Outline of the 3D PPFV method used by Sayram: Yang et al., 2021

Xin Tao

November 20, 2024

The general quasilinear diffusion equation to be solved is

$$\frac{\partial f}{\partial t} = \frac{1}{G} \frac{\partial}{\partial Q_i} \left(GD_{ij} \frac{\partial f}{\partial Q_j} \right). \tag{1}$$

To solve is using a finite volume method, we rewrite it as

$$G\frac{\partial f}{\partial t} = \frac{\partial}{\partial Q_i} \left(GD_{ij} \frac{\partial f}{\partial Q_j} \right) \equiv \nabla \cdot (\Lambda \cdot \nabla f). \tag{2}$$

To simplify notation, we will let $\nabla \equiv \nabla_Q$ from now on. The equation has Dirichlet boundary conditions and Neumann boundary conditions on boundaries Γ_D and Γ_N , respectively. The Neumann boundary condition, or the flux at the boundary, must satisfy

$$(\Lambda \cdot \nabla f) \cdot \mathbf{n} \ge 0. \tag{3}$$

Applying the Gaussian divergence theorem to a control cell with center K, we have

$$\int_{K} G \frac{\partial f}{\partial t} dV = \int_{K} \nabla \cdot (\mathbf{\Lambda} \cdot \nabla f) dV = \oint_{\partial K} (\mathbf{\Lambda} \cdot \nabla f) \cdot d\mathbf{A}.$$
 (4)

Denoting the total flux \tilde{F} as

$$\tilde{F} \equiv -\oint_{\partial K} (\mathbf{\Lambda} \cdot \nabla f) \cdot d\mathbf{A}. \tag{5}$$

Numerically, the boundary of the cell K is dividied into faces, σ , and $\tilde{F} = \sum_{\sigma \in \partial K} \tilde{F}_{K,\sigma}$. we rewrite the above equation as

$$\int_{K} G \frac{\partial f}{\partial t} dV = -\sum_{\sigma \in \partial K} \tilde{F}_{K,\sigma}.$$
 (6)

with

$$\tilde{F}_{K,\sigma} = -\int_{\sigma} (\Lambda \cdot \nabla f) \cdot \boldsymbol{n}_{K,\sigma} dA.$$
 (7)

Numerically, Equation (6) is approximated as

$$G_K V_K \frac{f_K^{t+\Delta t} - f_K^t}{\Delta t} \approx -\sum_{\sigma \in \partial K} \tilde{F}_{K,\sigma},$$
 (8)

with each flux across σ face as

$$\tilde{F}_{K,\sigma} \approx -|\sigma|[\Lambda_K \cdot (\nabla f)_K] \cdot \boldsymbol{n}_{K,\sigma} = -|\sigma| \boldsymbol{n}_{K,\sigma} \cdot \Lambda_K \cdot (\nabla f)_K. \tag{9}$$

According to Yang et al., 2021, and considering that we are dealing with a time dependent diffusion problem, we write the flux $\tilde{F}_{K,\sigma}$ in the following form if σ is not a boundary face constructed using the so-called one-sided flux $F_{K,\sigma}$ and $F_{L,\sigma}$ as

$$\tilde{F}_{K,\sigma} = \mu_{K,\sigma} F_{K,\sigma} - \mu_{L,\sigma} F_{L,\sigma}. \tag{10}$$

Here, L is the a neighboring cell of K, sharing the face σ . We will use the first type of one-sided flux in Yang et al., 2021. The one-sided flux is

$$F_{K,\sigma} = \sum_{i=1}^{N_{K,\sigma}} a_{K,\sigma,i} (f_K - f_{K,\sigma,i})$$

$$\tag{11}$$

Here $N_{K,\sigma}$ is the number of tetrahedrons constructed with one vertex in the center of K, and the face σ (see Figure 1 of Yang et al., 2021). For our case of regular mesh in 3D, $N_{K,\sigma}=4$. The coefficient $a_{K,\sigma,i}$ is given by

$$a_{K,\sigma,i} = |\sigma| \mathbf{n}_{K,\sigma} \cdot \Lambda_K \cdot \boldsymbol{\beta}_{K,\sigma,i},$$
(12)

where

$$\beta_{K,\sigma,i} = \frac{1}{N_{K,\sigma}} \left(\alpha_{K,\sigma,i}^2 + \alpha_{K,\sigma,i-1}^3 + \frac{1}{N_{K,\sigma}} \sum_{i=1}^{N_{K,\sigma}} \alpha_{K,\sigma,i}^1 \right).$$
(13)

