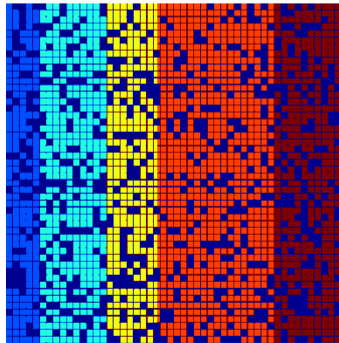


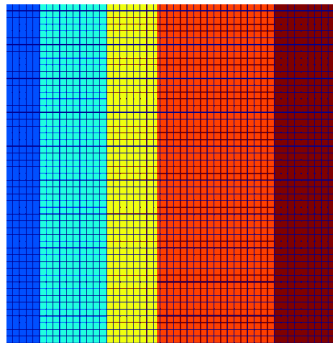
ROBUST PCA

D - observation



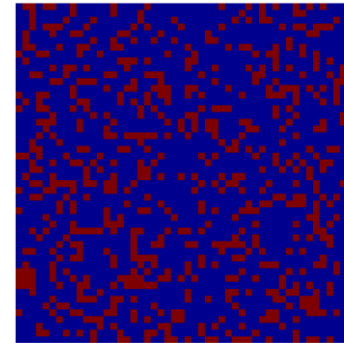
=

A_0 - low-rank



+

E_0 - sparse



Problem: Given $D = A_0 + E_0$, recover A_0 and E_0

Low-rank component

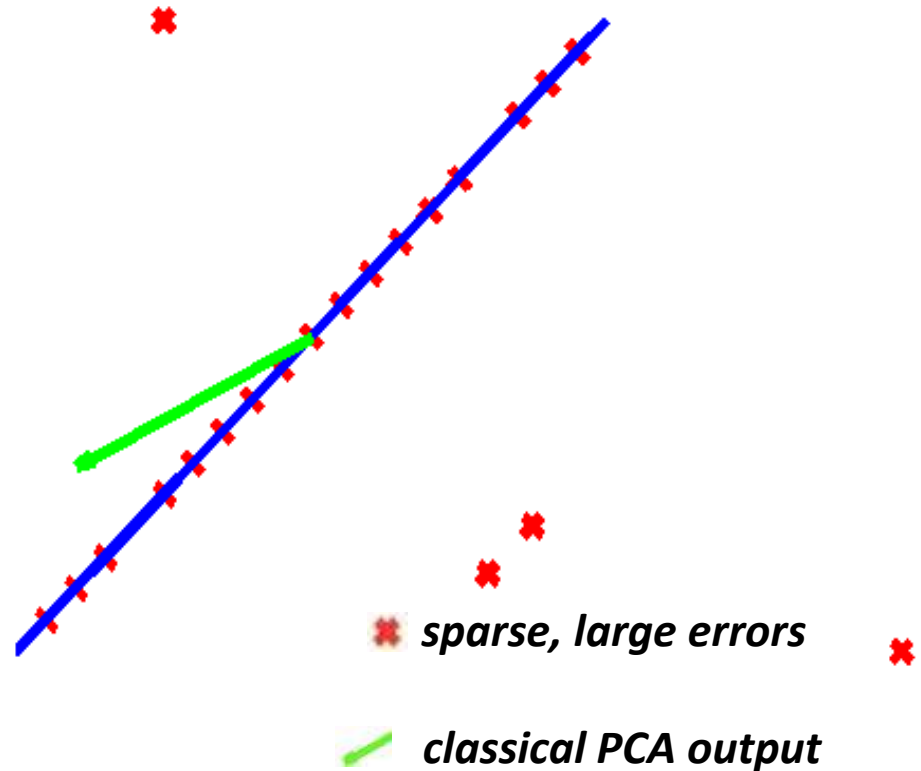
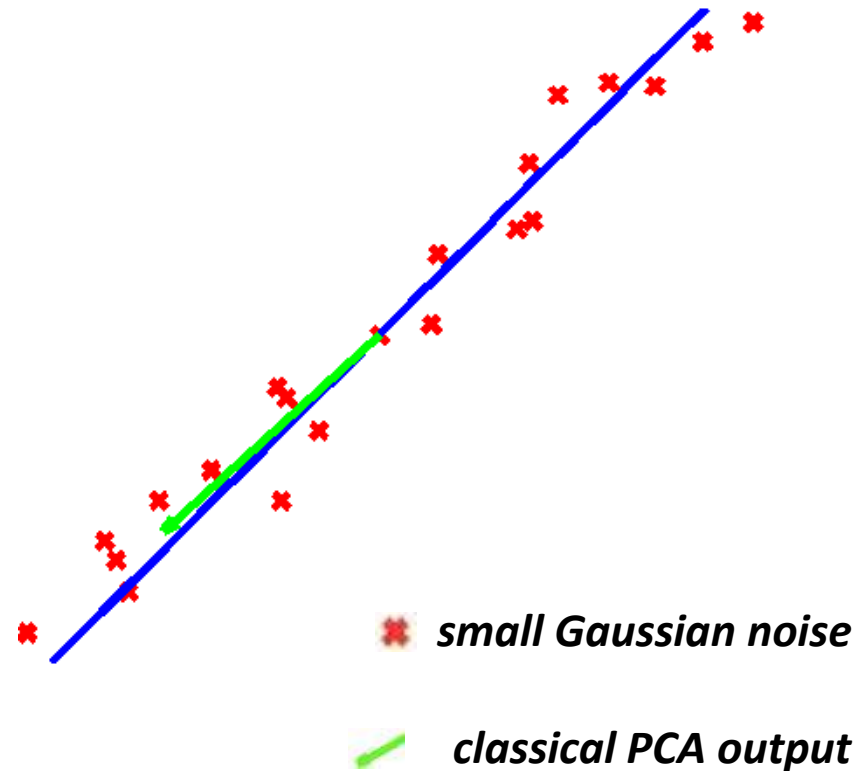
Sparse component (gross errors)



