# Formalizing the proof of an intermediate-level algebra theorem — An experiment

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**Abstract.** — Proof assistants are computer softwares that allow us to write mathematical proofs so as to assess their correctness. In November 2021, I started the project of checking the simplicity of the alternating groups within the Lean theorem prover and its mathlib library. This text aims at reviewing this experiment.

**Résumé.** — Les assistants de preuves sont des logiciels qui permettent de rédiger des démonstrations mathématiques et d'en garantir leur correction. En novembre 2021, j'ai débuté un projet de vérification de la simplicité des groupes alternés au sein de l'assistant de preuve Lean, et de sa librairie mathlib. Ce texte est un essai de compte rendu de cette expérience.

#### 1. Introduction

Human mathematics is written in plain language, and we all know examples of shortcomings that lead to "proofs" of wrong results. We also know for now more than hundred years ago, notably by the works of PEANO (1889) or WHITEHEAD & RUSSELL (1927), that mathematics can be written using axiomatic systems, and, at least in principle, in a rigid syntactic way, so as to avoid such problems, at least if the chosen axiomatic system does not lead to contradiction. I write "in principle", because this rigid syntactic writing is extremly verbose: It took hundreds of pages to Whitehead and Russell to prove that 1+1=2. One may find a pleasant, large audience, account of this quest in the comic book DOXIADIS & PAPADIMITRIOU (2009).

Since the 1950s, the development of computers led mathematicians to propose to use their mechanical force to develop fully formalized proofs of the mathematical corpus. Among such examples, let us mention N. G. De Bruijn's Automath (1967), A. Trybulec's Mizar (1973), G. Huet's team project Coq (1989), C. Coquand's Agda (1999) or L. de Moura's Lean (2013)...

In recent years, these softwares have allowed us to check delicate parts of the mathematical corpus: Appel and Haken's proof the Four color theorem (the regions delimited by a finite planar graph can be colored in four colors so that any two neighboring regions have different colors); Feit and Thompson's proof of the Odd order theorem (any finite group of odd cardinality is solvable), by GONTHIER (2008) and GONTHIER *et al* (2013), (both in Coq); Hales's proof of the Kepler conjecture (the standard, "cubic close", sphere packing is the densest one), by HALES *et al* (2017) (in HOL Light); following the challenge of SCHOLZE (2022), the proof of a

delicate homological algebra result of Clausen and Scholze (in Lean, the so called "Liquid tensor experiment", 2022, by COMMELIN and TOPAZ, with the help of many more people involved); or Gromov's proof of the h-principle and the sphere eversion theorem by MASSOT, VAN DOORN & NASH (2022), also in Lean.

Actually, the latter results were not formalized in plain Lean, but were built on the Lean mathematical library mathlib. Led by a group of approximately 25 people, plus some 15 reviewers, this mathematical library is an ongrowing effort of roughly 300 people, with (as today) approximately 45 000 definitions and 110 000 mathematical statements ("theorems") that cover many fields of mathematics, such as additive combinatorics, complex variables, differential geometry and Lebesgue integration... So that a collective effort is at all possible, the initial authors of mathlib had to make careful architecture and design decisions, described in (THE MATHLIB COMMUNITY, 2020). As Lean/mathlib is an open source project, it is also relatively easy to install it on one's own computer, and start joining this collective effort. This is also facilitated by a comprehensive website and an online discussion board where contributors share their problems and, remarkably generously, insights.

In November 2021, I embarked in checking in Lean/mathlib the proof that the alternating group of a finite set of cardinality at least 5 is a simple group. While this mathematical result is of a smaller scale, compared to the above-quoted accomplishements, it belongs to the classical (under)graduate mathematical corpus, and I felt interesting to experiment the formalization process on a result of this intermediate level. For reasons I will try to share, I chose a nonstandard way to do that, that led me to unsuspected mathematical territories.

This text is a retrospective account of this journey.

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# 2. Solvability, simplicity

Let us first recall the terms of the statement we have in mind.

**Theorem 2.1.** — Let n be an integer such that  $n \ge 5$ . The alternating group  $\mathfrak{A}_n$  is a simple group.

(For  $n \le 2$ , the group  $\mathfrak{A}_n$  is trivial; for n = 3, it is cyclic of order 3; for n = 4, it is a nonabelian solvable group of order 12, its derived subgroup is an abelian subgroup of index 3.)

In the Lean language, this theorem can be formulated as follows:

LISTING 1. Simplicity of the alternating groups of order at least five

```
theorem alternating_group.normal_subgroups \{\alpha : \text{Type}^*\}
  [decidable_eq \alpha] [fintype \alpha]
  (h\alpha : 5 \leq fintype.card \alpha)
  {N : subgroup (alternating\_group \alpha)}
  (hnN : N.normal) (ntN : nontrivial N) : N = T
```

The command theorem initiates a statement of a theorem, followed by the name given to it, here alternating\_group.normal\_subgroups, and followed by a sequence of arguments which are surrounded by various kinds of parentheses.

The first of these arguments,  $\alpha$ , is declared as a type, the basic notion of "dependent type theory", the formal language of Lean: in this case, one may think of  $\alpha$  as a set. The next arguments impose that it is also finite, and  $h\alpha$  is the assumption that it has at least five members. The next three parameters are N, which is declared as a subgroup of the alternating group on  $\alpha$ , hnN which imposes that it is a normal subgroup, and ntN that it is nontrivial (which, in the mathlib library, means that it is not reduced to the unit element).

The conclusion of that theorem follows the colon symbol: N = T, meaning that N is the full group of the alternating group. In the actual code, this 5-line text is followed by the symbol := and the actual *proof* of this statement.

Every object of type theory is a type, and what Lean does is allowing the user to write down new types, or members of those types. For example, in the example above N is a member of the type subgroup (alternating\_group  $\alpha$ ). Lean provides a few basic means to define new types from older; for example, if  $\alpha$  and  $\beta$  are types, there is a type  $\alpha \to \beta$  which represents "functions" from  $\alpha$  to  $\beta$ , in the sense that if  $f: \alpha \rightarrow \beta$  is such a function and  $a: \alpha$  (read: "a is a member of the type  $\alpha$ "), then f a is a member of the type  $\beta$ , with obvious rules regarding equality. Functions of multiple arguments can be defined "à la Curry": for example, if  $\alpha$ ,  $\beta$  and  $\gamma$  are types, then  $f : \alpha \to \beta \to \gamma$  maps  $a : \alpha$  to  $f a : \beta \to \gamma$ , which maps  $b : \beta$  to fa b :  $\gamma$ , etc. Even the expression N =  $\top$  of listing 1 designates a type, namely, the type of proofs of equality between the two members N and  $\top$  of the type subgroup (alternating\_group  $\alpha$ ), and the (omitted) code that follows constructs a member of that type, that is, a proof of that statement: type theory puts mathematical structures and theorems on the same level.

