

1. What is the difference between an interleaved image representation and a planar image representation in memory?

Planar Representation stores color channels contiguously (e.g., all reds, then greens, then blues). Example: [R: 128, ...], [G: 128, ...], [B: 128, ...]

Interleaved Representation stores pixel data consecutively by color channel (e.g., RGBRGB...) for more efficient individual pixel processing. E.g.: we use $\text{src}[(i * \text{cols} + j) * 3 + k]$ to represent the row where k is 0,1,2.

2. Give a couple of subjective explanations of what a filter can do.

Do image processing by modifying the variations in pixels, e.g. exposure, color balance and negatives to build up new color feature.

Do edge detection by applying horizontal or vertical sobel filter.

3. What are a couple of ways of handling boundary issues (the edges of the image) when applying a filter?

Pad the data with 0, or replicated the previous padding format of row or col.
Ignore outside where filter cannot fully overlap with the input image.

4. If you have a 3x3 filter, how many operations per pixel are required for convolution? What about a 5x5 filter? What about a 7x7 filter? What about a 1x11 filter?

3x3 filter: multiplication $3 \times 3 = 9$; additions $= 9 - 1 = 8$; total = 17 ops/ pixel

5x5 filter: multiplication $5 \times 5 = 25$; additions $= 25 - 1 = 24$; total = 49 ops/ pixel

7x7 filter: multiplication $7 \times 7 = 49$; additions $= 49 - 1 = 48$; total = 97 ops/ pixel

1x11 filter: multiplication $1 \times 11 = 11$; additions $= 11 - 1 = 10$; total = 21 ops/ pixel

5. Full convolution is convolution where the result contains all possible ways the two filters could overlap. What happens if you do full convolution between the following two filters?

$$\begin{array}{ccc|c} 1 & 2 & 1 & -1 \\ & & & X \\ & & & 0 \\ & & & 1 \end{array}$$

3 * 3 matrix

$$\begin{array}{ccc} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{array}$$