# Geometry of k-contact manifolds

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#### *k*-contact forms

#### Definition

A k-contact form on an open subset  $U \subset M$  is a differential one-form on U taking values in  $\mathbb{R}^k$ , let us say  $\eta \in \Omega^1(U, \mathbb{R}^k)$ , such that

- (1)  $\ker \eta \subset \mathrm{T}U$  is a regular non-zero distribution of corank k,
- (2)  $\ker d\eta \subset TU$  is a regular distribution of rank k,
- (3)  $\ker \eta \cap \ker d\eta = 0$ .

If the k-contact form  $\eta$  is defined on M, the pair  $(M, \eta)$  is called a **co-oriented** k-contact manifold and  $\ker \mathrm{d} \eta$  is called the **Reeb** distribution of  $(M, \eta)$ .

If, in addition,  $\dim M = n + nk + k$  for some  $n, k \in \mathbb{N}$  and there exists an integrable distribution  $\mathcal{V}$  contained in  $\ker \eta$  with  $\operatorname{rank} \mathcal{V} = nk$ , we say that  $(M, \eta, \mathcal{V})$  is a **polarised co-oriented** k-contact manifold. We call the distribution  $\mathcal{V}$  a **polarisation** of  $(M, \eta)$ .

#### The case k=1

The condition  $\ker \eta \neq 0$  is assumed so as to avoid non-interesting examples and retrieve standard contact geometry in the case k=1.

Consider  $\eta$  to be any non-vanishing one-form on  $M=\mathbb{R}$ . Thus,  $\mathrm{d}\eta=0$  and  $\ker\mathrm{d}\eta=\mathrm{T}\mathbb{R}$ . Hence, all conditions (1), (2), and (3) are satisfied. Nevertheless, we want a one-contact form to be a contact form and a non-vanishing  $\eta$  on  $\mathbb{R}$  is not a contact form since its kernel is not a contact distribution.

#### Dimension of polarised k-contact manifolds

If  $(M, \eta)$  admits a polarisation  $\mathcal{V}$ , then  $\dim M = n + nk + k$  for some  $n, k \in \mathbb{N}$ . Note that

$$n + nk + k = (n+1)(k+1) - 1$$
,

so  $\dim M+1$  must be a composite number. Thus, if  $(M, \eta, \mathcal{V})$  is a polarised k-contact manifold,  $\dim M+1$  cannot be a prime number.

### Reeb vector fields

#### **Theorem**

Let  $(M, \eta = \sum_{\alpha=1}^k \eta^{\alpha} \otimes e_{\alpha})$  be a co-oriented k-contact manifold. There exists a unique family of vector fields  $R_1, \ldots, R_k \in \mathfrak{X}(M)$ , such that

$$\iota_{R_{\alpha}}\eta^{\beta} = \delta^{\beta}_{\alpha}, \qquad \iota_{R_{\alpha}}\mathrm{d}\eta^{\beta} = 0,$$

for  $\alpha, \beta = 1, \dots, k$ . The vector fields  $R_1, \dots, R_k$  commute between themselves, i.e.

$$[R_{\alpha}, R_{\beta}] = 0, \qquad \alpha, \beta = 1, \dots, k.$$

In addition,  $\ker d\eta$  is spanned by those vector fields, namely  $\ker d\eta = \langle R_1, \dots, R_k \rangle$ .

We call **Reeb** k-vector field of  $(M, \eta)$  the integrable k-vector field  $\mathbf{R} = (R_1, \dots, R_k)$ .

Note that  $\mathscr{L}_{R_{\alpha}} \eta = 0$  for every  $\alpha$ .

