# WEEK 2

1. Analyse and implement Vacuum Cleaner Agent.

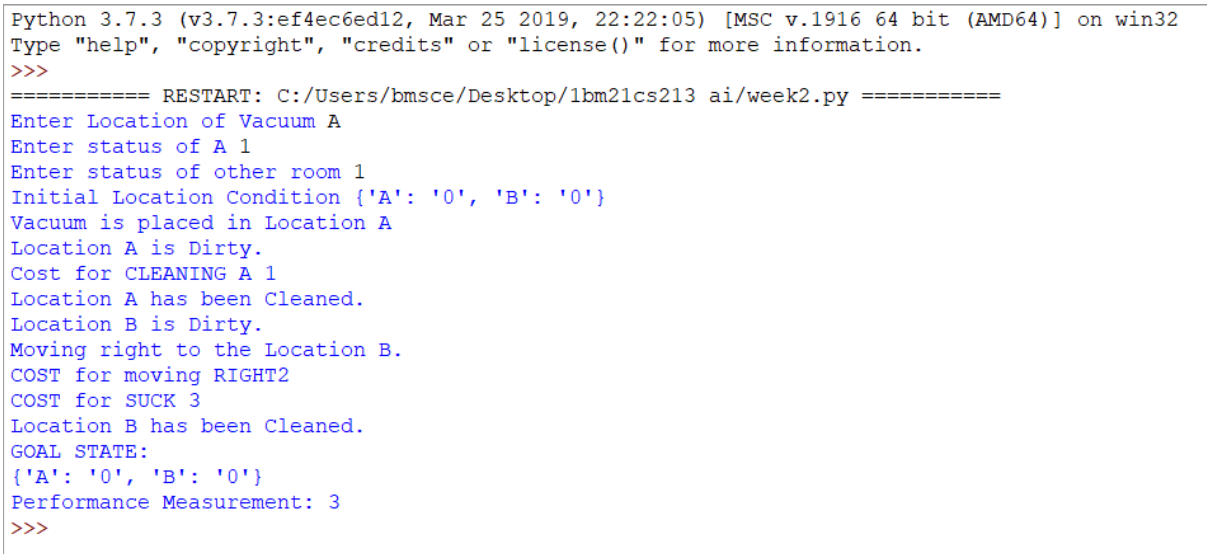
Program:

```
def vacuum_world():
        # initializing goal_state
        # 0 indicates Clean and 1 indicates Dirty
    goal_state = {'A': '0', 'B': '0'}
    cost = 0


    location_input = input("Enter Location of Vacuum ") #user_input
of location vacuum is placed
    status_input = input("Enter status of " + location_input + " ")
#user_input if location is dirty or clean
    status_input_complement = input("Enter status of other room ")
    print("Initial Location Condition " + str(goal_state))


    if location_input == 'A':
        # Location A is Dirty.
        print("Vacuum is placed in Location A ")
        if status_input == '1':
            print("Location A is Dirty. ")
            # suck the dirt  and mark it as clean
            goal_state['A'] = '0'
            cost += 1                   #cost for suck
    print("Cost for CLEANING A " + str(cost))
    print("Location A has been Cleaned. ")

    if status_input_complement == '1':
        # if B is Dirty
        print("Location B is Dirty.")
        print("Moving right to the Location B. ")
        cost += 1                   #cost for moving right
        print("COST for moving RIGHT" + str(cost))
        # suck the dirt and mark it as clean
        goal_state['B'] = '0'
        cost += 1                   #cost for suck
        print("COST for SUCK " + str(cost))
        print("Location B has been Cleaned. ")
    else:
        print("No action" + str(cost))
        # suck and mark clean
        print("Location B is already clean. ")

if status_input == '0':
    print("Location A is already clean ")
    if status_input_complement == '1':# if B is Dirty
        print("Location B is Dirty.")
        print("Moving RIGHT to the Location B. ")
```

```
            cost += 1                    #cost for moving right
            print("COST for moving RIGHT " + str(cost))
            # suck the dirt and mark it as clean
            goal_state['B'] = '0'
            cost += 1                    #cost for suck
            print("Cost for SUCK" + str(cost))
            print("Location B has been Cleaned. ")
        else:
            print("No action " + str(cost))
            print(cost)
            # suck and mark clean
            print("Location B is already clean.")

else:
    print("Vacuum is placed in location B ")
    # Location B is Dirty.
    if status_input == '1':
        print("Location B is Dirty.")
        # suck the dirt  and mark it as clean
        goal_state['B'] = '0'
        cost += 1  # cost for suck
        print("COST for CLEANING " + str(cost))
        print("Location B has been Cleaned.")
    if status_input_complement == '1':
        # if A is Dirty
        print("Location A is Dirty.")
        print("Moving LEFT to the Location A. ")
        cost += 1  # cost for moving right
        print("COST for moving LEFT " + str(cost))
        # suck the dirt and mark it as clean
        goal_state['A'] = '0'
        cost += 1  # cost for suck
        print("COST for SUCK " + str(cost))
        print("Location A has been Cleaned. ")

else:
    print(cost)
    # suck and mark clean
    print("Location B is already clean. ")

    if status_input_complement == '1':  # if A is Dirty
        print("Location A is Dirty.")
        print("Moving LEFT to the Location A. ")
        cost += 1  # cost for moving right
        print("COST for moving LEFT " + str(cost))
        # suck the dirt and mark it as clean
        goal_state['A'] = '0'
```

```
                cost += 1  # cost for suck
                print("Cost for SUCK " + str(cost))
                print("Location A has been Cleaned. ")
            else:
                print("No action " + str(cost))
                # suck and mark clean
                print("Location A is already clean.")

    # done cleaning
    print("GOAL STATE: ")
    print(goal_state)
    print("Performance Measurement: " + str(cost))


vacuum_world()
```

Output:



```
Python 3.7.3 (v3.7.3:ef4ec6ed12, Mar 25 2019, 22:22:05) [MSC v.1916 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>> 
=========== RESTART: C:/Users/bmsce/Desktop/1bm21cs213 ai/week2.py ===========
Enter Location of Vacuum A
Enter status of A 1
Enter status of other room 1
Initial Location Condition {'A': '0', 'B': '0'}
Vacuum is placed in Location A
Location A is Dirty.
Cost for CLEANING A 1
Location A has been Cleaned.
Location B is Dirty.
Moving right to the Location B.
COST for moving RIGHT2
COST for SUCK 3
Location B has been Cleaned.
GOAL STATE:
{'A': '0', 'B': '0'}
Performance Measurement: 3
>>> 
```