x2 x3
];
```

#### PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3 p4

% create parameter vector
model.sym.p = [p1,p2,p3,p4];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

#### CONSTANTS ( for these no sensitivities will be computed ) this part is optional and can be omitted

```
% create parameter syms
syms k1 k2 k3 k4

% create parameter vector
model.sym.k = [k1 k2 k3 k4];
```

#### SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

% piecewise defined function
model.sym.xdot(1) = -p1*heaviside(t-p4)*x1;
% inhomogeneous
model.sym.xdot(2) = +p2*x1*exp(-0.1*t)-p3*x2 ;
model.sym.xdot(3) = -1.5*x3;
```

#### INITIAL CONDITIONS

```

model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = k1;
model.sym.x0(2) = k2;
model.sym.x0(3) = k3;

```

## OBSERVALES

```

model.sym.y = sym(zeros(1,1));

model.sym.y(1) = p4 * (x1+x2+x3);

```

## EVENTS this part is optional and can be omitted

```

syms t

% events fire when there is a zero crossing of the root function
model.event(1) = amievent(x3-x2,0,t);
model.event(2) = amievent(x3-x1,0,t);

end

ans =
    param: 'log10'
      sym: [1x1 struct]
    event: [1x2 amievent]

```

### 3.1.2 Simulation

```
function example_events()
```

## COMPILATION

```

[exdir,~,~]=fileparts(which('example_events.m'));
% compile the model
amiwrap('model_events','model_events_syms',exdir)

```

```

Generating model struct ...
Parsing model struct ...

```

```

Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.

```

## SIMULATION

```

% time vector
t = linspace(0,10,20);
p = [0.5;2;0.5;0.5];
k = [4,8,10,4];

options = amioption('sensi',0,...
    'maxsteps',1e4,...
    'nmaxevent', 2);
D = amidata(length(t),1,2,2,4);
% load mex into memory
[~] = which('simulate_model_events'); % fix for inaccessability problems
sol = simulate_model_events(t,log10(p),k,D,options);

tic
sol = simulate_model_events(t,log10(p),k,D,options);
disp(['Time elapsed with cvodes: ' num2str(toc) ])

```

```
Time elapsed with cvodes: 0.0037064
```

## ODE15S

```

ode_system = @(t,x,p,k) [-p(1)*heaviside(t-p(4))*x(1);
    +p(2)*x(1)*exp(-0.1*t)-p(3)*x(2);
    -1.5*x(3)];
% event_fn = @(t,x) [x(3) - x(2);
%     x(3) - x(1)];
% 'Events',event_fn
options_ode15s = odeset('RelTol',options.rtol,'AbsTol',options.atol,'MaxStep',options.maxsteps);

tic
[~, X_ode15s] = ode15s(@(t,x) ode_system(t,x,p,k),t,k(1:3),options_ode15s);
disp(['Time elapsed with ode15s: ' num2str(toc) ])

```

Time elapsed with ode15s: 0.074866

## PLOTTING

```

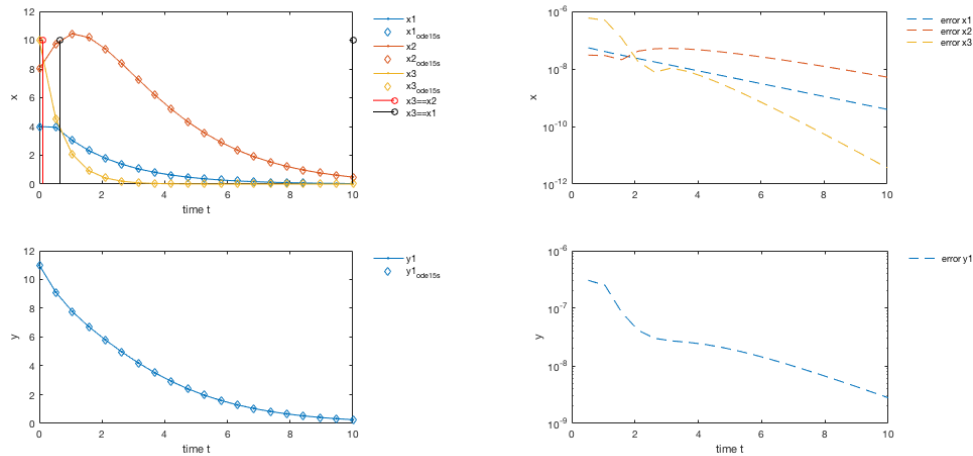
figure
c_x = get(gca,'ColorOrder');
subplot(2,2,1)
for ix = 1:size(sol.x,2)
    plot(t,sol.x(:,ix),'-','Color',c_x(ix,:))
    hold on
    plot(t,X_ode15s(:,ix),'d','Color',c_x(ix,:))
end
stem(sol.z(:,1),sol.z(:,1)*0+10,'r')
stem(sol.z(:,2),sol.z(:,2)*0+10,'k')
legend('x1','x1_ode15s','x2','x2_ode15s','x3','x3_ode15s','x3==x2','x3==x1','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('x')
box on
subplot(2,2,2)
plot(t,abs(sol.x-X_ode15s),'--')
set(gca,'YScale','log')
legend('error x1','error x2','error x3','Location','NorthEastOutside')
legend boxoff
ylabel('x')

subplot(2,2,3)
plot(t,sol.y,'-','Color',c_x(1,:))
hold on
plot(t,p(4)*sum(X_ode15s,2),'d','Color',c_x(1,:))
legend('y1','y1_ode15s','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('y')
box on

subplot(2,2,4)
plot(t,abs(sol.y-p(4)*sum(X_ode15s,2)),'--')
set(gca,'YScale','log')
legend('error y1','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('y')
box on

set(gcf,'Position',[100 300 1200 500])

```



## FORWARD SENSITIVITY ANALYSIS

```
options.sensi = 1;

sol = simulate_model_events(t, log10(p), k, D, options);
```

## FINITE DIFFERENCES

```
eps = 1e-4;
xi = log10(p);
for ip = 1:4;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_events(t, xip, k, D, options);
    sx_fd(:, :, ip) = (solp.x - sol.x) / eps;
    sy_fd(:, :, ip) = (solp.y - sol.y) / eps;
    sz_fd(:, :, ip) = (solp.z - sol.z) / eps;
end
```

## PLOTTING

```
figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for ix = 1:size(sol.x,2)
        plot(t, sol.sx(:, ix, ip), '-.', 'Color', c_x(ix, :))
        plot(t, sx_fd(:, ix, ip), 'd', 'Color', c_x(ix, :))
    end
    legend('sx1', 'sx1_fd', 'sx2', 'sx2_fd', 'sx3', 'sx3_fd', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('sx')
    box on

    subplot(4,2,ip*2)
    plot(t, abs(sol.sx(:, :, ip) - sx_fd(:, :, ip)), '--')
    legend('error sx1', 'error sx2', 'error sx3', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('error')
    set(gca, 'YScale', 'log')
    box on
end
set(gcf, 'Position', [100 300 1200 500])

figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for iy = 1:size(sol.y,2)
        plot(t, sol.sy(:, iy, ip), '-.', 'Color', c_x(iy, :))
    end
end
```

```

    plot(t,sy_fd(:,iy,ip),'d','Color',c_x(iy,:))
end
legend('syl','syl_fd','Location','NorthEastOutside')
legend boxoff
title(['observable sensitivity for p' num2str(ip)])
xlabel('time t')
ylabel('sy')
box on

subplot(4,2,ip*2)
plot(t,abs(sol.sy(:, :, ip)-sy_fd(:, :, ip)),'--')
legend('error syl','Location','NorthEastOutside')
legend boxoff
title(['error observable sensitivity for p' num2str(ip)])
xlabel('time t')
ylabel('error')
set(gca,'YScale','log')
box on

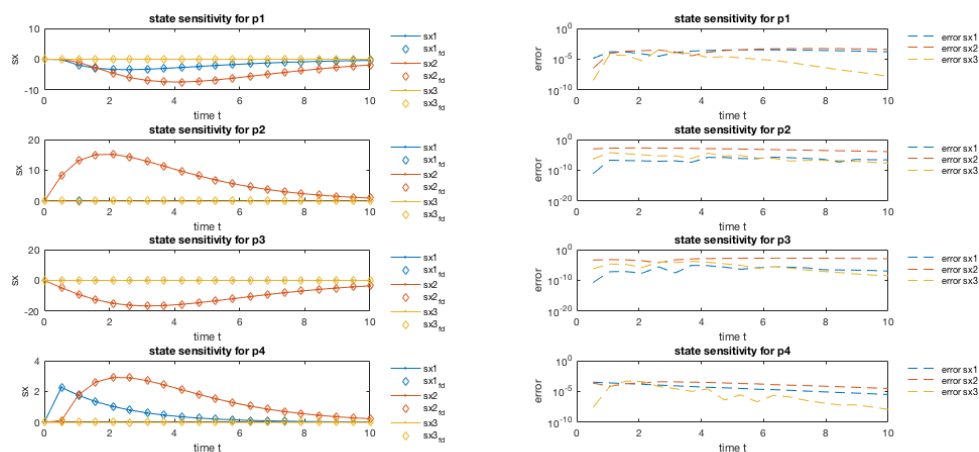
end
set(gcf,'Position',[100 300 1200 500])

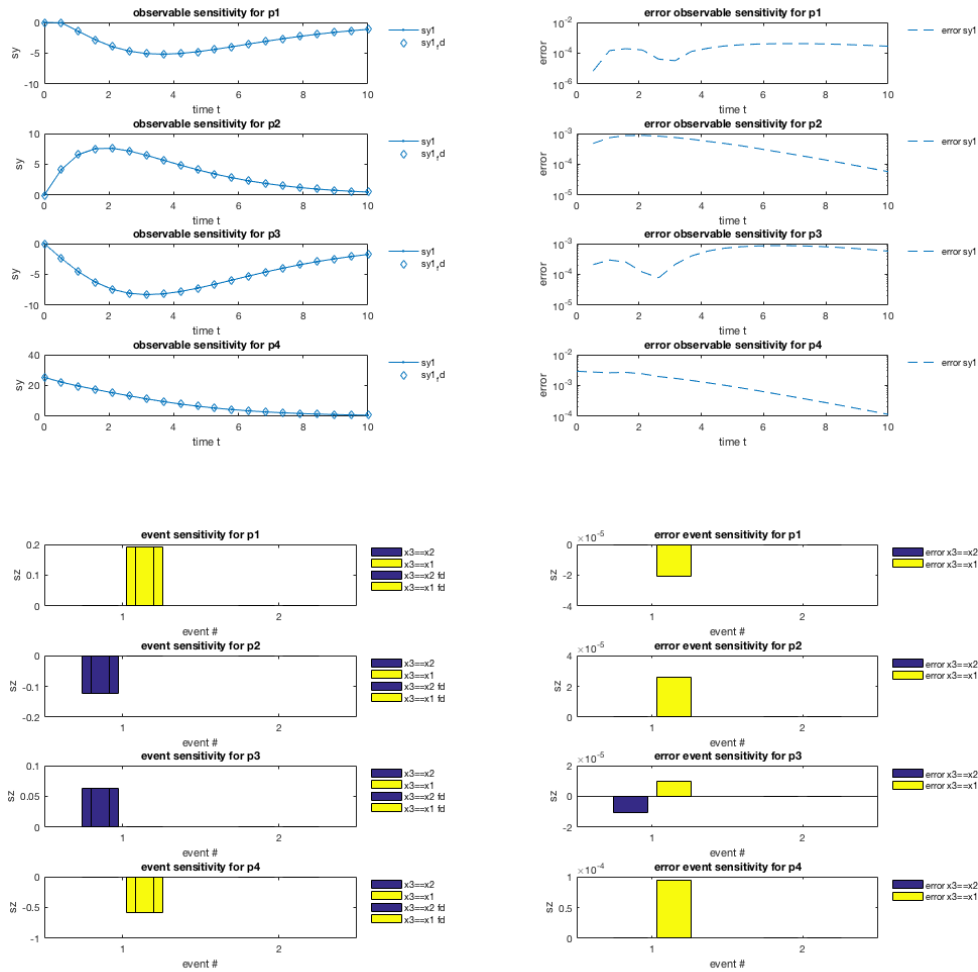
figure
for ip = 1:4
    subplot(4,2,2*ip-1)
    bar(1:options.nmaxevent,sol.sz(1:options.nmaxevent,:,ip),0.8)
    hold on
    bar(1:options.nmaxevent,sz_fd(1:options.nmaxevent,:,ip),0.4)
    legend('x3==x2','x3==x1','x3==x2 fd','x3==x1 fd','Location','NorthEastOutside')
    legend boxoff
    title(['event sensitivity for p' num2str(ip)])
    xlabel('event #')
    ylabel('sz')
    box on

    subplot(4,2,2*ip)
    bar(1:options.nmaxevent,sol.sz(1:options.nmaxevent,:,ip)-sz_fd(1:options.nmaxevent,:,ip),0.8)
    legend('error x3==x2','error x3==x1','Location','NorthEastOutside')
    legend boxoff
    title(['error event sensitivity for p' num2str(ip)])
    xlabel('event #')
    ylabel('sz')
    box on
end
set(gcf,'Position',[100 300 1200 500])

drawnow

```





end

## 3.2 Example Dirac

### 3.2.1 Model Definition

```
function [model] = model_dirac_syms()
```

#### STATES

```
% create state syms
syms x1 x2

% create state vector
model.sym.x = [ x1 x2 ];
```

#### PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3 p4

% create parameter vector
model.sym.p = [p1,p2,p3,p4];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```



## SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

% piecewise defined function
model.sym.xdot(1) = -p1*x1 + dirac(t-p2);
% inhomogeneous
model.sym.xdot(2) = p3*x1 - p4*x2 ;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = 0;
model.sym.x0(2) = 0;
```

## OBSERVABLES

```
model.sym.y = sym(zeros(1,1));

model.sym.y(1) = x2;

end

ans =
    sym: [1x1 struct]
    param: 'log10'
```

## 3.2.2 Simulation

```
function example_dirac()
```

## COMPILATION

```
[exdir,~,~]=fileparts(which('example_dirac.m'));
% compile the model
amiwrap('model_dirac','model_dirac_syms',exdir)
```

```
Generating model struct ...
Parsing model struct ...
```

```
Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

## SIMULATION

```
% time vector
t = linspace(0,3,1001);
p = [1;0.5;2;3];
k = [];

options = amioption('sensi',0,...
    'maxsteps',1e4);

% load mex into memory
[msg] = which('simulate_model_dirac'); % fix for inaccessability problems
sol = simulate_model_dirac(t,log10(p),k,[],options);

tic
sol = simulate_model_dirac(t,log10(p),k,[],options);
disp(['Time elapsed with amiwrap: ' num2str(toc) ])
```

Time elapsed with amiwrap: 0.0045507

## ODE15S

```
sig = 1e-2;
delta_num = @(tau) exp(-1/2*(tau/sig).^2)/(sqrt(2*pi)*sig);

ode_system = @(t,x,p,k) [-p(1)*x(1)+delta_num(t-p(2));
    +p(3)*x(1) - p(4)*x(2)];

options_ode45 = odeset('RelTol',options.rtol,'AbsTol',options.atol,'MaxStep',options.maxsteps);

tic
[~, X_ode45] = ode45(@(t,x) ode_system(t,x,p,k),t,[0;0],options_ode45);
disp(['Time elapsed with ode45: ' num2str(toc) ])
```

Time elapsed with ode45: 0.080371

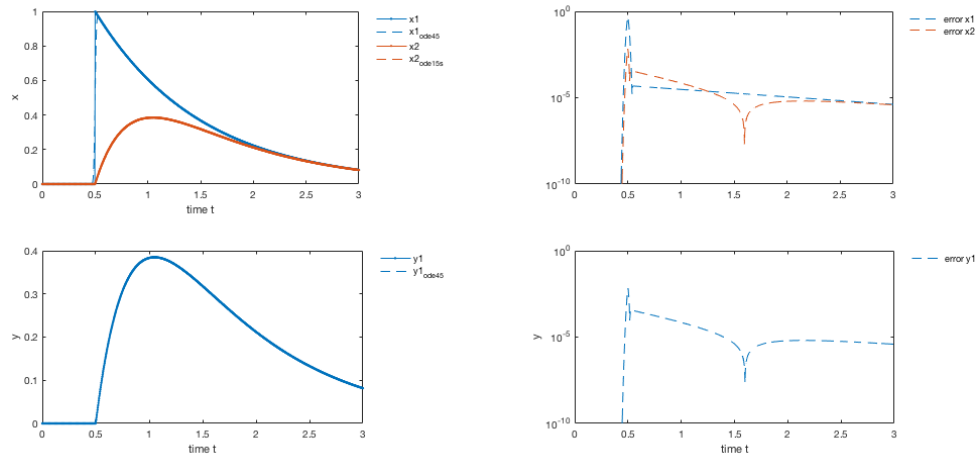
## PLOTTING

```
figure
c_x = get(gca,'ColorOrder');
subplot(2,2,1)
for ix = 1:size(sol.x,2)
    plot(t,sol.x(:,ix),'.-','Color',c_x(ix,:))
    hold on
    plot(t,X_ode45(:,ix),'--','Color',c_x(ix,:))
end

legend('x1','x1_ode45','x2','x2_ode15s','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('x')
box on
subplot(2,2,2)
plot(t,abs(sol.x-X_ode45),'--')
set(gca,'YScale','log')
ylim([1e-10,1e0])
legend('error x1','error x2','Location','NorthEastOutside')
legend boxoff

subplot(2,2,3)
plot(t,sol.y,'.-','Color',c_x(1,:))
hold on
plot(t,X_ode45(:,2),'--','Color',c_x(1,:))
legend('y1','y1_ode45','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('y')
box on

subplot(2,2,4)
plot(t,abs(sol.y-X_ode45(:,2)), '--')
set(gca,'YScale','log')
ylim([1e-10,1e0])
legend('error y1','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('y')
box on
set(gcf,'Position',[100 300 1200 500])
```



## FORWARD SENSITIVITY ANALYSIS

```
options.sensi = 1;

sol = simulate_model_dirac(t, log10(p), k, [], options);
```

## FINITE DIFFERENCES

```
eps = 1e-4;
xi = log10(p);
for ip = 1:4;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_dirac(t, xip, k, [], options);
    sx_fd(:, :, ip) = (solp.x - sol.x) / eps;
    sy_fd(:, :, ip) = (solp.y - sol.y) / eps;
end
```

## PLOTTING

```
figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for ix = 1:size(sol.x,2)
        plot(t, sol.sx(:,ix,ip), '.-', 'Color', c_x(ix,:))
        plot(t, sx_fd(:,ix,ip), '--', 'Color', c_x(ix,:))
    end
    ylim([-2,2])
    legend('x1', 'x1_fd', 'x2', 'x2_fd', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('x')
    box on

    subplot(4,2,ip*2)
    plot(t, abs(sol.sx(:, :, ip) - sx_fd(:, :, ip)), 'r--')
    legend('error x1', 'error x2', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('error')
    ylim([1e-12, 1e0])
    set(gca, 'YScale', 'log')
    box on
end
set(gcf, 'Position', [100 300 1200 500])

figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for iy = 1:size(sol.y,2)
```

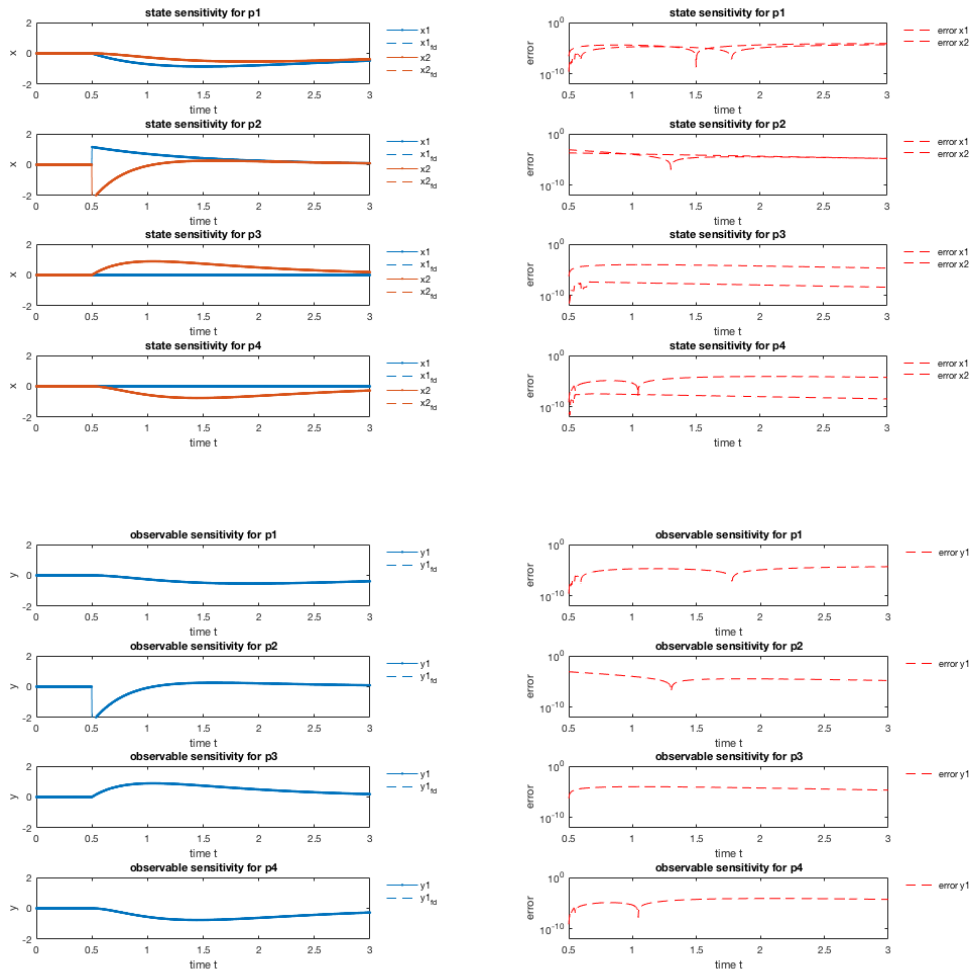
```

        plot(t,sol.sy(:,iy,ip),'.-','Color',c_x(iy,:))
        plot(t,sy_fd(:,iy,ip),'--','Color',c_x(iy,:))
    end
    ylim([-2,2])
    legend('y1','y1_fd','Location','NorthEastOutside')
    legend boxoff
    title(['observable sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('y')
    box on

    subplot(4,2,ip*2)
    plot(t,abs(sol.sy(:,ip)-sy_fd(:,ip)),'r--')
    legend('error y1','Location','NorthEastOutside')
    legend boxoff
    title(['observable sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('error')
    ylim([1e-12,1e0])
    set(gca,'YScale','log')
    box on
end
set(gcf,'Position',[100 300 1200 500])

drawnow

```



end

### 3.3 Example Steady State

#### 3.3.1 Model Definition

```
function [model] = model_steadystate_syms()
```

## STATES

```
% create state syms
syms x1 x2 x3
```

```
% create state vector
model.sym.x = [
x1 x2 x3
];
```

## PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3 p4 p5
```

```
% create parameter vector
model.sym.p = [p1,p2,p3,p4,p5];
```

```
% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

## CONSTANTS ( for these no sensitivities will be computed ) this part is optional and can be omitted

```
% create parameter syms
syms k1 k2 k3 k4
```

```
% create parameter vector
model.sym.k = [k1 k2 k3 k4];
```

## SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t
```

```
model.sym.xdot = sym(zeros(size(model.sym.x)));
```

```
% piecewise defined function
model.sym.xdot(1) = -2*p1*x1^2 - p2*x1*x2 + 2*p3*x2 + p4*x3 + p5;
% inhomogeneous
model.sym.xdot(2) = +p1*x1^2 - p2*x1*x2 - p3*x2 + p4*x3;
model.sym.xdot(3) = p2*x1*x2 - p4*x3 - k4*x3;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));
```

```
model.sym.x0(1) = k1;
model.sym.x0(2) = k2;
model.sym.x0(3) = k3;
```

## OBSERVALES

```
model.sym.y = model.sym.x;
```

```
end
```

```
ans =
    sym: [1x1 struct]
    param: 'log10'
```

### 3.3.2 Simulation

```
function example_steadystate
```

#### COMPILATION

```
[exdir,~,~]=fileparts(which('example_steadystate.m'));
% compile the model
amiwrap('model_steadystate','model_steadystate_syms',exdir)
```

```
Generating model struct ...
Parsing model struct ...
```

```
Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

#### SIMULATION

```
% time vector
t = linspace(0,300,20);
p = [1;0.5;0.4;2;0.1];
k = [0.1,0.4,0.7,1];

options = amioption('sensi',0,...
    'maxsteps',1e4);
% load mex into memory
sol = simulate_model_steadystate(t,log10(p),k,[],options);

tic
sol = simulate_model_steadystate(t,log10(p),k,[],options);
disp(['Time elapsed with cvodes: ' num2str(toc) ])
```

```
Time elapsed with cvodes: 0.004374
```