# A first example

The manifold  $M=(\bigoplus^k \mathrm{T}^*Q)\times \mathbb{R}^k$  has a natural k-contact form

$$\eta_Q = \sum_{\alpha=1}^k (\mathrm{d}z^\alpha - \theta^\alpha) \otimes e_\alpha = \sum_{\alpha=1}^k (\mathrm{d}z^\alpha - p_i^\alpha \mathrm{d}q^i) \otimes e_\alpha,$$

where  $\theta^{\alpha}$  is the pull-back to M of the Liouville one-form  $\theta$  of the cotangent bundle  $\mathrm{T}^*Q$ . Thus,  $(M, \eta_Q, \mathcal{V})$  is a polarised co-oriented k-contact manifold, where  $\mathcal{V} \subset \ker \eta$  is the vertical distribution or the projection  $M \longrightarrow Q \times \mathbb{R}^k$  and  $\mathrm{rank} \ \mathcal{V} = nk$ . In local coordinates,

$$\ker \eta_Q = \left\langle \frac{\partial}{\partial p_i^{\alpha}}, \frac{\partial}{\partial q^i} + p_i^{\alpha} \frac{\partial}{\partial z^{\alpha}} \right\rangle, \qquad \mathcal{V} = \left\langle \frac{\partial}{\partial p_i^{\alpha}} \right\rangle.$$

Hence,  $d\eta_Q = (dq^i \wedge dp_i^{\alpha}) \otimes e_{\alpha}$ , the Reeb vector fields are  $R_{\alpha} = \partial/\partial z^{\alpha}$  for  $\alpha = 1, \ldots, k$ , and

$$\ker d\eta_Q = \left\langle \frac{\partial}{\partial z^1}, \dots, \frac{\partial}{\partial z^k} \right\rangle.$$

#### Jet bundles I

Consider the first-order jet bundle  $J^1=J^1(M,E)$  of a fibre bundle  $E\to M$  of rank k with adapted coordinates  $\{x^i,y^\alpha,y^\alpha_i\}$  on an open set U. Its Cartan distribution

$$C = \left\langle \frac{\partial}{\partial x^i} + \sum_{\alpha=1}^k y_i^{\alpha} \frac{\partial}{\partial y^{\alpha}}, \frac{\partial}{\partial y_i^{\alpha}} \right\rangle$$

has rank m(k+1) and it is globally defined. Note that  $[\mathcal{C},\mathcal{C}]=\mathrm{T}J^1.$ 

On the open subset U of  $J^1$ , there exists a k-contact form

$$\eta = \sum_{\alpha=1}^{k} \left( dy^{\alpha} - \sum_{i=1}^{m} y_i^{\alpha} dx^i \right) \otimes e_{\alpha},$$

such that  $\ker \eta = \mathcal{C}|_U$ . Moreover,

$$\left\langle \frac{\partial}{\partial y^{\alpha}} \right\rangle = \ker \mathrm{d} \boldsymbol{\eta} \,.$$

#### Jet bundles II

This example is quite interesting due to the fact that, given another set of adapted coordinates  $\{\bar{x}^i, \bar{y}^\alpha, \bar{y}^\alpha_i\}$  on  $\bar{U}$  to  $J^1$ , the  $\mathbb{R}^k$ -valued differential one-form

$$\bar{\boldsymbol{\eta}} = (\mathrm{d}\bar{y}^{\alpha} - \bar{y}_{i}^{\alpha}\mathrm{d}\bar{x}^{i}) \otimes e_{\alpha}$$

is different from  $\eta$ , but

$$\ker \boldsymbol{\eta}|_{U \cap \bar{U}} = \ker \bar{\boldsymbol{\eta}}|_{U \cap \bar{U}} = \mathcal{C}|_{U \cap \bar{U}},$$
$$\left\langle \frac{\partial}{\partial y^{\alpha}} \right\rangle = \ker d\boldsymbol{\eta} \neq \ker d\bar{\boldsymbol{\eta}} = \left\langle \frac{\partial}{\partial \bar{y}^{\alpha}} \right\rangle,$$

and  $\ker \bar{\eta} \oplus \ker d\bar{\eta} = T\bar{U}$ .

Consequently, locally defined k-contact forms associated with adapted coordinates to  $J^1$  and their differentials do not need to be globally defined, but they share the same kernel given by the Cartan distribution.