Simple groups are those (nontrivial) groups whose only normal subgroups are the two obvious examples, the full group and trivial group {e}. When a nontrivial group G is not simple, it admits a normal subgroup H such that  $H \neq \{e\}$  and  $H \neq G$ ; then one can (try to) study G through its projection to the quotient group G/H, whose kernel is H. When we restrict ourselves to finite groups, a full "dévissage" is possible and a common metaphor presents finite simple groups as the "elementary particles" of finite group theory. In this direction, a legendary theorem whose proof involved hundreds of mathematicians and hundreds of mathematical papers written over

a period of 50 years, is the classification of finite simple groups: All finite simple groups appear in a list of groups of the following form:

- The cyclic group  $\mathbf{Z}/p\mathbf{Z}$ , for some prime number p;
- The alternating group  $\mathfrak{A}_n$ , for some integer  $n \ge 5$ ;
- Lists of finite groups "of Lie type", related to linear algebra over finite fields, whose easiest examples consist of the projective special linear groups  $PSL(n, \mathbf{F}_q)$  over a finite field of cardinality q, assuming  $q \ge 4$  if n = 2 ( $PSL(2, \mathbf{F}_2)$ ) and  $PSL(2, \mathbf{F}_3)$  are respectively isomorphic to  $\mathfrak{S}_3$  and  $\mathfrak{A}_4$ , hence are not simple);
- A list of 26 (so called "sporadic") groups, related to exceptional combinatorial geometries, such as the Matthieu groups  $M_{11}$ ,  $M_{12}$ ,  $M_{22}$ ,  $M_{23}$  and  $M_{24}$ .

The difficult part of the classification of finite simple groups asserts that those finite groups are the only simple groups, but we are only concerned here by the easy part of the classification, that these groups are indeed simple.

The first ones, cyclic groups of prime order, are simple: it follows from Lagrange's theorem (the order of a subgroup divides the order of the group) that they have no other subgroup than themselves and the trivial subgroup.

As an aside remark, let us note that the center Z(G) of a group G, the set of elements  $g \in G$  which commute with any other element of G, is also a normal subgroup. Consequently, if G is simple, then either Z(G) = G, in which case G is commutative, hence a cyclic group of prime order, or  $Z(G) = \{e\}$ . This explains why, from the second item on, all groups of the above list have trivial center.

On the second item of that list come the alternating groups, which are the very subject of this note, and whose simplicity is often established in algebra lectures related to Galois theory and the solvability of algebraic equations (in one variable). While Abel and Ruffini had proved that general algebraic equations of degree  $\geq 5$  cannot be solved by radicals, Galois's theorem refines that result by proving that a given algebraic equation is solvable by radicals if and only if its Galois group is solvable. The notion of a group of an equation was introduced by Galois, as well as the notion of a normal subgroup and of solvable group, although he did not give a name to these two concepts: the Galois group is the subgroup of the permutations of the roots that preserve all algebraic relations with rational coefficients; and a finite group G is solvable if it is trivial or if, by induction, it admits a nontrivial normal subgroup H which is itself solvable and such that the quotient group G/H is commutative. In modern terms, we say that a group G is solvable if its "derived series" G,D(G),D(D(G))..., the decreasing sequence of subgroups obtained by successively taking commutator subgroups, eventually reaches the identity subgroup.

In that perspective, the Abel–Ruffini theorem boils down to the fact that a general equation of degree n has Galois group the full symmetric group  $\mathfrak{S}_n$ , and that, for  $n \geq 5$ , it is not solvable, itself a direct consequence of the following more precise result.

**Proposition 2.2.** — Let n be an integer such that  $n \ge 5$ . The commutator subgroup of  $\mathfrak{S}_n$  is the alternating group  $\mathfrak{A}_n$ . The commutator subgroup of the alternating group  $\mathfrak{A}_n$  is itself.

*Proof.* — Any commutator has signature 1, so that  $D(\mathfrak{S}_n) \subseteq \mathfrak{A}_n$ . On the other hand, a commutator of two transpositions (a b) and (c d) is trivial if they are equal or have disjoint supports, but is equal to a 3-cycle otherwise, as the following computation shows

$$(a b)(c a)(a b)(c a) = (a b c).$$

We see that any 3-cycle can we written as a commutator, so that  $D(\mathfrak{S}_n)$  contains all 3-cycles, which are known to generate the alternating group  $\mathfrak{A}_n$ . (This works for  $n \ge 3.$ 

To prove that  $D(\mathfrak{A}_n)$  is  $\mathfrak{A}_n$  itself, we prove that the quotient group  $K = \mathfrak{A}_n/D(\mathfrak{A}_n)$ is trivial. The group  $\mathfrak{A}_n$  is generated by 3-cycles g, so their images generate K. The hypothesis  $n \ge 5$  implies that all 3-cycles are conjugate in  $\mathfrak{A}_n$ ; consequently, they all have the same image in K, say k, and  $K = \langle k \rangle$ . Since the square of a 3-cycle g = (abc) is again a 3-cycle, namely  $g^2 = (acb)$ , one has  $k = k^2$ , hence k = e and  $K = \{e\}.$ 

The relation with simplicity is that noncommutative solvable groups cannot be simple. In fact, it is an elementary observation that the commutator subgroup D(G) of any group G is a normal subgroup of G; if G is simple, then either  $D(G) = \{e\}$ , which means that G is commutative, or D(G) = G. So Galois's theorem on algebraic equations of degree  $\geq 5$  is often subsumed in mentioning that the alternating group  $\mathfrak{A}_n$  is simple for  $n \geq 5$ , although the result which is needed is the easier proposition given above.

It is sometimes written that Galois proved that simplicity theorem, although the only explicit statement I could find in his works is the fact that the smallest possible cardinality of a simple (noncommutative) finite group (he says "indecomposable") is  $5\cdot 4\cdot 3$ , but he does not state that it corresponds to the alternating group  $\mathfrak{A}_5$ . On the other hand, group theorists of the 19th century, from Lagrange and Ruffini to Jordan, gradually built the tools to understand Galois's theorem in terms of the simplicity of the alternating group.

There are many relatively easy proofs of the simplicity of  $\mathfrak{A}_n$  for  $n \ge 5$ , such as, for example, the one given by (JACOBSON, 1985, p. 247), but none of them looks as being completely straightforward, in the sense that they do not tell why they work. Moreover, some of them build on case disjunctions, or mental reasonings which, although they are quite familiar to us, remain a bit awkward to specify exactly, to the point that I am not even sure that our explanations suffice to our students.

