Coursera Machine Learning Project

Xenia Sokolova 2020, april 2

COURSERA MACHINE LEARNING PROJECT

Weight Lifting Exercises Dataset

EXECUTIVE SUMMARY

We propose a dataset with 5 classes (sitting-down, standing-up, standing, walking, and sitting) collected on 8 hours of activities of 4 healthy subjects. The goal of the project is to predict the manner in which they did the exercise.

BASIC EXPLORATORY DATA ANALYSIS

Downloading r packages:

```
library(readr)
library(caret)
## Loading required package: lattice
## Loading required package: ggplot2
library(randomForest)
## randomForest 4.6-14
## Type rfNews() to see new features/changes/bug fixes.
##
## Attaching package: 'randomForest'
## The following object is masked from 'package:ggplot2':
##
##
       margin
library(dplyr)
## Attaching package: 'dplyr'
## The following object is masked from 'package:randomForest':
##
##
       combine
```

```
## The following objects are masked from 'package:stats':
##
##
       filter, lag
## The following objects are masked from 'package:base':
##
##
       intersect, setdiff, setequal, union
Loading data:
setwd("C:/Users/xssok/Documents")
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-training.csv",
               "pml-training.csv")
download.file("https://d396qusza40orc.cloudfront.net/predmachlearn/pml-testing.csv",
               "pml-testing.csv")
training_pml <-read.csv("pml-training.csv")</pre>
testing_pml <- read.csv("pml-testing.csv")</pre>
Checking dimensions of the training and testing data:
dim(training_pml)
## [1] 19622
                160
dim(testing_pml)
## [1] 20 160
Cross validation:
set.seed(1234)
inTrain <- createDataPartition(y=training_pml$classe,</pre>
                                 p=0.6, list=FALSE)
training <- training_pml[inTrain,] ## subset data into training set</pre>
testing <- training_pml[-inTrain,] ## subset data into test set</pre>
Explore the training set:
dim(training)
## [1] 11776
               160
dim(testing)
## [1] 7846 160
```

