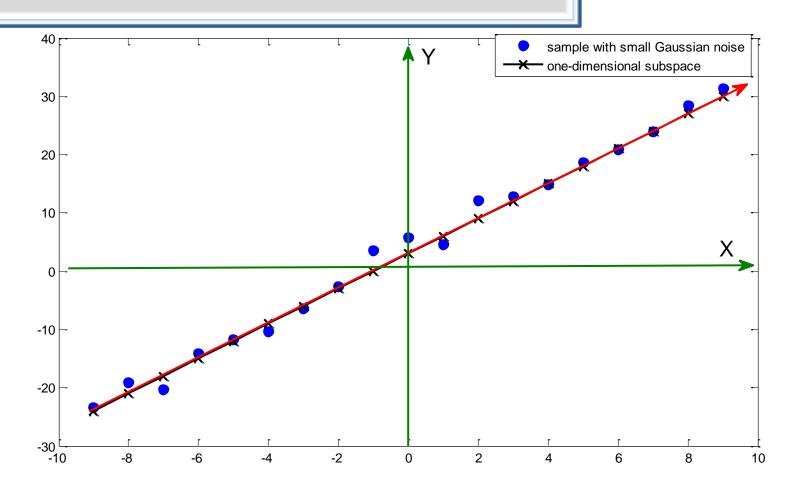


Problem: Given
$$D=A_0+E_0$$
, recover A_0 and E_0 Low-rank component Sparse component (gross errors)