So my initial idea was to find a proof that would be of a more systematic nature, using arguments that are more prone to generalization. The principle of such a proof, already hinted to in the book of WILSON (2009), is given by the Iwasawa criterion, to which I now turn.

### 3. The Iwasawa criterion for simplicity

IWASAWA (1941) proposed a proof of the simplicity of the projective special linear group PSL(n,F) of a field F of cardinality at least 4. Before that, this theorem was limited to the case of finite fields (Dickson) or fields of characteristic  $\neq 2$  (van der Waerden). From that proof, the following geometric criterion can be extrated.

**Theorem 3.1.** — Let a group G act on a set X, and assume that we are given, for every  $x \in X$ , a subgroup T(x) of G, such that the following properties hold:

- For every  $x \in X$ , the group T(x) is commutative;
- For every  $g \in G$  and every  $x \in X$ , one has  $T(g \cdot x) = gT(x)g^{-1}$ ;
- The groups T(x) generate G.

If, moreover, the action of G on X is quasiprimitive, then any normal subgroup N of G that acts nontrivially on X contains the commutator subgroup D(G) of G.

An action of a group G on a set X is said to be *quasiprimitive* if any normal subgroup of G which acts nontrivially on X acts transitively. This property may look obscure, but it appears naturally in the framework of *primitive* actions, a classic theme of 19th century group theory which remained very important in finite group theory but seems to have disappeared from the algebra package we offer to undergraduate students. Let us define it in terms of partitions of X (sets of nonempty disjoint subsets of X whose union is X):

**Definition 3.2.** — A transitive action of a group G on a set X is primitive if there are exactly two partitions of X which are invariant under G, the coarse partition {X} and the discrete partition consisting of all singletons.

In particular, this definition implies that the set X has at least two elements.

If H is a normal subgroup of X, then the partition of X in orbits of H is an invariant partition; consequently, if the action of X is primitive, then either H acts trivially, or it acts transitively: for every  $x, x' \in X$ , there exists  $h \in H$  such that  $h \cdot x = x'$ . This shows that primitive actions are quasiprimitive.

Higher transitivity conditions give important examples of primitive actions.

**Lemma 3.3.** — Let us assume that the action of G is 2-fold transitive: X has at least two elements and for any two pairs (x, y) and (x', y') of distinct elements of X, there exists  $g \in G$  such that  $g \cdot x = x'$  and  $g \cdot y = y'$ . Then this action is primitive.

The proof is elementary: consider an element B of a partition  $\Sigma$  of X which has at least two elements x,y and let us show that B=X. Let  $z\in X$  be such that  $z\neq x,y$ . By the 2-fold transitivity condition applied to (x,y) and (x,z), there exists  $g\in G$  such that  $g\cdot x=x$  and  $g\cdot y=z$ . The set  $g\cdot B$  belongs to  $\Sigma$  but has a common point with B, namely x, so that  $g\cdot B=B$ . In particular,  $z\in B$ . This proves that B=X.

We just observed that members of a G-invariant partition are subsets B of X such that either  $g \cdot B \cap B = \emptyset$  or  $g \cdot B = B$ ; in the traditional terminology of group theory, they are called *blocks*, and blocks which are neither empty, nor singletons, nor the full sets are called *blocks of imprimitivity*. Conversely, if B is a nonempty block and

if the action is transitive, then the set of all  $g \cdot B$ , for  $g \in G$ , gives a G-invariant partition of X.

As an example of a transitive, but not primitive action, one may consider the action of  $\mathfrak{S}_4$  on the set of pairs of elements of  $\{1,2,3,4\}$ : in this case, there are nontrivial blocks, such as  $B = \{\{1,2\},\{3,4\}\}$ . In fact, we will have to meet this example later, and some variants of it.

The terminology "primitive" comes from Galois, in the language of equations: as explained by (NEUMANN, 2006, p. 390), when the Galois group G of an irreducible polynomial equation f(x) = 0 acts on its roots, there are m blocks of size n if and only if there is an auxiliary equation of degree m the adjunction of one root of which allows f to be factored as  $f_1f_2$ , where  $f_1$  has degree n.

The Lean definitions follow these descriptions, see listing 2, with a few adjustments to follow the general mathlib conventions.

LISTING 2. Blocks, primitive actions

```
variables (G : Type*) {X : Type*} [has_smul G X]
/-- A trivial block is a subsingleton or ⊤ (it is not necessarily a
   ...block)-/
def is_trivial_block (B : set X) := B.subsingleton V B = T
/-- A block is a set which is either fixed or moved to a disjoint subset
def is_block (B : set X) := (set.range (\lambda g : G, g ·
   B)).pairwise_disjoint id
/-- An action is preprimitive if it is pretransitive and
the only blocks are the trivial ones -/
class is_preprimitive
extends is_pretransitive G X : Prop :=
(has_trivial_blocks' : ∀ {B : set X}, (is_block G B) → is_trivial_block
   B)
```

First of all, definitions are always given under very minimal hypotheses, one idea being that they could serve in more general contexts than the ones that are generally considered, so as to avoid the need for infinite variations of otherwise identical proofs. Another principle to have definitions as general as possible is that changing a definition later on requires to adjust all theorems that refer to it, a painful and long task. In our case, "actions" of a type G on another type X just presumes a map  $G \to X \to X$  embodied in the predicate has\_smul G X, and then denoted by the symbol, not even requiring that G has an inner multiplicative structure! It is reminiscent of the "groups with operators" introduced in the first chapter of (BOURBAKI, 1998) with a similar intention.

Then a "subset" B of X (something called set X) is a block if and only if the sets g · B, for g in X, are pairwise equal or disjoint. The (possibly) obscure definition makes use of mathlib's general predicate set.pairwise\_disjoint.

Trivial blocks are detected by the predicate is\_trivial\_block, defined as either "subsingletons" (the empty set or a singleton, with definition " $\forall x, y \in B, x = y$ ") or the full set  $\top$ .

Another mathlib idiosyncracy that appears in the definitions above is the concept of "pretransitive" actions, meaning "transitive but possibly empty". Again, the idea is to defer the non-emptiness hypotheses to the statements that actually and explicitly need them. We thus define an action to be preprimitive if it is pretransitive and if all blocks are trivial.

In what follows, it will be important to use the following equivalent characterization of primitive actions. (Recall that the fixator  $G_x$  of an element x in X is the subgroup of G consisting of all  $g \in G$  such that  $g \cdot x = x$ .)

**Lemma 3.4.** — The action of G on X is primitive if and only if it is transitive and if for every  $x \in X$ , its fixator  $G_x$  is a maximal<sup>(1)</sup> subgroup of G.