### Jet bundles III

Let us analyse a simple example given by a fibre bundle  $(x,y) \in \mathbb{R}^2 \mapsto x \in \mathbb{R}$ . Consider the first-order jet bundle  $J^1(\mathbb{R},\mathbb{R}^2)$  with induced variables  $\{x,y,\dot{y}\}$ . The new adapted coordinates given by

$$\bar{x} = x, \qquad \bar{y} = (1 + x^2)y,$$

lead to a new adapted coordinate system on  $J^1(\mathbb{R},\mathbb{R}^2)$  of the form

$$\bar{x} = x$$
,  $\bar{y} = (1 + x^2)y$ ,  $\dot{\bar{y}} = (1 + x^2)\dot{y} + 2xy$ .

Hence,

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial \bar{x}} + 2\frac{\bar{x}\bar{y}}{1 + \bar{x}^2} \frac{\partial}{\partial \bar{y}} + \frac{2}{1 + \bar{x}^2} \left( \bar{y} + \bar{x}\dot{\bar{y}} - \frac{2\bar{x}^2\bar{y}}{1 + \bar{x}^2} \right) \frac{\partial}{\partial \dot{\bar{y}}},$$
$$\frac{\partial}{\partial y} = (1 + \bar{x}^2) \frac{\partial}{\partial \bar{y}} + 2\bar{x}\frac{\partial}{\partial \dot{\bar{y}}}, \qquad \frac{\partial}{\partial \dot{y}} = (1 + \bar{x}^2) \frac{\partial}{\partial \dot{\bar{y}}}.$$

As above,  $\langle \partial/\partial y \rangle \neq \langle \partial/\partial \bar{y} \rangle$  at a generic point, while  $\bar{\eta} = (1+x^2)\eta$ .

For a contact form  $\eta$  on M, one has that  $[\ker \eta, \ker \eta] = TM$ .

For k-contact forms, only the following result can be ensured.

### Proposition

Given a k-contact form  $\eta$  on M, one has that  $\ker d\eta$  is an integrable distribution and  $[\ker \eta, \ker \eta]_x \supseteq \ker \eta_x$  at every point  $x \in M$ .

In some particular cases, one has  $[\ker \eta, \ker \eta] = TM$  for a k-contact form  $\eta$ , but it is not needed in general as shown in the following example. Notwithstanding,  $[\ker \eta, \ker \eta] = TM$  is satisfied for k-contact manifolds with a polarisation.

### Example

Let us provide a k-contact form on M such that  $[\ker \eta, \ker \eta] \neq TM$ . Consider  $\mathbb{R}^2_\times \times \mathbb{R}^2$ , where  $\mathbb{R}_\times = (0, \infty)$ , and a global coordinate system  $\{x, p, z_1, z_2\}$  in  $\mathbb{R}^2_\times \times \mathbb{R}^2$ , namely  $x, p \in \mathbb{R}_\times, z_1, z_2 \in \mathbb{R}$ . If

$$\boldsymbol{\eta} = (\mathrm{d}z_1 - p\,\mathrm{d}x) \otimes e_1 + (\mathrm{d}z_2 - x\,\mathrm{d}p) \otimes e_2,$$

it follows that

$$\ker \boldsymbol{\eta} = \langle X_1 = x \partial_{z_2} + \partial_p, \ X_2 = p \partial_{z_1} + \partial_x \rangle,$$

$$d\eta = dx \wedge dp \otimes e_1 - dx \wedge dp \otimes e_2, \quad \ker d\eta = \langle \partial_{z_1}, \partial_{z_2} \rangle.$$

Then,  $\ker \eta \cap \ker d\eta = 0$  with  $\ker \eta \neq 0$ , corank  $\ker \eta = 2$ , rank  $\ker d\eta = 2$ , and

$$[\ker \boldsymbol{\eta}, \ker \boldsymbol{\eta}] = \ker \boldsymbol{\eta} \oplus \langle \partial_{z_1} - \partial_{z_2} \rangle \subsetneq \mathrm{T}(\mathbb{R}^2_{\times} \times \mathbb{R}^2).$$

Note that  $[X_1, X_2]$  does not take values in  $\ker \eta$  at any point of M, but  $\eta$  is a two-contact form.