Here the superscripts 1, 2, 3 do not mean the power of 1,2, and 3. The corresponding variables are defined by

$$egin{aligned} oldsymbol{lpha}_{K,\sigma,i}^1 &= rac{(oldsymbol{x}_{K,\sigma,i} - oldsymbol{x}_K) imes (oldsymbol{x}_{K,\sigma,i+1} - oldsymbol{x}_K)}{6V_{T_i}}, \ oldsymbol{lpha}_{K,\sigma,i}^2 &= rac{(oldsymbol{x}_{K,\sigma,i+1} - oldsymbol{x}_K) imes (oldsymbol{x}_{K,\sigma,O} - oldsymbol{x}_K)}{6V_{T_i}}, \ oldsymbol{lpha}_{K,\sigma,i}^3 &= rac{(oldsymbol{x}_{K,\sigma,O} - oldsymbol{x}_K) imes (oldsymbol{x}_{K,\sigma,i} - oldsymbol{x}_K)}{6V_{T_i}}. \end{aligned}$$

Yang et al proved that $\sum_i a_{K,\sigma,i} > 0$.

The definition of $\mu_{K,\sigma}$ and $\mu_{L,\sigma}$ are

$$\begin{cases} \mu_{K,\sigma} = \mu_{L,\sigma} = 0.5, & a_{K,\sigma} = a_{L,\sigma} = 0.\\ \mu_{K,\sigma} = \frac{|a_{L,\sigma}|}{|a_{K,\sigma}| + |a_{L,\sigma}|}, \mu_{L,\sigma} = \frac{|a_{K,\sigma}|}{|a_{K,\sigma}| + |a_{L,\sigma}|}, & \text{otherwise.} \end{cases}$$
(14)

Here $a_{K,\sigma}$ and $a_{L,\sigma}$ are given by

$$a_{K,\sigma} = \sum_{i=1}^{N_{K,\sigma}} a_{K,\sigma,i} f_{K,i}^t,$$
$$a_{L,\sigma} = \sum_{i=1}^{N_{L,\sigma}} a_{L,\sigma,i} f_{L,i}^t.$$

Furthermore, define

$$B_{\sigma} = \begin{cases} \mu_{L,\sigma} a_{L,\sigma} - \mu_{K,\sigma} a_{K,\sigma}, & \sigma \in \mathcal{E}_K \cap \mathcal{E}_K, \\ -a_{K,\sigma}, & \sigma \in \mathcal{E}_K \cap \Gamma_D, \end{cases}$$
 (15)

and

$$B_{\sigma}^{+} = \frac{|B_{\sigma}| + B_{\sigma}}{2},$$
$$B_{\sigma}^{-} = \frac{|B_{\sigma}| - B_{\sigma}}{2}.$$

Clearly, $B_{\sigma}^{\pm} \geq 0$.

The final expression of $\tilde{F}_{K,\sigma}$ is

$$\tilde{F}_{K,\sigma} \approx A_{K,\sigma} f_K^{t+\Delta t} - A_{L,\sigma} f_L^{t+\Delta t} + \mathcal{O}(\epsilon).$$
 (16)

We will ignore the $\mathcal{O}(\epsilon)$ term from now on. For flux conservation, naturally,

$$\tilde{F}_{L,\sigma} \approx A_{L,\sigma} f_L^{t+\Delta t} - A_{K,\sigma} f_K^{t+\Delta t}.$$
 (17)

Here coefficients $A_{K,\sigma}$ and $A_{L,\sigma}$ are functions of f^t , so the above expression is a nonlinear two point flux approximation (NLTPF).