重慶大學
CHONGQING UNIVERSITY

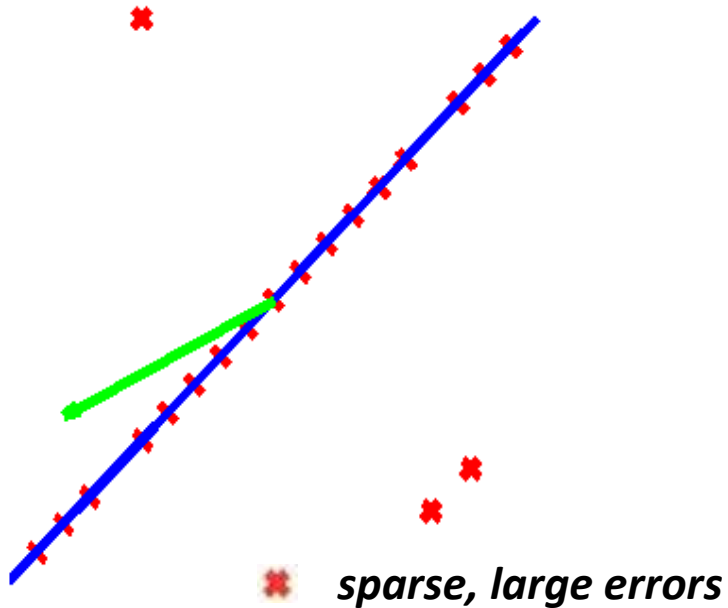
ROBUST PCA

经典PCA局限性



ROBUST PCA

提出 Robust PCA



给出: $D = A_0 + E_0$, 恢复 A_0 和 E_0

Low-rank
component

Sparse component
(gross errors)



$$\min \text{rank}(A) + \gamma \|E\|_0 \quad \text{subj } A + E = D.$$

低秩: $\text{rank}(A) = \#\{\sigma_i(A) \neq 0\}$.

稀疏: $\|E\|_0 = \#\{E_{ij} \neq 0\}$.