#### ODE15S

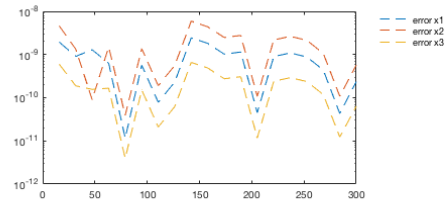
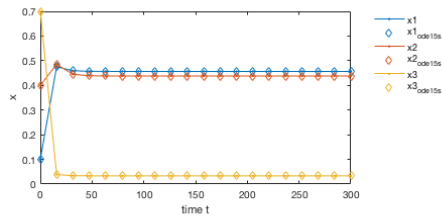
```
ode_system = @(t,x,p,k) [-2*p(1)*x(1)^2 - p(2)*x(1)*x(2) + 2*p(3)*x(2) + p(4)*x(3) + p(5);
    + p(1)*x(1)^2 - p(2)*x(1)*x(2) - p(3)*x(2) + p(4)*x(3);
    + p(2)*x(1)*x(2) - p(4)*x(3) - k(4)*x(3)];
options_ode15s = odeset('RelTol',options.rtol,'AbsTol',options.atol,'MaxStep',options.maxsteps);

tic
[~, X_ode15s] = ode15s(@(t,x) ode_system(t,x,p,k),t,k(1:3),options_ode15s);
disp(['Time elapsed with ode15s: ' num2str(toc) ])
```

```
Time elapsed with ode15s: 0.066508
```

#### PLOTTING

```
figure
c_x = get(gca,'ColorOrder');
subplot(2,2,1)
for ix = 1:size(sol.x,2)
    plot(t,sol.x(:,ix),'.-','Color',c_x(ix,:))
    hold on
    plot(t,X_ode15s(:,ix),'d','Color',c_x(ix,:))
end
legend('x1','x1_ode15s','x2','x2_ode15s','x3','x3_ode15s','Location','NorthEastOutside')
legend boxoff
xlabel('time t')
ylabel('x')
box on
subplot(2,2,2)
plot(t,abs(sol.x-X_ode15s),'--')
set(gca,'YScale','log')
legend('error x1','error x2','error x3','Location','NorthEastOutside')
legend boxoff
set(gcf,'Position',[100 300 1200 500])
```



## FORWARD SENSITIVITY ANALYSIS

```
options.sensi = 1;
options.sens_ind = [3,1,2,4];

sol = simulate_model_steadystate(t,log10(p),k,[],options);
```

## FINITE DIFFERENCES

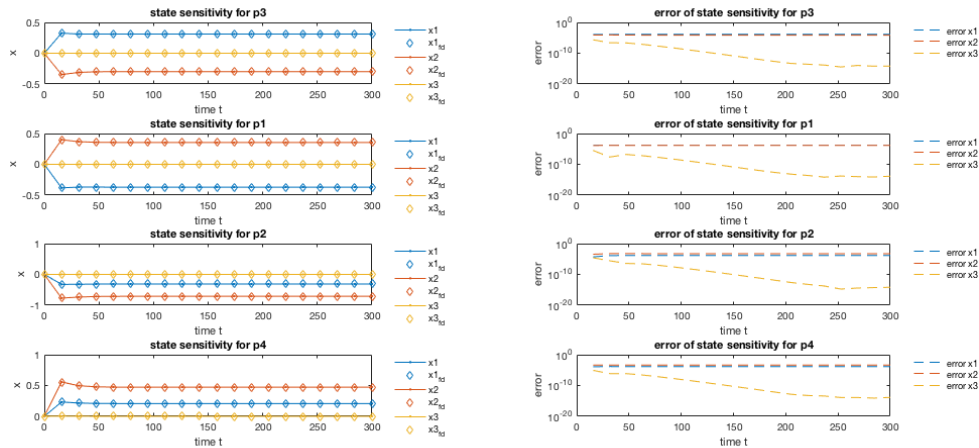
```
eps = 1e-3;

xi = log10(p);
for ip = 1:4;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_steadystate(t,xip,k,[],options);
    sx_fd(:, :, ip) = (solp.x - sol.x)/eps;
    sy_fd(:, :, ip) = (solp.y - sol.y)/eps;
end
```

## PLOTTING

```
figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for ix = 1:size(sol.x,2)
        plot(t,sol.sx(:,ix,ip),'.-','Color',c_x(ix,:))
        plot(t,sx_fd(:,ix,options.sens_ind(ip)),'d','Color',c_x(ix,:))
    end
    legend('x1','x1_fd','x2','x2_fd','x3','x3_fd','Location','NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(options.sens_ind(ip))])
    xlabel('time t')
    ylabel('x')
    box on

    subplot(4,2,ip*2)
    plot(t,abs(sol.sx(:, :, ip)-sx_fd(:, :, options.sens_ind(ip))), '--')
    legend('error x1','error x2','error x3','Location','NorthEastOutside')
    legend boxoff
    title(['error of state sensitivity for p' num2str(options.sens_ind(ip))])
    xlabel('time t')
    ylabel('error')
    set(gca,'YScale','log')
    box on
end
set(gcf,'Position',[100 300 1200 500])
```



## STEADY STATE SENSITIVITY

```

sssens = NaN(size(sol.sx));
for it = 2:length(t)
    tt = [0,t(it)];
    options.sensi_meth = 'ss';
    solss = simulate_model_steadystate(tt,log10(p),k,[],options);
    sssens(it,:) = solss.sx;
    sssdot(it,:) = solss.xdot;
end

```

## PLOTTING

```

figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for ix = 1:size(sol.x,2)
        plot(t,sol.sx(:,ix,ip),'.-','Color',c_x(ix,:))
        plot(t,sssens(:,ix,ip),'d-','Color',c_x(ix,:))
    end
    legend('x1','x1_ss','x2','x2_ss','x3','x3_ss','Location','NorthEastOutside')
    legend boxoff
    title(['state steady sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('x')
    box on

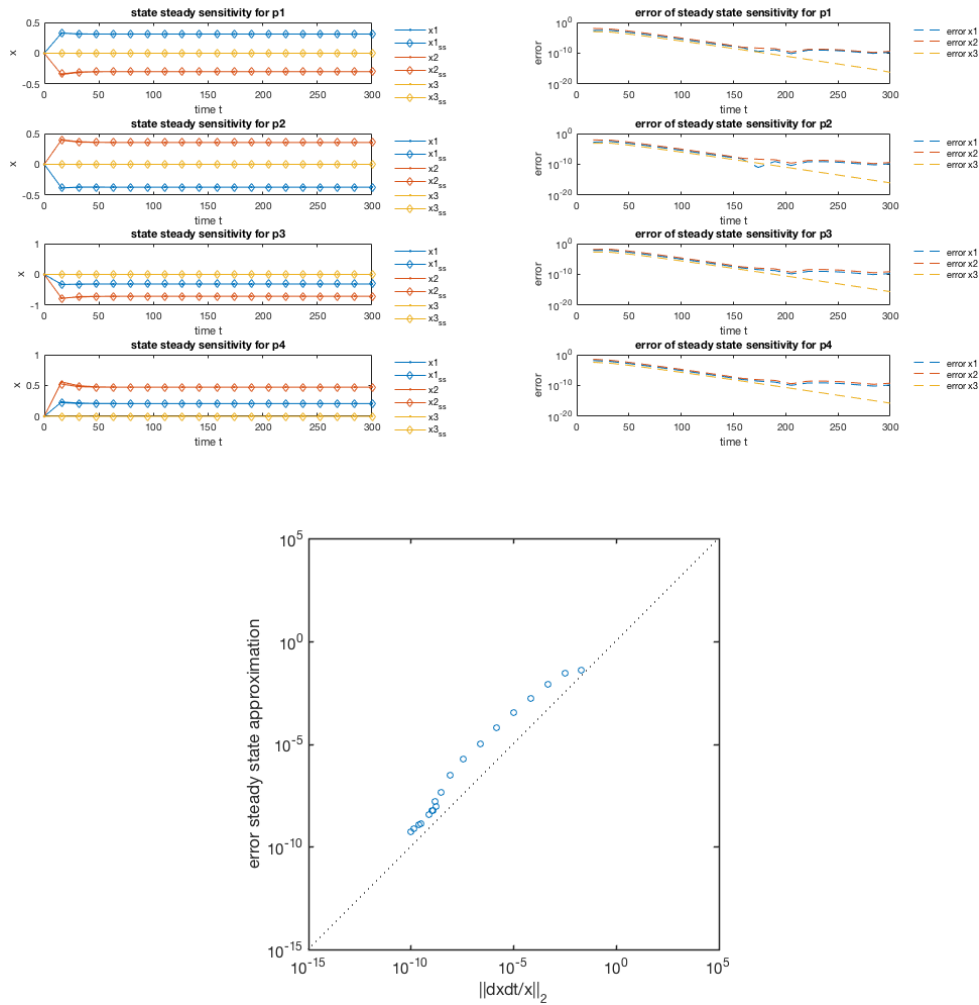
    subplot(4,2,ip*2)
    plot(t,abs(sol.sx(:, :, ip)-sssens(:, :, ip)),'--')
    legend('error x1','error x2','error x3','Location','NorthEastOutside')
    legend boxoff
    title(['error of steady state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('error')
    set(gca,'YScale','log')
    box on
end
set(gcf,'Position',[100 300 1200 500])

figure
scatter(sqrt(sum((ssxdot./sol.x).^2,2)),sqrt(sum(sum((sol.sx-sssens).^2,2),3)))
hold on
plot([1e-15,1e5],[1e-15,1e5],'k:')
set(gca,'YScale','log')
set(gca,'XScale','log')
box on
axis square
xlabel('||dxdt/x||_2')
ylabel('error steady state approximation')
set(gca,'FontSize',15)
set(gca,'LineWidth',1.5)
set(gcf,'Position',[100 300 1200 500])

drawnow

```





end

### 3.4 Example JAK/STAT Adjoint

#### 3.4.1 Model Definition

```
function [model] = model_jakstat_syms()
```

#### STATES

```
syms STAT pSTAT pSTAT_pSTAT npSTAT_npSTAT nSTAT1 nSTAT2 nSTAT3 nSTAT4 nSTAT5
model.sym.x = [
    STAT, pSTAT, pSTAT_pSTAT, npSTAT_npSTAT, nSTAT1, nSTAT2, nSTAT3, nSTAT4, nSTAT5 ...
];
```

#### PARAMETERS

```
syms p1 p2 p3 p4 init_STAT Omega_cyt Omega_nuc sp1 sp2 sp3 sp4 sp5 offset_tSTAT offset_pSTAT scale_tSTAT scale_pSTAT sigma
model.sym.p = [p1,p2,p3,p4,init_STAT,sp1,sp2,sp3,sp4,sp5,offset_tSTAT,offset_pSTAT,scale_tSTAT,scale_pSTAT,sigma_pSTAT,si
model.param = 'log10';
model.sym.k = [Omega_cyt,Omega_nuc];
```

## INPUT

```
syms t
u(1) = spline_pos5(t, 0.0, sp1, 5.0, sp2, 10.0, sp3, 20.0, sp4, 60.0, sp5, 0, 0.0);
```

Warning: Support of strings that are not valid variable names or define a number will be removed in a future release. To create symbolic expressions, first create symbolic variables and then use operations on them.

## SYSTEM EQUATIONS

```
model.sym.xdot = sym(zeros(size(model.sym.x)));

model.sym.xdot(1) = (Omega_nuc*p4*nSTAT5 - Omega_cyt*STAT*p1*u(1))/Omega_cyt;
model.sym.xdot(2) = STAT*p1*u(1) - 2*p2*pSTAT^2;
model.sym.xdot(3) = p2*pSTAT^2 - p3*pSTAT_pSTAT;
model.sym.xdot(4) = -(Omega_nuc*p4*npSTAT_npSTAT - Omega_cyt*p3*pSTAT_pSTAT)/Omega_nuc;
model.sym.xdot(5) = -p4*(nSTAT1 - 2*npSTAT_npSTAT);
model.sym.xdot(6) = p4*(nSTAT1 - nSTAT2);
model.sym.xdot(7) = p4*(nSTAT2 - nSTAT3);
model.sym.xdot(8) = p4*(nSTAT3 - nSTAT4);
model.sym.xdot(9) = p4*(nSTAT4 - nSTAT5);
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = init_STAT;
```

## OBSERVABLES

```
model.sym.y = sym(zeros(3,1));

model.sym.y(1) = offset_pSTAT + scale_pSTAT/init_STAT*(pSTAT + 2*pSTAT_pSTAT);
model.sym.y(2) = offset_tSTAT + scale_tSTAT/init_STAT*(STAT + pSTAT + 2*(pSTAT_pSTAT));
model.sym.y(3) = u(1);
```

## SIGMA

```
model.sym.sigma_y = sym(size(model.sym.y));

model.sym.sigma_y(1) = sigma_pSTAT;
model.sym.sigma_y(2) = sigma_tSTAT;
model.sym.sigma_y(3) = sigma_pEpoR;

end

ans =
    sym: [1x1 struct]
    param: 'log10'
```

### 3.4.2 Simulation

```
function example_jakstat_adjoint()

% compile the model
[exdir,~,~]=fileparts(which('example_jakstat_adjoint.m'));
amiwrap('model_jakstat','model_jakstat_adjoint_syms',exdir)

num = xlsread(fullfile(exdir,'pnas_data_original.xls'));

D.t = num(:,1);
D.condition= [1.4,0.45];
D.Y = num(:, [2,4,6]);
D.Sigma_Y = NaN(size(D.Y));
D = amidata(D);
```

```

xi = [0.60
      3
      -0.95
      -0.0075
      0
      -2.8
      -0.26
      -0.075
      -0.41
      -5
      -0.74
      -0.64
      -0.11
      0.027
      -0.5
      0
      -0.5];

options.sensi = 0;
sol = simulate_model_jakstat([],xi,[],D,options);

figure
for iy = 1:3
    subplot(2,2,iy)
    plot(D.t,D.Y(:,iy),'rx')
    hold on
    plot(sol.t,sol.y(:,iy),'.-')
    xlim([0,60])
    xlabel('t')
    switch(iy)
        case 1
            ylabel('pStat')
        case 2
            ylabel('tStat')
        case 3
            ylabel('pEpoR')
    end
    ylim([0,1.2])
end
set(gcf,'Position',[100 300 1200 500])

% generate new
xi_rand = xi + 0.1;
options.sensi = 1;
options.sensi_meth = 'adjoint';
sol = simulate_model_jakstat([],xi_rand,[],D,options);

options.sensi = 0;
eps = 1e-4;
fd_grad = NaN(length(xi),1);
for ip = 1:length(xi)
    xip = xi_rand;
    xip(ip) = xip(ip) + eps;
    psol = simulate_model_jakstat([],xip,[],D,options);
    fd_grad(ip) = (psol.llh-sol.llh)/eps;
end

figure
scatter(abs(sol.sllh),abs(fd_grad))
set(gca,'XScale','log')
set(gca,'YScale','log')
xlim([1e-2,1e2])
ylim([1e-2,1e2])
box on
hold on
axis square
plot([1e-2,1e2],[1e-2,1e2],'k:')
xlabel('adjoint sensitivity absolute value of gradient element')
ylabel('finite difference absolute value of gradient element')
set(gcf,'Position',[100 300 1200 500])

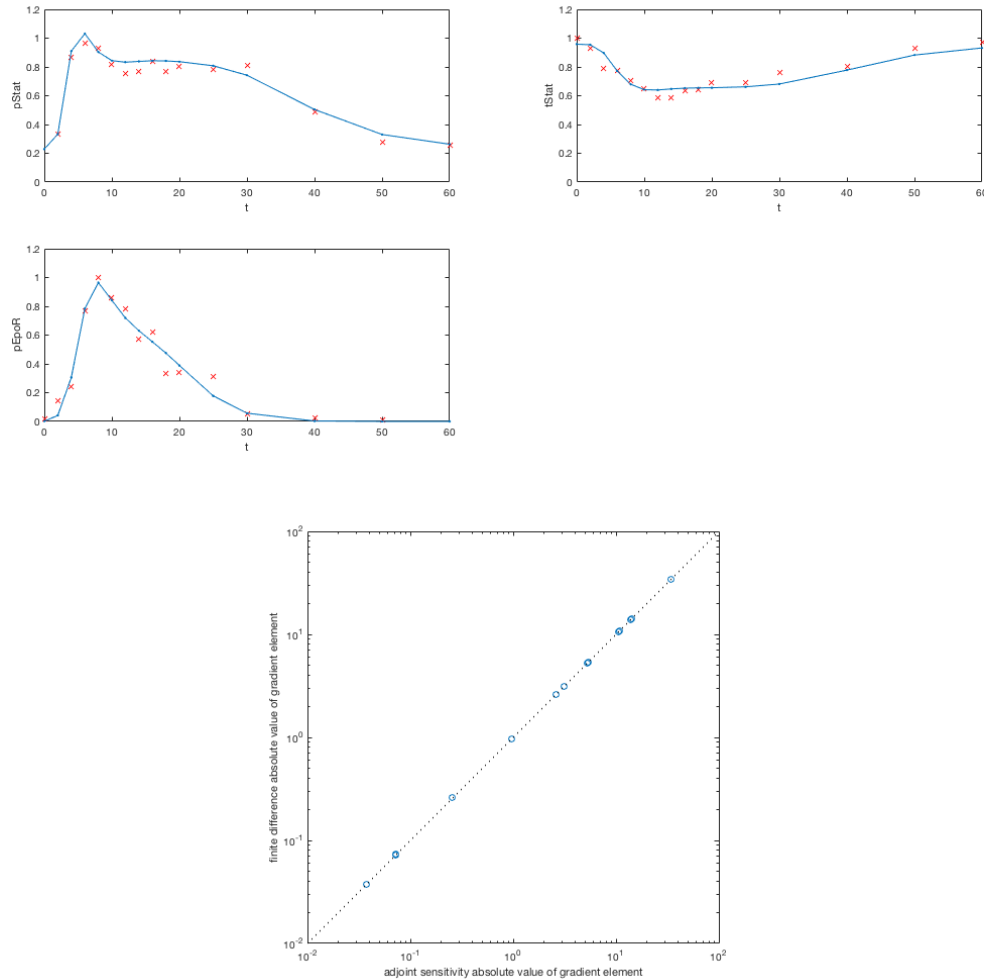
drawnow

end

Generating model struct ...
Parsing model struct ...

Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.

```



## 3.5 Example Dirac Adjoint

### 3.5.1 Model Definition

```
function [model] = model_dirac_adjoint_syms()
```

#### STATES

```
% create state syms
syms x1 x2

% create state vector
model.sym.x = [ x1 x2 ];
```

#### PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3 p4

% create parameter vector
model.sym.p = [p1,p2,p3,p4];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

#### SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

% piecewise defined function
model.sym.xdot(1) = -p1*x1 + dirac(t-p2);
% inhomogeneous
model.sym.xdot(2) = p3*x1 - p4*x2 ;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = 0;
model.sym.x0(2) = 0;
```

## OBSERVALES

```
model.sym.y = sym(zeros(1,1));

model.sym.y(1) = x2;

end

ans =
    sym: [1x1 struct]
    param: 'log10'
```

### 3.5.2 Simulation

```
function example_dirac_adjoint()
```

## COMPILATION

```
[exdir,~,~]=fileparts(which('example_dirac_adjoint.m'));
% compile the model
amiwrap('model_dirac_adjoint','model_dirac_adjoint_syms',exdir)

Generating model struct ...
Parsing model struct ...

Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

## SIMULATION

```
% time vector
tout = linspace(0,4,9);
tfine = linspace(0,4,10001);
p = [1;0.4;2;3];
k = [];

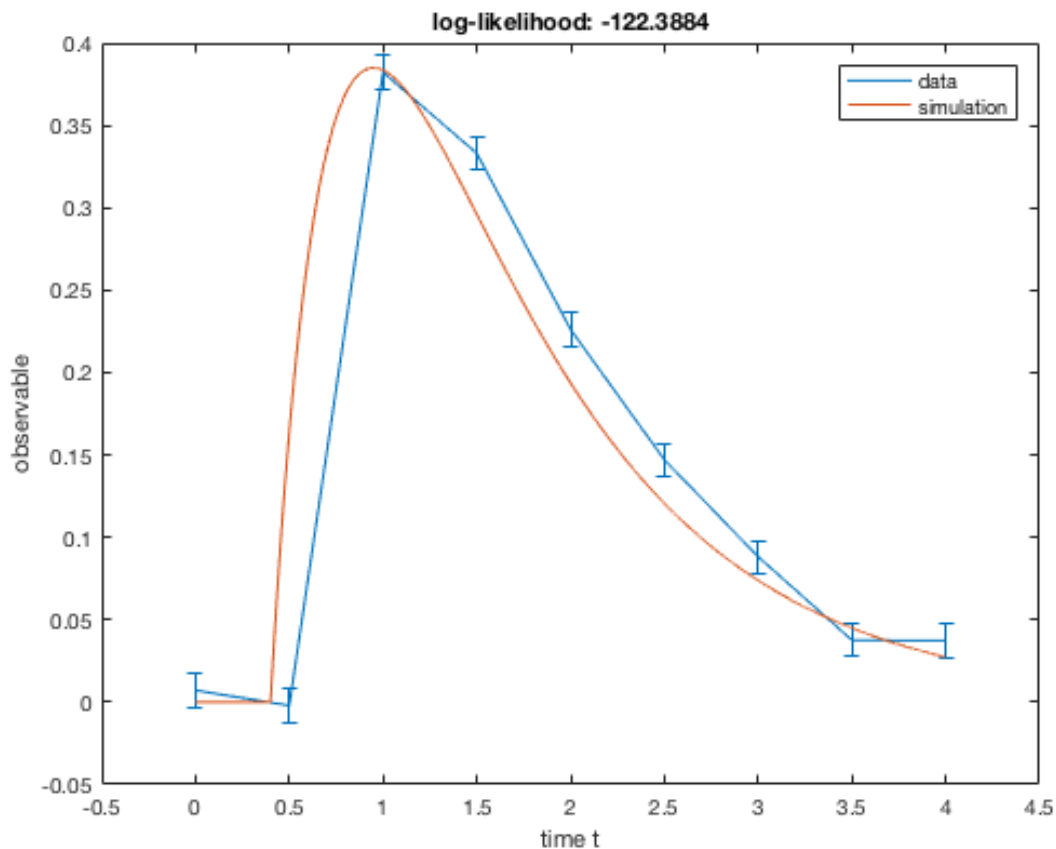
D.Y = [ 0.00714742903826096
        -0.00204966058299775
         0.382159034587845
         0.33298932672138
         0.226111476113441
         0.147028440865854
         0.0882468698791813
         0.0375887796628869
         0.0373422340295005];

D.Sigma_Y = 0.01*ones(size(D.Y));
```

```

options.sensi = 1;
options.sensi_meth = 'adjoint';
options.maxsteps = 1e5;
sol = simulate_model_dirac_adjoint(tout,log10(p),k,D,options);
options.sensi = 0;
solfine = simulate_model_dirac_adjoint(tfine,log10(p),k,[],options);
figure
errorbar(tout,D.Y,D.Sigma_Y)
hold on
plot(tfine,solfine.y)
legend('data','simulation')
xlabel('time t')
ylabel('observable')
title(['log-likelihood: ' num2str(sol.llh) ])

```



FD

```

eps = 1e-4;
xi = log10(p);
grad_fd_f = NaN(4,1);
grad_fd_b = NaN(4,1);
for ip = 1:4;
    options.sensi = 0;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solpf = simulate_model_dirac_adjoint(tout,xip,k,D,options);
    grad_fd_f(ip,1) = (solpf.llh-sol.llh)/eps;
    xip = xi;
    xip(ip) = xip(ip) - eps;
    solpb = simulate_model_dirac_adjoint(tout,xip,k,D,options);
    grad_fd_b(ip,1) = -(solpb.llh-sol.llh)/eps;
end

figure
plot(abs(grad_fd_f),abs(sol.sllh),'o')
hold on
plot(abs(grad_fd_b),abs(sol.sllh),'o')
set(gca,'XScale','log')
set(gca,'YScale','log')

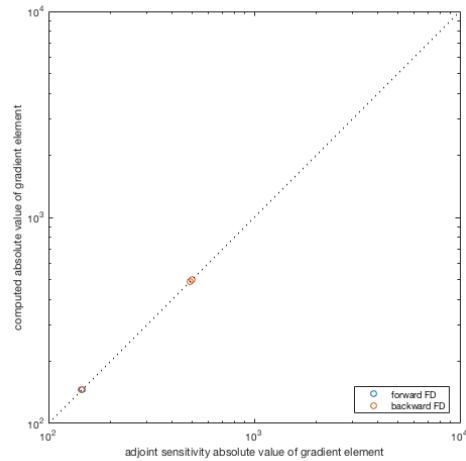
```

```

hold on
axis square
plot([1e2,1e4],[1e2,1e4],'k:')
xlim([1e2,1e4])
ylim([1e2,1e4])
legend('forward FD','backward FD','Location','SouthEast')
xlabel('adjoint sensitivity absolute value of gradient element')
ylabel('computed absolute value of gradient element')
set(gcf,'Position',[100 300 1200 500])

drawnow