Combining above equations, we can find that expressions of $A_{K,\sigma}$ and $A_{L,\sigma}$ are given by

$$A_{K,\sigma} = \mu_{K,\sigma} \sum_{i=1}^{N_{K,\sigma}} a_{K,\sigma,i} + \frac{B_{\sigma}^+}{f_K^t + \epsilon},$$
$$A_{L,\sigma} = \mu_{L,\sigma} \sum_{i=1}^{N_{L,\sigma}} a_{L,\sigma,i} + \frac{B_{\sigma}^-}{f_L^t + \epsilon}.$$

If $\sigma \in \Gamma_D$, we denote it as σ_D , the face with Dirichlet boundary condition, then

$$\tilde{F}_{K,\sigma_D} \approx F_{K,\sigma_D} = \left(\sum_{i=1}^{N_{K,\sigma_D}} a_{K,\sigma_D,i} + \frac{B_{\sigma_D}^+}{f_K^t + \epsilon}\right) f_K^{t+\Delta t} - B_{\sigma_D}^-.$$
(18)

Note that the coefficient of $f_K^{t+\Delta t}$ is similar to $A_{K,\sigma}$ but with $\mu_{K,\sigma}=1$, so we define

$$A_{K,\sigma_D} = \sum_{i=1}^{N_{K,\sigma_D}} a_{K,\sigma_D,i} + \frac{B_{\sigma_D}^+}{f_K^t + \epsilon}.$$
 (19)

If $\sigma \in \Gamma_N$, we denote it as σ_N , the face with Neumann boundary condition, then the flux is given directly by the boundary condition; i.e.,

$$\tilde{F}_{K,\sigma_N} \approx -|\sigma_N| \boldsymbol{n}_{K,\sigma_N} \cdot \Lambda_K \cdot (\nabla f)_K.$$
 (20)

Putting things together, we have Equation (8) as

$$\frac{G_K V_K}{\Delta t} \left(f_K^{t+\Delta t} - f_K^t \right) = -\sum_{\sigma} \left(A_{K,\sigma} f_K^{t+\Delta t} - A_{L,\sigma} f_L^{t+\Delta t} \right) \tag{21}$$

$$-\left(\sum_{\sigma_D} A_{K,\sigma_D}\right) f_K^{t+\Delta t} \tag{22}$$

$$+\sum_{\sigma_D} B_{\sigma_D}^- + \sum_{\sigma_N} \left[\boldsymbol{n}_{K,\sigma_N} \cdot \Lambda_K \cdot \nabla f_K \right]. \tag{23}$$

Denoting $U_{KK} \equiv G_K V_K / \Delta t$, we rewrite the above equation

$$\begin{bmatrix} U_{KK} + \sum_{\sigma} A_{K,\sigma} + \sum_{\sigma_D} A_{K,\sigma_D} \end{bmatrix} f_K^{t+\Delta t} - \sum_{\sigma} A_{L,\sigma} f_{L,\sigma}^{t+\Delta t}$$
$$= \sum_{\sigma_D} B_{\sigma_D}^- + \sum_{\sigma_N} (\boldsymbol{n}_{K,\sigma_N} \cdot \Lambda_K \cdot \nabla f_K) + U_{KK} f_K^t.$$

The above equation can be written in the matrix form as

$$\mathsf{M} \cdot \boldsymbol{f}^{t+\Delta t} = \boldsymbol{R}. \tag{24}$$

where the right hand side vector R is given by

$$R_K = \sum_{\sigma_D} B_{\sigma_D}^- + \sum_{\sigma_N} (\boldsymbol{n}_{K,\sigma_N} \cdot \Lambda_K \cdot \nabla f_K) + U_{KK} f_K^t.$$
 (25)

The matrix M has the following components:

$$M_{KK} = U_{KK} + \sum_{\sigma} A_{K,\sigma} + \sum_{\sigma_D} A_{K,\sigma_D},$$

$$M_{KL} = -A_{L,\sigma}.$$

where L is the neighboring cell of K sharing the face σ . By construction, $R_K > 0$, and M has the following properties $M_{KK} > 0$, and $M_{KL} < 0$, and the summation along the K_{th} column is nonnegative; i.e.,

$$\sum_{L} M_{LK} \ge 0. \tag{26}$$

To see this, we note that $M_{LK}=-A_{K,\sigma}$; therefore,

$$\sum_{L} M_{LK} = U_{KK} + \sum_{\sigma_D} A_{K,\sigma_D} \ge 0.$$
(27)

These properties of M makes it an M-matrix.