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# LUCRARE DE DIPLOMĂ

## Deep Learning în jocuri

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# BACHELOR THESIS

## Playing games with Deep Learning

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# Abstract

Deep Learning is a new, interesting and a fast-growing field of Machine Learning. It combines the classical model of multilayer perceptrons with layers of feature extraction inspired from visual cortex of the brain. Moreover, dealing with the curse of dimensionality is another advantage when we talk about Convolutional Neural Networks. This paper proposes an alternative to the classical reinforcement learning techniques, such as Q-Learning and SARSA. The question which arises is this: what if we make an agent and allow it to play a game based on information from visual frames and rewards recieved during the game?

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# Chapter 1

## Introduction

### 1.1 Motivation

Humans have always felt the need to explore and find a way to a better life. Starting with stone tools (2.6 million years ago) and continuing with personal computers are only some proof in human evolution. Lately, we have discovered Machine Learning which have the purpose to allow machines for learning to do different tasks.

Deep learning is a subfield of machine learning area and it is inspired by how the human brain works. Through deep learning, we are trying to solve some of the most pressuring human problems as cancer classification (benign or malignant tumor)[1], self-driving cars based on pedestrian detections[2] or recognizing digits taken by Google Street View[3], all using unsupervised learning of features.

This paper propose an in-dept look of solving reinforcement learning problems, using convolutional neural networks. More exactly, we want to design an agent which is capable of learning to play a game[4] seeing only the pixels from the frames and being rewarded after finishing the game.

This idea was brought to attention in 2013, when Alex Graves et al. from DeepMind<sup>1</sup> came with the idea of creating a convolutional neural network capable of playing different Atari 2600 games, being as good as a game tester. The motivation behind this experiment is not only connected with the fact that we have a machine capable of playing games, but the more important problem is that they achieved the generalization of a machine that could learn several types of games, which in fact is the starting of a new revolution in machine learning. If we are capable of making one unique algorithm that can solve multiple tasks, we are capable of simulating the real human brain and capable of reducing complex problems to another ones, much more simple and thus, we can reduce programming burden and solving problems as cancer classification.

### 1.2 Project description

This paper presents two different algorithms in creating a good agent which can learn playing games. It is worth mentioning that the agent does not know the rules and can not infer with some rules at the beginning of the game. The whole topic has been splitted in three parts:

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<sup>1</sup><http://deeptmind.com/>

running Q-Learning on Hanoi Towers game, learning values predicted by Q-Learning using a convolutional neural network and connecting the first two parts together.

First of them is the classical Q-Learning, which is searching the optimal policy for taking actions from each state of the game. We will discuss about exploration vs exploitation problem, how to determine the learning rate suitable for our purposes, how many episodes we have to play until we determine a policy close to the optimal one.

The second topic we approach in this paper is the possibility of predicting continuous output from image. Practically, we take the dataset from Q-Learning which contains image as input and a table of four values corresponding to the four possible actions in Hanoi Tower games: up, down, left and right.

The last part is the one we combine the first two modules.

### 1.3 Technologies

All algorithms described in this paper have been implemented using Torch<sup>1</sup>, a deep learning framework written in Lua<sup>2</sup>, a scripting language based on a C API. For creating the game, generating frames or modifying images LOVE platform<sup>3</sup> was the close alternative which is also written in Lua. For interactive computing(image/filter visualization) iTorch<sup>4</sup> has been used.

Why Lua and Torch? They provide a fast environment as opposed to another ones[5], multiple modules with functions already implemented such as transfer functions(tanh, sigmoid), loss functions(Mean Squared Error, Negative Log Likelihood) or convolutional layers(SpatialMaxPooling, SpatialSubSampling)

### 1.4 Structure of this paper

[Chapter 2](#)

[Chapter 3](#)

[Chapter 4](#)

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### 1.5 Copyright infringement

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<sup>1</sup><http://torch.ch/>

<sup>2</sup><http://www.lua.org/about.html>

<sup>3</sup>[https://love2d.org/wiki/Main\\_Page](https://love2d.org/wiki/Main_Page)

<sup>4</sup><https://github.com/facebook/iTorch>

## Chapter 2

# State of the art

Being a large domain, deep learning imposes a research in multiple subdomains, neuroscience, reinforcement learning, neural networks and convolutional neural networks. That being said, this chapter is dedicated to gathering information on each of them.

## 2.1 Reinforcement learning

### 2.1.1 History

The history of reinforcement learning starts with the pavlovian experiment[6] in 1903, when Pavlov tried to demonstrate that there is a connection between conditioned and unconditioned stimulus. The unconditioned response of salivation of a dog is fired up by bringing an unconditioned stimulus as food. If we try to make the dog to salivate in the presence of a neutral stimulus(the sound of a bell) we won't succeed, but if we use in the same time the unconditioned and neutral stimulus we can make the dog salivate and transform the bell and salivation in conditioned stimulus and conditioned response.

### 2.1.2 Q-Learning. Sarsa

#### Q-Learning

## Chapter 3

# System design and implementation

Sys



# Chapter 4

## Results

Results

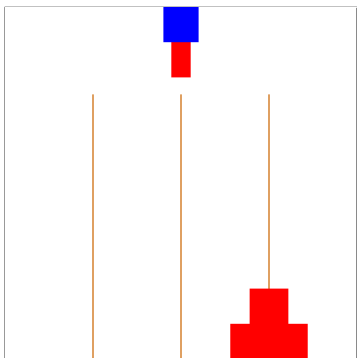


Figure 4.1:  
A really Awesome Image

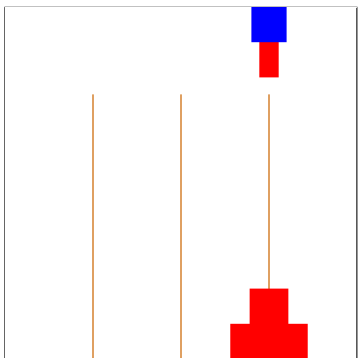


Figure 4.2:  
A really Awesome Image

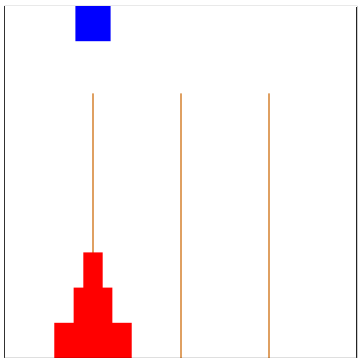


Figure 4.3:  
97,6530  
100,0000  
93,8538  
92,5261

## Chapter 5

# Conclusions

Conclusions

## Chapter 6

# Future work

Future work

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