```



```
end
```

## 3.6 Example Dirac Second Order Forward

### 3.6.1 Model Definition

```
function [model] = model_dirac_secondorder_syms()
```

#### STATES

```

% create state syms
syms x1 x2

% create state vector
model.sym.x = [ x1 x2 ];

```

#### PARAMETERS ( for these sensitivities will be computed )

```

% create parameter syms
syms p1 p2 p3 p4

% create parameter vector
model.sym.p = [p1,p2,p3,p4];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';

```

#### SYSTEM EQUATIONS

```

% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

```

```
% piecewise defined function
model.sym.xdot(1) = -p1*x1 + dirac(t-p2);
% inhomogeneous
model.sym.xdot(2) = p3*x1 - p4*x2 ;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = 0;
model.sym.x0(2) = 0;
```

## OBSERVALES

```
model.sym.y = sym(zeros(1,1));

model.sym.y(1) = x2;

end
```

```
ans =
    sym: [1x1 struct]
    param: 'log10'
```

### 3.6.2 Simulation

```
function example_dirac_secondorder()
```

## COMPILATION

```
[exdir,~,~]=fileparts(which('example_dirac_secondorder.m'));
% compile the model
amiwrap('model_dirac_secondorder','model_dirac_secondorder_syms',exdir,1)

Generating model struct ...
x | k | p | deltax | xdot | deltaxdot | ddeltaxdx | ddeltaxdp | ddeltaxdt | root | drootdx | sx | drootdp | drootdt | dtaudp
z |

Generating C code ...
deltasx | deltax | dsigma_ydp | dsigma_zdp | dydp | dzdp | root | sigma_y | sigma_z | stau | xdot | y | z | headers | wrapfun
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

## SIMULATION

```
% time vector
t = linspace(0,3,1001);
p = [1;0.5;2;3];
k = [];

options = amioption('sensi',0,...
    'maxsteps',1e4);

% load mex into memory
[msg] = which('simulate_model_secondorder_dirac'); % fix for inaccessability problems
options.sensi = 2;
sol = simulate_model_dirac_secondorder(t,log10(p),k,[],options);
```

## FORWARD SENSITIVITY ANALYSIS



```
options.sensi = 2;

sol = simulate_model_dirac_secondorder(t,log10(p),k,[],options);
```

## FINITE DIFFERENCES

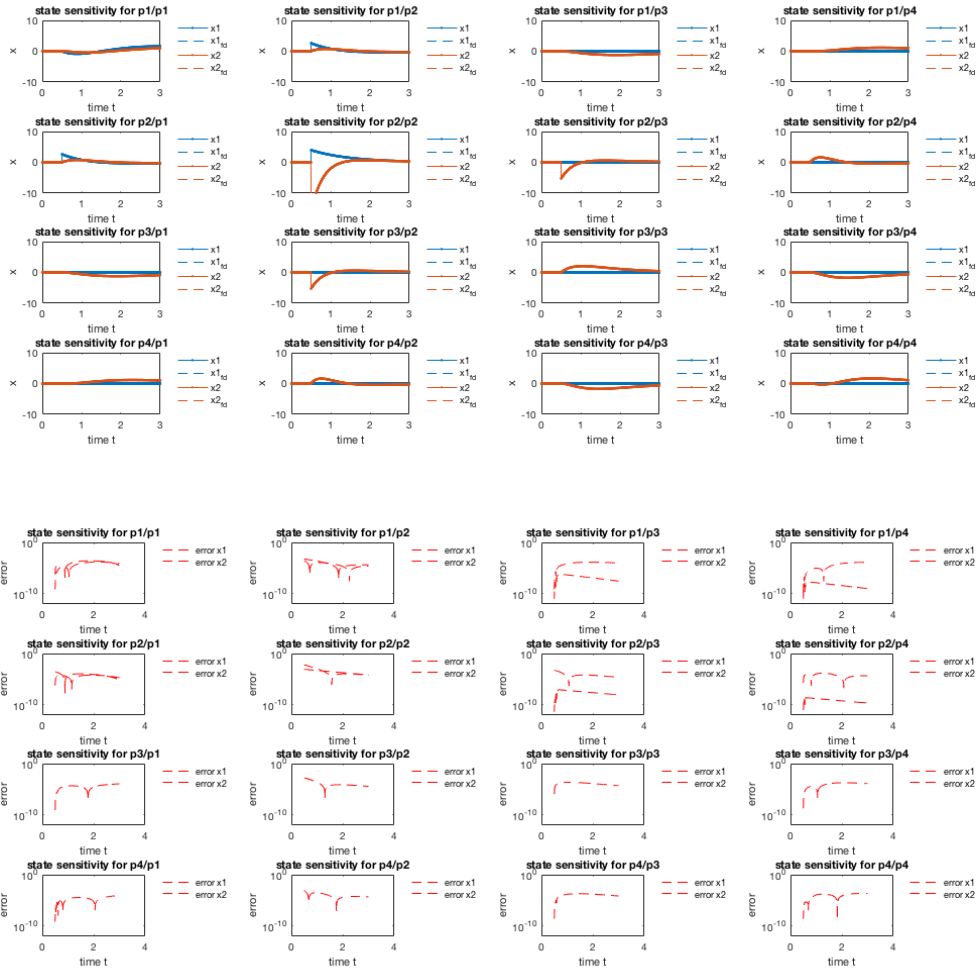
```
options.sensi = 1;

eps = 1e-4;
xi = log10(p);
for ip = 1:4;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_dirac_secondorder(t,xip,k,[],options);
    s2x_fd(:, :, ip) = (solp.sx - sol.sx)/eps;
    s2y_fd(:, :, ip) = (solp.sy - sol.sy)/eps;
end
```

## PLOTTING

```
figure
c_x = get(gca,'ColorOrder');
for ip = 1:4
    for jp = 1:4
        subplot(4,4,(ip-1)*4+jp)
        hold on
        for ix = 1:size(sol.x,2)
            plot(t,sol.s2x(:,ix,ip,jp),'.-','Color',c_x(ix,:))
            plot(t,s2x_fd(:,ix,ip,jp),'--','Color',c_x(ix,:))
        end
        ylim([-10,10])
        legend('x1','x1_fd','x2','x2_fd','Location','NorthEastOutside')
        legend boxoff
        title(['state sensitivity for p' num2str(ip) '/p' num2str(jp)])
        xlabel('time t')
        ylabel('x')
        box on
    end
end
set(gcf,'Position',[100 300 1200 500])
figure
for ip = 1:4
    for jp = 1:4
        subplot(4,4,(ip-1)*4+jp)
        plot(t,abs(sol.s2x(:, :, ip, jp)-s2x_fd(:, :, ip, jp)), 'r--')
        legend('error x1','error x2','Location','NorthEastOutside')
        legend boxoff
        title(['state sensitivity for p' num2str(ip) '/p' num2str(jp)])
        xlabel('time t')
        ylabel('error')
        ylim([1e-12,1e0])
        set(gca,'YScale','log')
        box on
    end
end
set(gcf,'Position',[100 300 1200 500])

drawnow
```



end

### 3.7 Example Dirac Directional Second Order Forward

#### 3.7.1 Model Definition

```
function [model] = model_dirac_seconddorder_vectmult_syms()
```

STATES

```
% create state syms
syms x1 x2

% create state vector
model.sym.x = [ x1 x2 ];
```

PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3 p4

% create parameter vector
model.sym.p = [p1,p2,p3,p4];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

## SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

% piecewise defined function
model.sym.xdot(1) = -p1*x1 + dirac(t-p2);
% inhomogeneous
model.sym.xdot(2) = p3*x1 - p4*x2 ;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = 0;
model.sym.x0(2) = 0;
```

## OBSERVALES

```
model.sym.y = sym(zeros(1,1));

model.sym.y(1) = x2;

end

ans =
    sym: [1x1 struct]
    param: 'log10'
```

## 3.7.2 Simulation

```
function example_dirac_secondorder_vectmult()
```

## COMPILATION

```
[exdir,~,~]=fileparts(which('example_dirac_secondorder_vectmult.m'));
% compile the model
amiwrap('model_dirac_secondorder_vectmult','model_dirac_secondorder_vectmult_syms',exdir,2)
```

Generating model struct ...

```
x | k | p | delta_x | xdot | delta_xdot | ddelta_xdx | ddelta_xdp | ddelta_xdt | root | drootdx | sx | drootdp | drootdt | dtaudp
z |
```

Generating C code ...

```
delta_sx | delta_x | dsigma_ydp | dsigma_zdp | dydp | dzdp | root | sigma_y | sigma_z | stau | xdot | y | z | headers | wrapfun
headers | wrapfunctions |
```

Compiling mex file ...

```
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

## SIMULATION

```
% time vector
t = linspace(0,3,1001);
p = [1;0.5;2;3];
k = [];
v = [0.7;0.3;1.4;0.1];

options = amioption('sensi',0,...
```

```

    'maxsteps',1e4);

% load mex into memory
[msg] = which('model_dirac_secondorder_vectmult'); % fix for inaccessability problems
options.sensi = 2;
sol = simulate_model_dirac_secondorder_vectmult(t,log10(p),k,[],options,v);

```

## FORWARD SENSITIVITY ANALYSIS

```

options.sensi = 2;

sol = simulate_model_dirac_secondorder_vectmult(t,log10(p),k,[],options,v);

```

## FINITE DIFFERENCES

```

options.sensi = 1;

eps = 1e-4;
xi = log10(p);
for ip = 1:4;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_dirac_secondorder_vectmult(t,xip,k,[],options);
    s2x_fd(:, :, ip) = sum(bsxfun(@times, (solp.sx - sol.sx)/eps, permute(v, [3,2,1])), 3);
    s2y_fd(:, :, ip) = sum(bsxfun(@times, (solp.sy - sol.sy)/eps, permute(v, [3,2,1])), 3);
end

```

## PLOTTING

```

figure
c_x = get(gca, 'ColorOrder');
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for ix = 1:size(sol.x,2)
        plot(t, sol.s2x(:, ix, ip), '.-', 'Color', c_x(ix, :))
        plot(t, s2x_fd(:, ix, ip), '--', 'Color', c_x(ix, :))
    end
    ylim([-10,10])
    legend('x1', 'x1_fd', 'x2', 'x2_fd', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('x')
    box on

    subplot(4,2,ip*2)
    plot(t, abs(sol.s2x(:, :, ip) - s2x_fd(:, :, ip)), 'r--')
    legend('error x1', 'error x2', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['state sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('error')
    ylim([1e-12, 1e0])
    set(gca, 'YScale', 'log')
    box on
end
set(gcf, 'Position', [100 300 1200 500])

figure
for ip = 1:4
    subplot(4,2,ip*2-1)
    hold on
    for iy = 1:size(sol.y,2)
        plot(t, sol.s2y(:, iy, ip), '.-', 'Color', c_x(iy, :))
        plot(t, s2y_fd(:, iy, ip), '--', 'Color', c_x(iy, :))
    end
    ylim([-10,10])
    legend('y1', 'y1_fd', 'Location', 'NorthEastOutside')
    legend boxoff
    title(['observable sensitivity for p' num2str(ip)])
    xlabel('time t')
    ylabel('y')
    box on

    subplot(4,2,ip*2)
    plot(t, abs(sol.s2y(:, :, ip) - s2y_fd(:, :, ip)), 'r--')

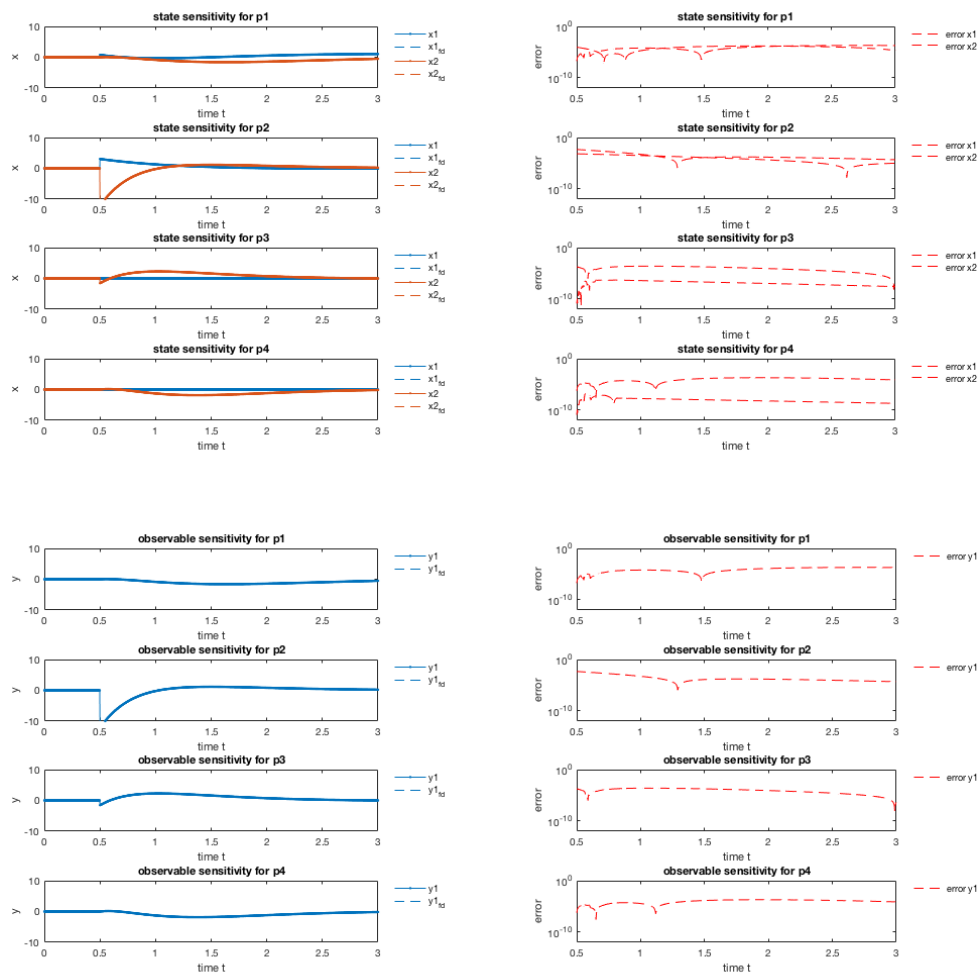
```

```

legend('error y1','Location','NorthEastOutside')
legend boxoff
title(['observable sensitivity for p' num2str(ip)])
xlabel('time t')
ylabel('error')
ylim([1e-12,1e0])
set(gca,'YScale','log')
box on
end
set(gcf,'Position',[100 300 1200 500])

drawnow

```



end

## 3.8 Example Adjoint

### 3.8.1 Model Definition

```
function [model] = model_adjoint_syms()
```

#### STATES

```

% create state syms
syms x1

% create state vector
model.sym.x = [x1];

```

## PARAMETERS ( for these sensitivities will be computed )

```
% create parameter syms
syms p1 p2 p3

% create parameter vector
model.sym.p = [p1 p2 p3];

% set the parametrisation of the problem options are 'log', 'log10' and
% 'lin' (default).
model.param = 'log10';
```

## SYSTEM EQUATIONS

```
% create symbolic variable for time
syms t

model.sym.xdot = sym(zeros(size(model.sym.x)));

% piecewise defined function
model.sym.xdot(1) = -p1*x1*heaviside(t-2) + p2;
```

## INITIAL CONDITIONS

```
model.sym.x0 = sym(zeros(size(model.sym.x)));

model.sym.x0(1) = p3;
```

## OBSERVALES

```
model.sym.y = sym(zeros(1,1));

model.sym.y(1) = x1;

end

ans =
    sym: [1x1 struct]
    param: 'log10'
```

### 3.8.2 Simulation

```
function example_adjoint()
```

## COMPILATION

```
[exdir,~,~]=fileparts(which('example_adjoint.m'));
% compile the model
amiwrap('model_adjoint','model_adjoint_syms',exdir)

Generating model struct ...
Parsing model struct ...

Generating C code ...
headers | wrapfunctions |
Compiling mex file ...
amici | Building with 'Xcode with Clang'.
MEX completed successfully.
Building with 'Xcode with Clang'.
MEX completed successfully.
```

## SIMULATION

```
% time vector
t = [linspace(0,4,5)];
p = [1.1,0.3,1];
k = [];

D.Y = [      1.0171
      1.3423
      1.6585
      0.9814
      0.3288];

D.Sigma_Y = 0.1*ones(size(D.Y));

options.sensi = 1;
options.sensi_meth = 'adjoint';
options.maxsteps = 1e4;
options.rtol = 1e-12;
options.atol = 1e-12;
% load mex into memory
[~] = which('simulate_model_adjoint'); % fix for inaccessability problems
sol = simulate_model_adjoint(t,log10(p),k,D,options);
```

## Plot

```
figure
subplot(3,1,1)
errorbar(t,D.Y,D.Sigma_Y)
hold on
% plot(t,sol.y)

xlabel('time t')
ylabel('observable')
title(['log-likelihood: ' num2str(sol.llh) ])

y = (p(2)*t + p(3)).*(t<2) + ( (2*p(2)+p(3)-p(2)/p(1))*exp(-p(1)*(t-2))+p(2)/p(1) ).*(t>=2);

tfine = linspace(0,4,100001);
xfine = (p(2)*tfine + 1).*(tfine<2) + ( (2*p(2)+p(3)-p(2)/p(1))*exp(-p(1)*(tfine-2))+p(2)/p(1) ).*(tfine>=2);

mu = zeros(1,length(tfine));
for it = 1:length(t)
    if(t(it)<=2)
        mu = mu + ((y(it)-D.Y(it))/(D.Sigma_Y(it)^2))*(tfine<=t(it));
    else
        mu = mu + ((y(it)-D.Y(it))/(D.Sigma_Y(it)^2))*exp(p(1)*(tfine-t(it))).*(tfine<=t(it)).*(tfine>2) + ((y(it)-D.Y(it))/(D.Sigma_Y(it)^2))*exp(p(1)*(tfine-t(it))).*(tfine>2);
    end
end
plot(tfine,xfine)
legend('data','simulation')
xlim([min(t)-0.5,max(t)+0.5])
subplot(3,1,2)
plot(tfine,mu)
ylabel('adjoint')
xlabel('time t')
xlim([min(t)-0.5,max(t)+0.5])

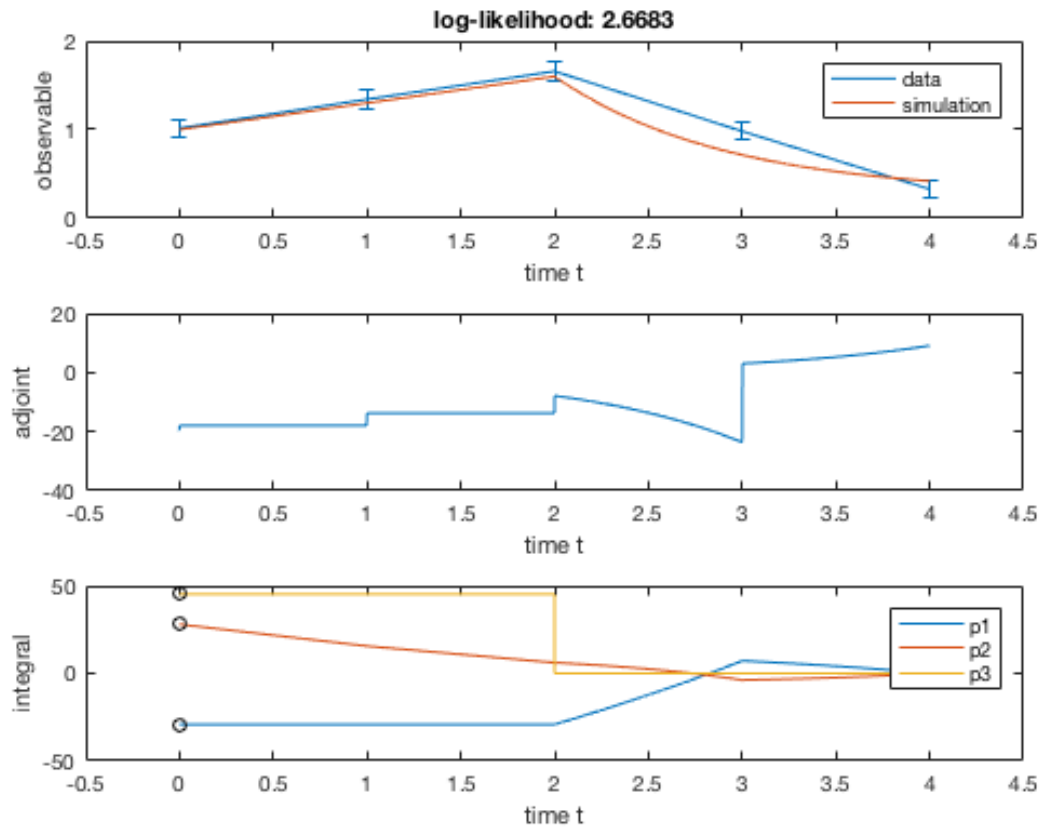
subplot(3,1,3)

plot(fliplr(tfine),-cumsum(fliplr(-mu.*xfine.*(tfine>2)))*p(1)*log(10)*(t(end)/numel(tfine)))
hold on
plot(fliplr(tfine),-cumsum(fliplr(mu))*p(2)*log(10)*(t(end)/numel(tfine)))
plot(tfine,-mu(1)*p(3)*log(10)*(tfine<2))
xlim([min(t)-0.5,max(t)+0.5])
ylabel('integral')
xlabel('time t')

legend('p1','p2','p3')

grad(1,1) = -trapz(tfine,-mu.*xfine.*(tfine>2))*p(1)*log(10);
grad(2,1) = -trapz(tfine,mu)*p(2)*log(10);
grad(3,1) = -mu(1)*p(3)*log(10);

plot(zeros(3,1),grad,'ko')
```



FD

```

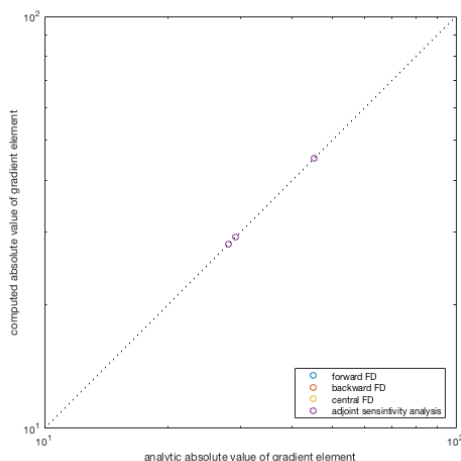
eps = 1e-5;
xi = log10(p);
grad_fd_f = NaN(3,1);
grad_fd_b = NaN(3,1);
for ip = 1:3;
    options.sensi = 0;
    xip = xi;
    xip(ip) = xip(ip) + eps;
    solp = simulate_model_adjoint(t,xip,k,D,options);
    grad_fd_f(ip,1) = (solp.llh-sol.llh)/eps;
    xip = xi;
    xip(ip) = xip(ip) - eps;
    solp = simulate_model_adjoint(t,xip,k,D,options);
    grad_fd_b(ip,1) = -(solp.llh-sol.llh)/eps;
end

figure
plot(abs(grad),abs(grad_fd_f),'o')
hold on
plot(abs(grad),abs(grad_fd_b),'o')
plot(abs(grad),mean([abs(grad_fd_b),abs(grad_fd_f)],2),'o')
plot(abs(grad),abs(sol.sllh),'o')
plot([1e1,1e2],[1e1,1e2],'k:')
set(gca,'XScale','log')
set(gca,'YScale','log')
axis square
legend('forward FD','backward FD','central FD','adjoint sensitivity analysis','Location','SouthEast')
xlabel('analytic absolute value of gradient element')
ylabel('computed absolute value of gradient element')
set(gcf,'Position',[100 300 1200 500])