str(training)

```
## 'data.frame':
                  11776 obs. of 160 variables:
## $ X
                            : int 2 3 4 5 6 7 8 10 11 12 ...
## $ user name
                            : Factor w/ 6 levels "adelmo", "carlitos", ...: 2 2 2 2 2 2 2 2 2 2 ...
                            : int 1323084231 1323084231 1323084232 1323084232 1323084232 1323084232
## $ raw_timestamp_part_1
                                  808298 820366 120339 196328 304277 368296 440390 484434 500302 528
   $ raw_timestamp_part_2
## $ cvtd_timestamp
                            : Factor w/ 20 levels "02/12/2011 13:32",...: 9 9 9 9 9 9 9 9 9 9 ...
                            : Factor w/ 2 levels "no", "yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ new_window
## $ num_window
                            : int 11 11 12 12 12 12 12 12 12 12 ...
                            : num 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.45 1.45 1.43 ...
## $ roll belt
## $ pitch belt
                            : num 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.17 8.18 8.18 ...
## $ yaw_belt
                            : num
                                  -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
## $ total_accel_belt
                            : int 3 3 3 3 3 3 3 3 3 ...
## $ kurtosis_roll_belt
                            : Factor w/ 397 levels "","-0.016850",..: 1 1 1 1 1 1 1 1 1 1 ...
                            : Factor w/ 317 levels "","-0.021887",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis picth belt
                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_belt
                            : Factor w/ 395 levels "","-0.003095",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness roll belt
## $ skewness_roll_belt.1
                            : Factor w/ 338 levels "","-0.005928",...: 1 1 1 1 1 1 1 1 1 1 ...
                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_yaw_belt
## $ max_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt
                                  NA NA NA NA NA NA NA NA NA ...
                            : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ max_yaw_belt
## $ min_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_belt
                            : int NA NA NA NA NA NA NA NA NA ...
                            : Factor w/ 68 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ min_yaw_belt
## $ amplitude_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
                            : int NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt
## $ amplitude_yaw_belt
                            : Factor w/ 4 levels "","#DIV/0!","0.00",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ var_total_accel_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_belt
                            : num NA NA NA NA NA NA NA NA NA ...
                            : num NA NA NA NA NA NA NA NA NA ...
## $ var roll belt
## $ avg_pitch_belt
                            : num NA NA NA NA NA NA NA NA NA ...
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt
                            : num
## $ var_pitch_belt
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
## $ avg_yaw_belt
                                  NA NA NA NA NA NA NA NA NA ...
                            : num
## $ stddev_yaw_belt
                            : num NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt
                            : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ gyros_belt_x
                                  : num
## $ gyros_belt_y
                                 0 0 0 0.02 0 0 0 0 0 0 ...
                            : num
## $ gyros_belt_z
                                  -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 0 -0.02 -0.02 ...
                            : num
## $ accel_belt_x
                            : int
                                  -22 -20 -22 -21 -21 -22 -22 -21 -21 -22 ...
## $ accel_belt_y
                                  4 5 3 2 4 3 4 4 2 2 ...
                            : int
## $ accel belt z
                            : int
                                  22 23 21 24 21 21 21 22 23 23 ...
## $ magnet_belt_x
                                 -7 -2 -6 -6 0 -4 -2 -3 -5 -2 ...
                           : int
## $ magnet_belt_y
                            : int 608 600 604 600 603 599 603 609 596 602 ...
## $ magnet_belt_z
                            : int
                                  -311 -305 -310 -302 -312 -311 -313 -308 -317 -319 ...
## $ roll_arm
                           ## $ pitch_arm
                           : num 22.5 22.5 22.1 22.1 22 21.9 21.8 21.6 21.5 21.5 ...
## $ yaw arm
                                  : num
## $ total_accel_arm
                            : int
                                  34 34 34 34 34 34 34 34 34 ...
## $ var_accel_arm
                            : num NA NA NA NA NA NA NA NA NA ...
```

```
## $ avg_roll_arm
                                                       NA NA NA NA NA NA NA NA NA ...
                                             : num
## $ stddev_roll_arm
                                                       NA NA NA NA NA NA NA NA NA ...
                                            : num
## $ var roll arm
                                                       NA NA NA NA NA NA NA NA NA ...