! Not always – original problem is NP-hard

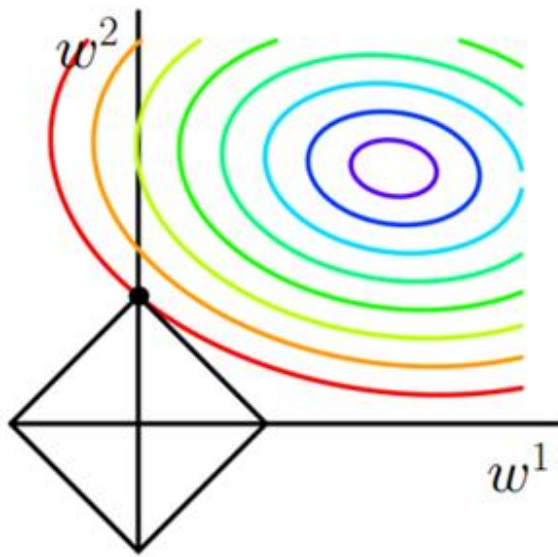
ROBUST PCA

Convex relaxation

0范数(L0): $\|E\|_0 = \#\{E_{ij} \neq 0\}$. \longrightarrow 1范数(L1): $\|E\|_1 = \sum_{ij} |E_{ij}|$.
最优凸近似

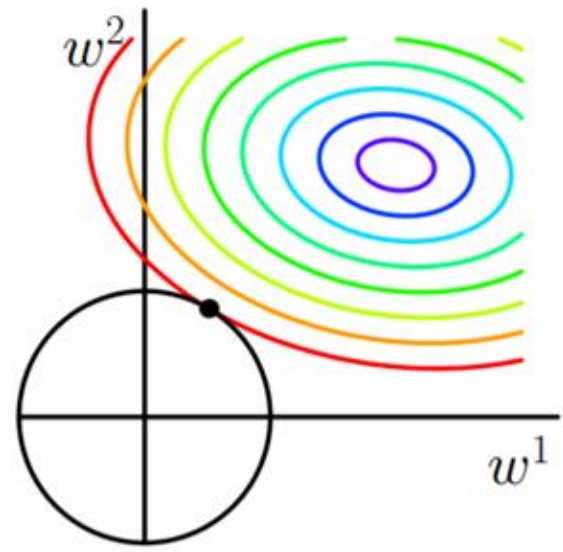
L1范数约束依然稀疏

$$\min_w \frac{1}{n} \|y - Xw\|^2, s.t. \|w\|_1 \leq C$$



L2范数约束无稀疏特性

$$\min_w \frac{1}{n} \|y - Xw\|^2, s.t. \|w\|_2 \leq C$$



Convex relaxation

$$\min \text{rank}(\textcolor{red}{A}) + \gamma \|\textcolor{green}{E}\|_0 \quad \text{subj} \quad \textcolor{red}{A} + \textcolor{green}{E} = D.$$

Convex  *relaxation*

$$\text{rank}(A) = \#\{\sigma_i(A) \neq 0\}.$$

最优 $\Downarrow\Downarrow$ 凸近似

$$\|A\|_* = \sum_i \sigma_i(A).$$

$$\|E\|_0 = \#\{E_{ij} \neq 0\}.$$

最优 $\Downarrow\Downarrow$ 凸近似

$$\|E\|_1 = \sum_{ij} |E_{ij}|.$$

$$\min \quad \|\textcolor{red}{A}\|_* + \gamma \|\textcolor{green}{E}\|_1 \quad \text{subj} \quad \textcolor{red}{A} + \textcolor{green}{E} = D$$