drawnow

```





end

## 4 Code Organization

In the following we will briefly outline what happens when a model is compiled. For a more detailed description we refer the reader to the documentation of the individual functions.

After specifying a model (see [Model Definition](#)) the user will typically compile the model by invoking `amiwrap()`. `amiwrap()` first instantiates an object of the class `amimodel`. The properties of this object are initialised based on the user-defined model. If the `o2flag` is active, all subsequent computations will also be carried out on the augmented system, which also includes the equations for forward sensitivities. This allows the computation of second order sensitivities in a forward-forward approach. A forward-adjoint approach will be implemented in the future.

The `fun` fields of this object will then be populated by `amimodel::parseModel()`. The `amimodel::fun` field contains all function definitions of type `amifun` which are required for model compilation. The set of functions to be considered will depend on the user specification of the model fields `amimodel::adjoint` and `amimodel::forward` (see [Options](#)) as well as the employed solver (CVODES or IDAS, see [Differential Equation](#)). For all considered functions `amimodel::parseModel()` will check their dependencies via `amimodel::checkDeps()`. These dependencies are a subset of the user-specified fields of `amimodel::fun` (see [Attach to Model Struct](#)). `amimodel::parseModel()` compares the hashes of all dependencies against the `amimodel::HTable` of possible previous compilations and will only compute necessary symbolic expressions if changes in these fields occurred.

For all functions for which `amimodel::fun` exists, `amimodel::generateC()` will generate C files. These files together with their respective header files will be placed in `$AMICIDIR/models/modelname`. `amimodel::generateC()` will also generate `wrapfunctions.h` and `wrapfunctions.c`. These files define and declare model unspecific wrapper functions around model specific functions. This construction allows us to use to build multiple different models against the same simulation routines by linking different realisations of these wrapper functions.

All the generated C functions are subsequently compiled by `amimodel::compileC()`. For all functions individual object files are created to reduce the computation cost of code optimization. Moreover necessary code from sundials and SuiteSparse is compiled as object files and placed in `/models/mexext`, where `mexext` stands for the string returned by matlab to the command `mexext`. The mex simulation file is compiled from `amiwrap.c`, linked against all object necessary of sundials, SuiteSparse and model specific functions. Depending on the required solver, the compilation will either include `cvodewrap.h` or `idawrap.h`. These files implement solver specific realisations of the AMI... functions used in `amiwrap.c` and `amici.c`. This allows the use of the same simulation routines for both CVODES and IDAS.

## 5 Hierarchical Index

## 5.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

<b>amievent</b>	<b>44</b>
<b>amifun</b>	<b>46</b>
<b>ExpData</b>	<b>70</b>
handle	
<b>amidata</b>	<b>41</b>
<b>amimodel</b>	<b>51</b>
<b>SBMLode</b>	<b>75</b>
SetGet	
<b>amioption</b>	<b>65</b>
<b>modelTest</b>	<b>71</b>
<b>ReturnData</b>	<b>72</b>
sym	
<b>optsym</b>	<b>71</b>
<b>TempData</b>	<b>80</b>
<b>UserData</b>	<b>87</b>

## 6 Class Index

### 6.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<b>amidata</b>	
AMIDATA provides a data container to pass experimental data to the simulation routine for likelihood computation	<b>41</b>
<b>amievent</b>	
AMIEVENT defines events which later on will be transformed into appropriate C code	<b>44</b>
<b>amifun</b>	
AMIFUN defines functions which later on will be transformed into appropriate C code	<b>46</b>
<b>amimodel</b>	
AMIMODEL carries all model definitions including functions and events	<b>51</b>
<b>amioption</b>	
AMIOPTION provides an option container to pass simulation parameters to the simulation routine	<b>65</b>
<b>ExpData</b>	
Struct that carries all information about experimental data	<b>70</b>
<b>modelTest</b>	
MODELTEST Summary of this class goes here Detailed explanation goes here	<b>71</b>

**optsym**

OPTSYM is an auxiliary class to gain access to the private symbolic property `s` which is necessary to be able to call `symobj::optimize` on it

71

**ReturnData**

Struct that stores all data which is later returned by the mex function

72

**SBMLNode**

SBMLMODEL provides an intermediate container between the SBML definition and an ami-model object

75

**TempData**

Struct that provides temporary storage for different variables

80

**UserData**

Struct that stores all user provided data

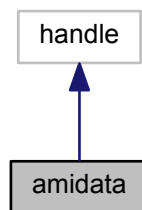
87

## 7 Class Documentation

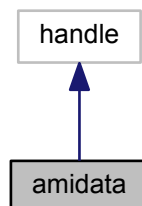
### 7.1 amidata Class Reference

AMIDATA provides a data container to pass experimental data to the simulation routine for likelihood computation.

Inheritance diagram for amidata:



Collaboration diagram for amidata:



## Public Member Functions

- [amidata](#) (matlabtypesubstitute varargin)  
*initialisation via struct*

## Public Attributes

- matlabtypesubstitute [nt](#) = 0  
*number of timepoints*
- matlabtypesubstitute [ny](#) = 0  
*number of observables*
- matlabtypesubstitute [nz](#) = 0  
*number of event observables*
- matlabtypesubstitute [ne](#) = 0  
*number of events*
- matlabtypesubstitute [nk](#) = 0  
*number of conditions/constants*
- matlabtypesubstitute [t](#) = double.empty("")  
*timepoints of observations*
- matlabtypesubstitute [Y](#) = double.empty("")  
*observations*
- matlabtypesubstitute [Sigma\\_Y](#) = double.empty("")  
*standard deviation of observations*
- matlabtypesubstitute [Z](#) = double.empty("")  
*event observations*
- matlabtypesubstitute [Sigma\\_Z](#) = double.empty("")  
*standard deviation of event observations*
- matlabtypesubstitute [condition](#) = double.empty("")  
*experimental condition*

### 7.1.1 Detailed Description

Definition at line 17 of file amidata.m.

### 7.1.2 Member Data Documentation

#### 7.1.2.1 [nt](#) = 0

**Default:** 0

Note

This property has custom functionality when its value is changed.

Definition at line 28 of file amidata.m.

#### 7.1.2.2 [ny](#) = 0

**Default:** 0

Note

This property has custom functionality when its value is changed.

Definition at line 36 of file amidata.m.

### 7.1.2.3 `nz = 0`

**Default:** 0

**Note**

This property has custom functionality when its value is changed.

Definition at line 44 of file amidata.m.

### 7.1.2.4 `ne = 0`

**Default:** 0

**Note**

This property has custom functionality when its value is changed.

Definition at line 52 of file amidata.m.

### 7.1.2.5 `nk = 0`

**Default:** 0

**Note**

This property has custom functionality when its value is changed.

Definition at line 60 of file amidata.m.

### 7.1.2.6 `t = double.empty("")`

**Default:** `double.empty("")`

**Note**

This property has custom functionality when its value is changed.

Definition at line 68 of file amidata.m.

### 7.1.2.7 `Y = double.empty("")`

**Default:** `double.empty("")`

**Note**

This property has custom functionality when its value is changed.

Definition at line 76 of file amidata.m.

### 7.1.2.8 `Sigma_Y = double.empty("")`

**Default:** `double.empty("")`

**Note**

This property has custom functionality when its value is changed.

Definition at line 84 of file amidata.m.

### 7.1.2.9 `Z = double.empty("")`

**Default:** `double.empty("")`

#### Note

This property has custom functionality when its value is changed.

Definition at line 92 of file amidata.m.

### 7.1.2.10 `Sigma_Z = double.empty("")`

**Default:** `double.empty("")`

#### Note

This property has custom functionality when its value is changed.

Definition at line 100 of file amidata.m.

### 7.1.2.11 `condition = double.empty("")`

**Default:** `double.empty("")`

#### Note

This property has custom functionality when its value is changed.

Definition at line 108 of file amidata.m.

## 7.2 amievent Class Reference

AMIEVENT defines events which later on will be transformed into appropriate C code.

### Public Member Functions

- `amievent` (matlabtypesubstitute `trigger`, matlabtypesubstitute `bolus`, matlabtypesubstitute `z`)  
*amievent constructs an amievent object from the provided input.*
- `mlhsInnrSubst< matlabtypesubstitute > setHflag (::double hflag)`  
*gethflag sets the hflag property.*

### Public Attributes

- `::symbolic trigger = sym.empty("")`  
*the trigger function activates the event on every zero crossing*
- `::symbolic bolus = sym.empty("")`  
*the bolus function defines the change in states that is applied on every event occurrence*
- `::symbolic z = sym.empty("")`  
*output function for the event*
- `matlabtypesubstitute hflag = logical.empty("")`  
*flag indicating that a heaviside function is present, this helps to speed up symbolic computations*

## 7.2.1 Detailed Description

Definition at line 17 of file amievent.m.

## 7.2.2 Constructor &amp; Destructor Documentation

7.2.2.1 amievent ( matlabtypesubstitute *trigger*, matlabtypesubstitute *bolus*, matlabtypesubstitute *z* )

## Parameters

<i>trigger</i>	trigger function, the event will be triggered on at all roots of this function
<i>bolus</i>	the bolus that will be added to all states on every occurrence of the event
<i>z</i>	the event output that will be reported on every occurrence of the event

Definition at line 75 of file amievent.m.

## 7.2.3 Member Function Documentation

7.2.3.1 mlhsInnerSubst<::amievent > setHflag ( ::double *hflag* )

## Parameters

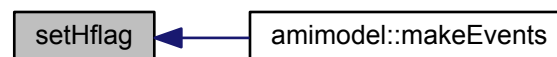
<i>hflag</i>	value for the hflag property
--------------	------------------------------

## Return values

<i>this</i>	updated event definition object
-------------	---------------------------------

Definition at line 18 of file setHflag.m.

Here is the caller graph for this function:



## 7.2.4 Member Data Documentation

## 7.2.4.1 trigger = sym.empty("")

## Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

Matlab documentation of property attributes.

**Default:** sym.empty("")

Definition at line 27 of file amievent.m.

## 7.2.4.2 bolus = sym.empty("")

**Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `sym.empty("")`

Definition at line 38 of file `amievent.m`.

#### 7.2.4.3 `z = sym.empty("")`

**Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `sym.empty("")`

Definition at line 49 of file `amievent.m`.

#### 7.2.4.4 `hflag = logical.empty("")`

**Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `logical.empty("")`

Definition at line 60 of file `amievent.m`.

## 7.3 amifun Class Reference

AMIFUN defines functions which later on will be transformed into appropriate C code.

### Public Member Functions

- `amifun` (matlabtypesubstitute `funstr`, matlabtypesubstitute model)
  - amievent constructs an amifun object from the provided input.*
- `noret::substitute printLocalVars` (::amimodel model,::fileid fid)
  - printlocalvars prints the C code for the initialisation of local variables into the file specified by fid.*
- `noret::substitute writeCcode_sensi` (::amimodel model,::fileid fid)
  - writeCcode\_sensi is a wrapper for writeCcode which loops over parameters and reduces overhead by check nonzero values*
- `noret::substitute writeCcode` (::amimodel model,::fileid fid)
  - writeCcode is a wrapper for gccode which initialises data and reduces overhead by check nonzero values*
- `noret::substitute gccode` (::amimodel model,::fileid fid)
  - gccode transforms symbolic expressions into c code and writes the respective expression into a specified file*
- `mlhsInnerSubst< matlabtypesubstitute > getDeps` (::amimodel model)
  - getDeps populates the sensiflag for the requested function*
- `mlhsInnerSubst< matlabtypesubstitute > getArgs` (::amimodel model)
  - getFArgs populates the fargstr property with the argument string of the respective model function (if applicable). model functions are not wrapped versions of functions which have a model specific name and for which the call is solver specific.*
- `mlhsInnerSubst< matlabtypesubstitute > getNVecs` ()
  - getfunargs populates the nvecs property with the names of the N\_Vector elements which are required in the execution of the function (if applicable). the information is directly extracted from the argument string*



- `mlhsInnerSubst< matlabtypesubstitute > getCVar ()`  
*getCVar populates the cvar property*
- `mlhsInnerSubst< matlabtypesubstitute > getSensiFlag ()`  
*getSensiFlag populates the sensiflag property*

#### Public Attributes

- `::symbolic sym = sym.empty("")`  
*symbolic definition struct*
- `::symbolic strsym = sym.empty("")`  
*short symbolic string which can be used for the reuse of precomputed values*
- `::symbolic strsym_old = sym.empty("")`  
*short symbolic string which can be used for the reuse of old values*
- `::char funstr = char.empty("")`  
*name of the model*
- `::char cvar = char.empty("")`  
*name of the c variable*
- `::char argstr = char.empty("")`  
*argument string (solver specific)*
- `::char fargstr = char.empty("")`  
*argument string (solver unspecific)*
- `::cell deps = cell.empty("")`  
*dependencies on other functions*
- `matlabtypesubstitute nvecs = cell.empty("")`  
*nvec dependencies*
- `matlabtypesubstitute sensiflag = logical.empty("")`  
*indicates whether the function is a sensitivity or derivative with respect to parameters*

#### 7.3.1 Detailed Description

Definition at line 17 of file `amifun.m`.

#### 7.3.2 Constructor & Destructor Documentation

##### 7.3.2.1 `amifun ( matlabtypesubstitute funstr, matlabtypesubstitute model )`

#### Parameters

<i>funstr</i>	name of the requested function
<i>model</i>	amimodel object which carries all symbolic definitions to construct the funtion

Definition at line 111 of file `amifun.m`.

#### 7.3.3 Member Function Documentation

##### 7.3.3.1 `noret::substitute printLocalVars ( ::amimodel model, ::fileid fid )`

#### Parameters

<i>model</i>	this struct must contain all necessary symbolic definitions
<i>fid</i>	file id in which the final expression is written

**Return values**

<i>fid</i>	Nothing
------------	---------

Definition at line 18 of file printLocalVars.m.

### 7.3.3.2 noret::substitute writeCcode\_sensi ( ::amimodel *model*, ::fileid *fid* )

**Parameters**

<i>model</i>	model definition object
<i>fid</i>	file id in which the final expression is written

**Return values**

<i>fid</i>	void
------------	------

Definition at line 18 of file writeCcode\_sensi.m.

### 7.3.3.3 noret::substitute writeCcode ( ::amimodel *model*, ::fileid *fid* )

**Parameters**

<i>model</i>	model definition object
<i>fid</i>	file id in which the final expression is written

**Return values**

<i>fid</i>	void
------------	------

Definition at line 18 of file writeCcode.m.

Here is the call graph for this function:



### 7.3.3.4 mlhsInnerSubst<::amifun > gccode ( ::amimodel *model*, ::fileid *fid* )

**Parameters**

<i>model</i>	model definition object
<i>fid</i>	file id in which the expression should be written

**Return values**

<i>this</i>	function definition object
-------------	----------------------------

Definition at line 18 of file gccode.m.

Here is the caller graph for this function:



#### 7.3.3.5 mlhsInnerSubst<::amifun > getDeps ( ::amimodel model )

##### Parameters

<i>model</i>	model definition object
--------------	-------------------------

##### Return values

<i>this</i>	updated function definition object
-------------	------------------------------------

Definition at line 18 of file getDeps.m.

#### 7.3.3.6 mlhsInnerSubst<::amifun > getArgs ( ::amimodel model )

##### Parameters

<i>model</i>	model definition object
--------------	-------------------------

##### Return values

<i>this</i>	updated function definition object
-------------	------------------------------------

Definition at line 18 of file getArgs.m.

#### 7.3.3.7 mlhsInnerSubst<::amifun > getNVecs ( )

##### Return values

<i>this</i>	updated function definition object
-------------	------------------------------------

Definition at line 18 of file getNVecs.m.

#### 7.3.3.8 mlhsInnerSubst<::amifun > getCVar ( )

##### Return values

<i>this</i>	updated function definition object
-------------	------------------------------------

Definition at line 18 of file getCVar.m.

#### 7.3.3.9 mlhsInnerSubst<::amifun > getSensiFlag ( )

##### Return values

<i>this</i>	updated function definition object
-------------	------------------------------------

Definition at line 18 of file getSensiFlag.m.

### 7.3.4 Member Data Documentation

7.3.4.1 `sym = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 27 of file amifun.m.

7.3.4.2 `strsym = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 35 of file amifun.m.

7.3.4.3 `strsym_old = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 43 of file amifun.m.

7.3.4.4 `funstr = char.empty("")`

**Default:** `char.empty("")`

Definition at line 51 of file amifun.m.

7.3.4.5 `cvar = char.empty("")`

**Default:** `char.empty("")`

Definition at line 59 of file amifun.m.

7.3.4.6 `argstr = char.empty("")`

**Default:** `char.empty("")`

Definition at line 67 of file amifun.m.

7.3.4.7 `fargstr = char.empty("")`

**Default:** `char.empty("")`

Definition at line 75 of file amifun.m.

7.3.4.8 `deps = cell.empty("")`

**Default:** `cell.empty("")`

Definition at line 83 of file amifun.m.

7.3.4.9 `nvecs = cell.empty("")`

**Default:** `cell.empty("")`

Definition at line 91 of file amifun.m.

## 7.3.4.10 sensiflag = logical.empty("")

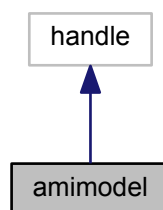
**Default:** logical.empty("")

Definition at line 99 of file amifun.m.

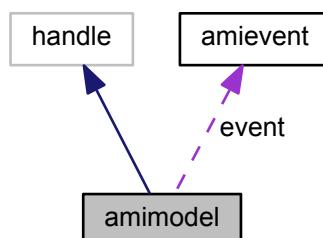
## 7.4 amimodel Class Reference

AMIMODEL carries all model definitions including functions and events.

Inheritance diagram for amimodel:



Collaboration diagram for amimodel:



## Public Member Functions

- [amimodel](#) (::string symfun,::string [modelname](#))  
*amimodel* initializes the model object based on the provided symfun and modelname
- noret::substitute [updateRHS](#) (matlabtypesubstitute xdot)  
*updateRHS* updates the private fun property .fun.xdot.sym (right hand side of the differential equation)
- noret::substitute [parseModel](#) ()  
*parseModel* parses the model definition and computes all necessary symbolic expressions.
- noret::substitute [generateC](#) ()  
*generateC* generates the c files which will be used in the compilation.

- `noret::substitute compileC ()`  
*compileC compiles the mex simulation file*
- `noret::substitute generateM (::amimodel amimodelo2)`  
*generateM generates the matlab wrapper for the compiled C files.*
- `noret::substitute getFun (::struct HTable,::string funstr)`  
*getFun generates symbolic expressions for the requested function.*
- `noret::substitute makeEvents ()`  
*makeEvents extracts discontinuities from the model right hand side and converts them into events*
- `noret::substitute makeSyms ()`  
*makeSyms extracts symbolic definition from the user provided model and checks them for consistency*
- `mlhsInnerSubst< matlabtypesubstitute > checkDeps (::struct HTable,::cell deps)`  
*checkDeps checks the dependencies of functions and populates sym fields if necessary*
- `mlhsInnerSubst< matlabtypesubstitute > loadOldHashes ()`  
*loadOldHashes loads information from a previous compilation of the model.*
- `mlhsInnerSubst< matlabtypesubstitute > augmento2 ()`  
*augmento2 augments the system equation to also include equations for sensitivity equation. This will enable us to compute second order sensitivities in a forward-adjoint or forward-forward approach later on.*
- `mlhsInnerSubst< matlabtypesubstitute > augmento2vec ()`  
*augmento2 augments the system equation to also include equations for sensitivity equation. This will enable us to compute second order sensitivities in a forward-adjoint or forward-forward approach later on.*

#### Public Attributes

- `::struct sym = struct.empty("")`  
*symbolic definition struct*
- `::struct fun = struct.empty("")`  
*struct which stores information for which functions c code needs to be generated*
- `::amievent event = amievent.empty("")`  
*struct which stores information for which functions c code needs to be generated*
- `::string modelname = char.empty("")`  
*name of the model*
- `::struct HTable = struct.empty("")`  
*struct that contains hash values for the symbolic model definitions*
- `::bool debug = false`  
*flag indicating whether debugging symbols should be compiled*
- `::bool adjoint = true`  
*flag indicating whether adjoint sensitivities should be enabled*
- `::bool forward = true`  
*flag indicating whether forward sensitivities should be enabled*
- `::double t0 = 0`  
*default initial time*
- `::string wtype = char.empty("")`  
*type of wrapper (cvcodes/idas)*
- `::int nx = double.empty("")`  
*number of states*
- `::int nxtrue = 0`  
*number of original states for second order sensitivities*
- `::int ny = double.empty("")`  
*number of observables*
- `::int nytrue = 0`  
*number of original observables for second order sensitivities*

- `::int np = double.empty("")`  
*number of parameters*
- `::int nk = double.empty("")`  
*number of constants*
- `::int nevent = double.empty("")`  
*number of events*
- `::int nz = double.empty("")`  
*number of event outputs*
- `::int nztrue = double.empty("")`  
*number of original event outputs for second order sensitivities*
- `::*int id = double.empty("")`  
*flag for DAEs*
- `::int ubw = double.empty("")`  
*upper Jacobian bandwidth*
- `::int lbw = double.empty("")`  
*lower Jacobian bandwidth*
- `::int nnz = double.empty("")`  
*number of nonzero entries in Jacobian*
- `::*int sparseidx = double.empty("")`  
*dataindexes of sparse Jacobian*
- `::*int rowvals = double.empty("")`  
*rowindexes of sparse Jacobian*
- `::*int colptrs = double.empty("")`  
*columnindexes of sparse Jacobian*
- `::*int sparseidxB = double.empty("")`  
*dataindexes of sparse Jacobian*
- `::*int rowvalsB = double.empty("")`  
*rowindexes of sparse Jacobian*
- `::*int colptrsB = double.empty("")`  
*columnindexes of sparse Jacobian*
- `::*cell funs = cell.empty("")`  
*cell array of functions to be compiled*
- `::string coptim = "-O3"`  
*optimisation flag for compilation*
- `::string param = "lin"`  
*default parametrisation*
- `matlabtypesubstitute wrap_path = char.empty("")`  
*path to wrapper*
- `matlabtypesubstitute recompile = false`  
*flag to enforce recompilation of the model*
- `matlabtypesubstitute cfun = struct.empty("")`  
*storage for flags determining recompilation of individual functions*
- `matlabtypesubstitute o2flag = 0`  
*flag which identifies augmented models 0 indicates no augmentation 1 indicates augmentation by first order sensitivities (yields second order sensitivities) 2 indicates augmentation by one linear combination of first order sensitivities (yields hessian-vector product)*
- `matlabtypesubstitute compver = 9`  
*counter that allows enforcing of recompilation of models after code changes*
- `matlabtypesubstitute z2event = double.empty("")`  
*vector that maps outputs to events*
- `matlabtypesubstitute splineflag = false`

- flag indicating whether the model contains spline functions*
  - matlabtypesubstitute **minflag** = false
- flag indicating whether the model contains min functions*
  - matlabtypesubstitute **maxflag** = false
- flag indicating whether the model contains max functions*
  - ::int **nw** = 0
- number of derived variables w, w is used for code optimization to reduce the number of frequently occurring expressions*
  - ::int **ndwdx** = 0
- number of derivatives of derived variables w, dwdx*
  - ::int **ndwdp** = 0
- number of derivatives of derived variables w, dwdp*

#### 7.4.1 Detailed Description

Definition at line 17 of file amimodel.m.

#### 7.4.2 Constructor & Destructor Documentation

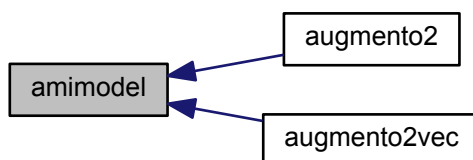
##### 7.4.2.1 amimodel ( ::string symfun, ::string modelname )

###### Parameters

<i>symfun</i>	this is the string to the function which generates the modelstruct. You can also directly pass the struct here
<i>modelname</i>	name of the model

Definition at line 506 of file amimodel.m.

Here is the caller graph for this function:



#### 7.4.3 Member Function Documentation

##### 7.4.3.1 noret::substitute updateRHS ( matlabtypesubstitute xdot )

###### Parameters

<i>xdot</i>	new right hand side of the differential equation
-------------	--

Definition at line 580 of file amimodel.m.

##### 7.4.3.2 noret::substitute generateC ( )



## Return values

<i>this</i>	model definition object
-------------	-------------------------

Definition at line 18 of file generateC.m.

## 7.4.3.3 noret::substitute compileC ( )

## Return values

<i>this</i>	model definition object
-------------	-------------------------

Definition at line 18 of file compileC.m.

## 7.4.3.4 noret::substitute generateM ( ::amimodel amimodelo2 )

## Parameters

<i>amimodelo2</i>	this struct must contain all necessary symbolic definitions for second order sensitivities
-------------------	--

## Return values

<i>this</i>	model definition object
-------------	-------------------------

Definition at line 18 of file generateM.m.

## 7.4.3.5 noret::substitute getFun ( ::struct HTable, ::string funstr )

## Parameters

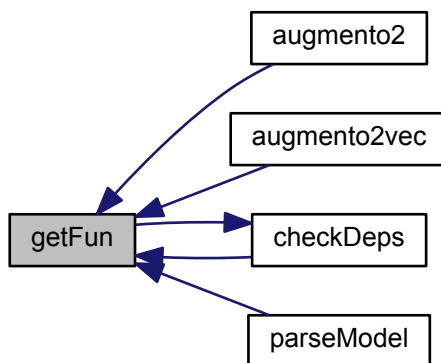
<i>HTable</i>	struct with hashes of symbolic definition from the previous compilation
<i>funstr</i>	function for which symbolic expressions should be computed

Definition at line 18 of file getFun.m.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 7.4.3.6 mlhsInnerSubst<::bool> checkDeps ( ::struct HTable, ::cell deps )

##### Parameters

<i>HTable</i>	struct with reference hashes of functions in its fields
<i>deps</i>	cell array with containing a list of dependencies

##### Return values

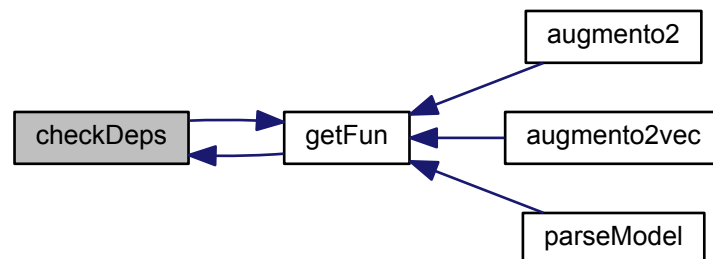
<i>cflag</i>	boolean indicating whether any of the dependencies have changed with respect to the hashes stored in HTable
--------------	---

Definition at line 18 of file checkDeps.m.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 7.4.3.7 mlhsInnerSubst<::struct> loadOldHashes ( )

Return values

<i>HTable</i>	struct with hashes of symbolic definition from the previous compilation
---------------	---

Definition at line 18 of file loadOldHashes.m.

Here is the caller graph for this function:



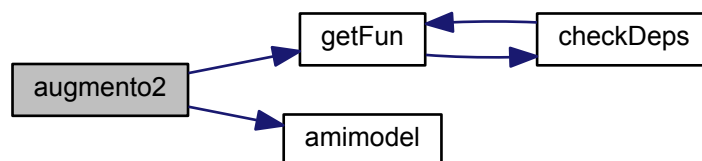
#### 7.4.3.8 mlhsInnerSubst< matlabtypesubstitute > augmento2 ( )

Return values

<i>this</i>	augmented system which contains symbolic definition of the original system and its sensitivities
-------------	--

Definition at line 18 of file augmento2.m.

Here is the call graph for this function:



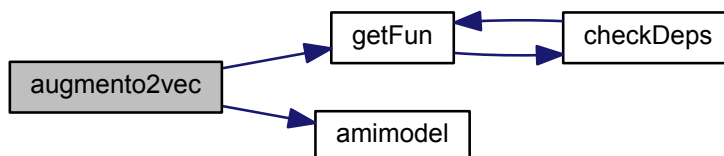
#### 7.4.3.9 mlhsInnerSubst< matlabtypesubstitute > augmento2vec ( )

Return values

<i>this</i>	augmented system which contains symbolic definition of the original system and its sensitivities
-------------	--

Definition at line 18 of file `augmento2vec.m`.

Here is the call graph for this function:



### 7.4.4 Member Data Documentation

#### 7.4.4.1 sym = struct.empty("")

Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

Matlab documentation of property attributes.

**Default:** `struct.empty("")`

Definition at line 27 of file `amimodel.m`.

#### 7.4.4.2 fun = struct.empty("")

**Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `struct.empty("")`

Definition at line 38 of file `amimodel.m`.

**7.4.4.3 event = amievent.empty("")****Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `amievent.empty("")`

Definition at line 49 of file `amimodel.m`.

**7.4.4.4 modelname = char.empty("")****Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `char.empty("")`

Definition at line 61 of file `amimodel.m`.

**7.4.4.5 HTable = struct.empty("")****Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `struct.empty("")`

Definition at line 72 of file `amimodel.m`.

**7.4.4.6 debug = false****Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `false`

Definition at line 83 of file `amimodel.m`.

**7.4.4.7 adjoint = true****Note**

This property has non-standard access specifiers: `SetAccess = Private, GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `true`

Definition at line 94 of file `amimodel.m`.

#### 7.4.4.8 forward = true

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** true

Definition at line 105 of file amimodel.m.

#### 7.4.4.9 t0 = 0

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** 0

Definition at line 116 of file amimodel.m.

#### 7.4.4.10 wtype = char.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** char.empty("")

Definition at line 127 of file amimodel.m.

#### 7.4.4.11 nx = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 138 of file amimodel.m.

#### 7.4.4.12 nxtrue = 0

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** 0

Definition at line 149 of file amimodel.m.

#### 7.4.4.13 ny = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 160 of file amimodel.m.

7.4.4.14 `nytrue = 0`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** 0

Definition at line 171 of file `amimodel.m`.

7.4.4.15 `np = double.empty("")`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 182 of file `amimodel.m`.

7.4.4.16 `nk = double.empty("")`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 193 of file `amimodel.m`.

7.4.4.17 `nevent = double.empty("")`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 204 of file `amimodel.m`.

7.4.4.18 `nz = double.empty("")`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 215 of file `amimodel.m`.

7.4.4.19 `nztrue = double.empty("")`

## Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 226 of file `amimodel.m`.

#### 7.4.4.20 `id = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 237 of file `amimodel.m`.

#### 7.4.4.21 `ubw = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 248 of file `amimodel.m`.

#### 7.4.4.22 `lbw = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 259 of file `amimodel.m`.

#### 7.4.4.23 `nnz = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 270 of file `amimodel.m`.

#### 7.4.4.24 `sparseidx = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 281 of file `amimodel.m`.

#### 7.4.4.25 `rowvals = double.empty("")`

##### Note

This property has non-standard access specifiers: `SetAccess = Private`, `GetAccess = Public`

[Matlab documentation of property attributes.](#)

**Default:** `double.empty("")`

Definition at line 292 of file `amimodel.m`.



#### 7.4.4.26 colptrs = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 303 of file amimodel.m.

#### 7.4.4.27 sparseidxB = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 314 of file amimodel.m.

#### 7.4.4.28 rowvalsB = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 325 of file amimodel.m.

#### 7.4.4.29 colptrsB = double.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 336 of file amimodel.m.

#### 7.4.4.30 funs = cell.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** cell.empty("")

Definition at line 347 of file amimodel.m.

#### 7.4.4.31 coptim = "-O3"

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** "-O3"

Definition at line 358 of file amimodel.m.

#### 7.4.4.32 param = "lin"

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** "lin"

Definition at line 369 of file amimodel.m.

#### 7.4.4.33 wrap\_path = char.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** char.empty("")

Definition at line 380 of file amimodel.m.

#### 7.4.4.34 recompile = false

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** false

Definition at line 391 of file amimodel.m.

#### 7.4.4.35 cfun = struct.empty("")

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** struct.empty("")

Definition at line 402 of file amimodel.m.

#### 7.4.4.36 o2flag = 0

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** 0

Definition at line 414 of file amimodel.m.

#### 7.4.4.37 compver = 9

##### Note

This property has non-standard access specifiers: SetAccess = Private, GetAccess = Public

[Matlab documentation of property attributes.](#)

**Default:** 9

Definition at line 431 of file amimodel.m.

7.4.4.38 `z2event = double.empty("")`

**Default:** `double.empty("")`

Definition at line 446 of file `amimodel.m`.

7.4.4.39 `splineflag = false`

**Default:** `false`

Definition at line 454 of file `amimodel.m`.

7.4.4.40 `minflag = false`

**Default:** `false`

Definition at line 462 of file `amimodel.m`.

7.4.4.41 `maxflag = false`

**Default:** `false`

Definition at line 470 of file `amimodel.m`.

7.4.4.42 `nw = 0`

**Default:** `0`

Definition at line 478 of file `amimodel.m`.

7.4.4.43 `ndwdx = 0`

**Default:** `0`

Definition at line 487 of file `amimodel.m`.

7.4.4.44 `ndwdp = 0`

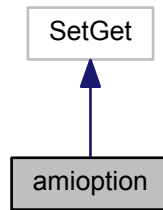
**Default:** `0`

Definition at line 495 of file `amimodel.m`.

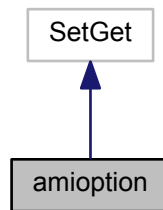
## 7.5 amioption Class Reference

AMIOPTION provides an option container to pass simulation parameters to the simulation routine.

Inheritance diagram for amioption:



Collaboration diagram for amioption:



### Public Member Functions

- `amioption` (matlabtypesubstitute varargin)  
*amioptions Construct a new amioptions object*

### Public Attributes

- matlabtypesubstitute `atol` = 1e-16  
*absolute integration tolerace*
- matlabtypesubstitute `rtol` = 1e-8  
*relative integration tolerace*
- matlabtypesubstitute `maxsteps` = 1e4  
*maximum number of integration steps*
- matlabtypesubstitute `sens_ind` = double.empty("")  
*index of parameters for which the sensitivities are computed*
- matlabtypesubstitute `qpositivex` = double.empty("")  
*index of states for which positivity should be enforced (currently this has no effect)*
- matlabtypesubstitute `tstart` = 0  
*starting time of the simulation*
- matlabtypesubstitute `lmm` = 2

- linear multistep method.*
- matlabtypesubstitute `iter` = 2  
*iteration method for linear multistep.*
- matlabtypesubstitute `linsol` = 9  
*linear solver*
- matlabtypesubstitute `stldet` = true  
*stability detection flag*
- matlabtypesubstitute `interpType` = 1  
*interpolation type*
- matlabtypesubstitute `lmmB` = 2  
*linear multistep method (backwards)*
- matlabtypesubstitute `iterB` = 2  
*iteration method for linear multistep (backwards).*
- matlabtypesubstitute `ism` = 1  
*forward sensitivity mode*
- matlabtypesubstitute `sensi_meth` = 1  
*sensitivity method*
- matlabtypesubstitute `sensi` = 0  
*sensitivity order*
- matlabtypesubstitute `nmaxevent` = 10  
*number of reported events*
- matlabtypesubstitute `ordering` = 1  
*reordering of states*
- matlabtypesubstitute `ss` = 0  
*steady state sensitivity flag*
- matlabtypesubstitute `sx0` = double.empty("")  
*custom initial sensitivity*
- matlabtypesubstitute `z2event` = double.empty("")  
*mapping of event outputs to events*
- matlabtypesubstitute `id` = double.empty("")  
*flag for DAE variables*

### 7.5.1 Detailed Description

Definition at line 17 of file amioption.m.

### 7.5.2 Constructor & Destructor Documentation

#### 7.5.2.1 `amioption ( matlabtypesubstitute varargin )`

`OPTS = amioption()` creates a set of options with each option set to its default value.

`OPTS = amioption(PARAM, VAL, ...)` creates a set of options with the named parameters altered with the specified values.

`OPTS = amioption(OLDOPTS, PARAM, VAL, ...)` creates a copy of OLDOPTS with the named parameters altered with the specified value

Note to see the parameters, check the documentation page for amioptions

Definition at line 217 of file amioption.m.

### 7.5.3 Member Data Documentation

#### 7.5.3.1 `atol = 1e-16`

**Default:** 1e-16

Definition at line 28 of file amioption.m.

#### 7.5.3.2 `rtol = 1e-8`

**Default:** 1e-8

Definition at line 36 of file amioption.m.

#### 7.5.3.3 `maxsteps = 1e4`

**Default:** 1e4

Definition at line 44 of file amioption.m.

#### 7.5.3.4 `sens_ind = double.empty("")`

**Default:** double.empty("")

Definition at line 52 of file amioption.m.

#### 7.5.3.5 `qpositivex = double.empty("")`

**Default:** double.empty("")

Definition at line 60 of file amioption.m.

#### 7.5.3.6 `tstart = 0`

**Default:** 0

Definition at line 69 of file amioption.m.

#### 7.5.3.7 `lmm = 2`

**Default:** 2

Definition at line 77 of file amioption.m.

#### 7.5.3.8 `iter = 2`

**Default:** 2

Definition at line 85 of file amioption.m.

#### 7.5.3.9 `linsol = 9`

**Default:** 9

Definition at line 93 of file amioption.m.

#### 7.5.3.10 stldet = true

**Default:** true

Definition at line 101 of file amioption.m.

#### 7.5.3.11 interpType = 1

**Default:** 1

Definition at line 109 of file amioption.m.

#### 7.5.3.12 ImmB = 2

**Default:** 2

Definition at line 117 of file amioption.m.

#### 7.5.3.13 iterB = 2

**Default:** 2

Definition at line 125 of file amioption.m.

#### 7.5.3.14 ism = 1

**Default:** 1

Definition at line 133 of file amioption.m.

#### 7.5.3.15 sensi\_meth = 1

**Default:** 1

Note

This property has custom functionality when its value is changed.

Definition at line 141 of file amioption.m.

#### 7.5.3.16 sensi = 0

**Default:** 0

Note

This property has custom functionality when its value is changed.

Definition at line 149 of file amioption.m.

#### 7.5.3.17 nmaxevent = 10

**Default:** 10

Definition at line 157 of file amioption.m.

### 7.5.3.18 ordering = 1

**Default:** 1

Definition at line 165 of file amioption.m.

### 7.5.3.19 ss = 0

**Default:** 0

Definition at line 173 of file amioption.m.

### 7.5.3.20 sx0 = double.empty("")

**Default:** double.empty("")

Definition at line 181 of file amioption.m.

### 7.5.3.21 z2event = double.empty("")

Note

This property has the MATLAB attribute `Hidden` set to true.

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 192 of file amioption.m.

### 7.5.3.22 id = double.empty("")

Note

This property has the MATLAB attribute `Hidden` set to true.

[Matlab documentation of property attributes.](#)

**Default:** double.empty("")

Definition at line 203 of file amioption.m.

## 7.6 ExpData Struct Reference

struct that carries all information about experimental data

