Static Single Assignment (SSA) Objectives

- Given a CFG, the student will be able to compute the dominator relation for the CFG.
- Given a CFG, the student will be able to compute the dominance frontier and iterated dominance frontier for each node in the CFG.
- Given a CFG, the student will be able to compute the SSA-form for the CFG.
- Given SSA-form, the student will be able to convert it to normal form.

SSA Form

- An improvement to DU-UD chains.
- sparse representation
- each variable is defined once → each use has one reaching definition
- use φ-nodes to merge multiple definitions reaching a single point

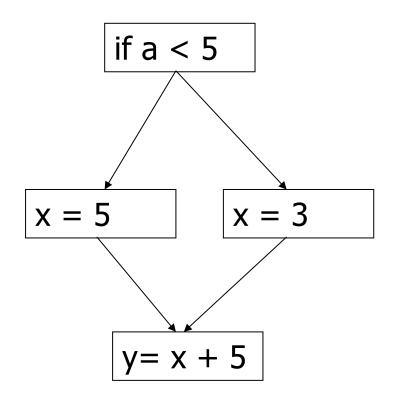
becomes

$$v_0 = 4$$

 $x_0 = v_0 + 5$
 $v_1 = 6$
 $y_0 = v_1 + 7$

Control Flow

- What do we do when there are multiple definitions reaching a single point?
- In the example to the right, what if the definition of x used at in the computation of y?

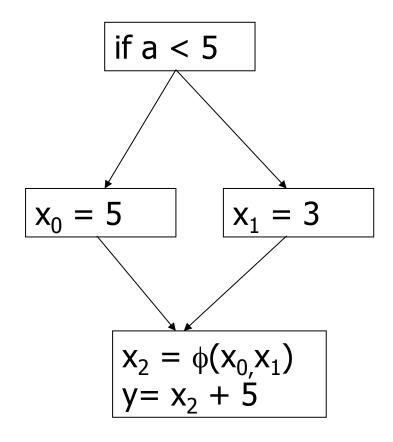


φ-nodes

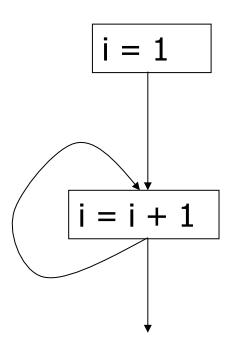
Defⁿ: Consider a block b in the CFG with predecessors $\{p_1, p_2, ..., p_n\}$ where n > 1. A ϕ -node

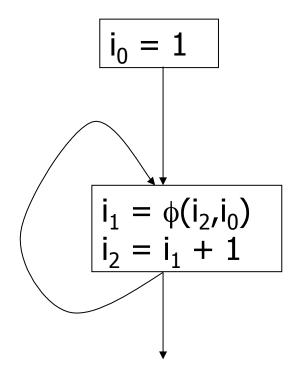
$$T_0 = \phi(T_1, T_2, ..., T_n)$$

in b gives the value of T_i to T_0 on entry to b if the execution path leading to b has p_i as the predecessor to b.



Another Example





Placing ϕ -nodes

- Find the join points
 - top of basic blocks where different definitions reach on different paths
- > Method
 - computing dominator relation for CFG
 - compute dominance frontiers for each basic block

Dominator Relation

Defn: A node n in a graph dominates a node m, denoted n >> m, if every path from the entry node to m contains n.

```
n >> n (reflexive)

n >> m \land n \neq m \rightarrow !(m >> n) (antisymmetric)

n >> m \land m >> r \rightarrow n >> r (transitive)
```

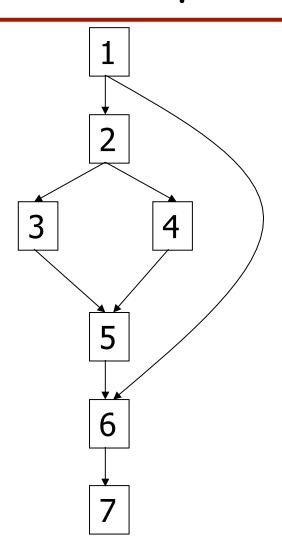
> >> is a partial order on the CFG nodes

Computing Dominators

```
D(v_0) = \{v_0\}
for each n \in V - \{v_0\} // \text{init}
D(n) = V
do \{
for each n \in V - \{v_0\}
D(n) = \{n\} \cup
\bigcap_{p \in \text{preds}(n)} D(p)
} until no D(n) changes
n \ge m \Leftrightarrow n = m \text{ or } \forall p \in \text{pred}(m) \text{ n } \ge p
```

- ENTRY dominates all nodes
- Since >> is a partial order, we can construct an ordering of all the nodes that each node dominates to construct a dominator tree.
- The immediate dominator of n, denoted idom(n), is its parent in the dominator tree.