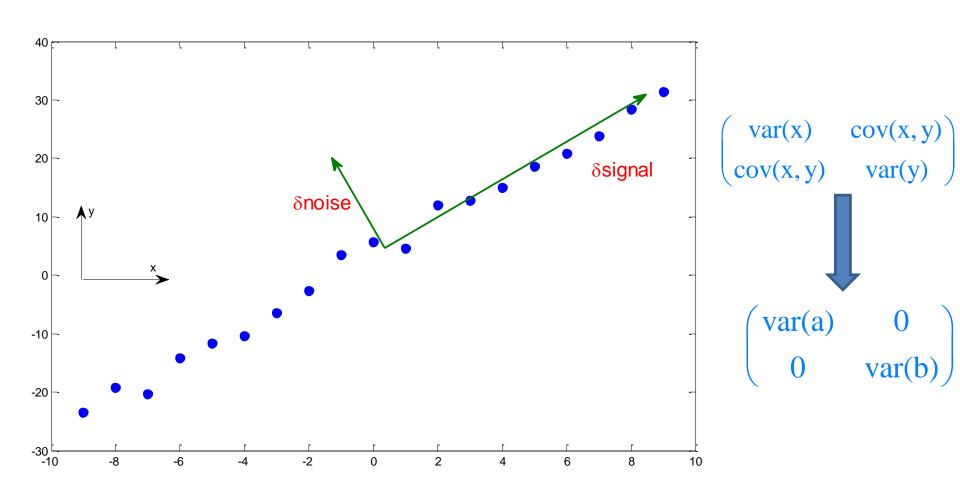




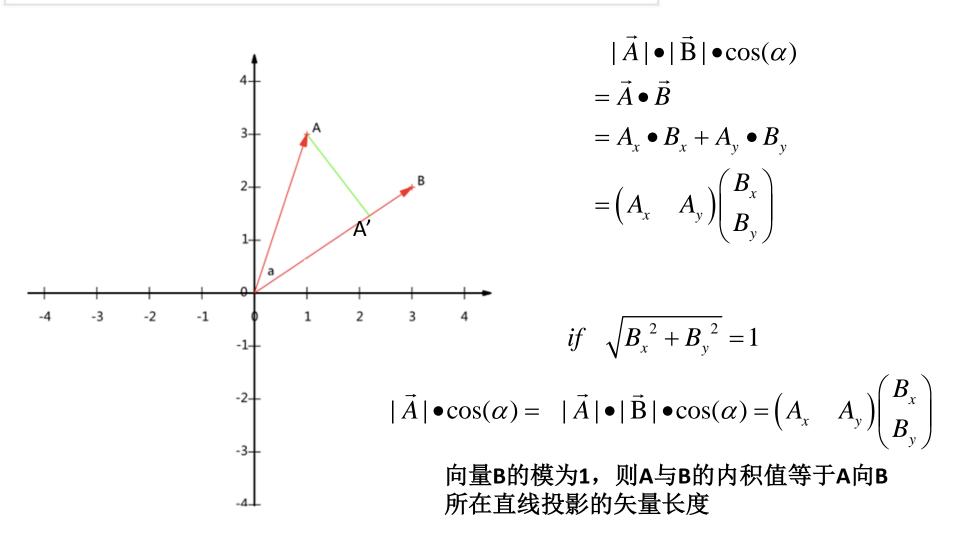
PCA直观理解



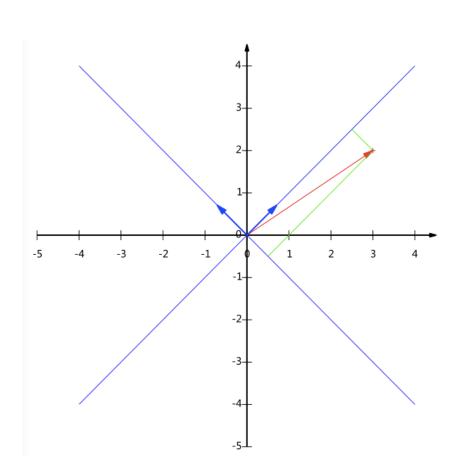
PCA直观理解



矩阵相乘与投影



矩阵相乘与坐标空间映射



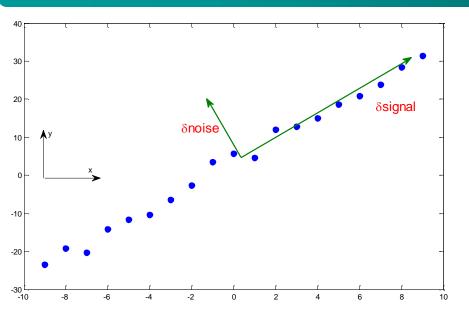
$$\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} \frac{5}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

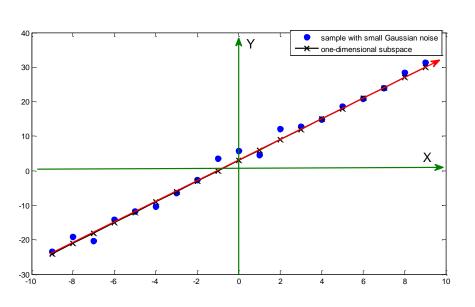
$$= \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 5 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\alpha = \left(\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right), \beta = \left(-\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right)$$

 α β 为单位向量,相互正交

$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} \begin{pmatrix} 3 \\ 2 \end{pmatrix} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \begin{pmatrix} 5 & 0 \\ 0 & -1 \end{pmatrix}$$





$$\begin{pmatrix} \alpha \\ \beta \end{pmatrix} \begin{pmatrix} var(x) & cov(x, y) \\ cov(x, y) & var(y) \end{pmatrix}$$
$$= \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \begin{pmatrix} var(a) & 0 \\ 0 & var(b) \end{pmatrix}$$

$$\begin{pmatrix} var(x) & cov(x, y) \\ cov(x, y) & var(y) \end{pmatrix} \alpha = var(a)\alpha$$

SVD

$$A_{m \times n} \qquad (A^{T} A) V_{i} = \lambda V_{i}$$

$$(AV_{i})^{T} (AV_{i}) = V_{i}^{T} (A^{T} AV_{i}) = V_{i}^{T} \lambda V_{i} = \lambda E$$