```
#include <edata.h>
```

### Public Attributes

- double \* [am\\_my](#)
- double \* [am\\_ysigma](#)
- double \* [am\\_mz](#)
- double \* [am\\_zsigma](#)

### 7.6.1 Detailed Description

Definition at line 18 of file edata.h.



### 7.6.2 Member Data Documentation

#### 7.6.2.1 double\* am\_my

observed data

Definition at line 20 of file edata.h.

#### 7.6.2.2 double\* am\_ysigma

standard deviation of observed data

Definition at line 22 of file edata.h.

#### 7.6.2.3 double\* am\_mz

observed events

Definition at line 25 of file edata.h.

#### 7.6.2.4 double\* am\_zsigma

standard deviation of observed events

Definition at line 27 of file edata.h.

## 7.7 modelTest Class Reference

MODELTEST Summary of this class goes here Detailed explanation goes here.

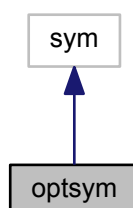
### 7.7.1 Detailed Description

Definition at line 17 of file modelTest.m.

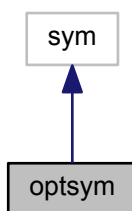
## 7.8 optsym Class Reference

OPTSYM is an auxiliary class to gain access to the private symbolic property `s` which is necessary to be able to call `symobj::optimize` on it.

Inheritance diagram for optsym:



Collaboration diagram for optsym:



### Public Member Functions

- [optsym](#) (matlabtypesubstitute symbol)  
*optsym converts the symbolic object into a optsym object*
- mlhsInnerSubst< matlabtypesubstitute > [getoptimized](#) ()  
*optsym calls symobj::optimize on the optsym object*

#### 7.8.1 Detailed Description

Definition at line 17 of file optsym.m.

#### 7.8.2 Member Function Documentation

##### 7.8.2.1 mlhsInnerSubst< matlabtypesubstitute > getoptimized ( )

Return values

<i>optimized</i>	symbolic object
------------------	-----------------

Definition at line 46 of file optsym.m.

### 7.9 ReturnData Struct Reference

struct that stores all data which is later returned by the mex function

```
#include <rdata.h>
```

#### Public Attributes

- double \* [am\\_tsdata](#)
- double \* [am\\_xdotdata](#)
- double \* [am\\_dxdotdpdata](#)
- double \* [am\\_dydxdata](#)
- double \* [am\\_dydpdata](#)
- double \* [am\\_Jdata](#)
- double \* [am\\_zdata](#)
- double \* [am\\_sigmazdata](#)

- double \* [am\\_szdata](#)
- double \* [am\\_ssigmazdata](#)
- double \* [am\\_xdata](#)
- double \* [am\\_sxdata](#)
- double \* [am\\_ydata](#)
- double \* [am\\_sigmaydata](#)
- double \* [am\\_sydata](#)
- double \* [am\\_ssigmaydata](#)
- double \* [am\\_numstepsdata](#)
- double \* [am\\_numstepsSdata](#)
- double \* [am\\_numrhsevalsdata](#)
- double \* [am\\_numrhsevalsSdata](#)
- double \* [am\\_orderdata](#)
- double \* [am\\_llhdata](#)
- double \* [am\\_chi2data](#)
- double \* [am\\_sllhdata](#)
- double \* [am\\_s2llhdata](#)

### 7.9.1 Detailed Description

Definition at line 42 of file `rdata.h`.

### 7.9.2 Member Data Documentation

#### 7.9.2.1 double\* am\_tsdata

timepoints

Definition at line 45 of file `rdata.h`.

#### 7.9.2.2 double\* am\_xdotdata

time derivative

Definition at line 47 of file `rdata.h`.

#### 7.9.2.3 double\* am\_dxdotdpdata

parameter derivative of time derivative

Definition at line 49 of file `rdata.h`.

#### 7.9.2.4 double\* am\_dydxdata

state derivative of observables

Definition at line 51 of file `rdata.h`.

#### 7.9.2.5 double\* am\_dydpdata

parameter derivative of observables

Definition at line 53 of file `rdata.h`.

#### 7.9.2.6 double\* am\_Jdata

Jacobian of differential equation right hand side

Definition at line 55 of file `rdata.h`.

**7.9.2.7 double\* am\_zdata**

event output

Definition at line 57 of file rdata.h.

**7.9.2.8 double\* am\_sigmazdata**

event output sigma standard deviation

Definition at line 59 of file rdata.h.

**7.9.2.9 double\* am\_szdata**

parameter derivative of event output

Definition at line 61 of file rdata.h.

**7.9.2.10 double\* am\_ssigmazdata**

parameter derivative of event output standard deviation

Definition at line 63 of file rdata.h.

**7.9.2.11 double\* am\_xdata**

state

Definition at line 65 of file rdata.h.

**7.9.2.12 double\* am\_sxdata**

parameter derivative of state

Definition at line 67 of file rdata.h.

**7.9.2.13 double\* am\_ydata**

observable

Definition at line 69 of file rdata.h.

**7.9.2.14 double\* am\_sigmaydata**

observable standard deviation

Definition at line 71 of file rdata.h.

**7.9.2.15 double\* am\_sydata**

parameter derivative of observable

Definition at line 73 of file rdata.h.

**7.9.2.16 double\* am\_ssigmaydata**

parameter derivative of observable standard deviation

Definition at line 75 of file rdata.h.

**7.9.2.17 double\* am\_numstepsdata**

number of integration steps forward problem

Definition at line 78 of file rdata.h.

**7.9.2.18 double\* am\_numstepsSdata**

number of integration steps backward problem

Definition at line 80 of file rdata.h.

**7.9.2.19 double\* am\_numrhsevalsdata**

number of right hand side evaluations forward problem

Definition at line 82 of file rdata.h.

**7.9.2.20 double\* am\_numrhsevalsSdata**

number of right hand side evaluations backward problem

Definition at line 84 of file rdata.h.

**7.9.2.21 double\* am\_orderdata**

employed order forward problem

Definition at line 86 of file rdata.h.

**7.9.2.22 double\* am\_llhdata**

likelihood value

Definition at line 89 of file rdata.h.

**7.9.2.23 double\* am\_chi2data**

chi2 value

Definition at line 91 of file rdata.h.

**7.9.2.24 double\* am\_sllhdata**

parameter derivative of likelihood

Definition at line 93 of file rdata.h.

**7.9.2.25 double\* am\_s2llhdata**

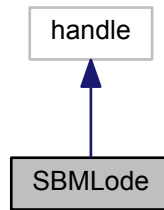
second order parameter derivative of likelihood

Definition at line 95 of file rdata.h.

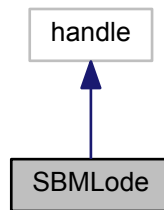
**7.10 SBMLode Class Reference**

SBMLMODEL provides an intermediate container between the SBML definition and an amimodel object.

Inheritance diagram for SBMLode:



Collaboration diagram for SBMLode:



### Public Member Functions

- `SBMLode` (matlabtypesubstitute filename)  
*`SBMLode` extracts information from an SBML definition and stores it in a symbolic format.*
- `noret::substitute writeAMICI` (matlabtypesubstitute filename, matlabtypesubstitute this, matlabtypesubstitute modelname)  
*`writeAMICI` writes the symbolic information from an `SBMLode` object into an AMICI model definition file*

### Public Attributes

- matlabtypesubstitute `state` = `sym.empty("")`  
*states*
- matlabtypesubstitute `observable` = `sym.empty("")`  
*observables*
- matlabtypesubstitute `observable_name` = `sym.empty("")`  
*names of observables*
- matlabtypesubstitute `param` = `sym.empty("")`  
*parameter names*
- matlabtypesubstitute `parameter` = `sym.empty("")`  
*parameter expressions*

- matlabtypesubstitute **constant** = sym.empty("")  
*constants*
- matlabtypesubstitute **reaction** = sym.empty("")  
*reactions*
- matlabtypesubstitute **compartment** = sym.empty("")  
*compartments*
- matlabtypesubstitute **volume** = sym.empty("")  
*compartment volumes*
- matlabtypesubstitute **initState** = sym.empty("")  
*initial condition of states*
- matlabtypesubstitute **condition** = sym.empty("")  
*condition*
- matlabtypesubstitute **flux** = sym.empty("")  
*reaction fluxes*
- matlabtypesubstitute **stoichiometry** = sym.empty("")  
*reaction stoichiometry*
- matlabtypesubstitute **xdot** = sym.empty("")  
*right hand side of reconstructed differential equation*
- matlabtypesubstitute **trigger** = sym.empty("")  
*event triggers*
- matlabtypesubstitute **bolus** = sym.empty("")  
*event boli*
- matlabtypesubstitute **funmath** = cell.empty("")  
*mathematical expressions for function*
- matlabtypesubstitute **funarg** = cell.empty("")
- matlabtypesubstitute **time\_symbol** = char.empty("")  
*symbol of time*
- matlabtypesubstitute **pnom** = double.empty("")  
*nominal parameters*
- matlabtypesubstitute **knom** = double.empty("")  
*nominal conditions*

### 7.10.1 Detailed Description

Definition at line 17 of file SBMLode.m.

### 7.10.2 Constructor & Destructor Documentation

#### 7.10.2.1 SBMLode ( matlabtypesubstitute *filename* )

Parameters

<i>filename</i>	target name of the model (excluding the suffix .xml/.sbml)
-----------------	--

Definition at line 193 of file SBMLode.m.

### 7.10.3 Member Function Documentation

#### 7.10.3.1 noret::substitute writeAMICI ( matlabtypesubstitute *filename*, matlabtypesubstitute *this*, matlabtypesubstitute *modelname* )

## Parameters

<i>modelName</i>	target name of the model ( <code>_syms.m</code> will be appended to the name )
------------------	--

Definition at line 18 of file `writeAMICI.m`.

## 7.10.4 Member Data Documentation

7.10.4.1 `state = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 28 of file `SBMLode.m`.

7.10.4.2 `observable = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 36 of file `SBMLode.m`.

7.10.4.3 `observable_name = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 44 of file `SBMLode.m`.

7.10.4.4 `param = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 52 of file `SBMLode.m`.

7.10.4.5 `parameter = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 60 of file `SBMLode.m`.

7.10.4.6 `constant = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 68 of file `SBMLode.m`.

7.10.4.7 `reaction = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 76 of file `SBMLode.m`.

7.10.4.8 `compartment = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 84 of file `SBMLode.m`.



7.10.4.9 `volume = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 92 of file SBMLode.m.

7.10.4.10 `initState = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 100 of file SBMLode.m.

7.10.4.11 `condition = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 108 of file SBMLode.m.

7.10.4.12 `flux = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 116 of file SBMLode.m.

7.10.4.13 `stoichiometry = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 124 of file SBMLode.m.

7.10.4.14 `xdot = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 132 of file SBMLode.m.

7.10.4.15 `trigger = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 140 of file SBMLode.m.

7.10.4.16 `bolus = sym.empty("")`

**Default:** `sym.empty("")`

Definition at line 148 of file SBMLode.m.

7.10.4.17 `funmath = cell.empty("")`

**Default:** `cell.empty("")`

Definition at line 156 of file SBMLode.m.

7.10.4.18 `time_symbol = char.empty("")`

**Default:** `char.empty("")`

Definition at line 166 of file SBMLode.m.

7.10.4.19 `pnom = double.empty("")`

**Default:** `double.empty("")`

Definition at line 174 of file SBMLode.m.

7.10.4.20 `knom = double.empty("")`

**Default:** `double.empty("")`

Definition at line 182 of file SBMLode.m.

## 7.11 TempData Struct Reference

struct that provides temporary storage for different variables