### Darboux coordinates

#### **Theorem**

Consider a polarised co-oriented k-contact manifold  $(M, \eta, \mathcal{V})$ . Then, there exists around every  $x \in M$  a local coordinate system  $\{x^i, y^\alpha, y^\alpha_i\}$  such that

$$\boldsymbol{\eta} = (\mathrm{d}y^{\alpha} - y_i^{\alpha} \mathrm{d}x^i) \otimes e_{\alpha}, \quad R_{\beta} = \frac{\partial}{\partial y^{\beta}}, \quad \mathcal{V} = \left\langle \frac{\partial}{\partial y_i^{\alpha}} \right\rangle, \quad \beta = 1, \dots, k.$$

### Example

The jet bundle  $J^1(M,E)$  is a polarised k-contact manifold with the polarisation

$$\mathcal{V} = \ker \mathrm{T}\pi_1 \cap \ker \boldsymbol{\eta} = \left\langle \frac{\partial}{\partial y_i^{\alpha}} \right\rangle \,,$$

where  $\pi_1: J^1(M, E) \longrightarrow M$  is the natural projection.

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#### k-contact distributions

#### Definition

A k-contact distribution on M is a distribution  $\mathcal{D} \subset TM$  such that, for each point  $x \in M$ , there is an open neighbourhood  $U \ni x$  and a k-contact form  $\eta$  on U such that  $\mathcal{D}|_U = \ker \eta$ . We say that  $(M,\mathcal{D})$  is a k-contact manifold.

Since a one-contact form is a contact form, a one-contact manifold  $(M,\mathcal{D})$  is a contact manifold.

This means that every associated contact form  $\eta$ , i.e.  $\mathcal{D}|_U = \ker \eta$  on an open subset  $U \subset M$ , satisfies that  $\eta \wedge (\mathrm{d}\eta)^n$  is a volume form for a unique  $n \in \mathbb{N}$ . As a consequence, it is said that  $\mathcal{D}$  is maximally non-integrable.

# Maximal non-integrability

#### Definition

Let  $\mathcal D$  be a regular distribution on M and let  $\pi\colon \mathrm{T} M\to \mathrm{T} M/\mathcal D$  be the natural vector bundle projection. Then,  $\mathcal D$  is maximally non-integrable in a distributional sense if  $\mathcal D\neq 0$  and the vector bundle mapping  $\rho\colon \mathcal D\times_M\mathcal D\to \mathrm{T} M/\mathcal D$  over M given by

$$\rho(v, v') = \pi([X, X']_x), \qquad \forall v, v' \in \mathcal{D}_x, \qquad \forall x \in M,$$

where X,X' are vector fields taking values in  $\mathcal D$  locally defined around x such that  $X_x=v$  and  $X_x'=v'$ , is non-degenerate.

Note that  $\rho(v, v') = -d\eta(v, v')$ .

### Proposition

Let  $\mathcal D$  be a distribution of corank one. Then,  $\mathcal D$  is maximally non-integrable in a distributional sense if, and only if,  $\mathcal D$  is maximally non-integrable in the contact sense.

### Proposition

A regular distribution  $\mathcal{D}$  on M is maximally non-integrable if, and only if, for every  $x \in M$  there exists an  $\zeta \in \Omega^1(U, \mathbb{R}^k)$ , where U is an open neighbourhood of x, associated with  $\mathcal{D}$  such that  $\mathrm{d}\zeta$  is non-degenerate when restricted to  $\mathcal{D}|_U$ .

### Proposition

If  $(M, \eta)$  is a co-oriented k-contact manifold, then  $\mathrm{d}\eta$  is non-degenerate when restricted to  $\ker \eta$ . In other words,  $\ker \eta$  is maximally non-integrable.

Since every k-contact distribution is on a neighbourhood U of every point  $x \in M$  of the form  $(U,\mathcal{D}|_U = \ker \eta)$ , it follows that it is maximally non-integrable.

### Corollary

Every k-contact distribution is maximally non-integrable.

The maximal non-integrability was introduced by L. Vitagliano. We will see that it is not equivalent be k-contact.