Example



Dominance Frontiers

- Defn: Node n is said to strictly dominate a node m, denoted n >> m, if n ≠ m ∧ n >> m.
- Defn: The dominance frontier of a node n consists of the successors of all nodes dominated by n that are not strictly dominated by n.
 - DF(n) ={m| $\exists p \in preds(m) \text{ where } n \geq p \land !(n >> m)$ }
- DF(n) is the set of nodes where a join point for a definition of a variable in n can occur

Computing Dominance Frontiers

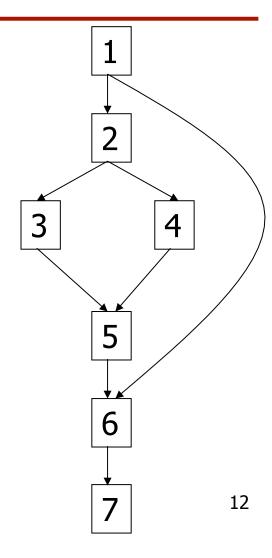
```
DF(n) = DF_{local}(n) \cup (\bigcup_{c \in child(n)} DF_{up}(c))
DF_{local}(n) = \{m \mid m \in succ(n) \land !(n \Rightarrow m)\}
DF_{up}(c) = \{m \mid m \in DF(c) \land !(idom(c) \Rightarrow m)\}
```

- DF_{local}(n) is the dominance frontier of n involving only the successors of n.
- > DF_{up}(c) propagates DF_{local} information up the dominator tree. Includes everything in the dominance frontier of the children of n that n does not dominate itself, excluding n.

Computing Dominance Frontiers

```
for each n \in DT in postorder {
    DF(n) = \emptyset
    for each c \in child(n) //DT
    for each m \in DF(c)
    if !(n >> m)
    DF(n) \cup = \{m\}
    for each m \in succ(n)
    if !(n >> m)
    DF(n) \cup = \{m\}
}
```

Compute the dominance frontier for the example



Placement of ϕ -nodes

> Let S_v be the set of all blocks with assignments to v plus the ENTRY node.

$$DF(S_v) = U_{n \in S_v}DF(n)$$

This is the set of all possible join points for assignments to v.

- > If we place ϕ -nodes in each $b \in DF(S_v)$ will this be correct?
 - Does S_v contain all blocks in the dominance frontier of all blocks with definitions of v?

Iterated Dominance Frontier

- \triangleright DF⁺(S_v) is the iterated dominance frontier for the set of definitions S_v
 - New blocks are potentially added for each ϕ -node insertion.
- Computing $DF^+(S_v)$ $DF_1(S_v) = DF(S_v)$ $DF_{i+1}(S_v) = DF(S_v \cup DF_i(S_v))$ $DF^+(S_v) = \bigcup_{i=1,\infty} DF_i(S_v)$

Iterated Dominance Frontier

```
Work = \varnothing

DF+(S<sub>v</sub>) = \varnothing

for each b \in S<sub>v</sub> {

Work \cup = {b}

}

while Work \neq \varnothing {

b = Work.Remove()

for each c \in DF(b)

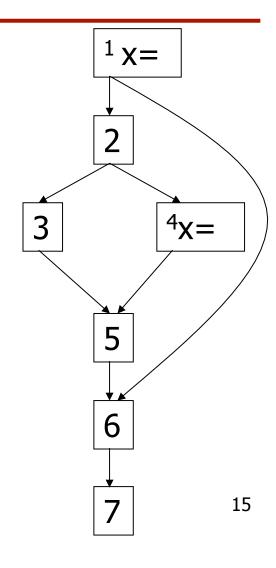
if c \notin DF+(S<sub>v</sub>) {

DF+(S<sub>v</sub>) \cup = {c}

Work \cup = {c}

}
```