```
#include <tdata.h>
```

### Public Attributes

- realtype [am\\_t](#)
- N\_Vector [am\\_x](#)
- N\_Vector [am\\_x\\_old](#)
- N\_Vector \* [am\\_x\\_disc](#)
- N\_Vector \* [am\\_xdot\\_disc](#)
- N\_Vector \* [am\\_xdot\\_old\\_disc](#)
- N\_Vector [am\\_dx](#)
- N\_Vector [am\\_dx\\_old](#)
- N\_Vector [am\\_xdot](#)
- N\_Vector [am\\_xdot\\_old](#)
- N\_Vector [am\\_xB](#)
- N\_Vector [am\\_xB\\_old](#)
- N\_Vector [am\\_dxB](#)
- N\_Vector [am\\_xQB](#)
- N\_Vector [am\\_xQB\\_old](#)
- N\_Vector \* [am\\_sx](#)
- N\_Vector \* [am\\_sdx](#)
- N\_Vector [am\\_id](#)
- DisMat [am\\_Jtmp](#)
- realtype \* [am\\_llhS0](#)
- realtype [am\\_g](#)
- realtype \* [am\\_dgdp](#)
- realtype \* [am\\_dgdx](#)
- realtype [am\\_r](#)
- realtype \* [am\\_drdp](#)
- realtype \* [am\\_drdx](#)
- realtype [am\\_rval](#)
- realtype \* [am\\_drvaldp](#)

- realtype \* [am\\_drvaldx](#)
- realtype \* [am\\_dzdx](#)
- realtype \* [am\\_dzdp](#)
- realtype \* [am\\_dydp](#)
- realtype \* [am\\_dydx](#)
- realtype \* [am\\_yS0](#)
- realtype \* [am\\_sigma\\_y](#)
- realtype \* [am\\_dsigma\\_ydp](#)
- realtype \* [am\\_sigma\\_z](#)
- realtype \* [am\\_dsigma\\_zdp](#)
- realtype \* [am\\_x\\_tmp](#)
- realtype \* [am\\_sx\\_tmp](#)
- realtype \* [am\\_dx\\_tmp](#)
- realtype \* [am\\_sdx\\_tmp](#)
- realtype \* [am\\_xdot\\_tmp](#)
- realtype \* [am\\_xB\\_tmp](#)
- realtype \* [am\\_xQB\\_tmp](#)
- realtype \* [am\\_dxB\\_tmp](#)
- realtype \* [am\\_id\\_tmp](#)
- int \* [am\\_rootsfound](#)
- int \* [am\\_rootidx](#)
- int \* [am\\_nroots](#)
- double \* [am\\_rootvals](#)
- realtype \* [am\\_deltax](#)
- realtype \* [am\\_deltasx](#)
- realtype \* [am\\_deltaxB](#)
- realtype \* [am\\_deltaqB](#)
- int [am\\_which](#)
- realtype \* [am\\_discs](#)
- realtype \* [am\\_irdiscs](#)

### 7.11.1 Detailed Description

Definition at line 78 of file tdata.h.

### 7.11.2 Member Data Documentation

#### 7.11.2.1 realtype am\_t

current time

Definition at line 80 of file tdata.h.

#### 7.11.2.2 N\_Vector am\_x

state vector

Definition at line 84 of file tdata.h.

#### 7.11.2.3 N\_Vector am\_x\_old

old state vector

Definition at line 86 of file tdata.h.

**7.11.2.4 N\_Vector\* am\_x\_disc**

array of state vectors at discontinuities

Definition at line 88 of file tdata.h.

**7.11.2.5 N\_Vector\* am\_xdot\_disc**

array of differential state vectors at discontinuities

Definition at line 90 of file tdata.h.

**7.11.2.6 N\_Vector\* am\_xdot\_old\_disc**

array of old differential state vectors at discontinuities

Definition at line 92 of file tdata.h.

**7.11.2.7 N\_Vector am\_dx**

differential state vector

Definition at line 94 of file tdata.h.

**7.11.2.8 N\_Vector am\_dx\_old**

old differential state vector

Definition at line 96 of file tdata.h.

**7.11.2.9 N\_Vector am\_xdot**

time derivative state vector

Definition at line 98 of file tdata.h.

**7.11.2.10 N\_Vector am\_xdot\_old**

old time derivative state vector

Definition at line 100 of file tdata.h.

**7.11.2.11 N\_Vector am\_xB**

adjoint state vector

Definition at line 102 of file tdata.h.

**7.11.2.12 N\_Vector am\_xB\_old**

old adjoint state vector

Definition at line 104 of file tdata.h.

**7.11.2.13 N\_Vector am\_dxB**

differential adjoint state vector

Definition at line 106 of file tdata.h.

**7.11.2.14 N\_Vector am\_xQB**

quadrature state vector

Definition at line 108 of file tdata.h.

**7.11.2.15 N\_Vector am\_xQB\_old**

old quadrature state vector

Definition at line 110 of file tdata.h.

**7.11.2.16 N\_Vector\* am\_sx**

sensitivity state vector array

Definition at line 112 of file tdata.h.

**7.11.2.17 N\_Vector\* am\_sdx**

differential sensitivity state vector array

Definition at line 114 of file tdata.h.

**7.11.2.18 N\_Vector am\_id**

index indicating DAE equations vector

Definition at line 116 of file tdata.h.

**7.11.2.19 DisMat am\_Jtmp**

Jacobian

Definition at line 118 of file tdata.h.

**7.11.2.20 realtype\* am\_llhS0**

parameter derivative of likelihood array

Definition at line 121 of file tdata.h.

**7.11.2.21 realtype am\_g**

data likelihood

Definition at line 123 of file tdata.h.

**7.11.2.22 realtype\* am\_dgdp**

parameter derivative of data likelihood

Definition at line 125 of file tdata.h.

**7.11.2.23 realtype\* am\_dgdx**

state derivative of data likelihood

Definition at line 127 of file tdata.h.

**7.11.2.24 realtype am\_r**

event likelihood

Definition at line 129 of file tdata.h.

**7.11.2.25 realtype\* am\_drdp**

parameter derivative of event likelihood

Definition at line 131 of file tdata.h.

**7.11.2.26 realtype\* am\_drdx**

state derivative of event likelihood

Definition at line 133 of file tdata.h.

**7.11.2.27 realtype am\_rval**

root function likelihood

Definition at line 135 of file tdata.h.

**7.11.2.28 realtype\* am\_drvaldp**

parameter derivative of root function likelihood

Definition at line 137 of file tdata.h.

**7.11.2.29 realtype\* am\_drvaldx**

state derivative of root function likelihood

Definition at line 139 of file tdata.h.

**7.11.2.30 realtype\* am\_dzdx**

state derivative of event

Definition at line 141 of file tdata.h.

**7.11.2.31 realtype\* am\_dzdp**

parameter derivative of event

Definition at line 143 of file tdata.h.

**7.11.2.32 realtype\* am\_dydp**

parameter derivative of observable

Definition at line 145 of file tdata.h.

**7.11.2.33 realtype\* am\_dydx**

state derivative of observable

Definition at line 147 of file tdata.h.

**7.11.2.34 realtype\* am\_yS0**

initial sensitivity of observable

Definition at line 149 of file tdata.h.

**7.11.2.35 realtype\* am\_sigma\_y**

data standard deviation

Definition at line 151 of file tdata.h.

**7.11.2.36 realtype\* am\_dsigma\_ydp**

parameter derivative of data standard deviation

Definition at line 153 of file tdata.h.

**7.11.2.37 realtype\* am\_sigma\_z**

event standard deviation

Definition at line 155 of file tdata.h.

**7.11.2.38 realtype\* am\_dsigma\_zdp**

parameter derivative of event standard deviation

Definition at line 157 of file tdata.h.

**7.11.2.39 realtype\* am\_x\_tmp**

state array

Definition at line 160 of file tdata.h.

**7.11.2.40 realtype\* am\_sx\_tmp**

sensitivity state array

Definition at line 162 of file tdata.h.

**7.11.2.41 realtype\* am\_dx\_tmp**

differential state array

Definition at line 164 of file tdata.h.

**7.11.2.42 realtype\* am\_sdx\_tmp**

differential sensitivity state array

Definition at line 166 of file tdata.h.

**7.11.2.43 realtype\* am\_xdot\_tmp**

time derivative state array

Definition at line 168 of file tdata.h.

**7.11.2.44 realtype\* am\_xB\_tmp**

differential adjoint state array

Definition at line 170 of file tdata.h.

**7.11.2.45 realtype\* am\_xQB\_tmp**

quadrature state array

Definition at line 172 of file tdata.h.

**7.11.2.46 realtype\* am\_dxB\_tmp**

differential adjoint state array

Definition at line 174 of file tdata.h.

**7.11.2.47 realtype\* am\_id\_tmp**

index indicating DAE equations array

Definition at line 176 of file tdata.h.

**7.11.2.48 int\* am\_rootsfound**

array of flags indicating which root has been found

array of length nr with the indices of the user functions gi found to have a root. For  $i = 0, \dots, nr-1$ , rootsfound[i] = 0 if gi has a root, and = 1 if not.

Definition at line 183 of file tdata.h.

**7.11.2.49 int\* am\_rootidx**

array of index which root has been found

Definition at line 185 of file tdata.h.

**7.11.2.50 int\* am\_nroots**

array of number of found roots for a certain event type

Definition at line 187 of file tdata.h.

**7.11.2.51 double\* am\_rootvals**

array of values of the root function

Definition at line 189 of file tdata.h.

**7.11.2.52 realtype\* am\_deltax**

change in x

Definition at line 193 of file tdata.h.

**7.11.2.53 realtype\* am\_deltasx**

change in sx

Definition at line 195 of file tdata.h.

**7.11.2.54 realtype\* am\_deltaxB**

change in xB

Definition at line 197 of file tdata.h.

**7.11.2.55 realtype\* am\_deltaqB**

change in qB

Definition at line 199 of file tdata.h.

**7.11.2.56 int am\_which**

integer for indexing of backwards problems

Definition at line 203 of file tdata.h.

**7.11.2.57 realtype\* am\_discs**

array containing the time-points of discontinuities

Definition at line 206 of file tdata.h.

**7.11.2.58 realtype\* am\_irdiscs**

array containing the index of discontinuities



Definition at line 208 of file tdata.h.

## 7.12 UserData Struct Reference

struct that stores all user provided data

```
#include <udata.h>
```

### Public Attributes

- double \* [am\\_qpositivex](#)
- int \* [am\\_plist](#)
- int [am\\_np](#)
- int [am\\_ny](#)
- int [am\\_nytrue](#)
- int [am\\_nx](#)
- int [am\\_nz](#)
- int [am\\_nztrue](#)
- int [am\\_ne](#)
- int [am\\_nt](#)
- int [am\\_nw](#)
- int [am\\_ndwdx](#)
- int [am\\_ndwdp](#)
- int [am\\_nnz](#)
- int [am\\_nmaxevent](#)
- double \* [am\\_p](#)
- double \* [am\\_k](#)
- double [am\\_tstart](#)
- double \* [am\\_ts](#)
- double \* [am\\_pbar](#)
- double \* [am\\_xbar](#)
- double \* [am\\_idlist](#)
- int [am\\_sensi](#)
- double [am\\_atol](#)
- double [am\\_rtol](#)
- int [am\\_maxsteps](#)
- int [am\\_ism](#)
- int [am\\_sensi\\_meth](#)
- int [am\\_linsol](#)
- int [am\\_interpType](#)
- int [am\\_lmm](#)
- int [am\\_iter](#)
- boolean\_t [am\\_stldet](#)
- int [am\\_ubw](#)
- int [am\\_lbw](#)
- boolean\_t [am\\_bsx0](#)
- double \* [am\\_sx0data](#)
- int [am\\_event\\_model](#)
- int [am\\_ordering](#)
- double \* [am\\_z2event](#)
- double \* [am\\_h](#)
- SlsMat [am\\_J](#)
- realtype \* [am\\_dxdotdp](#)
- realtype \* [am\\_w](#)

- realtype \* [am\\_dwdx](#)
- realtype \* [am\\_dwdp](#)
- realtype \* [am\\_M](#)
- realtype \* [am\\_dfdx](#)
- booleantype [am\\_nan\\_dxdotdp](#)
- booleantype [am\\_nan\\_J](#)
- booleantype [am\\_nan\\_JSparse](#)
- booleantype [am\\_nan\\_xdot](#)
- booleantype [am\\_nan\\_xBdot](#)
- booleantype [am\\_nan\\_qBdot](#)

### 7.12.1 Detailed Description

Definition at line 77 of file `udata.h`.

### 7.12.2 Member Data Documentation

#### 7.12.2.1 `double* am_qpositivex`

positivity flag

Definition at line 79 of file `udata.h`.

#### 7.12.2.2 `int* am_plist`

parameter reordering

Definition at line 82 of file `udata.h`.

#### 7.12.2.3 `int am_np`

number of parameters

Definition at line 84 of file `udata.h`.

#### 7.12.2.4 `int am_ny`

number of observables

Definition at line 86 of file `udata.h`.

#### 7.12.2.5 `int am_nytrue`

number of observables in the unaugmented system

Definition at line 88 of file `udata.h`.

#### 7.12.2.6 `int am_nx`

number of states

Definition at line 90 of file `udata.h`.

#### 7.12.2.7 `int am_nz`

number of event outputs

Definition at line 92 of file `udata.h`.

#### 7.12.2.8 `int am_nztrue`

number of event outputs in the unaugmented system

Definition at line 94 of file udata.h.

#### 7.12.2.9 int am\_ne

number of events

Definition at line 96 of file udata.h.

#### 7.12.2.10 int am\_nt

number of timepoints

Definition at line 98 of file udata.h.

#### 7.12.2.11 int am\_nw

number of common expressions

Definition at line 100 of file udata.h.

#### 7.12.2.12 int am\_ndwdx

number of derivatives of common expressions wrt x

Definition at line 102 of file udata.h.

#### 7.12.2.13 int am\_ndwdp

number of derivatives of common expressions wrt p

Definition at line 104 of file udata.h.

#### 7.12.2.14 int am\_nnz

number of nonzero entries in jacobian

Definition at line 106 of file udata.h.

#### 7.12.2.15 int am\_nmaxevent

maximal number of events to track

Definition at line 108 of file udata.h.

#### 7.12.2.16 double\* am\_p

parameter array

Definition at line 111 of file udata.h.

#### 7.12.2.17 double\* am\_k

constants array

Definition at line 113 of file udata.h.

#### 7.12.2.18 double am\_tstart

starting time

Definition at line 116 of file udata.h.

#### 7.12.2.19 double\* am\_ts

timepoints

Definition at line 118 of file udata.h.

**7.12.2.20 double\* am\_pbar**

scaling of parameters

Definition at line 121 of file udata.h.

**7.12.2.21 double\* am\_xbar**

scaling of states

Definition at line 123 of file udata.h.

**7.12.2.22 double\* am\_idlist**

flag array for DAE equations

Definition at line 126 of file udata.h.

**7.12.2.23 int am\_sensi**

flag indicating whether sensitivities are supposed to be computed

Definition at line 129 of file udata.h.

**7.12.2.24 double am\_atol**

absolute tolerances for integration

Definition at line 131 of file udata.h.

**7.12.2.25 double am\_rtol**

relative tolerances for integration

Definition at line 133 of file udata.h.

**7.12.2.26 int am\_maxsteps**

maximum number of allowed integration steps

Definition at line 135 of file udata.h.

**7.12.2.27 int am\_ism**

internal sensitivity method

a flag used to select the sensitivity solution method. Its value can be CV SIMULTANEOUS or CV STAGGERED. Only applies for Forward Sensitivities.

Definition at line 141 of file udata.h.

**7.12.2.28 int am\_sensi\_meth**

method for sensitivity computation

CW\_FSA for forward sensitivity analysis, CW\_ASA for adjoint sensitivity analysis

Definition at line 147 of file udata.h.

**7.12.2.29 int am\_linsol**

linear solver specification

Definition at line 149 of file udata.h.

**7.12.2.30 int am\_interpType**

interpolation type

specifies the interpolation type for the forward problem solution which is then used for the backwards problem. can be either CV\_POLYNOMIAL or CV\_HERMITE

Definition at line 154 of file udata.h.

**7.12.2.31 int am\_lmm**

linear multistep method

specifies the linear multistep method and may be one of two possible values: CV\_ADAMS or CV\_BDF.

Definition at line 160 of file udata.h.

**7.12.2.32 int am\_iter**

nonlinear solver

specifies the type of nonlinear solver iteration and may be either CV\_NEWTON or CV\_FUNCTIONAL.

Definition at line 166 of file udata.h.

**7.12.2.33 boolean\_t am\_stldet**

flag controlling stability limit detection

Definition at line 169 of file udata.h.

**7.12.2.34 int am\_ubw**

upper bandwidth of the jacobian

Definition at line 172 of file udata.h.

**7.12.2.35 int am\_lbw**

lower bandwidth of the jacobian

Definition at line 174 of file udata.h.

**7.12.2.36 boolean\_t am\_bsx0**

flag for sensitivity initialisation

flag which determines whether analytic sensitivities initialisation or provided initialisation should be used

Definition at line 180 of file udata.h.

**7.12.2.37 double\* am\_sx0data**

sensitivity initialisation

Definition at line 183 of file udata.h.

**7.12.2.38 int am\_event\_model**

error model for events

Definition at line 186 of file udata.h.

**7.12.2.39 int am\_ordering**

state ordering

Definition at line 189 of file udata.h.

**7.12.2.40 double\* am\_z2event**

index indicating to which event an event output belongs

Definition at line 192 of file udata.h.

**7.12.2.41 double\* am\_h**

flag indicating whether a certain heaviside function should be active or not

Definition at line 195 of file udata.h.

**7.12.2.42 SlsMat am\_J**

tempory storage of Jacobian data across functions

Definition at line 198 of file udata.h.

**7.12.2.43 realtype\* am\_dxdotdp**

tempory storage of dxdotdp data across functions

Definition at line 200 of file udata.h.

**7.12.2.44 realtype\* am\_w**

tempory storage of w data across functions

Definition at line 202 of file udata.h.

**7.12.2.45 realtype\* am\_dwdx**

tempory storage of dwdx data across functions

Definition at line 204 of file udata.h.

**7.12.2.46 realtype\* am\_dwdp**

tempory storage of dwdp data across functions

Definition at line 206 of file udata.h.

**7.12.2.47 realtype\* am\_M**

tempory storage of M data across functions

Definition at line 208 of file udata.h.

**7.12.2.48 realtype\* am\_dfdx**

tempory storage of dfdx data across functions

Definition at line 210 of file udata.h.

**7.12.2.49 booleantype am\_nan\_dxdotdp**

flag indicating whether a NaN in dxdotdp has been reported

Definition at line 213 of file udata.h.

**7.12.2.50 booleantype am\_nan\_J**

flag indicating whether a NaN in J has been reported

Definition at line 215 of file udata.h.

**7.12.2.51** `boolean`type `am_nan_JSparse`

flag indicating whether a NaN in JSparse has been reported

Definition at line 217 of file `udata.h`.

**7.12.2.52** `boolean`type `am_nan_xdot`

flag indicating whether a NaN in xdot has been reported

Definition at line 219 of file `udata.h`.

**7.12.2.53** `boolean`type `am_nan_xBdot`

flag indicating whether a NaN in xBdot has been reported

Definition at line 221 of file `udata.h`.

**7.12.2.54** `boolean`type `am_nan_qBdot`

flag indicating whether a NaN in qBdot has been reported

Definition at line 223 of file `udata.h`.

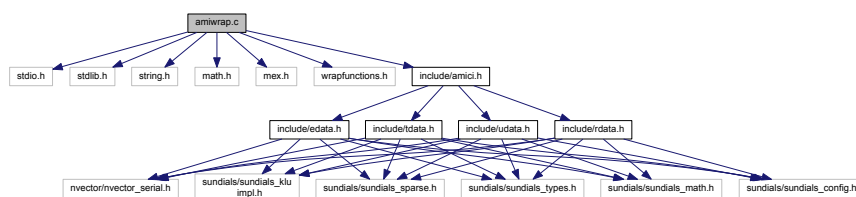
## 8 File Documentation

### 8.1 `amiwrap.c` File Reference

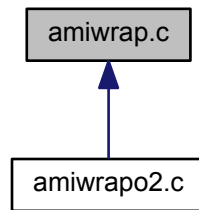
core routines for mex interface

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>
#include <mex.h>
#include "wrapfunctions.h"
#include <include/amici.h>
```

Include dependency graph for `amiwrap.c`:



This graph shows which files directly or indirectly include this file:



#### Macros

- `#define _USE_MATH_DEFINES` /\* MS definition of PI and other constants \*/
- `#define M_PI` 3.14159265358979323846

#### Functions

- void `mexFunction` (int *nlhs*, mxArray \**plhs*[], int *nrhs*, const mxArray \**prhs*[])

##### 8.1.1 Detailed Description

This file defines the fuction `mexFunction` which is executed upon calling the mex file from matlab

##### 8.1.2 Function Documentation

###### 8.1.2.1 void `mexFunction` ( int *nlhs*, mxArray \* *plhs*[], int *nrhs*, const mxArray \* *prhs*[] )

`mexFunction` is the main function of the mex simulation file this function carries out all numerical integration and writes results into the sol struct.

#### Parameters

in	<i>nlhs</i>	number of output arguments of the matlab call <b>Type:</b> int
out	<i>plhs</i>	pointer to the array of output arguments <b>Type:</b> mxArray
in	<i>nrhs</i>	number of input arguments of the matlab call <b>Type:</b> int
in	<i>prhs</i>	pointer to the array of input arguments <b>Type:</b> mxArray

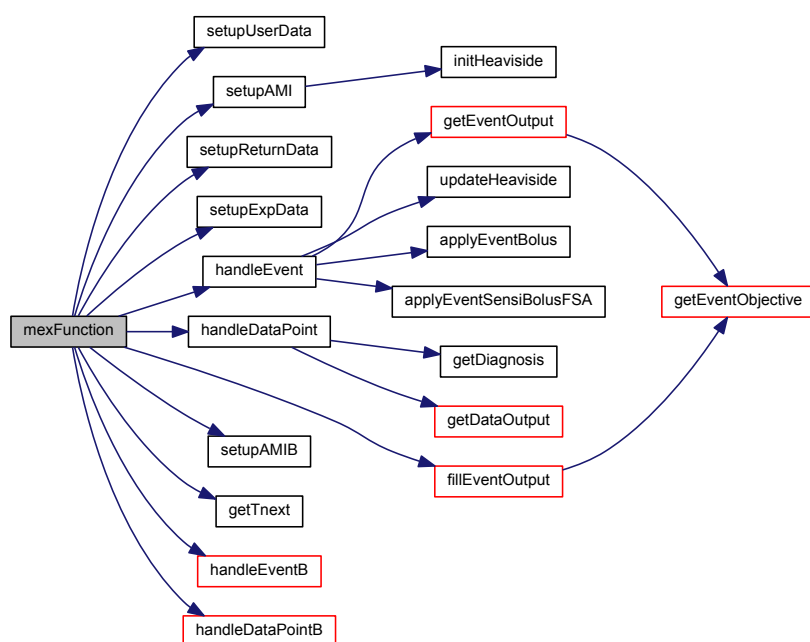
#### Returns

void

Definition at line 29 of file `amiwrap.c`.



Here is the call graph for this function:



## 8.2 amiwrap.m File Reference

AMIWRAP generates c mex files for the simulation of systems of differential equations via CVODES and IDAS.

### Functions

- `noret::substitute` [amiwrap](#) (`matlabtypesubstitute varargin`)

*AMIWRAP generates c mex files for the simulation of systems of differential equations via CVODES and IDAS.*

### 8.2.1 Function Documentation

### 8.2.1.1 noret::substitute amiwrap ( matlabtypesubstitute *varargin* )

#### Parameters

<i>varargin</i>	<pre>1 amiwrap ( modelname, symfun, tdir, o2flag )</pre> <p><i>Required Parameters for varargin:</i></p> <ul style="list-style-type: none"> <li>• modelname specifies the name of the model which will be later used for the naming of the simulation file</li> <li>• symfun specifies a function which executes model definition see <a href="#">Model Definition</a> for details</li> <li>• tdir target directory where the simulation file should be placed <b>Default:</b> \$AMI-CIDIR/models/modelname</li> <li>• o2flag boolean whether second order sensitivities should be enabled <b>Default:</b> false</li> </ul>
-----------------	---

#### Return values

<i>o2flag</i>	void
---------------	------

Definition at line 17 of file amiwrap.m.

## 8.3 SBML2AMICI.m File Reference

SBML2AMICI generates AMICI model definition files from SBML.

#### Functions

- noret::substitute [SBML2AMICI](#) (matlabtypesubstitute filename, matlabtypesubstitute modelname)  
*SBML2AMICI generates AMICI model definition files from SBML.*

### 8.3.1 Function Documentation

#### 8.3.1.1 noret::substitute SBML2AMICI ( matlabtypesubstitute *filename*, matlabtypesubstitute *modelname* )

#### Parameters

<i>filename</i>	name of the SBML file (withouth extension)
<i>modelname</i>	name of the model, this will define the name of the output file

#### Return values

<i>modelname</i>	void
------------------	------

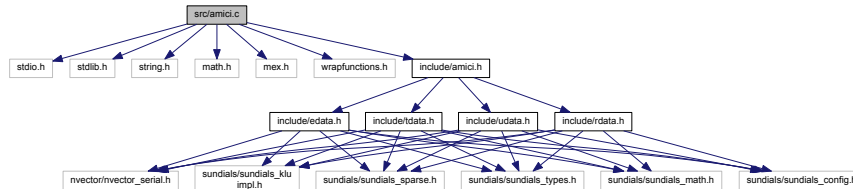
Definition at line 17 of file SBML2AMICI.m.