### Lie symmetries

#### Definition

A **Lie symmetry** of a distribution  $\mathcal D$  on M is a vector field X on M such that  $[X,\mathcal D]\subset\mathcal D$ .

### Corollary

Every k-contact distribution  $\mathcal{D}$  on M admits, on an open neighbourhood U of each point  $x \in M$ , an integrable k-vector field  $\mathbf{S} = (S_1, \ldots, S_k) \in \mathfrak{X}^k(U)$ , whose components are Lie symmetries of  $\mathcal{D}$  such that

$$\mathcal{D}|_U \oplus \langle S_1, \dots, S_k \rangle = \mathrm{T}U.$$
 (1)

There exist distributions that have k commuting Lie symmetries but are not k-contact distributions (because they are involutive, for instance). We will see that maximal non-integrability is not a sufficient condition for a regular distribution to become k-contact by giving a maximally non-integrable distributions that do not admit k commuting Lie symmetries satisfying (1).

# Lie flags

#### Definition

The **Lie flag** of a distribution  $\mathcal{D} \subset TM$  is a series of distributions  $\mathcal{D}, \mathcal{D}^{1)}, \mathcal{D}^{2)}, \ldots$  on M, where  $\mathcal{D}^{\ell)}$  is the distribution spanned by the Lie brackets of the vector fields taking values in  $\mathcal{D}$  and  $\mathcal{D}^{\ell-1)}$ , namely

$$\mathcal{D}^{\ell)} = [\mathcal{D}, \mathcal{D}^{\ell-1}], \qquad \ell \in \mathbb{N},$$

where we denote  $\mathcal{D}^{0)}=\mathcal{D}.$  We call small growth function of the Lie flag of  $\mathcal{D}$  the vector function

$$\mathcal{G}_{\mathcal{D}}(x) = (\dim \mathcal{D}_x, \dim \mathcal{D}_x^{(1)}, \dots), \quad \forall x \in M.$$

# Lie flags

Since  $\mathcal{D}$  is smooth by assumption, the distributions  $\mathcal{D}^{\ell)}$  are smooth and  $\mathcal{D}^{\ell-1)} \subset \mathcal{D}^{\ell-1)}$  for every  $\ell \in \mathbb{N}$ .

The sequence  $\mathcal{G}_{\mathcal{D}}(x)$  is (not strictly) increasing and stabilises since it is upper-bounded by  $\dim M$  at every  $x \in M$ .

### Proposition

Let us define  $\mathcal{D} = \ker \eta$  for a k-contact form  $\eta$ , and let  $R_1, \ldots, R_k$  be the associated Reeb vector fields. Then, the one-parameter groups of diffeomorphisms of the Reeb vector fields leave invariant the rank of every  $\mathcal{D}^{\ell}$  for  $\ell \in \mathbb{N} \cup \{0\}$ .

The next example shows that maximal non-integrability is not equivalent to be k-contact.

# Example (part 1)

Consider  $\mathbb{R}^4$  endowed with linear coordinates  $\{x,y,z,t\}$  and the regular distribution given by

$$\mathcal{D} = \langle X_1 = \partial_x, \ X_2 = \partial_y + (x^3/3 + z^2x + t^2)\partial_z + x\partial_t \rangle.$$

Then,

$$\mathcal{D}^{1)} = \langle X_1, X_2, (x^2 + z^2)\partial_z + \partial_t \rangle, 
\mathcal{D}^{2)} = \langle X_1, X_2, (x^2 + z^2)\partial_z + \partial_t, 2x\partial_z, (2x^3z/3 + t - zt^2)\partial_z \rangle.$$

 $\mathcal{D}^1$ ) has rank three everywhere, while  $\mathcal{D}^2$ ) has rank three when x=0 and t(1-zt)=0, and four elsewhere. The space  $S\subset\mathbb{R}^4$  defined by x=0 and t(1-zt)=0 has to be invariant relative to the action of the Reeb vector fields if  $\mathcal{D}$  is a two-contact distribution. Note that S is a regular submanifold whose tangent space is given by the annihilator of the differential forms

$$\theta^1 = dx$$
,  $\theta^2 = (1 - 2zt)dt - t^2dz$ .