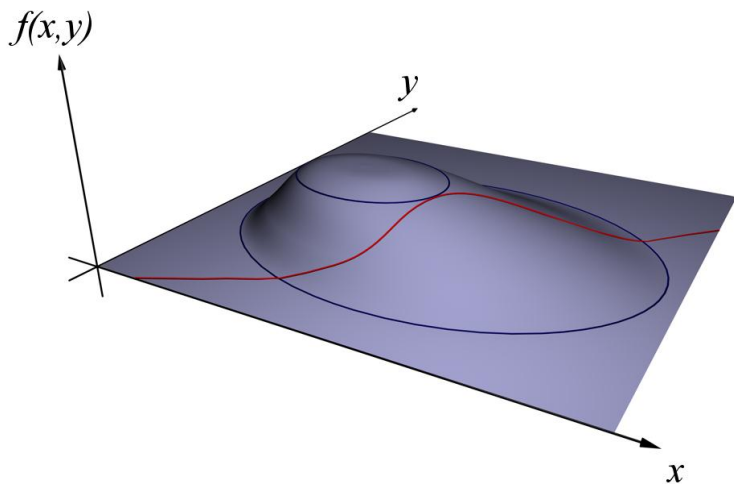
NP问题转化为凸函数约束问题

ROBUST PCA

拉格朗日乘子法原理

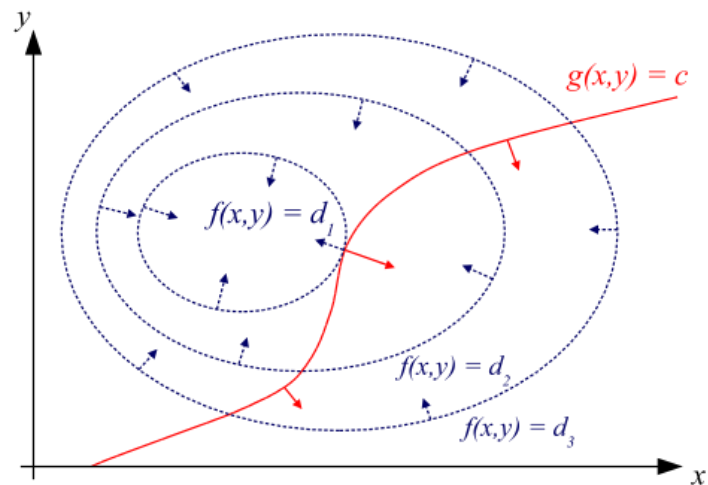
约束问题

$$\begin{aligned} \max \quad & f(x, y) \\ \text{s.t.} \quad & g(x, y) = c \end{aligned}$$



极值点位置:

$$\nabla[f(x, y) + \lambda(g(x, y) - c)] = 0$$



约束问题

$$\begin{aligned} \max \quad & f(x) \\ \text{s.t.} \quad & g_i(x) = 0 \quad i = 1, 2, \dots, n \end{aligned}$$

