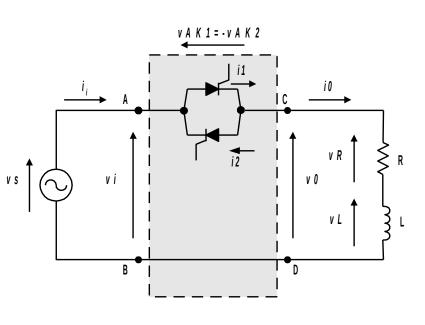
Controladores de Tensão CA Monofásicos

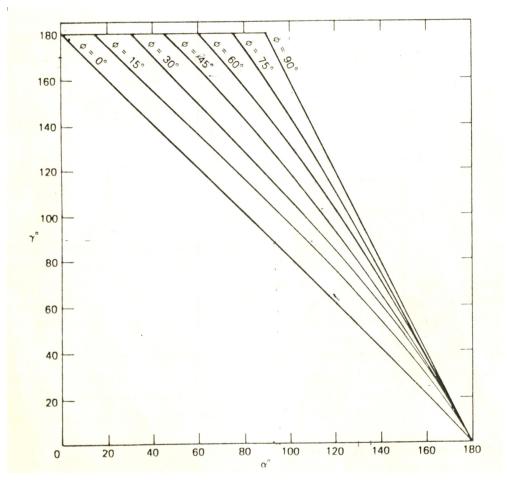
Curvas de Projeto

CONTROLADOR DE TENSÃO CA MONOFÁSICO Ângulo de Condução – Carga RL



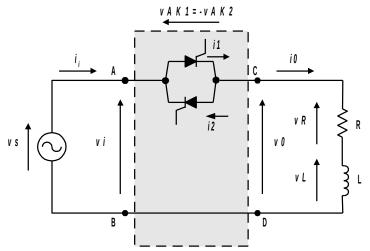
$$\operatorname{sen}(\beta - \phi) = \operatorname{sen}(\alpha - \phi) \cdot e^{[\alpha - \beta]/\tan \phi}$$

$$\gamma = \beta - \alpha \le 180^{\circ}$$



CONTROLADOR DE TENSÃO CA MONOFÁSICO

Corrente Média Normalizada por Tiristor – Carga RL

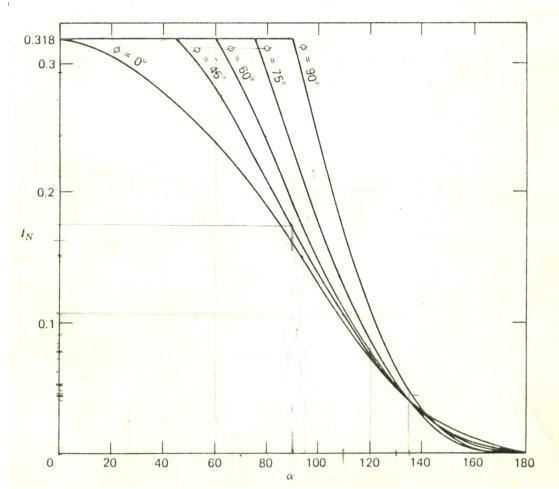


$$i_N = \operatorname{sen}(\omega \cdot t - \phi) - e^{(\alpha - \omega \cdot t)/\tan \phi} \cdot \operatorname{sen}(\alpha - \phi)$$

$$i_N = \frac{i(\omega.t)}{I_{base}}$$
 ; $I_{base} = \frac{\sqrt{2}.V}{Z}$

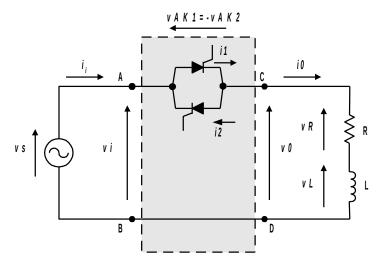
$$Z = \sqrt{R^2 + (\omega \cdot L)^2}$$
; $\phi = \arctan(\omega \cdot L/R)$

$$I_{N} = \frac{1}{2.\pi} \int_{\alpha}^{\beta = \gamma + \alpha} i_{N} . d\omega t$$



CONTROLADOR DE TENSÃO CA MONOFÁSICO

Corrente RMS Normalizada por Tiristor – Carga RL

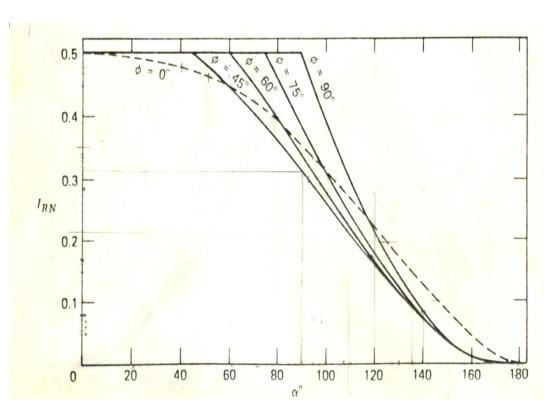


$$i_N = \operatorname{sen}(\omega \cdot t - \phi) - e^{(\alpha - \omega \cdot t)/\tan \phi} \cdot \operatorname{sen}(\alpha - \phi)$$

$$i_N = i(\omega.t)/I_{base}$$
 ; $I_{base} = \sqrt{2.V}/Z$

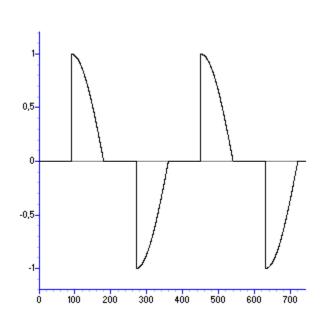
$$Z = \sqrt{R^2 + (\omega \cdot L)^2}$$
; $\phi = \arctan(\omega \cdot L/R)$

$$I_{RN} = \sqrt{\frac{1}{2.\pi} \int_{\alpha}^{\beta = \gamma + \alpha} i_N^2 . d\omega t}$$



CONTROLADOR DE TENSÃO CA MONOFÁSICO

Amplitude dos três primeiros Harmônicos Carga Resistiva - R



 $H_{n\alpha} = \frac{\text{valor rms do n}^0 \text{ harmônico no ângulo } \alpha}{\text{valor rms da corrente de linha para } \alpha = 0^0}$

$$H_{n\alpha} = \frac{I_n(\alpha)}{I_1(\alpha = 0^0)}$$