 Compute the iterated dominance frontier for the example



Inserting ϕ -nodes

```
Perform live-variable analysis for each T \in Variables if T \in Globals { S = \{b \mid b \text{ has a def of } T\} \cup \{Entry\} Compute DF^+(S) for each b \in DF^+(S) if T \in b.LiveIn { n = |pred(b)| insert T = \phi(T_1,...,T_n) in b }
```

- Insert ϕ -nodes for previous example.
- leave parameters to φnodes named by path
 - renaming will get the correct names

Renaming Temporaries

- Need to replace uses with new names
 - walk the dominator tree
 - replace uses dominated by a definition

```
for each T \in Variables
NameStack(T) = \emptyset
Rename(ENTRY)
```

Renaming Algorithm

```
Rename(b) { for each I \in \Phi(b) of the form T_0 = \phi(T_1,...,T_n) { push NewName() on NameStack(T_0) Definition(Top(NameStack(T_0)) = I } for each I \in b in order { for each T \in Operand(I) { replace T by Top(NameStack(T)) add I to Uses(Top(NameStack(T))) } I = T arget(I) push NewName() on NameStack(I) Definition(Top(NameStack(I)) = I
```

Renaming Algorithm Contd.

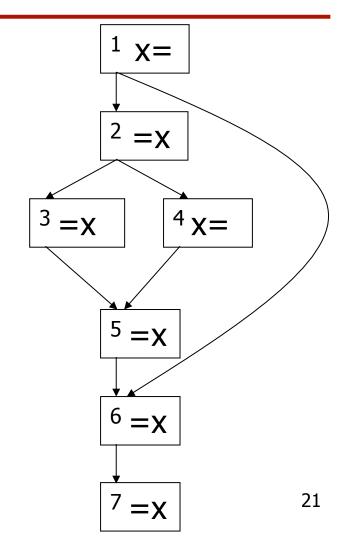
```
for each s \in succ(b) { // successor in CFG j = WhichPredecessor(s,b) for each I \in \Phi(s) of the form T_0 = \phi(T_1,...,T_n) { replace T_j by Top(NameStack(T_j)) add I to Uses(Top(NameStack(T_j))) } } for each c \in Children(b) // in dominator tree Rename(c)
```

Renaming Algorithm Contd.

```
for each I \in b in reverse order { T = Target(I) replace T by Pop(NameStack(T)) } for each I \in \Phi(b) of the form T_0 = \phi(T_1,...,T_n) { replace T_0 by Pop(NameStack(T_0)) }
```

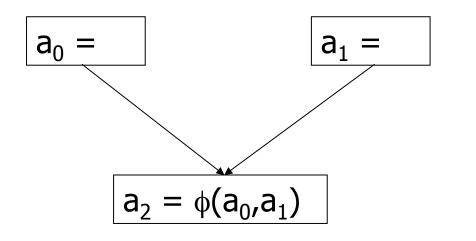
Example

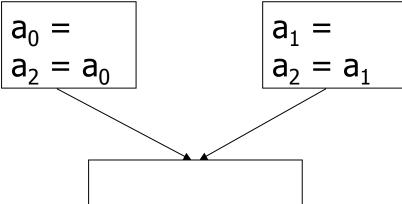
Convert the code to the right to SSA



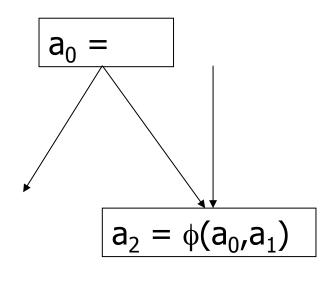
SSA to Normal Form

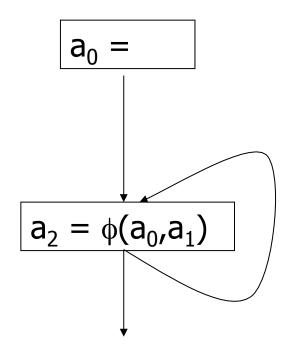
- \$\phi\$-nodes require copies from operands to l-value for each operand
- Becomes





Problems with Direct Translation

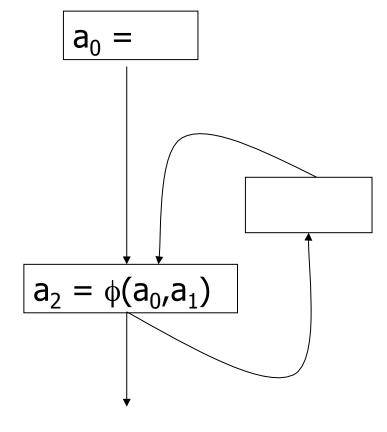




- Cannot move a copy into predecessor
- Cannot put copy at beginning of block

Critical Edges

- An edge where the tail of the edge has more than one predecessor and the head of the edge has more than one successor is called the critical edge.
- The solution is to insert a basic block on all critical edges so that the CFG has none.