                                             : num
## $ avg_pitch_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_arm
                                             : num
                                                       NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_arm
##
     $ stddev_yaw_arm
                                             : num
                                                      NA NA NA NA NA NA NA NA NA ...
##
     $ var_yaw_arm
                                             : num
                                                       NA NA NA NA NA NA NA NA NA ...
## $ gyros_arm_x
                                             : num
                                                      ## $ gyros_arm_y
                                             : num
                                                      -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 -0.03 ...
                                                       -0.02 -0.02 0.02 0 0 0 0 -0.02 0 0 ...
##
     $ gyros_arm_z
                                             : num
##
     $ accel_arm_x
                                                      -290 -289 -289 -289 -289 -289 -289 -288 -290 -288 ...
                                             : int
## $ accel_arm_y
                                                     110 110 111 111 111 111 111 110 110 111 ...
                                            : int
## $ accel_arm_z
                                                       -125 -126 -123 -123 -122 -125 -124 -124 -123 -123 ...
                                            : int
##
     $ magnet_arm_x
                                             : int
                                                       -369 -368 -372 -374 -369 -373 -372 -376 -366 -363 ...
## $ magnet_arm_y
                                            : int 337 344 344 337 342 336 338 334 339 343 ...
## $ magnet arm z
                                             : int 513 513 512 506 513 509 510 516 509 520 ...
                                            : Factor w/ 330 levels "","-0.02438",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_roll_arm
## $ kurtosis_picth_arm
                                            : Factor w/ 328 levels "","-0.00484",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_arm
                                            : Factor w/ 395 levels "","-0.01548",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_arm
                                            : Factor w/ 331 levels "","-0.00051",..: 1 1 1 1 1 1 1 1 1 1 ...
                                            : Factor w/ 328 levels "","-0.00184",...: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_pitch_arm
                                             : Factor w/ 395 levels "","-0.00311",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness yaw arm
## $ max_roll_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_arm
                                             : int NA NA NA NA NA NA NA NA NA ...
## $ min_roll_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_arm
                                             : num NA NA NA NA NA NA NA NA NA ...
                                             : int \ \mbox{NA} \mbox{NA} \ \mbox{NA} 
## $ min_yaw_arm
##
     $ amplitude_roll_arm
                                             : num
                                                       NA NA NA NA NA NA NA NA NA ...
##
     $ amplitude_pitch_arm
                                            : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_yaw_arm
                                             : int NA NA NA NA NA NA NA NA NA ...
## $ roll_dumbbell
                                             : num 13.1 12.9 13.4 13.4 13.4 ...
## $ pitch dumbbell
                                                       -70.6 -70.3 -70.4 -70.4 -70.8 ...
                                             : num
## $ yaw_dumbbell
                                             : num -84.7 -85.1 -84.9 -84.9 -84.5 ...
## $ kurtosis_roll_dumbbell : Factor w/ 398 levels "","-0.0035","-0.0073",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_picth_dumbbell : Factor w/ 401 levels "","-0.0163","-0.0233",..: 1 1 1 1 1 1 1 1 1 1 ...
     $ kurtosis_yaw_dumbbell
                                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
##
## $ skewness_roll_dumbbell : Factor w/ 401 levels "","-0.0082","-0.0096",..: 1 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_pitch_dumbbell : Factor w/ 402 levels "","-0.0053","-0.0084",..: 1 1 1 1 1 1 1 1 1 1 ...
                                            : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_yaw_dumbbell
     $ max roll dumbbell
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                                             : num NA NA NA NA NA NA NA NA NA ...
                                             : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 ...
## $ max_yaw_dumbbell
##
                                             : num NA NA NA NA NA NA NA NA NA ...
     $ min_roll_dumbbell
## $ min_pitch_dumbbell
                                             : num NA NA NA NA NA NA NA NA NA ...
## $ min_yaw_dumbbell
                                             : Factor w/ 73 levels "","-0.1","-0.2",..: 1 1 1 1 1 1 1 1 1 1 1 ...
[list output truncated]
```