无约束的目标函数替代原约束问题

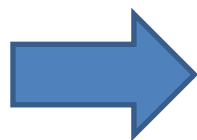


$$\max \quad L(x, \lambda_i) = f(x) + \sum_{i=1}^n \lambda_i g_i(x)$$

极值问题

增广拉格朗日乘子法

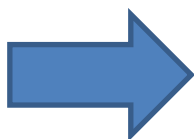
迭代解法



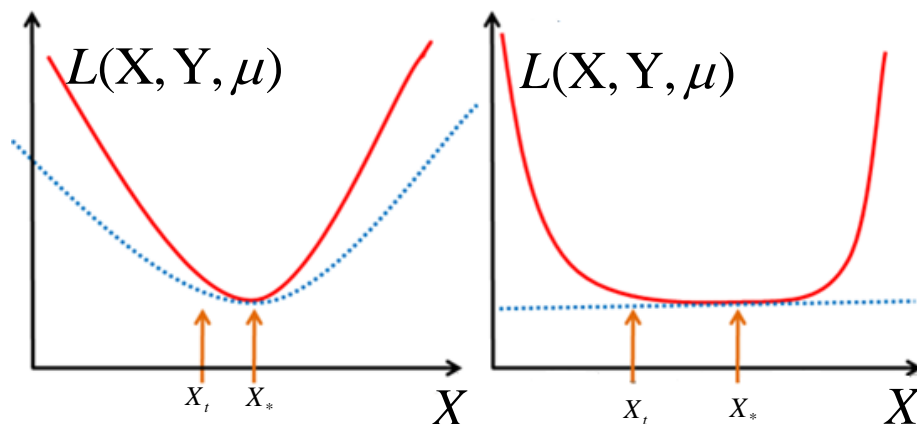
$$\min f(x), \quad s.t \quad h(x) = 0$$

$$L(X, Y, \mu) = f(X) + \langle Y, h(X) \rangle + \frac{\mu}{2} \|h(X)\|_2^2$$

强凸



- 1: $\rho \geq 1$.
 - 2: **while** not converged **do**
 - 3: Solve $X_{k+1} = \arg \min_X L(X, Y_k, \mu_k)$.
 - 4: $Y_{k+1} = Y_k + \mu_k h(X_{k+1})$;
 - 5: Update μ_k to μ_{k+1} .
 - 6: **end while**
- Output:** X_k .



RPCA via the Inexact ALM Method

$$\min \text{rank}(\mathbf{A}) + \gamma \|\mathbf{E}\|_0 \quad \text{subj} \quad \mathbf{A} + \mathbf{E} = \mathbf{D}.$$

$$f(\mathbf{x}) = \|\mathbf{A}\|_* + \lambda \|\mathbf{E}\|_1, \text{ and } \quad h(\mathbf{x}) = \mathbf{D} - \mathbf{A} - \mathbf{E}$$

$$L(\mathbf{A}, \mathbf{E}, \mathbf{Y}, \mu) = \|\mathbf{A}\|_* + \lambda \|\mathbf{E}\|_1 + \langle \mathbf{Y}, \mathbf{D} - \mathbf{A} - \mathbf{E} \rangle + \frac{\mu}{2} \|\mathbf{D} - \mathbf{A} - \mathbf{E}\|_2^2$$

Input: Observation matrix $\mathbf{D} \in \mathbb{R}^{m \times n}$, λ .

1: $\mathbf{Y}_0 = \mathbf{D}/J(\mathbf{D})$; $\mathbf{E}_0 = \mathbf{0}$; $\mu_0 > 0$; $\rho > 1$; $k = 0$.

2: **while** not converged **do**

3: // Lines 4-5 solve $\mathbf{A}_{k+1} = \arg \min_{\mathbf{A}} L(\mathbf{A}, \mathbf{E}_k, \mathbf{Y}_k, \mu_k)$.

4: $(\mathbf{U}, \mathbf{S}, \mathbf{V}) = \text{svd}(\mathbf{D} - \mathbf{E}_k + \mu_k^{-1} \mathbf{Y}_k)$;

5: $\mathbf{A}_{k+1} = \mathbf{U} \mathbf{S}_{\mu_k^{-1}} [\mathbf{S}] \mathbf{V}^T$.

6: // Line 7 solves $\mathbf{E}_{k+1} = \arg \min_{\mathbf{E}} L(\mathbf{A}_{k+1}, \mathbf{E}, \mathbf{Y}_k, \mu_k)$.

7: $\mathbf{E}_{k+1} = \mathcal{S}_{\lambda \mu_k^{-1}} [\mathbf{D} - \mathbf{A}_{k+1} + \mu_k^{-1} \mathbf{Y}_k]$.

8: $\mathbf{Y}_{k+1} = \mathbf{Y}_k + \mu_k (\mathbf{D} - \mathbf{A}_{k+1} - \mathbf{E}_{k+1})$.

9: Update μ_k to μ_{k+1} .

10: $k \leftarrow k + 1$.

11: **end while**

Output: $(\mathbf{A}_k, \mathbf{E}_k)$.

ROBUST PCA

RPCA求解

For a 1000x1000 matrix of rank 50, with 10% (100,000) entries randomly corrupted: $\min \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = D.$

Algorithms	Accuracy	Rank	$\ E\ _0$	# iterations	time (sec)
IT	5.99e-006	50	101,268	8,550	119,370.3
DUAL	8.65e-006	50	100,024	822	1,855.4
APG	5.85e-006	50	100,347	134	1,468.9
APG _p	5.91e-006	50	100,347	134	82.7
EALM _p	2.07e-007	50	100,014	34	37.5
IALM _p	3.83e-007	50	99,996	23	11.8

10,000
times
speedup!