$$\Rightarrow |AV_{i}| = \lambda$$

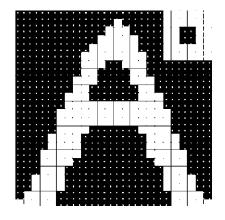
$$\begin{split} \boldsymbol{U}_i = & \frac{A\boldsymbol{V}_i}{\sqrt{A\boldsymbol{V}_i}} = \frac{A\boldsymbol{V}_i}{\sqrt{\lambda_i}} & \boldsymbol{\sigma}_i = \sqrt{\lambda_i} & \boldsymbol{U}_i = \frac{A\boldsymbol{V}_i}{\boldsymbol{\sigma}_i} \\ & \boldsymbol{U}_i^T\boldsymbol{U}_i = (\frac{A\boldsymbol{V}_i}{\boldsymbol{\sigma}_i})^T \frac{A\boldsymbol{V}_i}{\boldsymbol{\sigma}_i} = \frac{\boldsymbol{V}_i^T\boldsymbol{A}^T\boldsymbol{A}\boldsymbol{V}_i}{\boldsymbol{\sigma}_i^2} = \frac{\boldsymbol{V}_i^T\boldsymbol{\lambda}\boldsymbol{V}_i}{\boldsymbol{\lambda}} = E \end{split}$$
 为单位向量,

$$U_i^T U_j = \left(\frac{AV_i}{\sigma_i}\right)^T \frac{AV_j}{\sigma_i} = \frac{V_i^T A^T A V_i}{\sigma_i \sigma_i} = \frac{V_i^T \lambda V_j}{\lambda} = 0$$
 相互正交

$$U_{i} = \frac{AV_{i}}{\sigma_{i}} \Rightarrow A = U \sum V^{-1} = U \sum V^{T}$$



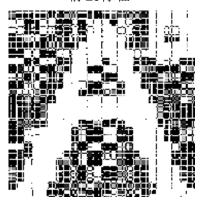
原图



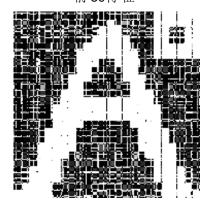
前 10特 征



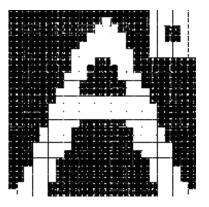
前 20特 征



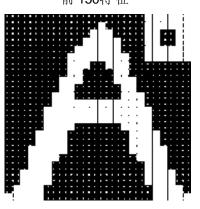
前 50特 征



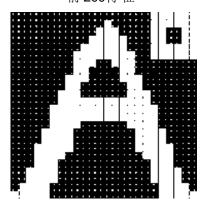
前 100特 征



前 150特 征

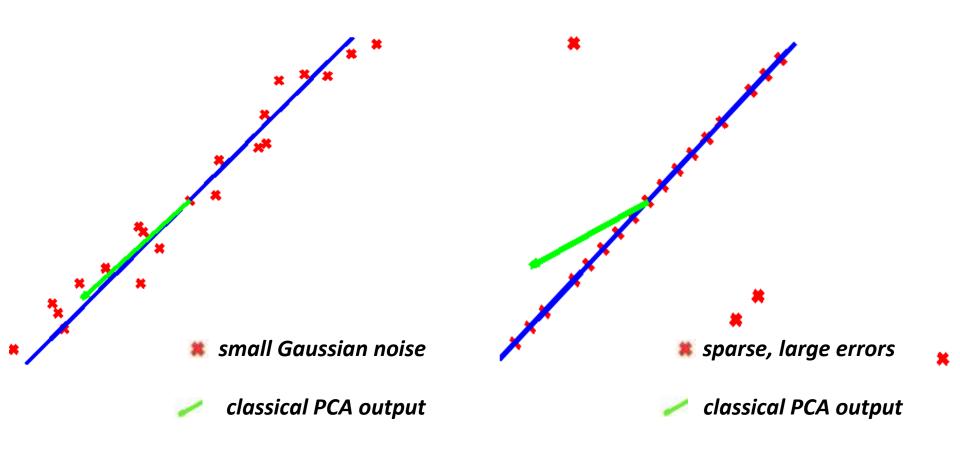


前 200特 征



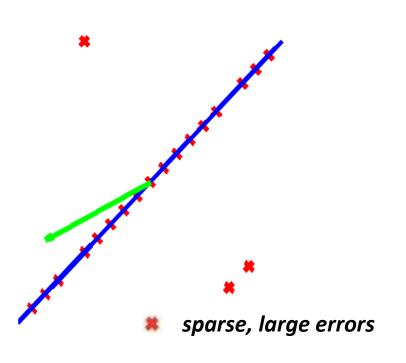


经典PCA局限性





提出 Robust PCA



给出:
$$D = A_0 + E_0$$
, 恢复 A_0 和 E_0

Low-rank component (gross errors)