More generally, one can show that for any  $x \in X$ , the mapping  $H \mapsto H \cdot x$  induces an order preserving bijection from the lattice of subgroups H of G such that  $G_x \subseteq H \subset G$ to the lattice of blocks B in X that contain x. We copied in listing 3 the Lean definition of this order preserving bijection (in fact, its inverse): it takes the form of an "order equivalence" of types, as indicated by the symbols  $\simeq$ 0. The first type, { B :set X //  $a \in B \land is_block G B$ }, is the type of all B : set X (basically, subsets of X) satisfying the properties that a ∈ B and is\_block G B, the latter type encoding that B is a block for the action of G on X (which could be left implicit, because B being of type set X, this type is known). Lean is capable to guess by itself that this type inherits the ordering relation given by inclusion on set X. The second type, set. Ici (stabilizer G a), designates, in the lattice subgroup G, the subset of those subgroups containing stabilizer G a. This "order equivalence" consists of two functions, to\_fun and inv\_fun, proofs (left\_inv and right\_inv) that they are inverse of each other, and a proof (map\_rel\_iff) that they respect the order. Then comes the definition of the function to\_fun, which maps such a B, together with the witnesses ha : a ∈ B and hB : is\_block G B, to stabilizer G B, accompanied with stabilizer\_of\_block hB ha. As one can guess, the former designates the stabilizer of B in G, together with the additional information that it contains stabilizer G a. That information is provided by the function stabilizer\_of\_block : is\_block G  $B \to a \in B \to stabilizer G a \leq stabilizer G B whose code, of course, had been$ given earlier in the source. The inverse function inv\_fun maps H : subgroup G together with hH : stablizer G a ≤ H to mul\_action.orbit H a which represents the orbit of a under the action of the subgroup H, together with the relevant proofs that this set contains a and is a block. Then come three proofs, left\_inv and right\_inv stating that the two preceding functions are inverse of each other, while map\_rel\_iff states that they respect the order relation. In the listing showed there, we replaced

<sup>&</sup>lt;sup>(1)</sup>Recall that a subgroup H of G is maximal if  $H \neq G$  and if any subgroup H' of G containing H is H or G.

these three proofs by ...; the codes of the first two ones are 2-line long, that of the third one is 17-line long.

LISTING 3. Order equivalence between blocks containing a point and subgroups containing its stabilizer

```
variables {G: Type*} [group G] {X : Type*} [mul_action G X]
/-- Order equivalence between blocks in X containing a point a
and subgroups of G containing the stabilizer of a
 (Wielandt, Finite Permutation Groups, th. 7.5)-/
def stabilizer_block_equiv [htGX : is_pretransitive G X] (a : X) :
  { B : set X // a \in B \land is_block G B } \simeqo set.Ici (stabilizer G a) := {
to_fun := \lambda (B, ha, hB), (stabilizer G B, stabilizer_of_block hB ha),
inv_fun := \lambda (H, hH), (mul_action.orbit H a,
  mul_action.mem_orbit_self a, is_block_of_suborbit hH>,
left_inv := ...,
right_inv := ...,
map_rel_iff' := ...,
end }
```

#### **3.5.** — We end this section with a proof of the Iwasawa criterion (theorem 3.1).

Fix a point  $a \in X$ . We first prove that the subgroup  $\langle N, T(a) \rangle$  generated by N and T(a) is equal to G. By assumption, N acts transitively on X. Since N is normal, the hypothesis that the action is quasiprimitive implies that for every  $b \in X$ , there exists  $n \in \mathbb{N}$  such that  $n \cdot a = b$ . Since  $nT(a)n^{-1} = T(b)$ , this implies that  $(\mathbb{N}, T(a))$ contains T(b). Since b is arbitrary, the subgroup  $\langle N, T(a) \rangle$  contains the subgroup generated by all T(x), for  $x \in X$ , which, by assumption, is G.

The subgroup N is normal; the desired conclusion that it is contains the derived subgroup of G is equivalent to the commutativity of the quotient G/N. Since  $\langle N, T(a) \rangle = G$ , the composition  $T(a) \to G \to G/N$  is surjective; since T(a) is commutative, we conclude that G/N is commutative, as we wished to.

#### 4. Normal subgroups of symmetric and alternating groups

In this section, we consider an integer n; we generally assume that  $n \ge 5$ .

The symmetric group  $\mathfrak{S}_n$  acts not only on the set  $X = \{1, ..., n\}$ , but also on the sets  $X^{[k]}$  of k-element subsets of X, for any integer k such that  $0 \le k \le n$ . The action is trivial if k = 0 or k = n, because then  $X^{[k]}$  is reduced to a single element, but it is faithful otherwise: any element  $g \neq e$  acts nontrivially. The following proposition asserts that this action is moreover primitive, unless n = 2k.

**Proposition 4.1.** — Let k and n be integers such that 0 < k < n - k < n. If  $4 \le n$ , then the actions of  $\mathfrak{A}_n$  and  $\mathfrak{S}_n$  on  $X^{[k]}$  are primitive.

Given this primitivity result, the approach of Iwasawa allows us to understand the normal subgroups of the symmetric and alternating groups. We will only need to use the cases k = 2, k = 3 and k = 4.

**4.2.** Let us first consider the case k=2. For any 2-element subset  $x=\{a,b\}$  of X, let us consider the subgroup T(x) generated by the transposition (ab): it is commutative of order 2; the relation  $(g \cdot a g \cdot b) = g(ab)g^{-1}$  implies that these subgroups satisfy the relation  $T(g \cdot x) = gT(x)g^{-1}$ ; and since  $\mathfrak{S}_n$  is generated by all transpositions, they generate the symmetric group. Consequently, Iwasawa's criterion implies that if this action is primitive, then any normal subgroup N of  $\mathfrak{S}_n$  such that  $N \neq \{e\}$  contains  $D(\mathfrak{S}_n)$ , which as we have seen, is equal to  $\mathfrak{A}_n$ . Since  $\mathfrak{S}_n/\mathfrak{A}_n$  has order 2, the only subgroups of  $\mathfrak{S}_n$  that contain  $\mathfrak{A}_n$  are  $\mathfrak{A}_n$  and  $\mathfrak{S}_n$ .

What about the primitivity assumption? Note that the action of  $\mathfrak{S}_n$  on  $X^{[2]}$  is not 2-fold transitive, because one cannot map  $\{1,2\}$  and  $\{1,3\}$  to the sets  $\{1,2\}$  and  $\{3,4\}$ . Let us observe that it is nevertherless primitive; here, we will use that 2 < n-2, that is, n > 4. (WILSON, 2009, §2.5.1) shows that the fixator of any element of  $X^{[2]}$  is a maximal subgroup, and we will discuss this in greater generality in the next section, but let me tell right now the following proof as explained to me by G. Chenevier.