Abnormal Edges

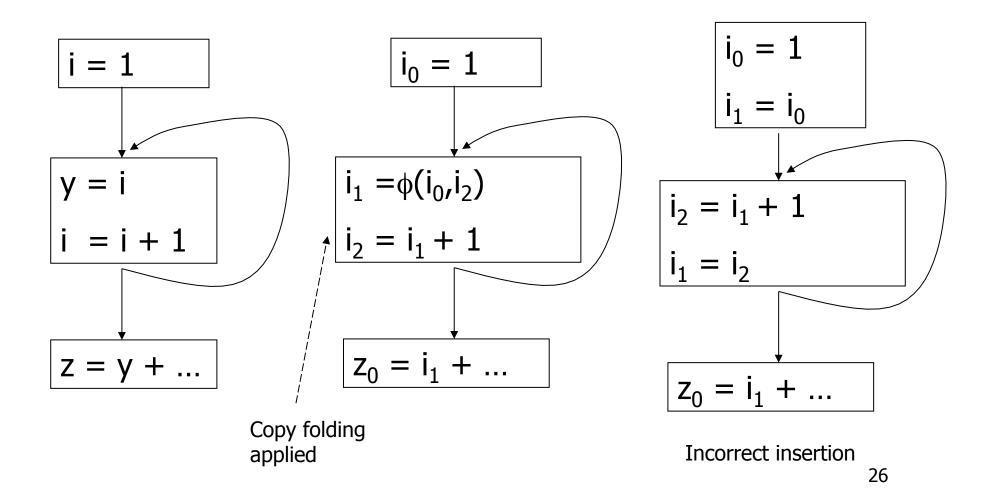
Edges where the head is not definite (known branch target) are called abnormal edges.

```
switch(a) {
  case 1:
    // no break statement
  case 2:
}
```

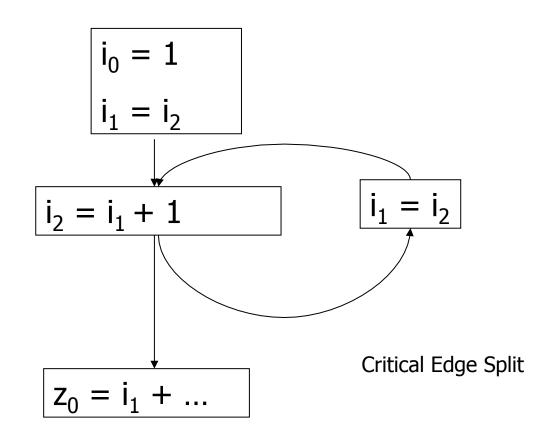
```
iLD
iMULI
iMULI
iLDA
br_table, r1
BR
r2(r1)
...
L1: nop
...
L2: nop
```