$$\min \operatorname{rank}(A) + \gamma ||E||_0 \operatorname{subj} A + E = D.$$

低秩:
$$rank(A) = \#\{\sigma_i(A) \neq 0\}.$$

稀疏:
$$||E||_0 = \#\{E_{ij} \neq 0\}$$
.

! Not always – original problem is NP-hard



Convex relaxation

0范数(L0):
$$||E||_0 = \#\{E_{ij} \neq 0\}$$
.

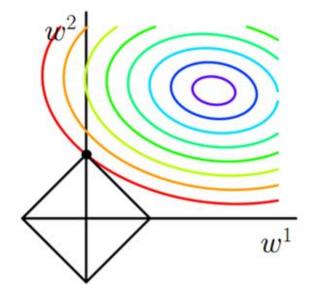


1范数(L1): $||E||_1 = \sum_{ij} |E_{ij}|$.

最优凸近似

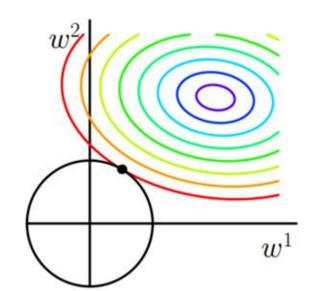
L1范数约束依然稀疏

$$\min_{w} \frac{1}{n} || y - Xw ||^2, s.t || w ||_1 \le C$$



L2范数约束无稀疏特性

$$\min_{w} \frac{1}{n} || y - Xw ||^2, s.t || w ||_2 \le C$$





Convex relaxation

$$\min \operatorname{rank}(A) + \gamma ||E||_0 \operatorname{subj} A + E = D.$$



$$\operatorname{rank}(A) = \#\{\sigma_i(A) \neq 0\}.$$
 $\|E\|_0 = \#\{E_{ij} \neq 0\}.$ 最优 ↓↓ 凸近似
$$\|A\|_* = \sum_i \sigma_i(A).$$
 $\|E\|_1 = \sum_{ij} |E_{ij}|.$

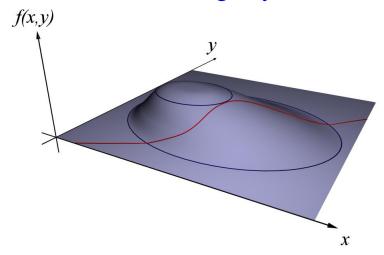
min
$$\| A \|_* + \gamma \| E \|_1$$
 subj $A + E = D$

NP问题转化为凸函数约束问题



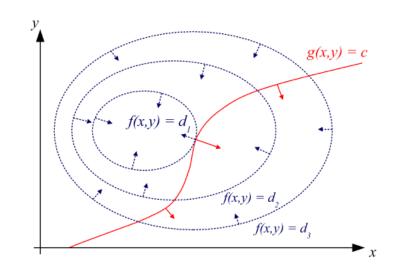
拉格朗日乘子法原理

约束 max f(x,y) 问题 s.t. g(x,y) = c



极值点位置:

$$\nabla[f(x,y) + \lambda(g(x,y) - c)] = 0$$



约束问题

无约束的目标函数替代原约束问题

极值问题

 $\max \quad f(\mathbf{x})$

$$s.t.$$
 $g_i(x) = 0$ $i = 1, 2..., n$



max

$$L(\mathbf{x}, \lambda_i) = f(\mathbf{x}) + \sum_{i=1}^n \lambda_i g_i(\mathbf{x})$$

增广拉格朗日乘子法



min f(x), s.t h(x) = 0

1:
$$\rho \ge 1$$
.