Let B be an imprimitivity block of  $X^{[2]}$ , and let  $\{a,b\}$  be a pair in B.

First assume that B contains another pair of the form  $\{a,c\}$ . Consider  $g \in G$  such that  $g \cdot a = c$  and  $g \cdot b = a$ ; then B and  $g \cdot B$  share the element  $\{a,c\}$ , so that  $g \cdot B = B$ ; consequently, B contains the pair  $\{g \cdot a, g \cdot c\} = \{c, g \cdot c\}$ , hence all pairs of the form  $\{c,d\}$ . Redoing the argument from  $\{a,c\}$  and  $\{c,d\}$  we deduce that B contains any pair, hence  $B = X^{[2]}$ .

Assume then that B contains a pair  $\{c,d\}$  which is disjoint from  $\{a,b\}$ . Since  $n \ge 5$ , we may consider a fifth element e in X; let us prove that  $\{c,e\} \in B$ . Indeed, there exists  $g \in \mathfrak{S}_n$  which maps a to a, b to b, c to c and d to e, hence  $\{a,b\}$  to itself, and  $\{c,d\}$  to  $\{c,e\}$ ; then B and  $g \cdot B$  have  $\{a,b\}$  in common, so that  $g \cdot B = B$  and  $\{c,e\} \in B$ . In particular, B contains two pairs  $\{c,d\}$  and  $\{c,e\}$  whose supports are not disjoint and the first part of the argument implies that  $B = X^{[2]}$ .

We thus obtain the following result (also a consequence of theorem 2.1).

# **Proposition 4.3.** — For $n \ge 5$ , the normal subgroups of $\mathfrak{S}_n$ are $\{e\}$ , $\mathfrak{A}_n$ and $\mathfrak{S}_n$ .

**4.4.** — We now pass to k=3. For any 3-element set  $x=\{a,b,c\}$  in X, we consider the alternating group T(x) of these three elements, viewed as a subgroup of  $\mathfrak{A}_n$ ; it is the subgroup generated by the 3-cycle  $(a\,b\,c)$ . As above, the relations  $T(g\cdot x)=gT(x)g^{-1}$  hold, and these subgroups generate the alternating group. Assuming that the action of  $\mathfrak{A}_n$  on  $X^{[3]}$  is primitive, we deduce from Iwasawa's criterion that any normal subgroup of  $\mathfrak{A}_n$  either is trivial, or contains  $D(\mathfrak{A}_n)$ ; in other words,  $\mathfrak{A}_n$  is simple.

We shall see in the next section that the primitivity condition holds for  $n \neq 6$  (and why it does not for n = 6), so the case n = 6 requires another argument.

**4.5.** — For this, let us consider k = 4. For any 4-element set  $x = \{a, b, c, d\}$  in X, let us consider Klein's Vierergruppe V(x) in the alternating group of these four elements, viewed as a subgroup of  $\mathfrak{A}_n$ . It is commutative of order 4, and consists of the identity and of the three "double transpositions" (a b)(c d), (a c)(b d) and

(ad)(bc). This is already an intrinsic definition of V(x) (permutations with support in x whose cycle type is either empty or (2,2); it can also be defined as the derived subgroup of the alternating group on these four elements. Consequently, the relations  $V(g \cdot x) = gV(x)g^{-1}$  hold. Let us show that these subgroups V(x) generate  $\mathfrak{A}_n$ ; the argument will use that  $n \ge 5$ . We start from the remark that  $\mathfrak{A}_n$ consists of permutations which are products of an even number of transpositions. If two successive transpositions in such a product have disjoint supports, they belong to some V(x). Otherwise, if their supports share an element a, say (a b)(a c), then using that  $n \ge 5$ , we can insert a cancelling product (d e)(d e), so that (a b)(d e) and (de)(ac) belong to subgroups of the form V(x).

Applying Iwasawa's criterion, this construction shows that the alternating group  $\mathfrak{A}_n$  is simple as soon as the action of  $\mathfrak{A}_n$  on  $X^{[4]}$  is primitive.

**4.6.** — We note that a variant of these arguments leads to a reasonably simple proof of the simplicity of  $\mathfrak{A}_5$ . Indeed, by taking complements, the action of  $\mathfrak{A}_n$  on  $X^{[k]}$  is isomorphic to the action on  $X^{[n-k]}$ . When n=5, the case k=4 is reduced to the case k = 1 and it suffices to prove that the action of  $\mathfrak{A}_5$  on X is primitive. To that aim, it suffices to observe that the action of  $\mathfrak{A}_5$  is 2-transitive. (In fact, it is even 3-transitive.)

## 5. Primitivity and maximal subgroups

To conclude the proof of theorem 2.1, it remains to explain the proof of proposition 4.1. The fixator of the element  $\{1,\ldots,k\}$  of  $X^{[k]}$  is the intersection of  $\mathfrak{A}_n$  with the subgroup  $\mathfrak{S}_k \times \mathfrak{S}_{n-k}$  associated with the partition of  $\{1,\ldots,n\}$  in  $\{1,\ldots,k\}$  and  $\{k+1,\ldots,n\}$ . Since the action of  $\mathfrak{A}_n$  on  $X^{[k]}$  is transitive, lemma 3.4 reduces us to prove that this subgroup is a maximal subgroup of  $\mathfrak{A}_n$ .

In this way, we note that the hypothesis  $n \neq 2k$  is really necessary for this proposition: the subgroup  $\mathfrak{S}_n \times \mathfrak{S}_n$  of  $\mathfrak{S}_{2n}$  is not maximal, it is a subgroup of index 2 of the stabilizer of the partition  $\{\{1,\ldots,n\},\{n+1,\ldots,2n\}\}$ , a group also described as the wreath product  $\mathfrak{S}_n \wr (\mathbf{Z}/2\mathbf{Z})$ .

**5.1.** — In §4.2, we saw an elementary proof of proposition 4.1 for k=2 and  $n \ge 5$ , and it seems likely that an elementary proof exists for any k. R. Rouquier gave me one that works for k = 3 and  $n \ge 7$ . However, I want to describe another approach, explained to me by M. Liebeck, that I think emphasizes the status of that proposition within finite group theory.

One of the first treatises on group theory is that of JORDAN (1870). Then groups were "permutation groups", permuting letters, (henceforth algebraic expressions on these letters), or, since the connection with the Galois theory of equations was explicit, roots of a polynomial equation.

It had been observed that the symmetric group on n letters is n-fold transitive almost by definition, given two systems of distinct elements in  $\{1, ..., n\}, x_1, ..., x_n$  and  $y_1, ..., y_n$ , say, there is a permutation g such that  $g \cdot x_i = y_i$  for all i, and g is even unique.