Must ensure that no blocks will need to be inserted on an abnormal critical edge

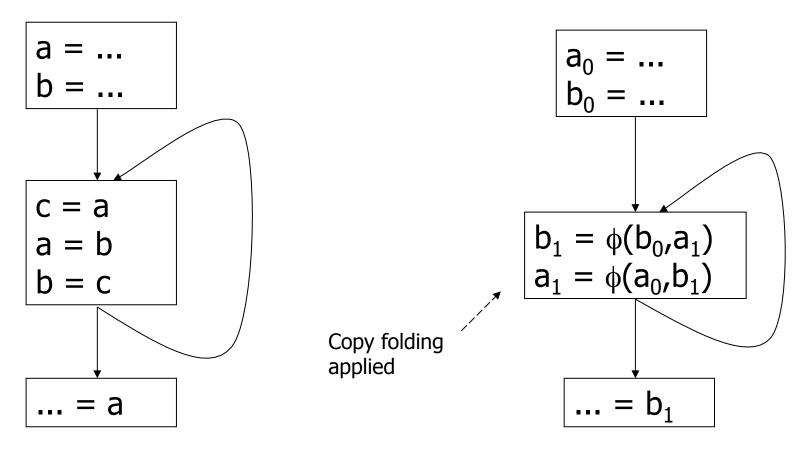
The Lost-Copy Problem



The Lost-Copy Problem

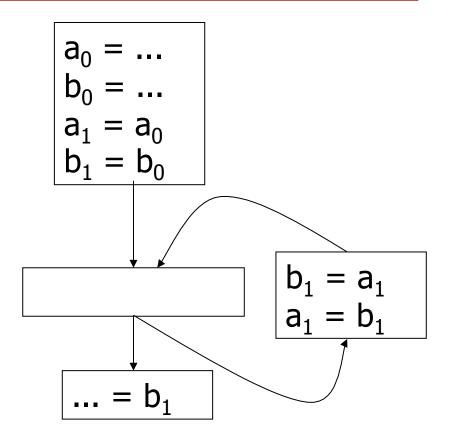


The Swap Problem

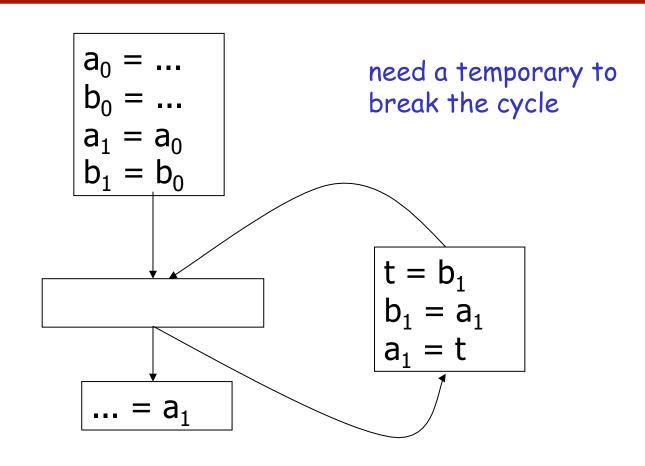


The Swap Problem

- > In a block b, all members of $\Phi(b)$ are executed simultaneously
- Direct translation of the previous code results in incorrect code.



Correct Translation



Translating to Normal Form

- Siven a CFG in SSA form and a partition $P=\{P_1,...P_n\}$ of the set of all variables, rewrite the CFG in normal form so that any two temporaries T_1 and T_2 in P_i are given the same temporary name and ϕ -nodes are replaced by equivalent copy operations. The partition must ensure that
 - In each block b, if two targets of ϕ -nodes are equivalent, then the corresponding arguments must be equivalent.
 - For each abnormal critical edge (c,b) if $T_0 = \phi(T_1,...,T_i,....T_n)$ is a ϕ -node in b and c is the ith predecessor of b, then T_0 and T_i must be equivalent (no copies on abnormal critical edges).
- > Each P_i has a single unique name
- Can use global value numbering to compute partition

Renaming ϕ -nodes

- Since all $i \in \Phi(b)$ are executed simultaneously, they need to be topologically sorted so that all uses of a variable T_i are generated before the definition.
- Since there may be cycles, these need to be handled separately
 - find cycles
 - break cycles with an additional temporary

Cycles within ϕ -nodes

- A graph R(b) such that the nodes are the elements of P and there is an edge from FIND(T_k) to FIND (T_l) if there are temporaries T_k and T_l such that $T_k = \phi(..., T_l, ...) \in \Phi(b)$.
- ▶ Use Tarjan's SCC algorithm to find cycles in R(b).

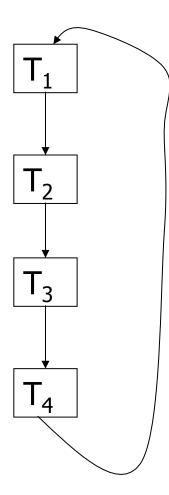
Cycles within ϕ -nodes

- For each SCC do the following
 - 1. Enumerate the cycle in some topological order such that the first node is a successor of the last.
 - 2. Generate one extra temporary, T.
 - 3. Generate an instruction to copy the temporary representing the first node into T.
 - 4. Translate all of the other nodes except the last one normally.
 - 5. Generate an instruction to copy T into the temporary corresponding to the final node.

