

Draw one sample of uncertain parameters



Episode - start

State 0 - 2020

Action 0

2020-2030 optimisation

State 1 - 2025

Reward 1



Action 4

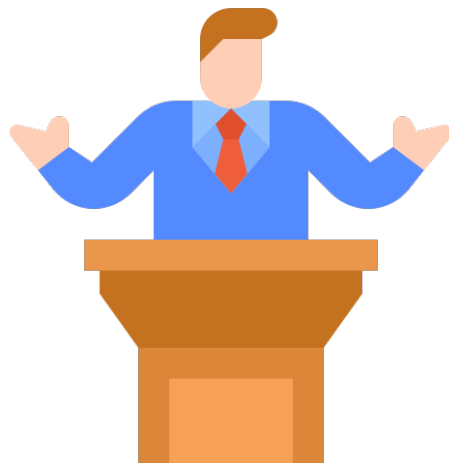
2040-2050 optimisation

State 5 - 2050

Reward 5

Episode - end

Agent



Action

a_n

Environment
(under uncertainties)

EnergyScope Pathway
Myopic

Y

$Y + 5$

$Y + 10$

Observation

o_n

r_n

Reward

o_{n+1}

r_{n+1}