## 8.4 src/amici.c File Reference

core routines for integration

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <math.h>
#include <mex.h>
#include "wrapfunctions.h"
#include <include/amici.h>
```

Include dependency graph for amici.c:



## Macros

- `#define _USE_MATH_DEFINES` /\* MS definition of PI and other constants \*/
- `#define M_PI` 3.14159265358979323846
- `#define initField2(FIELD, D1, D2)`
- `#define initField3(FIELD, D1, D2, D3)`
- `#define readOptionScalar(OPTION, TYPE)`
- `#define readOptionData(OPTION)`
- `#define AMI_SUCCESS` 0

## Functions

- `UserData` `setupUserData` (const mxArray \*prhs[])
- `ReturnData` `setupReturnData` (mxArray \*plhs[], void \*user\_data, double \*pstatus)
- `ExpData` `setupExpData` (const mxArray \*prhs[], void \*user\_data)
- void \* `setupAMI` (int \*status, void \*user\_data, void \*temp\_data)
- void `setupAMIB` (int \*status, void \*ami\_mem, void \*user\_data, void \*temp\_data)
- void `getDataSensisFSA` (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getDataSensisASA` (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getDataOutput` (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getEventSensisFSA` (int \*status, int ie, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*temp\_data)
- void `getEventSensisFSA_tf` (int \*status, int ie, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*temp\_data)
- void `getEventSensisASA` (int \*status, int ie, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getEventSigma` (int \*status, int ie, int iz, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getEventObjective` (int \*status, int ie, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `getEventOutput` (int \*status, realtype \*tlastroot, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void `fillEventOutput` (int \*status, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)

- void [handleDataPoint](#) (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void [handleDataPointB](#) (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*temp\_data)
- void [handleEvent](#) (int \*status, int iroot, realtype \*tlastroot, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*exp\_data, void \*temp\_data)
- void [handleEventB](#) (int \*status, int iroot, void \*ami\_mem, void \*user\_data, void \*temp\_data)
- realtype [getTnext](#) (realtype \*troot, int iroot, realtype \*tdata, int it, void \*user\_data)
- void [applyEventBolus](#) (int \*status, void \*ami\_mem, void \*user\_data, void \*temp\_data)
- void [applyEventSensiBolusFSA](#) (int \*status, void \*ami\_mem, void \*user\_data, void \*temp\_data)
- void [initHeaviside](#) (int \*status, void \*user\_data, void \*temp\_data)
- void [updateHeaviside](#) (int \*status, void \*user\_data, void \*temp\_data)
- void [updateHeavisideB](#) (int \*status, int iroot, void \*user\_data, void \*temp\_data)
- void [getDiagnosis](#) (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data)
- void [getDiagnosisB](#) (int \*status, int it, void \*ami\_mem, void \*user\_data, void \*return\_data, void \*temp\_data)

### 8.4.1 Macro Definition Documentation

#### 8.4.1.1 #define initField2( FIELD, D1, D2 )

**Value:**

```
mxArray *mx ## FIELD; \
mx ## FIELD = mxCreateDoubleMatrix(D1,D2,mxREAL); \
FIELD ## data = mxGetPr(mx ## FIELD); \
mxSetField(mxsol,0,#FIELD,mx ## FIELD)
```

@ brief initialise matrix and attach to the field @ param FIELD name of the field to which the matrix will be attached  
@ param D1 number of rows in the matrix @ param D2 number of columns in the matrix

Definition at line 25 of file amici.c.

#### 8.4.1.2 #define initField3( FIELD, D1, D2, D3 )

**Value:**

```
mxArray *mx ## FIELD; \
const mwSize dims ## FIELD[]={D1,D2,D3}; \
mx ## FIELD = mxCreateNumericArray(3,dims ## FIELD,mxDOUBLE_CLASS,mxREAL); \
FIELD ## data = mxGetPr(mx ## FIELD); \
mxSetField(mxsol,0,#FIELD,mx ## FIELD)
```

@ brief initialise tensor and attach to the field @ param FIELD name of the field to which the tensor will be attached  
@ param D1 number of rows in the tensor @ param D2 number of columns in the tensor @ param D3 number of elements in the third dimension of the tensor

Definition at line 38 of file amici.c.

#### 8.4.1.3 #define readOptionScalar( OPTION, TYPE )

**Value:**

```
if(mxGetProperty(prhs[3],0,#OPTION)){ \
    OPTION = (TYPE)mxGetScalar(mxGetProperty(prhs[3],0,#OPTION)); \
} else { \
    mexWarnMsgIdAndTxt("AMICI:mex:OPTION","Provided options are not of class amioption!"); \
    return(NULL); \
}
```

@ brief extract information from a property of a matlab class (scalar) @ param OPTION name of the property @ param TYPE class to which the information should be cast

Definition at line 50 of file amici.c.

8.4.1.4 #define readOptionData( *OPTION* )**Value:**

```

if (mxGetProperty(prhs[3], 0, #OPTION)) { \
    OPTION = mxGetData(mxGetProperty(prhs[3], 0, #OPTION)); \
} else { \
    mexWarnMsgIdAndTxt("AMICI:mex:OPTION", "Provided options are not of class amioption!"); \
    return(NULL); \
}

```

@ brief extract information from a property of a matlab class (matrix) @ param *OPTION* name of the property  
 Definition at line 62 of file amici.c.

## 8.4.1.5 #define AMI\_SUCCESS 0

return value for successful execution

Definition at line 71 of file amici.c.

## 8.4.2 Function Documentation

8.4.2.1 UserData setupUserData ( const mxArray \* *prhs*[ ] )

setupUserData extracts information from the matlab call and returns the corresponding [UserData](#) struct

**Parameters**

<i>in</i>	<i>prhs</i>	pointer to the array of input arguments <b>Type:</b> mxArray
-----------	-------------	---

**Returns**

udata: struct containing all provided user data

**Type:** [UserData](#)

Definition at line 73 of file amici.c.

Here is the caller graph for this function:

8.4.2.2 ReturnData setupReturnData ( mxArray \* *plhs*[ ], void \* *user\_data*, double \* *pstatus* )

setupReturnData initialises the return data struct

**Parameters**

in	<i>plhs</i>	user input <b>Type:</b> mxArray
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>pstatus</i>	pointer to the flag indicating the execution status <b>Type:</b> double

**Returns**

rdata: return data struct  
**Type:** [ReturnData](#)

user udata

Definition at line 217 of file amici.c.

Here is the caller graph for this function:



#### 8.4.2.3 ExpData setupExpData ( const mxArray \* *prhs*[], void \* *user\_data* )

setupExpData initialises the experimental data struct

**Parameters**

in	<i>prhs</i>	user input <b>Type:</b> *mxArray
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>

**Returns**

edata: experimental data struct  
**Type:** [ExpData](#)

user udata

Definition at line 315 of file amici.c.

Here is the caller graph for this function:



8.4.2.4 void\* setupAMI ( int \* *status*, void \* *user\_data*, void \* *temp\_data* )

setupAMIs initialises the ami memory object

**Parameters**

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
in	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

ami\_mem pointer to the cvodes/idas memory block

Definition at line 422 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 8.4.2.5 void setupAMIB ( int \* *status*, void \* *ami\_mem*, void \* *user\_data*, void \* *temp\_data* )

setupAMIB initialises the AMI memory object for the backwards problem

**Parameters**

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ami_mem</i>	pointer to the solver memory object of the forward problem
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
in	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

ami\_mem pointer to the cvodes/idas memory block for the backward problem

Definition at line 742 of file amici.c.



Here is the caller graph for this function:



**8.4.2.6** void `getDataSensisFSA` ( int \* *status*, int *it*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`getDataSensisFSA` extracts data information for forward sensitivity analysis

#### Parameters

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	index of current timepoint <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

void

Definition at line 937 of file amici.c.

Here is the caller graph for this function:



**8.4.2.7** void `getDataSensisASA` ( int \* *status*, int *it*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`getDataSensisASA` extracts data information for adjoint sensitivity analysis

**Parameters**

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	index of current timepoint <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 999 of file amici.c.

Here is the caller graph for this function:



**8.4.2.8** void `getDataOutput` ( int \* *status*, int *it*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

getDataOutput extracts output information for data-points

**Parameters**

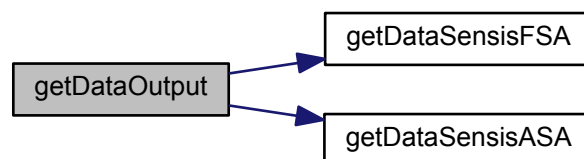
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	index of current timepoint <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

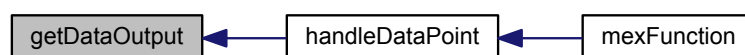
void

Definition at line 1050 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.9** `void getEventSensisFSA ( int * status, int ie, void * ami_mem, void * user_data, void * return_data, void * temp_data )`

`getEventSensisFSA` extracts event information for forward sensitivity analysis

#### Parameters

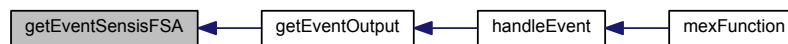
out	<i>status</i>	flag indicating success of execution <b>Type:</b> int
in	<i>ie</i>	index of event type <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1105 of file amici.c.

Here is the caller graph for this function:



**8.4.2.10** void `getEventSensisFSA_tf` ( int \* *status*, int *ie*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *temp\_data* )

`getEventSensisFSA_tf` extracts event information for forward sensitivity analysis for events that happen at the end of the considered interval

**Parameters**

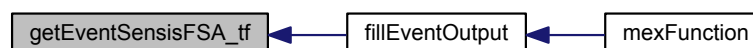
out	<i>status</i>	flag indicating success of execution <b>Type:</b> int
in	<i>ie</i>	index of event type <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1135 of file amici.c.

Here is the caller graph for this function:



**8.4.2.11** void `getEventSensisASA` ( int \* *status*, int *ie*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`getEventSensisASA` extracts event information for adjoint sensitivity analysis

## Parameters

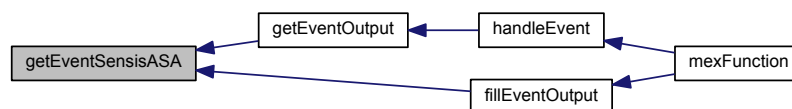
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ie</i>	index of event type <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

## Returns

void

Definition at line 1166 of file amici.c.

Here is the caller graph for this function:



**8.4.2.12** void `getEventSigma` ( int \* *status*, int *ie*, int *iz*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`getEventSigma` extracts fills `sigma_z` either from the user defined function or from user input

## Parameters

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ie</i>	event type index <b>Type:</b> int
in	<i>iz</i>	event output index <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>

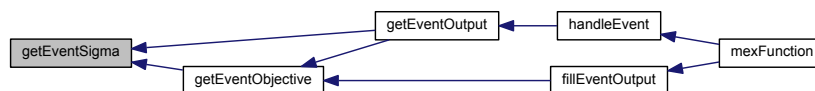
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1236 of file amici.c.

Here is the caller graph for this function:



**8.4.2.13** void `getEventObjective` ( int \* *status*, int *ie*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

getEventObjective updates the objective function on the occurrence of an event

**Parameters**

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ie</i>	event type index <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

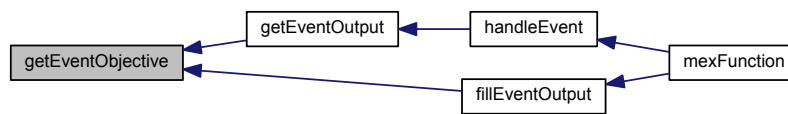
void

Definition at line 1275 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.14** `void getEventOutput ( int * status, realtype * tlastroot, void * ami_mem, void * user_data, void * return_data, void * exp_data, void * temp_data )`

`getEventOutput` extracts output information for events

#### Parameters

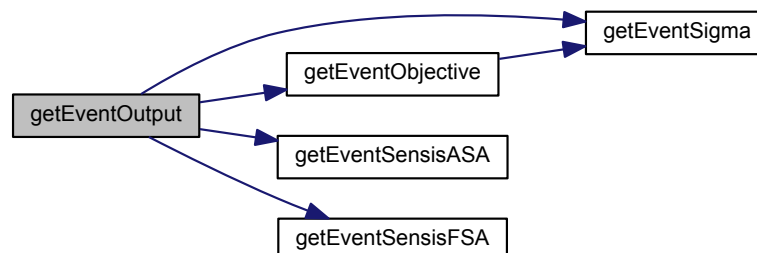
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>tlastroot</i>	timepoint of last occurred event <b>Type:</b> *realtype
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

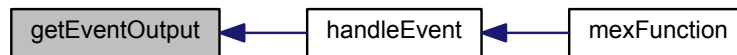
void

Definition at line 1317 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.15** void fillEventOutput ( int \* *status*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

fillEventOutput fills missing roots at last timepoint

#### Parameters

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

void

Definition at line 1387 of file amici.c.

Here is the call graph for this function:





Here is the caller graph for this function:



**8.4.2.16** void `handleDataPoint` ( int \* *status*, int *it*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`handleDataPoint` executes everything necessary for the handling of data points

#### Parameters

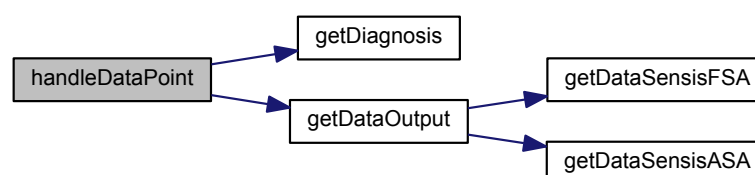
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	index of data point <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

void

Definition at line 1439 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.17** `void handleDataPointB ( int * status, int it, void * ami_mem, void * user_data, void * return_data, void * temp_data )`

handleDataPoint executes everything necessary for the handling of data points for the backward problems

#### Parameters

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	index of data point <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

void

Definition at line 1494 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.18** void `handleEvent` ( int \* *status*, int *iroot*, realtype \* *tlastroot*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *exp\_data*, void \* *temp\_data* )

`handleEvent` executes everything necessary for the handling of events

#### Parameters

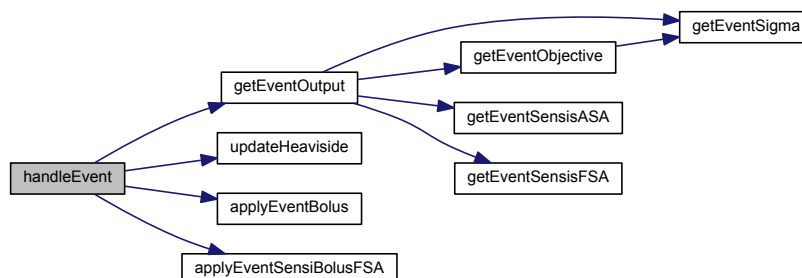
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
out	<i>iroot</i>	index of event <b>Type:</b> int
out	<i>tlastroot</i>	pointer to the timepoint of the last event <b>Type:</b> *realtype
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
in	<i>exp_data</i>	pointer to the experimental data struct <b>Type:</b> <a href="#">ExpData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

void

Definition at line 1525 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.4.2.19** void `handleEventB` ( int \* *status*, int *iroot*, void \* *ami\_mem*, void \* *user\_data*, void \* *temp\_data* )

`handleEventB` executes everything necessary for the handling of events for the backward problem

#### Parameters

out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
out	<i>iroot</i>	index of event <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

#### Returns

cv\_status updated status flag  
**Type:** int

Definition at line 1626 of file amici.c.

Here is the call graph for this function:



Here is the caller graph for this function:



#### 8.4.2.20 realtype getNext ( realtype \* troot, int iroot, realtype \* tdata, int it, void \* user\_data )

getNext computes the next timepoint to integrate to. This is the maximum of tdata and troot but also takes into account if it<0 or iroot<0 where these expressions do not necessarily make sense

##### Parameters

in	<i>troot</i>	timepoint of next event <b>Type:</b> realtype
in	<i>iroot</i>	index of next event <b>Type:</b> int
in	<i>tdata</i>	timepoint of next data point <b>Type:</b> realtype
in	<i>it</i>	index of next data point <b>Type:</b> int
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>

##### Returns

tnext next timepoint  
**Type:** realtype

Definition at line 1684 of file amici.c.

Here is the caller graph for this function:



#### 8.4.2.21 void applyEventBolus ( int \* status, void \* ami\_mem, void \* user\_data, void \* temp\_data )

applyEventBolus applies the event bolus to the current state

**Parameters**

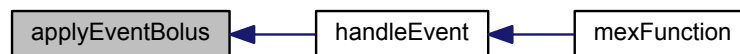
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1729 of file amici.c.

Here is the caller graph for this function:

**8.4.2.22 void applyEventSensiBolusFSA ( int \* status, void \* ami\_mem, void \* user\_data, void \* temp\_data )**

applyEventSensiBolusFSA applies the event bolus to the current sensitivities

**Parameters**

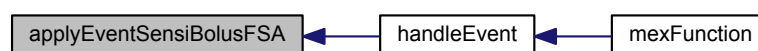
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1764 of file amici.c.

Here is the caller graph for this function:



#### 8.4.2.23 void initHeaviside ( int \* *status*, void \* *user\_data*, void \* *temp\_data* )

initHeaviside initialises the heaviside variables h at the initial time t0 heaviside variables activate/deactivate on event occurrences

**Parameters**

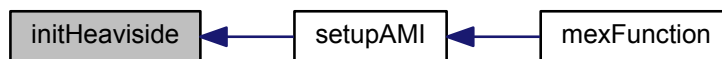
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1802 of file amici.c.

Here is the caller graph for this function:

**8.4.2.24 void updateHeaviside ( int \* *status*, void \* *user\_data*, void \* *temp\_data* )**

updateHeaviside updates the heaviside variables h on event occurrences

**Parameters**

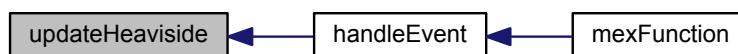
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

Definition at line 1835 of file amici.c.

Here is the caller graph for this function:

**8.4.2.25 void updateHeavisideB ( int \* *status*, int *iroot*, void \* *user\_data*, void \* *temp\_data* )**

updateHeavisideB updates the heaviside variables h on event occurrences for the backward problem



## Parameters

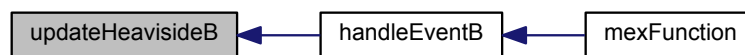
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>iroot</i>	discontinuity occurrence index <b>Type:</b> int
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

## Returns

void

Definition at line 1864 of file amici.c.

Here is the caller graph for this function:



#### 8.4.2.26 void getDiagnosis ( int \* status, int it, void \* ami\_mem, void \* user\_data, void \* return\_data )

getDiagnosis extracts diagnosis information from solver memory block and writes them into the return data struct

## Parameters

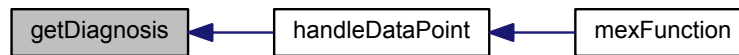
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	time-point index <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>

**Returns**

void

Definition at line 1894 of file amici.c.

Here is the caller graph for this function:



**8.4.2.27** void `getDiagnosisB` ( int \* *status*, int *it*, void \* *ami\_mem*, void \* *user\_data*, void \* *return\_data*, void \* *temp\_data* )

`getDiagnosisB` extracts diagnosis information from solver memory block and writes them into the return data struct for the backward problem

**Parameters**

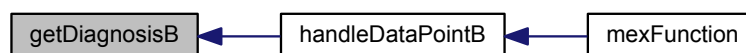
out	<i>status</i>	flag indicating success of execution <b>Type:</b> *int
in	<i>it</i>	time-point index <b>Type:</b> int
in	<i>ami_mem</i>	pointer to the solver memory block <b>Type:</b> *void
in	<i>user_data</i>	pointer to the user data struct <b>Type:</b> <a href="#">UserData</a>
out	<i>return_data</i>	pointer to the return data struct <b>Type:</b> <a href="#">ReturnData</a>
out	<i>temp_data</i>	pointer to the temporary data struct <b>Type:</b> <a href="#">TempData</a>

**Returns**

void

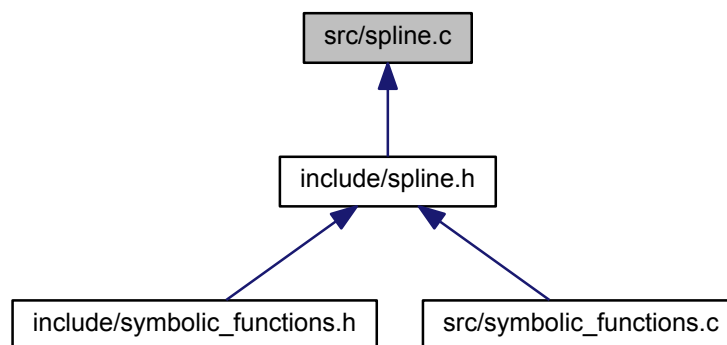
Definition at line 1932 of file amici.c.

Here is the caller graph for this function:

**8.5 src/spline.c File Reference**

definition of spline functions

This graph shows which files directly or indirectly include this file:



## Functions

- static int [spline](#) (int n, int end1, int end2, double slope1, double slope2, double x[], double y[], double b[], double c[], double d[])
- static double [seval](#) (int n, double u, double x[], double y[], double b[], double c[], double d[])
- static double [deriv](#) (int n, double u, double x[], double b[], double c[], double d[])
- static double [sinteg](#) (int n, double u, double x[], double y[], double b[], double c[], double d[])

### 8.5.1 Detailed Description

#### Author

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### 8.5.2 Function Documentation

**8.5.2.1** static int spline ( int n, int end1, int end2, double slope1, double slope2, double x[], double y[], double b[], double c[], double d[] ) [static]

Evaluate the coefficients b[i], c[i], d[i], i = 0, 1, .. n-1 for a cubic interpolating spline

$S(xx) = Y[i] + b[i] * w + c[i] * w**2 + d[i] * w**3$  where  $w = xx - x[i]$  and  $x[i] \leq xx \leq x[i+1]$

The n supplied data points are x[i], y[i], i = 0 ... n-1.

#### Parameters

in	n	The number of data points or knots (n >= 2)
in	end1	0: default condition 1: specify the slopes at x[0]
in	end2	0: default condition 1: specify the slopes at x[n-1]
in	slope1	slope at x[0]
in	slope2	slope at x[n-1]
in	x[]	the abscissas of the knots in strictly increasing order

in	$y[]$	the ordinates of the knots
out	$b[]$	array of spline coefficients
out	$c[]$	array of spline coefficients
out	$d[]$	array of spline coefficients

**Return values**

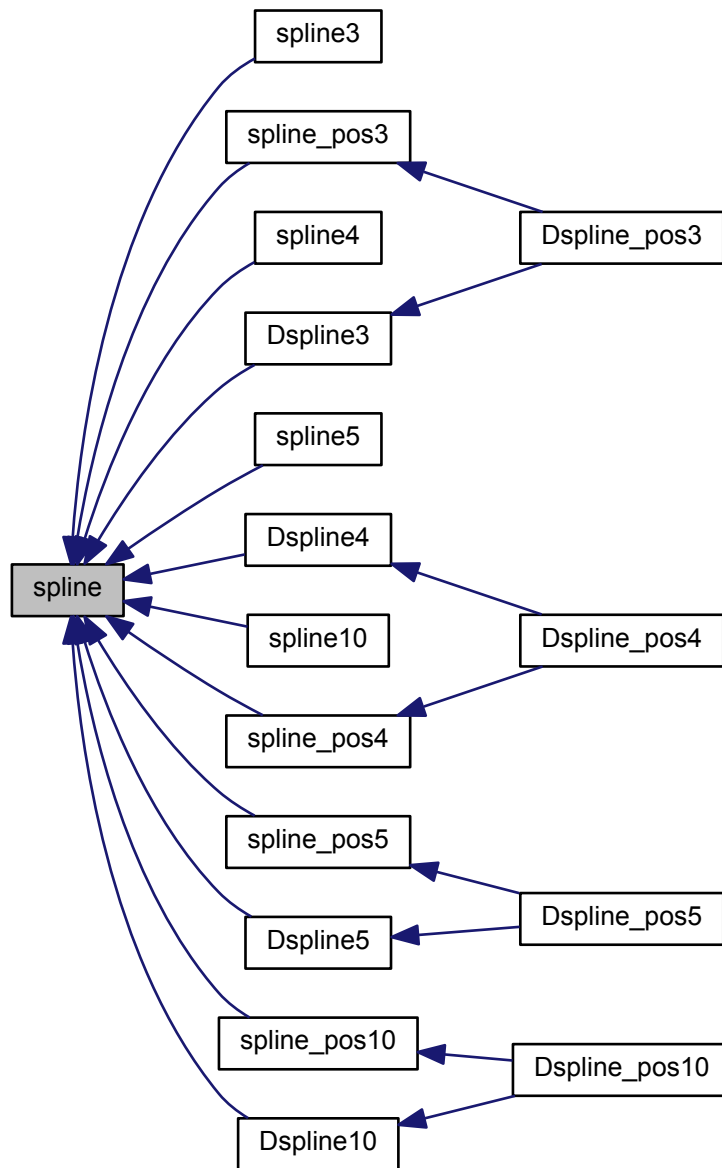
0	normal return
1	less than two data points; cannot interpolate
2	$x[]$ are not in ascending order

**Notes**

- The accompanying function [seval\(\)](#) may be used to evaluate the spline while deriv will provide the first derivative.
- Using  $p$  to denote differentiation  $y[i] = S(X[i])$   $b[i] = Sp(X[i])$   $c[i] = Spp(X[i])/2$   $d[i] = Sppp(X[i])/6$  ( Derivative from the right )
- Since the zero elements of the arrays ARE NOW used here, all arrays to be passed from the main program should be dimensioned at least  $[n]$ . These routines will use elements  $[0 .. n-1]$ .
- Adapted from the text Forsythe, G.E., Malcolm, M.A. and Moler, C.B. (1977) "Computer Methods for Mathematical Computations" Prentice Hall
- Note that although there are only  $n-1$  polynomial segments,  $n$  elements are required in  $b$ ,  $c$ ,  $d$ . The elements  $b[n-1]$ ,  $c[n-1]$  and  $d[n-1]$  are set to continue the last segment past  $x[n-1]$ .

Definition at line 66 of file spline.c.

Here is the caller graph for this function:



**8.5.2.2** static double seval ( int *n*, double *u*, double *x*[], double *y*[], double *b*[], double *c*[], double *d*[] ) [static]

Evaluate the cubic spline function

$S(x) = y[i] + b[i] * w + c[i] * w^2 + d[i] * w^3$  where  $w = u - x[i]$  and  $x[i] \leq u \leq x[i+1]$  Note that Horner's rule is used. If  $u < x[0]$  then  $i = 0$  is used. If  $u > x[n-1]$  then  $i = n-1$  is used.

**Parameters**

in	<i>n</i>	The number of data points or knots ( $n \geq 2$ )
in	<i>u</i>	the abscissa at which the spline is to be evaluated
in	<i>x[]</i>	the abscissas of the knots in strictly increasing order
in	<i>y[]</i>	the ordinates of the knots
in	<i>b</i>	array of spline coefficients computed by <a href="#">spline()</a> .
in	<i>c</i>	array of spline coefficients computed by <a href="#">spline()</a> .
in	<i>d</i>	array of spline coefficients computed by <a href="#">spline()</a> .

**Returns**

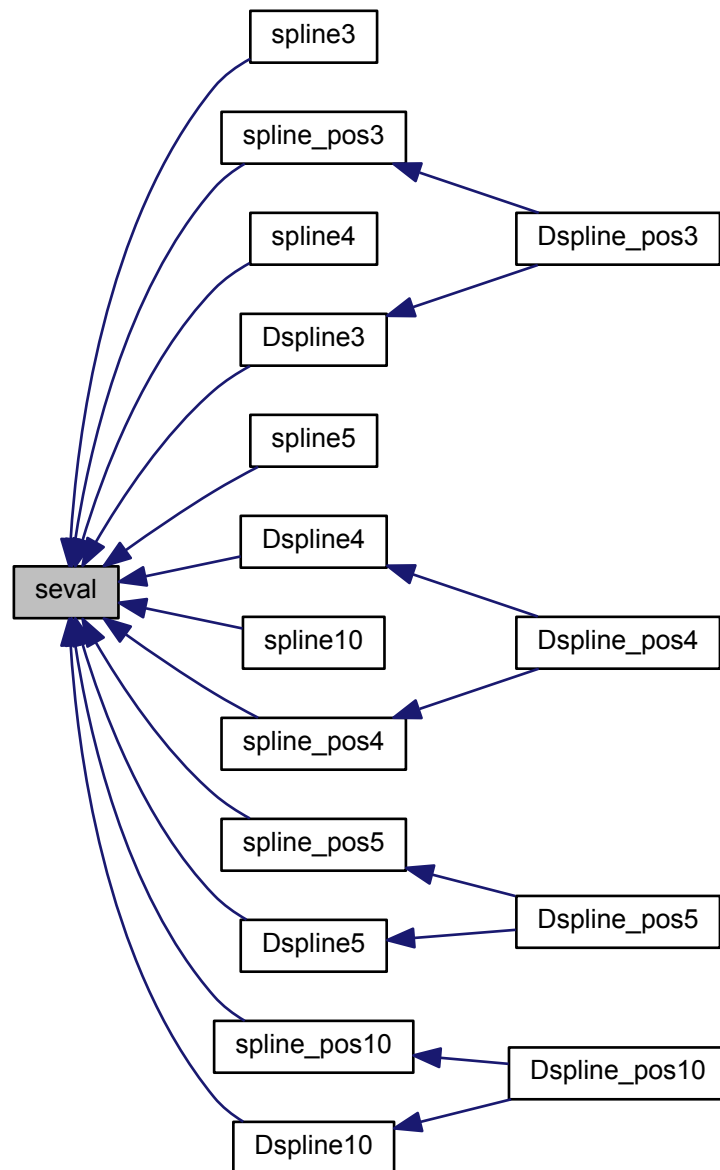
the value of the spline function at *u*

**Notes**

- If *u* is not in the same interval as the previous call then a binary search is performed to determine the proper interval.

Definition at line 208 of file `spline.c`.

Here is the caller graph for this function:



**8.5.2.3** static double deriv ( int n, double u, double x[], double b[], double c[], double d[] ) [static]

Evaluate the derivative of the cubic spline function

$S(x) = B[i] + 2.0 * C[i] * w + 3.0 * D[i] * w^2$  where  $w = u - X[i]$  and  $X[i] \leq u \leq X[i+1]$  Note that Horner's rule is used. If  $U < X[0]$  then  $i = 0$  is used. If  $U > X[n-1]$  then  $i = n-1$  is used.

**Parameters**

in	$n$	the number of data points or knots ( $n \geq 2$ )
in	$u$	the abscissa at which the derivative is to be evaluated
in	$x$	the abscissas of the knots in strictly increasing order
in	$b$	array of spline coefficients computed by <a href="#">spline()</a>
in	$c$	array of spline coefficients computed by <a href="#">spline()</a>
in	$d$	array of spline coefficients computed by <a href="#">spline()</a>

**Returns**

the value of the derivative of the spline function at  $u$

**Notes**

- If  $u$  is not in the same interval as the previous call then a binary search is performed to determine the proper interval.

Definition at line 264 of file `spline.c`.

**8.5.2.4** `static double sinteg ( int  $n$ , double  $u$ , double  $x[]$ , double  $y[]$ , double  $b[]$ , double  $c[]$ , double  $d[]$  )` `[static]`

Integrate the cubic spline function

$S(xx) = y[i] + b[i] * w + c[i] * w**2 + d[i] * w**3$  where  $w = u - x[i]$  and  $x[i] \leq u \leq x[i+1]$

The integral is zero at  $u = x[0]$ .

If  $u < x[0]$  then  $i = 0$  segment is extrapolated. If  $u > x[n-1]$  then  $i = n-1$  segment is extrapolated.

**Parameters**

in	$n$	the number of data points or knots ( $n \geq 2$ )
in	$u$	the abscissa at which the spline is to be evaluated
in	$x[]$	the abscissas of the knots in strictly increasing order
in	$y[]$	the ordinates of the knots
in	$b$	array of spline coefficients computed by <a href="#">spline()</a> .
in	$c$	array of spline coefficients computed by <a href="#">spline()</a> .
in	$d$	array of spline coefficients computed by <a href="#">spline()</a> .

**Returns**

the value of the spline function at  $u$

**Notes**

- If  $u$  is not in the same interval as the previous call then a binary search is performed to determine the proper interval.

Definition at line 324 of file `spline.c`.

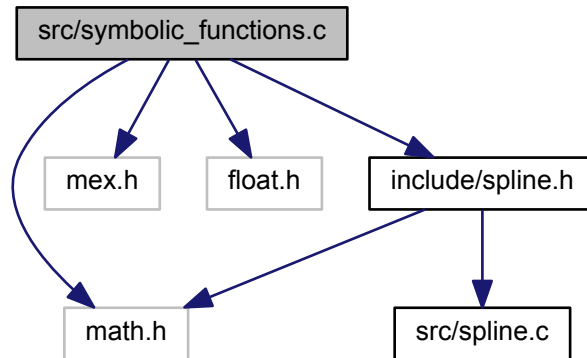
**8.6 src/symbolic\_functions.c File Reference**

definition of symbolic functions