ROBUST PCA

应用

Background
Modeling

Video D



Low-rank appx. A



Sparse error E

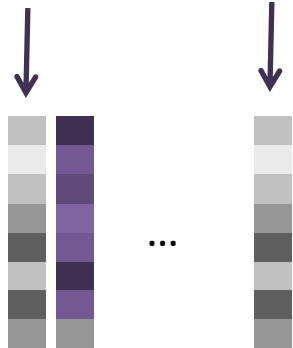


$$D = A + E$$

ROBUST PCA

Removing Shadows and Specularities from Face Images

58 images of one person under varying lighting:



D

$RPCA$



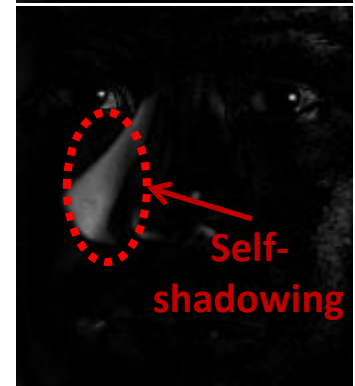
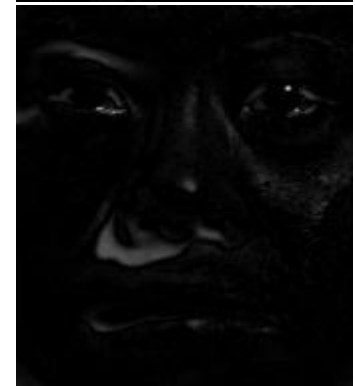
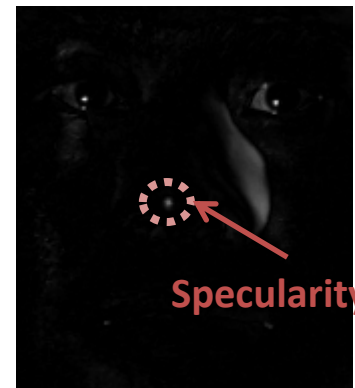
D