# Example (part 2)

Indeed,  $\theta^1 \wedge \theta^2$  does not vanish at any point of  $\mathbb{R}^4$  and the subset x=0 and t(1-zt)=0 is a regular submanifold. If  $\mathcal D$  is a two-contact distribution, the Reeb vector fields of any associated k-contact form  $\boldsymbol{\eta} \in \Omega^1(U,\mathbb{R}^2)$  must be tangent to S.

In particular, at points where x=0 and t=0, one has that  $\mathrm{T}S=\langle\theta^1,\theta^2\rangle^\circ=\langle\partial_y,\partial_z\rangle$ . Note that the two Reeb vector fields must span such a subspace, i.e.  $\ker\mathrm{d}\boldsymbol{\eta}=\langle\partial_y,\partial_z\rangle$  when x=0 and t=0. But  $\mathcal{D}=\langle\partial_x,\partial_y\rangle$  at such points of S, thus if  $\mathcal{D}|_U=\ker\boldsymbol{\eta}$ , then  $\ker\mathrm{d}\boldsymbol{\eta}\cap\ker\boldsymbol{\eta}=\langle\partial_y\rangle$ .

This is a contradiction and  $\mathcal D$  is not the kernel of any two-contact form. On the other hand, it is immediate that  $\rho\colon \mathcal D\times_{\mathbb R^4}\mathcal D\to T\mathbb R^4/\mathcal D$  is non-degenerate and  $\mathcal D$  is maximally non-integrable.

#### Main result

Previous results imply that a k-contact distribution is a maximally non-integrable distribution admitting around each point k commuting Lie symmetries giving a supplementary to the k-contact distribution.

The converse is also true and, in fact, the maximal non-integrability and the existence of k commuting Lie symmetries spanning a supplementary distribution characterise k-contact distributions.

#### **Theorem**

A distribution  $\mathcal{D}$  on M is a k-contact distribution if, and only if,

- lacksquare  $\mathcal D$  is maximally non-integrable and,
- for every  $x \in M$ , there exists an open neighbourhood  $U \ni x$  such that there is an integrable k-vector field  $\mathbf{S} = (S_1, \ldots, S_k)$  of Lie symmetries of  $\mathcal{D}|_U$  such that

$$\langle S_1,\ldots,S_k\rangle\oplus\mathcal{D}|_U=\mathrm{T}U$$
.

## Lie groups

### Example

Consider a Lie group G and a basis  $X_1^L, \ldots, X_r^L$  of left-invariant vector fields on G and a basis  $X_1^R, \ldots, X_r^R$  of right-invariant vector fields.

Let  $\mathcal D$  be the distribution spanned by  $X_1^L$  and  $X_2^L$ . Assume that  $[X_1^L,X_2^L] \notin \mathcal D$  and  $X_3^R,\dots,X_r^R$  commute among themselves.

Then  $\mathcal{D}=\langle X_1^L,X_2^L\rangle$  is a (r-2)-contact distribution of rank two and Reeb vector fields  $X_3^R,\ldots,X_r^R.$ 

### Example

One can prove that the Lie group SU(n) is a coorientable n-contact manifold.

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#### Definition

Two differential one-forms  $\zeta, \bar{\zeta} \in \Omega^1(U, \mathbb{R}^k)$  are **compatible** if  $\ker \zeta = \ker \bar{\zeta}$  is a regular distribution.

We will now examine whether a form  $\zeta \in \Omega^1(U, \mathbb{R}^k)$  admits an associated k-contact form  $\eta \in \Omega^1(U, \mathbb{R}^k)$ .