Only slightly less obvious was the fact that the alternating group on n letters is (n-2)-fold transitive: given distinct systems  $x_1, \ldots, x_{n-2}$  and  $y_1, \ldots, y_{n-2}$ , there are exactly two permutations g, g' such that  $g \cdot x_i = g' \cdot x_i = y_i$  for all i, and  $g'g^{-1}$  is the permutation that exchanges the two elements of  $\{1, \ldots, n\}$  not in  $\{y_1, \ldots, y_{n-2}\}$ ; in particular, one of them is even and the other is odd.

It had also been observed that beyond these two cases, a permutation subgroup on n letters has to act much less transitively and 19th century mathematicians proved many theorems that aimed at quantifying this limit. For example, Mathieu had proved that unless it contains the alternating group, a subgroup of  $\mathfrak{S}_n$  isn't n/2-fold transitive, while JORDAN (1872) proved that it isn't m-fold transitive if n-m is a prime number > 2.

As explained in CAMERON (1981), once the classification of simple finite groups had been achieved, it could be checked on the list that a 6-fold transitive subgroup of  $\mathfrak{S}_n$  must be symmetric or alternating.

Parallel to the classification is the understanding of all maximal subgroups of a given finite simple group. In the case of the alternating group, an explicit list has been provided independently by M. O'Nan and L. Scott. As remarked by CAMERON (1981), this question is closely related to the description of all subgroups of the symmetric group  $\mathfrak{S}_n$  which act primitively on  $\{1, \ldots, n\}$ .

This classification theorem takes the given form: Let G be a strict subgroup of  $\mathfrak{A}_n$  or  $\mathfrak{S}_n$ ; then G is conjugate to a subgroup of one of six types of which the first three take the form:

- (a) A product  $\mathfrak{S}_m \times \mathfrak{S}_{n-m}$ , where 0 < m < n the *intransitive case*.
- (b) The "wreath product"  $\mathfrak{S}_m \wr \mathfrak{S}_p$ , where n = pm, namely the subgroup generated by the product of p symmetric groups acting on p disjoint sets of m letters (isomorphic to  $\mathfrak{S}_m \times \cdots \times \mathfrak{S}_m$ ), and a permutation that permutes cyclically these p sets the *imprimitive case*;
- (c) An *affine group* of an  $\mathbf{F}_p$ -vector space of dimension d, where  $n = p^d$  is the power of a prime number.

It applies in particular to maximal subgroups, and LIEBECK et~al~(1987) established the converse assertion, deciding which of the groups of this list are maximal. That case (a) is maximal when  $m \neq n-m$  is exactly the statement of proposition 4.1. However, when n=2m, case (a) is not maximal but case (b) gives the corresponding maximal case. For n=4, for example, the subgroup given by (b) has order 8, hence is a 2-sylow subgroup of  $\mathfrak{S}_4$ , while the subgroup  $\mathfrak{S}_2 \times \mathfrak{S}_2$  has order 4.

Cases of the form (c) were of particular interest to Galois, who proved that they appear for the Galois groups of irreducible equations of prime degree which are solvable by radicals. In other words, solvable and transitive subgroups of  $\mathfrak{S}_p$  can be viewed, up to conjugacy, as a group of permutations of the form  $x \mapsto ax + b$  on  $\mathbf{F}_p$ , for  $a \in \mathbf{F}_p^{\times}$  and  $b \in \mathbf{F}_p$ . Since the identity is the only permutation of that form that fixes two elements, Galois obtains that an irreducible equation of prime degree is

solvable by radicals if and only if any of its roots can be expressed rationally by any two of them.

Galois also defined primitive algebraic equations which correspond exactly to the case where the Galois group acts primitively on their roots. In the solvable case, he proved that the degree has to be a power  $p^n$  of a prime number p and, up to an enumeration of the vector space  $\mathbf{F}_p^n$ , the Galois group G is a subgroup of the group of permutations of the form  $x \mapsto Ax + b$ , for  $A \in GL(n, \mathbb{F}_p)$  and  $b \in \mathbb{F}_p^n$ , that contains all translations  $x \mapsto x + b$ . Moreover, the subgroup  $G_0$  of  $GL(n, \mathbf{F}_p)$  consisting of all elements of G of the form  $x \mapsto Ax$  has no nontrivial invariant subspace. The interested reader shall find more details on this fascinating story in chapter 14 of Cox (2012).

**5.2.** — But let us go back to the promised proof of proposition 4.1. Let G be a subgroup of  $\mathfrak{A}_n$  strictly containing  $(\mathfrak{S}_k \times \mathfrak{S}_{n-k}) \cap \mathfrak{A}_n$ , where 0 < k < n and  $n \neq 2k$ . We need to prove that G coincides with  $\mathfrak{A}_n$ . By symmetry, we may assume that k < n - k. The case k = 1 is easy. Indeed, the action of  $\mathfrak{A}_n$  on  $\{1, \ldots, n\}$  is (n - 2)-fold transitive, hence it is 2-fold transitive, because  $n \ge 4$ , hence it is primitive. We now assume that  $2 \le k$ ; then  $n \ge 5$ .

A theorem of (JORDAN, 1870, Note C to §398, page 664) asserts that a primitive subgroup of  $\mathfrak{S}_n$  that contains a cycle of prime order p is at least (n-p+1)-fold transitive. When p = 2, we get that this subgroup is (n - 1)-fold transitive, hence it has to be the whole  $\mathfrak{S}_n$ , while when p=3, it is (n-2)-fold transitive, and it is not too difficult to deduce that it contains  $\mathfrak{A}_n$ . Since  $1 \le k < n - k < n$  and  $n \ge 5$ , we have  $n-k \ge 3$  and our subgroup G contains a 3-cycle. To conclude, it remains to establish that it acts primitively on  $\{1, \ldots, n\}$ .

One first proves that G acts transitively on  $\{1, ..., n\}$ . In fact, G contains the subgroups  $\mathfrak{S}_k$  and  $\mathfrak{S}_{n-k}$ ; in particular, it acts transitively on the elements of each subset  $\{1,\ldots,k\}$  and  $\{k+1,\ldots,n\}$ , hence it has at most two orbits. But since it strictly contains  $(\mathfrak{S}_k \times \mathfrak{S}_{n-k}) \cap \mathfrak{A}_n$ , it cannot leave  $\{1,\ldots,k\}$  and  $\{k+1,\ldots,n\}$  invariant.

Arguing as for transitivity, G acts k-fold transitively on  $\{1, ..., k\}$  and (n - k)-fold transitively on  $\{k+1,\ldots,n\}$ ; since  $2 \le k < n-k$ , it acts in particular 2-fold transitively, hence primitively, on both of these sets.

We consider imprimitivity blocks B for the action of G, assuming that they have at least two elements and are distinct from  $\{1, ..., n\}$ .