A



E

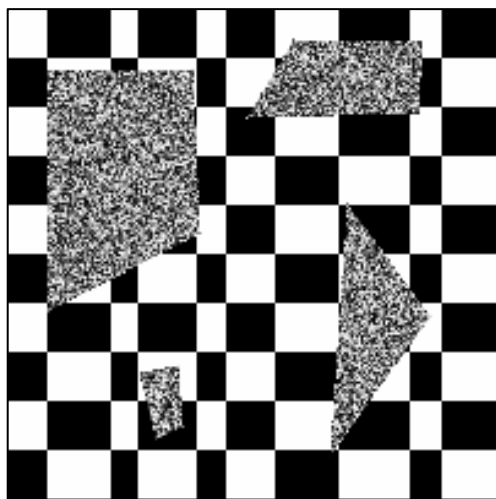


Specularity

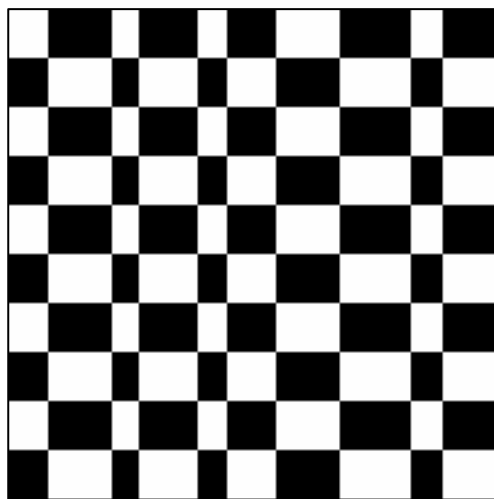
Self-shadowing

ROBUST PCA

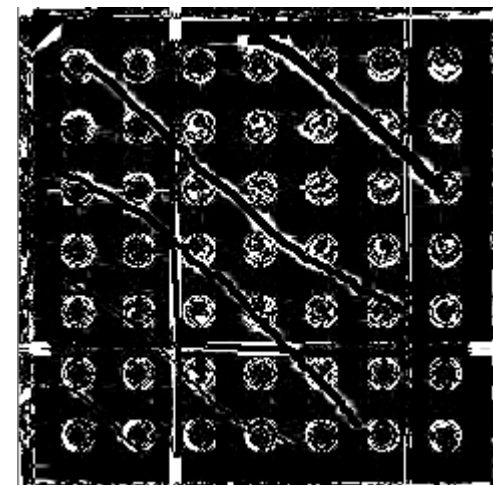
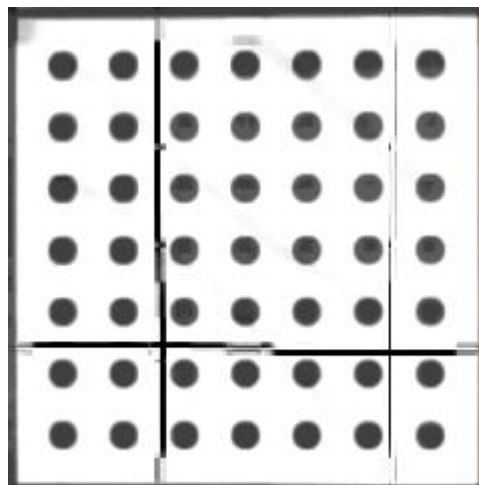
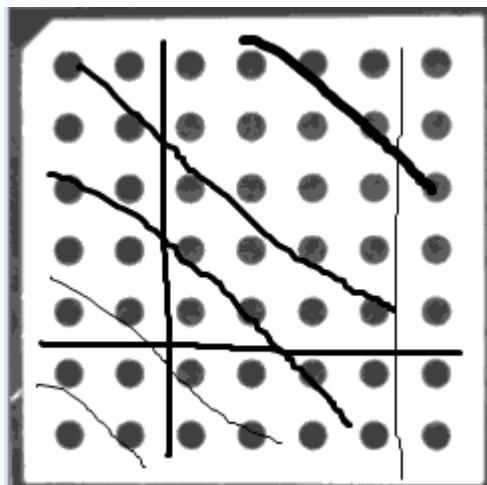
D



Low-rank Texture A

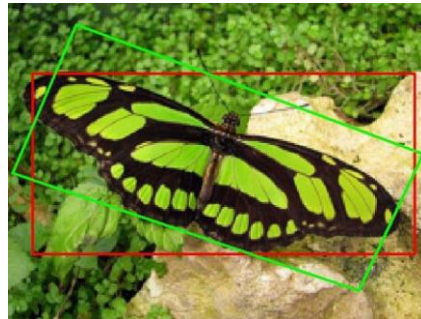
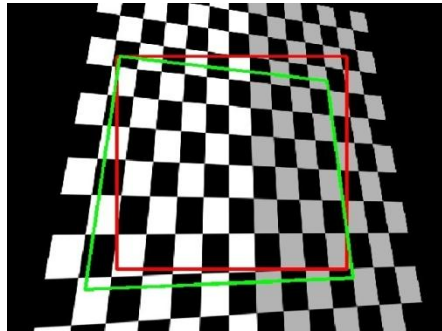


Corruptions E

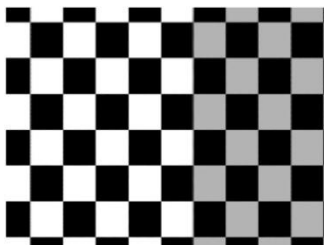


ROBUST PCA

Input (red window D)



Output (rectified green window A)



ROBUST PCA

参考:

[Prof. Yi Ma](#)

http://perception.csl.illinois.edu/matrix-rank/sample_code.html

[github](#)

<https://github.com/andrewssobral/lrslibrary>

[Optimization](#)

<http://www.stat.purdue.edu/~vishy/introml/notes/Optimization.pdf>

[Lagrange multiplier](#)

https://en.wikipedia.org/wiki/Lagrange_multiplier

[RPCA](#)

Robust Principal Component Analysis?

[IALM](#)

The Augmented Lagrange Multiplier Method for
Exact Recovery of Corrupted Low-Rank Matrices



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