Example

$$T_1 = \phi(..., T_2, ...)$$

 $T_2 = \phi(..., T_3, ...)$
 $T_3 = \phi(..., T_4, ...)$
 $T_4 = \phi(..., T_1, ...)$



```
foreach b \in G {
   for each \ i \in b \ \{
    foreach T \in Operands(i)
        replace T by FIND(T)
    foreach T \in Targets(i)
        replace T by FIND(T)
    if i = (T = T)
        delete i from b
   foreach c \in pred(b)
    call eliminate-\phi(c,b,whichpred(c,b))
foreach b \in G
   remove \phi-nodes from b
```

```
procedure eliminate-\( \phi(c,b,i) \)
call eliminateBuild(b,i)
if nodeSet ≠ Ø {
    Visited = Stack = Ø
    foreach T ∈ nodeSet
        if T ∉ Visited
        call elimForward(T)
    Visited = Ø
    while Stack ≠ Ø {
        pop T from Stack
        if T ∉ Visited
        call elimCreate(T)
    }
}
end eliminate-\( \phi(c,b,i) \)
```

```
procedure elimForward(T)
   add T to Visited
   foreach S ∈ elimSucc(T)
   if S ∉Visited
      elimForward(S)
   push T onto Stack
end elimForward
```

```
procedure eliminateBuild(b,i)
                                       procedure elimName(T)
   nodeSet = \emptyset
                                          if T ∉ nodeSet {
   foreach T_0 = \phi(..., T_i,...) \in \Phi(b)
                                            add T to nodeSet
    x_0 = FIND(T_0)
                                            elimSucc(T) = \emptyset
    x_1 = FIND(T_i)
                                            elimPred(T) = \emptyset
    if x_0 \neq x_1 {
         call elimName(x_0)
                                       end elimName
         call elimName(x_1)
         add x_0 to elimPred(x_1)
         add x_1 to elimSucc(x_0)
end eliminateBuild
```

```
procedure elimCreate(T)
   if elimUnvisitPred(T) {
    create new temp U
    append "U=T" to C
    foreach p∈elimPred(T)
     if p∉Visited {
        call elimBack(p)
        append "P=U" to C
   else if elimSucc(T)≠∅ {
    add T to Visited
    take S from elimSucc(T)
    append "T=5" to C
end elimCreate
```

```
function elimUnvisitPred(T)
    foreach p ∈ elimPred(T)
    if p ∉ Visited
        return true
    return false
end elimUnvisitPred

procedure elimBack(T)
    add T to Visited
    foreach p ∈ elimPred(T)
    if p ∉ Visited {
        call elimBack(p)
        append "P=T" to C
    }
end elimBack
```

Example

$$F = \phi(...,B,...)$$

$$C = \phi(...,D,...)$$

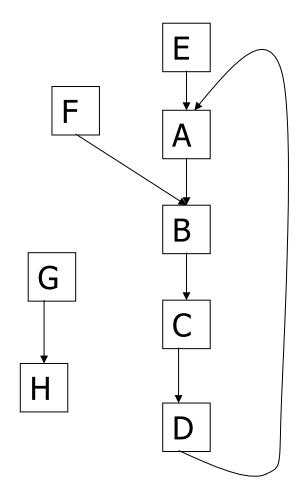
$$E = \phi(...,A,...)$$

$$G = \phi(...,H,...)$$

$$B = \phi(...,C,...)$$

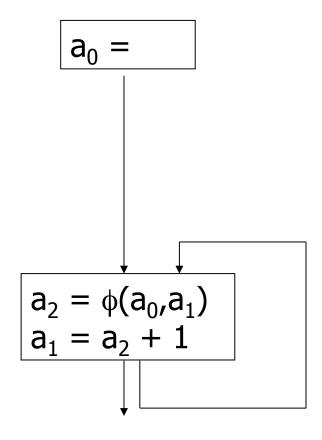
$$D = \phi(...,A,...)$$

$$A = \phi(...,B,...)$$



Critical Edges Re-visited

- In the CFG to the right, if a₂ is not used outside the block, the new basic block is unnecessary.
- Since inserting a block on a back edge puts a jump in loop, splitting the critical edge is not advisable.



Critical Edges Re-visited

If a₂ is used outside the block, add a copy to a temporary t and replace the uses of a₂ outside the block with t