First observe that B cannot contain  $\{k+1,\ldots,n\}$ , because its translates  $g \cdot B$ , for  $g \in B$  such that  $g \cdot B \neq B$ , would have to be contained in  $\{1, \ldots, k\}$ , which is impossible since k < n - k. In particular, B meets  $\{k + 1, ..., n\}$  in at most one element. If it is disjoint from  $\{k+1,\ldots,n\}$ , it is contained in  $\{1,\ldots,k\}$ . Since G acts primitively on  $\{1,\ldots,k\}$ , one then has  $B=\{1,\ldots,k\}$ . Consider an element g of G which does not stabilize  $\{1,\ldots,k\}$ . Then  $g\cdot B$  is a block distinct from B, hence disjoint, so that  $g\cdot B$ is a block contained in  $\{k+1,\ldots,n\}$ . By primitivity,  $g\cdot B=\{k+1,\ldots,n\}$ , contradicting the beginning of the proof.

In particular, there are elements  $a \in \{1, ..., k\} \cap B$  and  $b \in \{k+1, ..., n\} \cap B$ . To conclude the proof by a contradiction, it suffices to establish that B contains  $\{k+1,\ldots,n\}$ . So let  $c \in \{k+1,\ldots,n\}$  and consider an element  $g \in G$  that fixes  $\{1,\ldots,k\}$  such that  $g \cdot b = c$ . Then  $g \cdot B$  and B both contain a, hence  $g \cdot B = B$ , hence  $c \in B$ , as was to be shown.

# 6. Intermezzo: conjugacy classes in symmetric groups

At the end, the proof of the simplicity theorem of the alternating group  $\mathfrak{A}_6$  required a discussion of the Klein subgroup of  $\mathfrak{A}_4$ . When we discuss this group between colleagues, possibly in class, the proof fact that it is indeed a subgroup usually boils down to a mere: "one checks that...".

Of course, such an argument is not sufficient for the computer, and I spent some time trying to imagine how we should prove such facts in the computer. The proof I resorted to happened to be fun, nevertheless slightly sophisticated.

Let  $X = \{a, b, c, d\}$  be a set with four elements, and let V be the subset of  $\mathfrak{S}_X$  consisting of the identity and of all double transpositions. In order to prove that V is a subgroup of  $\mathfrak{S}_X$ , I prove that V is the only 2-sylow subgroup of  $\mathfrak{A}_X$ . The proof runs as follows, in which we consider an arbitrary 2-sylow subgroup S of  $\mathfrak{A}_X$ .

- Since  $\mathfrak{S}_4$  has cardinality 4! = 24, the alternating group  $\mathfrak{A}_4$  has cardinality 12, and S has cardinality 4.
- The order of any element g of S divides 4; since its entries thus divide 4, the cycle type of g belongs to (), (2), (2,2) or (4). Since the second and last cases give odd permutations, we have  $g \in V$ ;
- Now the number of permutation of a given cycle type in a symmetric group can be computed explicitly, more on this below, and the computation shows that V has 4 elements;
  - Since S and V both have 4 elements, and  $S \subseteq V$ , this proves V = S, as claimed.

The computation of the number of permutations of a given cycle type in the symmetric group  $\mathfrak{S}_X$  is by itself a classic and important result in combinatorics of finite permutation groups. We return to the general case of a finite set X, let n be its cardinality, and consider a partition  $\pi$  of the integer n; let us write  $m_i$  for the number of parts equal to i. A permutation of cycle type  $\pi$  takes the form  $(a_1)(a_2)...(a_{m_1})(b_1b_1')(b_2b_2')...(b_{m_2}b_{m_2}')...:$   $m_1$  cycles of length 1,  $m_2$  cycles of length 2, etc. In order to compute the number of permutations of cycle type  $\pi$ , we just have to fill the letters with distinct elements of X, which apparently makes for n! permutations. However, for each cycle of length i, only the cyclic ordering of the elements matters, so we have to divide the result by  $\prod i^{m_i}$ . Moreover, the order in which we write the  $m_i$  cycles of given length i does not matter, so the result needs to be further divided by  $\prod m_i!$ . Finally, the number of permutations of cycle type  $\pi$  is  $n!/\prod i^{m_i} \prod m_i!$ .

There is however a more conceptual, and more precise, way to prove this formula. Fix any permutation g which has cycle type  $\pi$ . Since the number we wish to compute is the cardinality of the orbit of g under the conjugation action, it suffices to prove that the cardinality of the centralizer  $Z_g$  of g is equal to  $\prod i^{m_i} \prod m_i!$ .

If  $h \in \mathbb{Z}_g$ , then  $hgh^{-1} = g$ , so that the cycles of  $hgh^{-1}$  are those of g. In other words,  $Z_g$  acts by conjugation on the set of cycles of g, respecting their lengths. This gives a group morphism  $\varphi: \mathbb{Z}_g \to \prod_i \mathfrak{S}_{m_i}$ .

This morphism is surjective. In fact, one can even show that  $\varphi$  has a section. Indeed, fix, for each cycle c of g, an element  $a_c$  in c; then, for any permutation  $\sigma$ of the set of cycles of g which preserves their lengths, there is a unique element  $h_{\sigma}$ of  $Z_g$  such that  $h_{\sigma}(a_c) = a_{\sigma(c)}$  for all c, and the map  $\sigma \mapsto h_{\sigma}$  is a group morphism.

Now, the kernel of  $\varphi$  is the subgroup of all elements  $h \in \mathbb{Z}_g$  such that  $hch^{-1} = c$  for all cycles c of g. Necessarily, h stabilizes the support of each such c, so it maps  $a_c$ to some power iterate of  $a_c$  under g; fix  $k_c \in \mathbf{Z}$  (modulo the cardinality  $n_c$  of the support of c) such that  $h(a_c) = g^{k_c}(a_c) = c^{k_c}(a_c)$ ; using the fact that c is a cycle, it follows that h acts like  $c^{k_c}$  on the support of c. Finally, we see that h is the product of these powers  $c^{k_c}$ . In other words,  $\ker(\varphi)$  is a product of cyclic groups,  $\prod_c(\mathbf{Z}/k_c\mathbf{Z})$ , which we rewrite as  $\prod_i (\mathbf{Z}/i\mathbf{Z})^{m_i}$ , since  $m_i$  is the number of cycles c such that  $n_c = i$ . In particular, the order of  $\ker(\varphi)$  is equal to  $\prod i^{m_i}$ .

Finally,  $\operatorname{Card}(\mathbf{Z}_g) = \operatorname{Card}(\operatorname{Im}(\varphi)) \operatorname{Card}(\ker(\varphi)) = \prod_i i^{m_i} \prod_i m_i!$ , as was to be shown.