```
#include <math.h>
#include <mex.h>
#include <float.h>
#include <include/spline.h>
```



Include dependency graph for symbolic\_functions.c:



#### Macros

- `#define TRUE 1`
- `#define FALSE 0`

#### Functions

- double `amilog` (double x)
- double `heaviside` (double x)
- double `sign` (double x)
- double `am_min` (double a, double b)
- double `Dam_min` (int id, double a, double b)
- double `am_max` (double a, double b)
- double `Dam_max` (int id, double a, double b)
- double `spline3` (double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt)
- double `spline_pos3` (double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt)
- double `spline4` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt)
- double `spline_pos4` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt)
- double `spline5` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt)
- double `spline_pos5` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt)
- double `spline10` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt)
- double `spline_pos10` (double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt)
- double `Dspline3` (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt)

- double [Dspline\\_pos3](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt)
- double [Dspline4](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt)
- double [Dspline\\_pos4](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt)
- double [Dspline5](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt)
- double [Dspline\\_pos5](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt)
- double [Dspline10](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt)
- double [Dspline\\_pos10](#) (int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt)

### 8.6.1 Detailed Description

This file contains definitions of various symbolic functions which

### 8.6.2 Macro Definition Documentation

#### 8.6.2.1 `#define TRUE 1`

bool return value true

Definition at line 16 of file symbolic\_functions.c.

#### 8.6.2.2 `#define FALSE 0`

bool return value false

Definition at line 18 of file symbolic\_functions.c.

### 8.6.3 Function Documentation

#### 8.6.3.1 `double amilog ( double x )`

c implementation of log function, this prevents returning NaN values for negative values

Parameters

$x$	argument
-----	----------

Returns

if( $x > 0$ ) then  $\log(x)$  else  $-\text{Inf}$

Definition at line 28 of file symbolic\_functions.c.

#### 8.6.3.2 `double heaviside ( double x )`

c implementation of matlab function heaviside

## Parameters

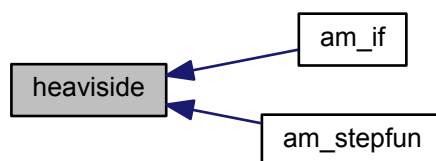
$x$	argument
-----	----------

## Returns

if( $x > 0$ ) then 1 else 0

Definition at line 43 of file symbolic\_functions.c.

Here is the caller graph for this function:

8.6.3.3 double sign ( double  $x$  )

c implementation of matlab function sign

## Parameters

$x$	argument
-----	----------

## Returns

0  
**Type:** double

Definition at line 59 of file symbolic\_functions.c.

8.6.3.4 double am\_min ( double  $a$ , double  $b$  )

c implementation of matlab function min

## Parameters

$a$	value1 <b>Type:</b> double
$b$	value2 <b>Type:</b> double

## Returns

if( $a < b$ ) then  $a$  else  $b$   
**Type:** double

Definition at line 79 of file symbolic\_functions.c.

8.6.3.5 double Dam\_min ( int  $id$ , double  $a$ , double  $b$  )

parameter derivative of c implementation of matlab function min

**Parameters**

<i>id</i>	argument index for differentiation
<i>a</i>	bool1 <b>Type:</b> double
<i>b</i>	bool2 <b>Type:</b> double

**Returns**

id == 1: if(a < b) then 1 else 0

**Type:** double

id == 2: if(a < b) then 0 else 1

**Type:** double

Definition at line 93 of file symbolic\_functions.c.

8.6.3.6 double am\_max ( double *a*, double *b* )

c implementation of matlab function max

**Parameters**

<i>a</i>	value1 <b>Type:</b> double
<i>b</i>	value2 <b>Type:</b> double

**Returns**

if(a > b) then a else b

**Type:** double

Definition at line 117 of file symbolic\_functions.c.

8.6.3.7 double Dam\_max ( int *id*, double *a*, double *b* )

parameter derivative of c implementation of matlab function max

**Parameters**

<i>id</i>	argument index for differentiation
<i>a</i>	bool1 <b>Type:</b> double
<i>b</i>	bool2 <b>Type:</b> double

**Returns**

id == 1: if(a > b) then 1 else 0

**Type:** double

id == 2: if(a > b) then 0 else 1

**Type:** double

Definition at line 131 of file symbolic\_functions.c.

8.6.3.8 double spline3 ( double *t*, double *t1*, double *p1*, double *t2*, double *p2*, double *t3*, double *p3*, int *ss*, double *dudt* )

spline function with 3 nodes

## Parameters

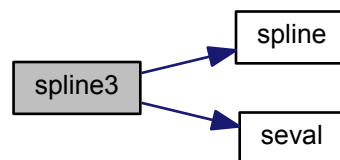
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

## Returns

spline(*t*)

Definition at line 164 of file symbolic\_functions.c.

Here is the call graph for this function:



**8.6.3.9** `double spline_pos3 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt )`

positive spline function with 3 nodes

## Parameters

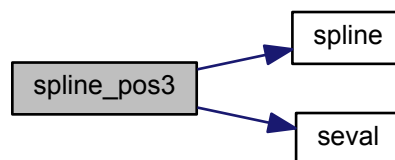
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

spline(t)

Definition at line 205 of file symbolic\_functions.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.10** `double spline4 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt )`

spline function with 4 nodes

**Parameters**

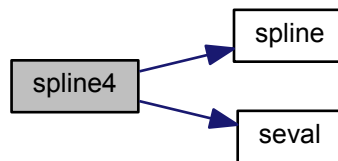
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

spline(t)

Definition at line 253 of file symbolic\_functions.c.

Here is the call graph for this function:



**8.6.3.11** `double spline_pos4 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt )`

positive spline function with 4 nodes

#### Parameters

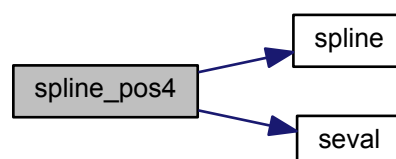
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

#### Returns

`spline(t)`

Definition at line 297 of file `symbolic_functions.c`.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.12** `double spline5 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt )`

spline function with 5 nodes

Parameters

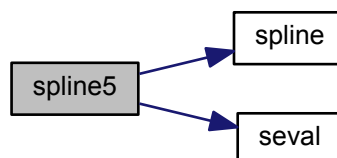
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

Returns

spline(*t*)

Definition at line 349 of file symbolic\_functions.c.

Here is the call graph for this function:



**8.6.3.13** `double spline_pos5 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt )`

positive spline function with 5 nodes



## Parameters

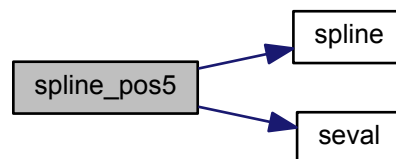
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

## Returns

spline(*t*)

Definition at line 397 of file symbolic\_functions.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.14** `double spline10 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt )`

spline function with 10 nodes

## Parameters

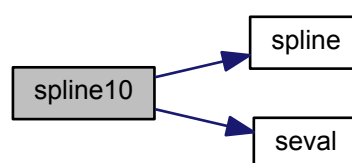
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>t6</i>	location of node 6
<i>p6</i>	spline value at node 6
<i>t7</i>	location of node 7
<i>p7</i>	spline value at node 7
<i>t8</i>	location of node 8
<i>p8</i>	spline value at node 8
<i>t9</i>	location of node 9
<i>p9</i>	spline value at node 9
<i>t10</i>	location of node 10
<i>p10</i>	spline value at node 10
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

## Returns

spline(*t*)

Definition at line 461 of file symbolic\_functions.c.

Here is the call graph for this function:



8.6.3.15 `double spline_pos10 ( double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt )`

positive spline function with 10 nodes

## Parameters

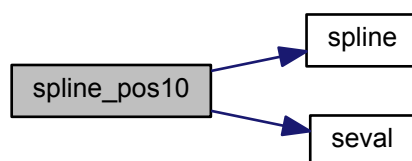
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>t6</i>	location of node 6
<i>p6</i>	spline value at node 6
<i>t7</i>	location of node 7
<i>p7</i>	spline value at node 7
<i>t8</i>	location of node 8
<i>p8</i>	spline value at node 8
<i>t9</i>	location of node 9
<i>p9</i>	spline value at node 9
<i>t10</i>	location of node 10
<i>p10</i>	spline value at node 10
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

## Returns

spline(t)

Definition at line 529 of file symbolic\_functions.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.16** `double Dspline3 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt )`

parameter derivative of spline function with 3 nodes

#### Parameters

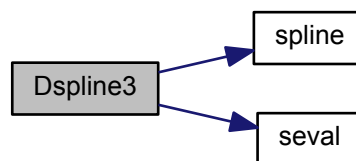
<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

#### Returns

`dspline(t)dp(id)`

Definition at line 590 of file `symbolic_functions.c`.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.17** `double Dspline_pos3 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, int ss, double dudt )`

parameter derivative of positive spline function with 3 nodes

## Parameters

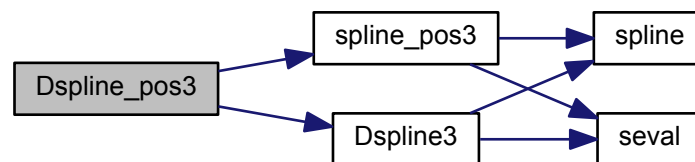
<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

## Returns

dspline(t)dp(id)

Definition at line 635 of file symbolic\_functions.c.

Here is the call graph for this function:



**8.6.3.18** `double Dspline4 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt )`

parameter derivative of spline function with 4 nodes

## Parameters

<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>ss</i>	flag indicating whether slope at first node should be user defined

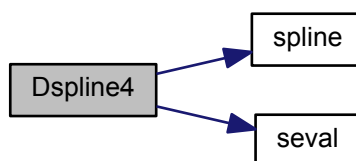
<i>dudt</i>	user defined slope at first node
-------------	----------------------------------

**Returns**

dspline(t)dp(id)

Definition at line 678 of file symbolic\_functions.c.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.19** `double Dspline_pos4 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, int ss, double dudt )`

parameter derivative of positive spline function with 4 nodes

**Parameters**

<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4

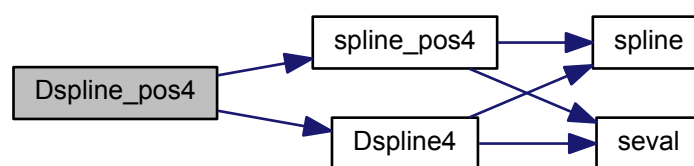
<i>p4</i>	spline value at node 4
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

dspline(t)dp(id)

Definition at line 727 of file symbolic\_functions.c.

Here is the call graph for this function:



8.6.3.20 `double Dspline5 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt )`

parameter derivative of spline function with 5 nodes

**Parameters**

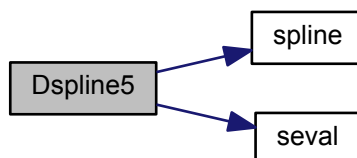
<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

`dspline(t)dp(id)`

Definition at line 772 of file `symbolic_functions.c`.

Here is the call graph for this function:



Here is the caller graph for this function:



**8.6.3.21** `double Dspline_pos5 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, int ss, double dudt )`

parameter derivative of positive spline function with 5 nodes

**Parameters**

<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5



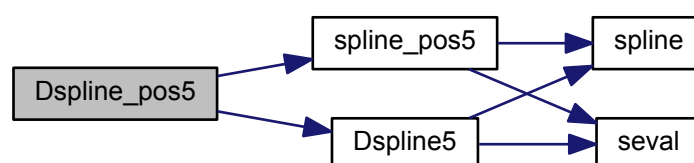
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

dspline(t)dp(id)

Definition at line 825 of file symbolic\_functions.c.

Here is the call graph for this function:



**8.6.3.22** double Dspline10 ( int *id*, double *t*, double *t1*, double *p1*, double *t2*, double *p2*, double *t3*, double *p3*, double *t4*, double *p4*, double *t5*, double *p5*, double *t6*, double *p6*, double *t7*, double *p7*, double *t8*, double *p8*, double *t9*, double *p9*, double *t10*, double *p10*, int *ss*, double *dudt* )

parameter derivative of spline function with 10 nodes

**Parameters**

<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>t6</i>	location of node 6
<i>p6</i>	spline value at node 6
<i>t7</i>	location of node 7
<i>p7</i>	spline value at node 7
<i>t8</i>	location of node 8
<i>p8</i>	spline value at node 8

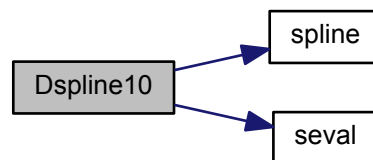
<i>t9</i>	location of node 9
<i>p9</i>	spline value at node 9
<i>t10</i>	location of node 10
<i>p10</i>	spline value at node 10
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

#### Returns

dspline(t)dp(id)

Definition at line 881 of file symbolic\_functions.c.

Here is the call graph for this function:



Here is the caller graph for this function:



8.6.3.23 `double Dspline_pos10 ( int id, double t, double t1, double p1, double t2, double p2, double t3, double p3, double t4, double p4, double t5, double p5, double t6, double p6, double t7, double p7, double t8, double p8, double t9, double p9, double t10, double p10, int ss, double dudt )`

parameter derivative of positive spline function with 10 nodes

#### Parameters

<i>id</i>	argument index for differentiation
<i>t</i>	point at which the spline should be evaluated
<i>t1</i>	location of node 1
<i>p1</i>	spline value at node 1

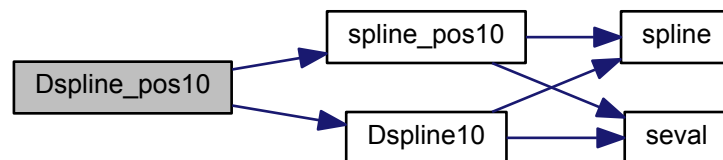
<i>t2</i>	location of node 2
<i>p2</i>	spline value at node 2
<i>t3</i>	location of node 3
<i>p3</i>	spline value at node 3
<i>t4</i>	location of node 4
<i>p4</i>	spline value at node 4
<i>t5</i>	location of node 5
<i>p5</i>	spline value at node 5
<i>t6</i>	location of node 6
<i>p6</i>	spline value at node 6
<i>t7</i>	location of node 7
<i>p7</i>	spline value at node 7
<i>t8</i>	location of node 8
<i>p8</i>	spline value at node 8
<i>t9</i>	location of node 9
<i>p9</i>	spline value at node 9
<i>t10</i>	location of node 10
<i>p10</i>	spline value at node 10
<i>ss</i>	flag indicating whether slope at first node should be user defined
<i>dudt</i>	user defined slope at first node

**Returns**

dspline(t)dp(id)

Definition at line 954 of file symbolic\_functions.c.

Here is the call graph for this function:

**8.7 symbolic/am\_and.m File Reference**

```
syms x y f = symfun(sym(cw_and(x,y)),[x y]); fun = f(a,b);
```

**Functions**

- mlhsInnerSubst< matlabtypesubstitute > [am\\_and](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
`syms x y f = symfun(sym(cw_and(x,y)),[x y]); fun = f(a,b);`

**8.8 symbolic/am\_ge.m File Reference**

```
syms x y f = symfun(sym(cw_ge(x,y)),[x y]); fun = f(a,b);
```

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_ge](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
 $\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_ge}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## 8.9 symbolic/am\_gt.m File Reference

$\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_gt}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_gt](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
 $\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_gt}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## 8.10 symbolic/am\_if.m File Reference

$\text{syms } x \ y \ z \ f = \text{symfun}(\text{sym}(\text{am\_if}(x, y, z)), [x \ y \ z]); \text{ fun} = f(\text{condition}, \text{truepart}, \text{falsepart});$

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_if](#) (matlabtypesubstitute condition, matlabtypesubstitute truepart, matlabtypesubstitute falsepart)  
 $\text{syms } x \ y \ z \ f = \text{symfun}(\text{sym}(\text{am\_if}(x, y, z)), [x \ y \ z]); \text{ fun} = f(\text{condition}, \text{truepart}, \text{falsepart});$

## 8.11 symbolic/am\_le.m File Reference

$\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_le}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_le](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
 $\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_le}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## 8.12 symbolic/am\_lt.m File Reference

$\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_lt}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_lt](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
 $\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{cw\_lt}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## 8.13 symbolic/am\_max.m File Reference

$\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{am\_max}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_max](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
 $\text{syms } x \ y \ f = \text{symfun}(\text{sym}(\text{am\_max}(x, y)), [x \ y]); \text{ fun} = f(a, b);$

## 8.14 symbolic/am\_min.m File Reference

```
syms x y f = symfun(sym(am_min(x,y)),[x y]); fun = f(a,b);
```

### Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_min](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
*syms x y f = symfun(sym(am\_min(x,y)),[x y]); fun = f(a,b);*

## 8.15 symbolic/am\_or.m File Reference

```
syms x y f = symfun(sym(cw_or(x,y)),[x y]); fun = f(a,b);
```

### Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_or](#) (matlabtypesubstitute a, matlabtypesubstitute b)  
*syms x y f = symfun(sym(cw\_or(x,y)),[x y]); fun = f(a,b);*

## 8.16 symbolic/am\_stepfun.m File Reference

```
syms x y f = symfun(sym(am_min(x,y)),[x y]); fun = f(a,b);
```

### Functions

- mlhsInnerSubst< matlabtypesubstitute > [am\\_stepfun](#) (matlabtypesubstitute t, matlabtypesubstitute tstart, matlabtypesubstitute vstart, matlabtypesubstitute tend, matlabtypesubstitute vend)  
*syms x y f = symfun(sym(am\_min(x,y)),[x y]); fun = f(a,b);*



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