table(training\$classe)

```
## A B C D E
## 3348 2279 2054 1930 2165
```

FEATURE SELECTION

Exclude first 7 columns: "X", "user_name", "raw_timestamp_part_1", "raw_timestamp_part_2", "cvtd_timestamp", "new_window", "num_window", because we don't need them for the prediction.

```
training_ex <- select(training, -(X:num_window))</pre>
```

Select variables with missing data (more than 95%) and exclude them from the data table:

```
training_ex[training_ex==""] <- NA
NArate <- apply(training_ex, 2, function(x) sum(is.na(x)))/nrow(training_ex)
training_cl <- training_ex[!(NArate>0.95)]
```

Now we've got 53 variables:

```
str(training_cl)
```

```
## 'data.frame':
                 11776 obs. of 53 variables:
                       : num 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.45 1.45 1.43 ...
## $ roll_belt
## $ pitch_belt
                       : num 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.17 8.18 8.18 ...
                             -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 -94.4 ...
## $ yaw_belt
                       : num
## $ total_accel_belt
                       : int
                             3 3 3 3 3 3 3 3 3 ...
##
   $ gyros_belt_x
                             : num
                             0 0 0 0.02 0 0 0 0 0 0 ...
## $ gyros_belt_y
                       : num
## $ gyros_belt_z
                       : num
                             -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 0 -0.02 -0.02 ...
                             -22 -20 -22 -21 -21 -22 -22 -21 -21 -22 ...
## $ accel_belt_x
                       : int
## $ accel_belt_y
                             4 5 3 2 4 3 4 4 2 2 ...
                       : int
## $ accel_belt_z
                             22 23 21 24 21 21 21 22 23 23 ...
                       : int
## $ magnet_belt_x
                             -7 -2 -6 -6 0 -4 -2 -3 -5 -2 ...
                       : int
                             608 600 604 600 603 599 603 609 596 602 ...
## $ magnet_belt_y
                       : int
##
   $ magnet belt z
                       : int
                             -311 -305 -310 -302 -312 -311 -313 -308 -317 -319 ...
## $ roll_arm
                             : num
                             22.5 22.5 22.1 22.1 22 21.9 21.8 21.6 21.5 21.5 ...
## $ pitch_arm
                       : num
## $ yaw arm
                             : num
## $ total_accel_arm
                       : int
                             34 34 34 34 34 34 34 34 34 ...
## $ gyros_arm_x
                       : num
                             ## $ gyros_arm_y
                             -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 -0.03 ...
                       : num
## $ gyros_arm_z
                       : num
                             -0.02 -0.02 0.02 0 0 0 0 -0.02 0 0 ...
## $ accel_arm_x
                       : int
                             -290 -289 -289 -289 -289 -289 -289 -288 -290 -288 ...
## $ accel_arm_y
                       : int
                             110 110 111 111 111 111 111 110 110 111 ...
                             -125 -126 -123 -123 -122 -125 -124 -124 -123 -123 ...
## $ accel_arm_z
                       : int
## $ magnet_arm_x
                             -369 -368 -372 -374 -369 -373 -372 -376 -366 -363 ...
                       : int
## $ magnet_arm_y
                             337 344 344 337 342 336 338 334 339 343 ...
                       : int
## $ magnet_arm_z
                             513 513 512 506 513 509 510 516 509 520 ...
                       : int
## $ roll_dumbbell
                       : num
                             13.1 12.9 13.4 13.4 13.4 ...
## $ pitch_dumbbell
                             -70.6 -70.3 -70.4 -70.4 -70.8 ...
                       : num
## $ yaw_dumbbell
                       : num
                             -84.7 -85.1 -84.9 -84.9 -84.5 ...
## $ total_accel_dumbbell: int
                            37 37 37 37 37 37 37 37 37 ...
## $ gyros dumbbell x
                       : num 0000000000...
```

```
## $ gyros_dumbbell_y
                       : num -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 -0.02 ...
## $ gyros_dumbbell_z : num 0 0 -0.02 0 0 0 0 0 0 ...
## $ accel_dumbbell_x : int
                             -233 -232 -232 -233 -234 -232 -234 -235 -233 -233 ...
## $ accel_dumbbell_y
                       : int 47 46 48 48 48 47 46 48 47 47 ...
## $ accel_dumbbell_z
                       : int
                             -269 -270 -269 -270 -269 -270 -272 -270 -269 -270 ...
## $ magnet dumbbell x : int -555 -561 -552 -554 -558 -551 -555 -558 -564 -554 ...
## $ magnet dumbbell y
                       : int
                             296 298 303 292 294 295 300 291 299 291 ...
## $ magnet_dumbbell_z
                       : num
                             -64 -63 -60 -68 -66 -70 -74 -69 -64 -65 ...
## $ roll_forearm
                       : num
                              28.3 28.3 28.1 28 27.9 27.9 27.8 27.7 27.6 27.5 ...
## $ pitch_forearm
                       : num
                             -63.9 -63.9 -63.9 -63.9 -63.9 -63.8 -63.8 -63.8 -63.8 ...
## $ yaw_forearm
                             : num
## $ total_accel_forearm : int
                              36 36 36 36 36 36 36 36 36 ...
## $ gyros_forearm_x : num
                             -0.02 0 0 -0.02 -0.03 -0.02 0 -0.02 -0.02 -0.03 ...
## $ accel_forearm_x
                       : int
                             192 196 189 189 193 195 193 190 193 191 ...
## $ accel_forearm_y
                             203 204 206 206 203 205 205 205 205 203 ...
                      : int
## $ accel_forearm_z
                             -216 -213 -214 -214 -215 -215 -213 -215 -214 -215 ...
                       : int
## $ magnet_forearm_x : int -18 -18 -16 -17 -9 -18 -9 -22 -17 -11 ...
## $ magnet_forearm_y
                       : num 661 658 658 655 660 659 660 656 657 657 ...
## $ magnet_forearm_z
                       : num 473 469 469 473 478 470 474 473 465 478 ...
## $ classe
                       : Factor w/ 5 levels "A", "B", "C", "D", ...: 1 1 1 1 1 1 1 1 1 1 ...
Applying PCA Since the number of variables are over 50:
preProc <- preProcess(training_cl[,-53], method="pca", thresh=.8) #12 components to capture 80 percent of
preProc
## Created from 11776 samples and 52 variables
##
## Pre-processing:
##
    - centered (52)
##
    - ignored (0)
    - principal component signal extraction (52)
    - scaled (52)
##
##
## PCA needed 12 components to capture 80 percent of the variance
preProc <- preProcess(training_cl[,-53], method="pca", thresh=.9) #18 components to capture 90 percent of
preProc
## Created from 11776 samples and 52 variables
##
## Pre-processing:
##
    - centered (52)
##
    - ignored (0)
##
    - principal component signal extraction (52)
    - scaled (52)
##
## PCA needed 18 components to capture 90 percent of the variance
```

```
preProc <- preProcess(training_cl[,-53],method="pca",thresh=.95) #24 components to capture
preProc

## Created from 11776 samples and 52 variables
##
## Pre-processing:
## - centered (52)
## - ignored (0)
## - principal component signal extraction (52)
## - scaled (52)
##
## PCA needed 24 components to capture 95 percent of the variance

preProc <- preProcess(training_cl[,-53],method="pca",pcaComp=24)
training_pca <- predict(preProc,training_cl[,-53])</pre>
```