## 7. Simplicity of classical groups

7.1. — The simplicity criterion is not explicitly stated by IWASAWA (1941), but it is directly proved and applied in the case of the projective special linear group PSL(n, F) acting on the projective space  $P_{n-1}(F)$  of lines in  $F^n$ . Unless F has 2 or 3 elements, a linear algebra argument shows that this action is 2-fold transitive, hence primitive.

For every line  $\ell \in \mathbf{P}_{n-1}(\mathbf{F})$ , consider the subgroup  $\mathbf{T}(\ell)$  of transvections with respect to  $\ell$ , namely the elements  $g \in SL(n, \mathbb{F})$  such that the range of g – id is contained in  $\ell$ . Using that SL(n,F) is generated by transvections, we see that they give rise to a datum as in Iwasawa's criterion. Consequently, any normal subgroup of SL(n,F)which acts nontrivially on  $\mathbf{P}_{n-1}(\mathbf{F})$  contains the commutator subgroup of  $\mathrm{SL}(n,\mathbf{F})$ , which is known to be SL(n,F) itself. Finally, the only elements of SL(n,F) which act trivially on  $\mathbf{P}_{n-1}(\mathbf{F})$  are the homotheties, and they form the center of  $\mathrm{SL}(n,\mathbf{F})$ , a finite subgroup isomorphic to the set of nth roots of unity in F. As a consequence, the quotient PSL(n, F) = SL(n, F)/Z(SL(n, F)) is a simple group.

**7.2.** — This reasoning can also be applied for other cases of geometric groups. In his paper, Iwasawa himself indicates that the same method works for the symplectic group PSp(2n,F) ("complex projective groups" in the earlier terminology) acting on the projective space  $\mathbf{P}_{2n-1}(\mathbf{F})$ . Iwasawa does not explicitly consider the notion of a primitive action in his paper: his arguments are only spelt out for a 2-fold transitive action. However, he mentions in a footnote that while the action of the symplectic group on  $P_{2n-1}(F)$  is not 2-fold transitive, it is quasiprimitive, and this suffices for his proof. On the other hand, KING (1981) established that the stabilizers of this action are maximal subgroups, so that this action is even primitive.

In fact, it seems that the simplicity of the appropriate groups of geometric transformations can all be established in this way.

I find it remarkable how much this method, that relates the simplicity of a group with the structure of its maximal subgroups, is absolutely in par with the point of view of Jordan and early group theorists!

## 8. Remarks regarding the formalized proof and the formalization process

As recalled in the introduction, implementation of mathematical proofs in computers is not a very recent activity, but the Lean/mathlib movement puts us at a crossroad in so that it makes an indefinitely-extending library of formalized proofs conceivable. Built on the experiment described in this note, I would like to risk myself to enumerating some remarks about this prospect, the hopes and fears it may rise.

Formalization of mathematical proofs has many goals.

Some of its proponents raise the idea that it will make us truly certain of the validity of the new mathematical theorems we prove. The idea here is that the traditional peer review seems to reach its limits, both for mathematical and sociological reasons.

Some papers are simply so complicated that nobody can reasonably claim to have checked their validity with absolute certainty. This was the case for Hales's proof of the Kepler conjecture, before he, leading a team of 21 mathematicians, formalized that proof. In some sense, this is still the case for the classification of finite simple groups, whose size and technicality makes it inacessible to most of the mathematical community.

On the other hand, most research papers are of an apparently smaller size, but the sociology of the fields evolved. The increasing importance of research grants for the funding of research, if not for obtaining permanent academic positions, led us to a stage where the collectivity wants their papers published more quickly that it can assert their validity, if not just read. As a consequence, papers are reviewed too quickly, their publication is conditioned to preliminary opinions, leading to all imaginable biases, and new journals are created to host this ever growing mathematical litterature.

If we could check ourselves the validity of our proofs within formalization software, and deliver it at the same time we submit a paper, it is likely that this paper could have been written in a different way: not just to quickly convince a referee that the proofs are true, but spending more time than we presently do to explain the statements, their interest, their context, the path that led to their proof, as well as aiming at a possibly larger audience.

For this to happen, we need a *huge* archive of mathematical proofs written in a common language, with common definitions. The experience of the Bourbaki books suggests that something is possible, but it also reminds that not all mathematicians will be willing to comply to the mathematical writing style of other.

If the style of Bourbaki has been sometimes defined as too abstract, it is nothing in comparison with that of mathlib. Indeed, in order to avoid repeating proofs, the authors of that library make a permanent effort to put its definitions and statements in a (natural, but possibly frightening) generality. Linear algebra starts with a discussion of semimodules over monoids, so that the relevant part applies to more exotic contexts, such as (max, +)-algebras. (Bourbaki made a similar step when they defined "groups with operators", but their notion does not seem to be commonly used.) In complex analysis, the characterization of analytic functions as functions which are differentiable in the complex sense is proved using the Kurzweil-Henstock integral, because that allows us to avoid any Lebesgue integrability assumption on the derivative.

One of the difficulties by working with many simultaneous group actions is that type theory, the inner language of Lean, does not allow the many abuses of language that we do while doing mathematics, without even thinking about it. Take, for example, a group G acting on a set X, a subset A of X, and a point  $a \in X - A$ . Then we can consider the fixator G<sub>A</sub> of A in X, and its action on X-A, then the fixator  $G_{A,a}$  of a in  $G_A$ , and its action on  $X-(A \cup \{a\})$ , which — obviously — coincides with the action of the fixator of  $A \cup \{a\}$  on its complement. However, these actions look sufficiently different to Lean, syntaxically, and it is not able to identify automatically. The suggestion I received on the Zulip discussion blackboard was that I should not even try to identify them, but that it was sufficient to relate them through equivariant maps. If groups G and H act on X and Y, and  $\varphi \colon G \to H$  is a morphism of groups, then a  $\varphi$ -equivariant map from  $X \to Y$  is just a map  $f: X \to Y$ such that  $f(g \cdot x) = \varphi(g) \cdot f(x)$  for all  $g \in G$  and  $x \in X$ . Then several basic results allow us to transfer primitivity or transitivity properties from the action of G on X to the action of H on Y, or vice versa. This is an example of an elementary definition, with basic companion results, that we probably wouldn't dare introducing explicitly in a standard mathematical discussion — probably too trivial for specialists, but already too obscure for beginners. Learning to appreciate the relevance of introducing such abstract concepts takes some time, requires a community of knowledgeable mathematicians, as well as the will to follow their point of view.

On the other hand, as the myth of the Babel tower should remind us, leaning towards some ever-expanding generality comes at a high risk, that the full edifice collapses. My own experiment has been agreeable enough to me to sincerely wish that the community skillfully avoids that risk.

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