2: while not converged do

3: Solve $X_{k+1} = \arg\min_{X} L(X, Y_k, \mu_k)$.

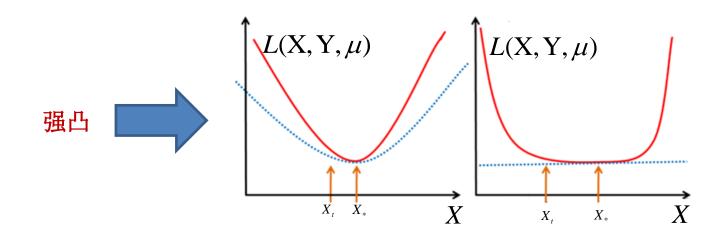
4: $Y_{k+1} = Y_k + \mu_k h(X_{k+1});$

5: Update μ_k to μ_{k+1} .

6: end while

Output: X_k .

$$L(X, Y, \mu) = f(X) + \langle Y, h(X) \rangle + \frac{\mu}{2} \| h(X) \|_{2}^{2}$$



RPCA via the Inexact ALM Method

$$\min \operatorname{rank}(A) + \gamma ||E||_0 \quad \operatorname{subj} \quad A + E = D.$$

$$f(x) = ||A||_* + \lambda ||E||_1$$
, and $h(x) = D - A - E$

$$L(A, E, Y, \mu) = ||A||_* + \lambda ||E||_1 + \langle Y, D - A - E \rangle + \frac{\mu}{2} ||D - A - E||_2^2$$

```
Input: Observation matrix D \in \mathbb{R}^{m \times n}, \lambda.

1: Y_0 = D/J(D); E_0 = 0; \mu_0 > 0; \rho > 1; k = 0.

2: while not converged do

3: // Lines 4-5 solve A_{k+1} = \arg\min_A L(A, E_k, Y_k, \mu_k).

4: (U, S, V) = \operatorname{svd}(D - E_k + \mu_k^{-1}Y_k);

5: A_{k+1} = US_{\mu_k^{-1}}[S]V^T.

6: // Line 7 solves E_{k+1} = \arg\min_E L(A_{k+1}, E, Y_k, \mu_k).

7: E_{k+1} = S_{\lambda\mu_k^{-1}}[D - A_{k+1} + \mu_k^{-1}Y_k].

8: Y_{k+1} = Y_k + \mu_k(D - A_{k+1} - E_{k+1}).

9: Update \mu_k to \mu_{k+1}.

10: k \leftarrow k+1.

11: end while Output: (A_k, E_k).
```

RPCA求解

For a 1000x1000 matrix of rank 50, with 10% (100,000) entries randomly corrupted: $\min \|A\|_* + \lambda \|E\|_1 \quad \mathrm{subj} \quad A + E = D.$

Algorithms	Accuracy	Rank	E _0	# iterations	time (sec)
IT	5.99e-006	50	101,268	8,550	119,370.3
DUAL	8.65e-006	50	100,024	822	1,855.4
APG	5.85e-006	50	100,347	134	1,468.9
APG _P	5.91e-006	50	100,347	134	82.7
EALM _P	2.07e-007	50	100,014	34	37.5
IALM _P	3.83e-007	50	99,996	23	11.8

10,000 times speedup!