APPLYING A MODEL

Our data have got non-bionominal outcome and large sample size, that's why we're using random forest method.

```
modFit <- randomForest(training_cl$classe ~ ., data=training_pca, do.trace=F)</pre>
print(modFit) # view results
##
## randomForest(formula = training_cl$classe ~ ., data = training_pca,
                                                                           do.trace = F)
                 Type of random forest: classification
##
                       Number of trees: 500
## No. of variables tried at each split: 4
##
          OOB estimate of error rate: 3.08%
##
## Confusion matrix:
##
       Α
            В
                C
                      D
                           E class.error
                      9
## A 3303
          18
               15
                           3 0.01344086
## B
      57 2171
                41
                      3
                           7 0.04738921
## C
       4
           34 1986
                     28
                           2 0.03310613
                           3 0.05025907
## D
       3
                90 1833
            1
## E
                22
                    12 2120 0.02078522
```

Checking on the test data:

```
testing_cl <- select(testing, -(X:num_window))
testing_cl[testing_cl==""] <- NA
NArate <- apply(testing_cl, 2, function(x) sum(is.na(x)))/nrow(testing_cl)
testing_cl <- testing_cl[!(NArate>0.95)]
testing_pca <- predict(preProc,testing_cl[,-53])
confusionMatrix(testing_cl$classe,predict(modFit,testing_pca))</pre>
```

Confusion Matrix and Statistics

```
##
##
            Reference
## Prediction
                Α
                          C
                               D
                                    Ε
           A 2213
                                     0
##
                     3
                           6
                               10
##
           В
               23 1470
                          24
                               0
                                     1
           С
                3
                     28 1321
                               15
##
                                     1
           D
                 5
                     0
                          58 1220
##
           Ε
##
                 2
                     8
                          13
                               9 1410
##
## Overall Statistics
##
##
                  Accuracy: 0.973
                    95% CI: (0.9691, 0.9765)
##
      No Information Rate: 0.2863
##
##
       P-Value [Acc > NIR] : < 2.2e-16
##
##
                     Kappa: 0.9658
##
##
  Mcnemar's Test P-Value : NA
##
## Statistics by Class:
##
                        Class: A Class: B Class: C Class: D Class: E
##
## Sensitivity
                          0.9853
                                 0.9742
                                          0.9290
                                                     0.9729
                                                              0.9965
                         0.9966 0.9924
                                          0.9927
                                                     0.9900
                                                              0.9950
## Specificity
                         0.9915 0.9684
## Pos Pred Value
                                          0.9656
                                                    0.9487
                                                              0.9778
## Neg Pred Value
                          0.9941 0.9938
                                           0.9844
                                                    0.9948
                                                              0.9992
## Prevalence
                                           0.1812
                                                    0.1598
                                                              0.1803
                          0.2863 0.1923
## Detection Rate
                          0.2821
                                  0.1874
                                           0.1684
                                                    0.1555
                                                              0.1797
## Detection Prevalence
                          0.2845
                                  0.1935
                                           0.1744
                                                     0.1639
                                                              0.1838
## Balanced Accuracy
                          0.9910 0.9833
                                            0.9608
                                                     0.9814
                                                              0.9957
```

PREDICTING CLASSES FOR TEST DATA (SIZE OF 20)

```
testing_pml_cl <- select(testing_pml, -(X:num_window))
testing_pml_cl[testing_pml_cl==""] <- NA
NArate <- apply(testing_pml_cl, 2, function(x) sum(is.na(x)))/nrow(testing_pml_cl)
testing_pml_cl <- testing_pml_cl[!(NArate>0.95)]
testing_pml_pca <- predict(preProc,testing_pml_cl[,-53])
testing_pml_cl$classe <- predict(modFit,testing_pml_pca)
cbind (as.character(testing_pml_cl$classe))</pre>
```

```
##
         [,1]
##
   [1,] "B"
##
   [2,] "A"
  [3,] "B"
##
##
  [4,] "A"
## [5,] "A"
##
   [6,] "E"
## [7,] "D"
## [8,] "B"
## [9,] "A"
```

```
## [10,] "A"
## [11,] "B"
## [12,] "C"
## [13,] "B"
## [14,] "A"
## [15,] "E"
## [16,] "E"
## [17,] "A"
## [18,] "B"
## [19,] "B"
```

CONCLUSION

In this analyses, 19622 observations from weight lifting exercise were used to analyze and predict correct body movement from others during the exercise. 60% of the total observations (11776 observations) were used to build a model by random forest method, and the rest of 40% of the observations (7846 observations) were used for model validation (cross-validation). The model statistics showed that the built model had the overall accuracy of 97% for the testing set, which is not overlapping with observations used to built the model. The sensitivity was in between 92%-99% and the specificity was over 99% for all classes. Overall, the model is well developed to predict the exercise classes during weight lifting. Therefore, under those condition, the model is expected to perform over 95% accuracy.