### Example

Consider  $\mathbb{R}^4$  with Cartesian coordinates  $\{x,y,z,p\}$  and  $\boldsymbol{\eta}=(\mathrm{d} x-y\,\mathrm{d} p)\otimes e_1+(\mathrm{d} z-p\,\mathrm{d} y)\otimes e_2$ . Then,

$$\ker \boldsymbol{\eta} = \left\langle y \frac{\partial}{\partial x} + \frac{\partial}{\partial p}, p \frac{\partial}{\partial z} + \frac{\partial}{\partial y} \right\rangle, \quad \ker \mathrm{d} \boldsymbol{\eta} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial z} \right\rangle$$

and  $\ker \mathrm{d} \boldsymbol{\eta} \cap \ker \boldsymbol{\eta} = 0$ . If follows that  $\boldsymbol{\eta}$  is a two-contact form. Consider now  $\boldsymbol{\zeta} = e^z \boldsymbol{\eta}$ . In this case,  $\ker \boldsymbol{\eta} = \ker \boldsymbol{\zeta}$ , but  $\mathrm{d} \boldsymbol{\zeta} = \mathrm{d} \zeta^1 \otimes e_1 + \mathrm{d} \zeta^2 \otimes e_2$  has zero kernel since  $\mathrm{d}(e^z \boldsymbol{\eta}^1)$  is a symplectic form on  $\mathbb{R}^4$ . Thus,  $\ker \mathrm{d} \boldsymbol{\zeta} = 0$  and  $\boldsymbol{\zeta}$  is not a two-contact form.

#### Definition

Every  $\zeta\in\Omega^1(U,\mathbb{R}^k)$  associated with a regular distribution gives rise to a non-vanishing differential k-form  $\Omega_\zeta=\zeta^1\wedge\cdots\wedge\zeta^k$  on U. A **conformal Lie symmetry of**  $\Omega_\zeta$  is a vector field X on U such that  $\mathscr{L}_X\Omega_\zeta=f_X\Omega_\zeta$  for some function  $f_X\in\mathscr{C}^\infty(U)$ .

### Proposition

Let  $(M, \eta)$  be a k-contact manifold and let  $\Omega_{\eta}$  be its associated differential k-form, then the Reeb vector fields are Lie symmetries of  $\Omega_{\eta}$ . The space of conformal symmetries of  $\Omega_{\zeta}$ , where  $\zeta$  is compatible with  $\eta$ , is a Lie algebra.

### Proposition

One has that  $\zeta, \bar{\zeta} \in \Omega^1(U, \mathbb{R}^k)$  with regular kernels are compatible if, and only if,  $\Omega_{\zeta}$  and  $\Omega_{\bar{\zeta}}$  are proportional. Moreover,  $\ker \zeta = \ker \Omega_{\zeta}$  and a vector field X on U is a Lie symmetry of  $\ker \zeta$  if, and only if, X is a conformal Lie symmetry of  $\Omega_{\zeta}$ .

This result implies that X is a conformal Lie symmetry of  $\Omega_{\pmb{\eta}}$ , if, and only if,  $\mathscr{L}_X \eta^\alpha = \sum_{\beta=1}^k f^\alpha_\beta \eta^\beta$  with  $\alpha=1,\ldots,k$  for certain functions  $f^\alpha_\beta \in \mathscr{C}^\infty(U)$  with  $\alpha,\beta=1,\ldots,k$ .

### Proposition

Let  $\zeta \in \Omega^1(M, \mathbb{R}^k)$  have a regular kernel different from zero and suppose that  $\mathrm{d}\zeta|_{\ker \zeta \times_U \ker \zeta}$  is non-degenerate. Assume that  $S_1, \ldots, S_k$  are conformal commuting Lie symmetries of  $\Omega_\zeta$  with  $S_1 \wedge \cdots \wedge S_k \neq 0$  such that  $\langle S_1, \ldots, S_k \rangle$  is a supplementary to  $\ker \zeta$ . Then,  $\zeta$  admits a compatible k-contact form  $\eta$ .

#### Theorem

An  $\zeta \in \Omega^1(U, \mathbb{R}^k)$  associated with a regular distribution  $\mathcal{D} \neq 0$  of corank k is compatible with a k-contact form if, and only if,  $\ker \zeta \cap \ker \mathrm{d}\zeta = 0$ , while  $\ker \mathrm{d}\zeta|_{\ker \zeta \times \ker \zeta} = 0$ , and  $\Omega_\zeta$  has k commuting conformal Lie symmetries spanning a supplementary to  $\ker \zeta$ .

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