应用

Background Modeling

D = A + E

 ${\it Video}\ D$







Low-rank appx. $\!A\!$







Sparse error $\,E\,$

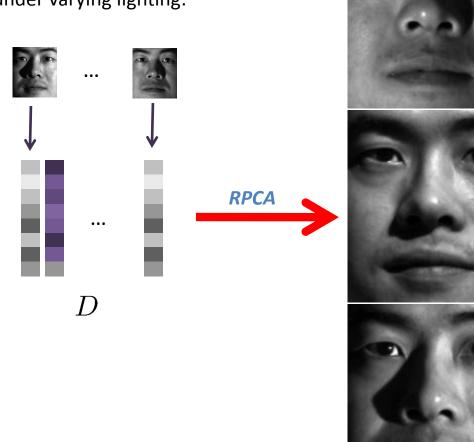


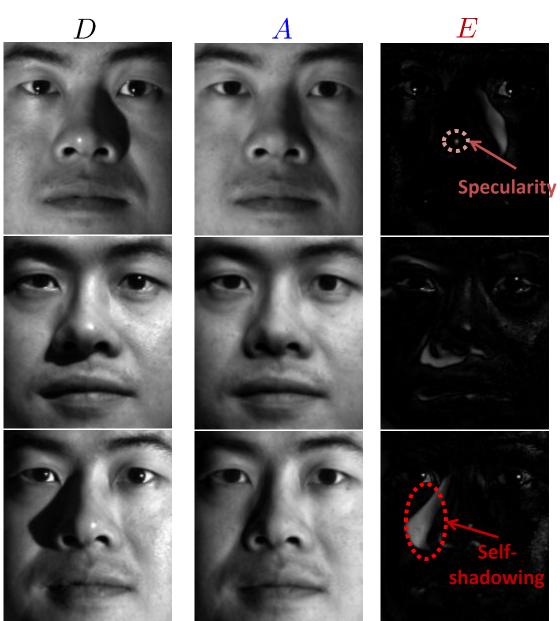


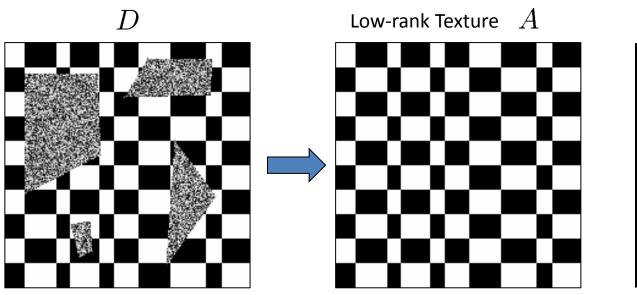


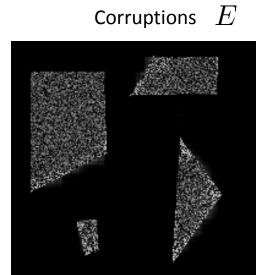
Removing Shadows and Specularities from Face Images

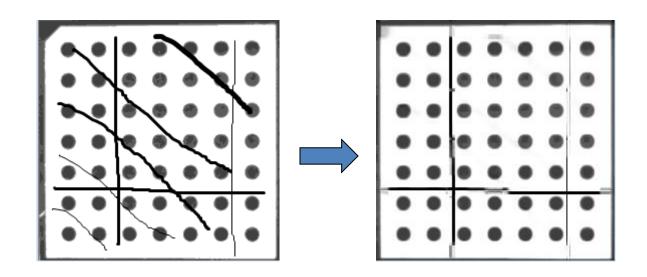
58 images of one person under varying lighting:

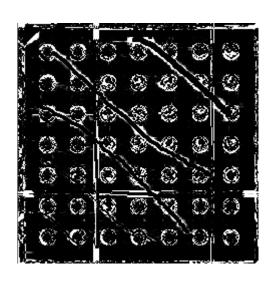




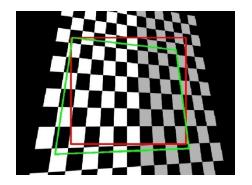


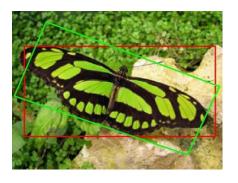






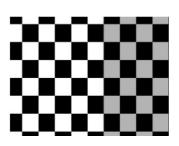
Input (red window D)







Output (rectified green window A)







IALM

参考:

Prof. Yi Ma http://perception.csl.illinois.edu/matrix-rank/sample_code.html

github https://github.com/andrewssobral/Irslibrary

Optimization http://www.stat.purdue.edu/~vishy/introml/notes/Optimization.pdf

Lagrange multiplier https://en.wikipedia.org/wiki/Lagrange_multiplier

RPCA Robust Principal Component Analysis?

The Augmented Lagrange Multiplier Method for Exact Recovery of Corrupted Low-Rank Matrices

