

Homework for Chapter 2 (Theoretical Questions)

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Problem I.

It is clear that $\mathcal{C}[a, b]$ is a vector space. We need to show that it is an inner product space.

(1) Real positivity:

$$\forall u \in \mathcal{C}[a, b], \quad \langle u, u \rangle = \int_a^b \rho(t) u(t) \overline{u(t)} dt = \int_a^b \rho(t) |u(t)|^2 dt \geq 0.$$

(2) Definiteness:

$$\langle u, u \rangle = 0 \Leftrightarrow \rho(t) |u(t)|^2 = 0 \Leftrightarrow |u(t)|^2 = 0 \Leftrightarrow u = 0$$

(3) Linearity in the first slot:

$$\begin{aligned} \forall u, v, w \in \mathcal{C}[a, b], \quad \langle u + w, v \rangle &= \int_a^b \rho(t) (u(t) + w(t)) \overline{v(t)} dt = \int_a^b \rho(t) u(t) \overline{v(t)} dt + \int_a^b \rho(t) w(t) \overline{v(t)} dt = \langle u, v \rangle + \langle w, v \rangle \\ \forall c \in \mathbb{C}, \quad \forall u, v \in \mathcal{C}[a, b], \quad \langle cu, v \rangle &= c \int_a^b \rho(t) u(t) \overline{v(t)} dt = c \langle u, v \rangle \end{aligned}$$

(4) conjugate symmetry:

$$\forall u, v \in \mathcal{C}[a, b] \quad \langle u, v \rangle = \int_a^b \rho(t) u(t) \overline{v(t)} dt = \overline{\int_a^b \overline{\rho(x) u(x) \overline{v(x)}} dx} = \overline{\int_a^b \rho(x) v(x) \overline{u(x)} dx} = \overline{\langle v, u \rangle}$$

We also need to verify the requirements of a norm,

(1) real positivity:

$$\|u\|_2 = \left(\int_a^b \rho(t) |u(t)|^2 dt \right)^{1/2} \geq 0, \quad \text{with } \|u\|_2 = 0 \Leftrightarrow u \equiv 0.$$

(2) homogeneity:

$$\forall c \in \mathbb{C}, \quad \|cu\|_2 = \left(\int_a^b \rho(t) |cu(t)|^2 dt \right)^{1/2} = |c| \left(\int_a^b \rho(t) |u(t)|^2 dt \right)^{1/2} = |c| \|u\|_2$$

(3) triangle inequality:

$$\forall u, v \in \mathcal{C}[a, b], \quad \|u + v\|_2 = \left(\int_a^b \rho(x) |u(x) + v(x)|^2 dx \right)^{1/2}$$

$$\leq \left(\int_a^b \rho(x) |u(x)|^2 dx \right)^{1/2} + \left(\int_a^b \rho(x) |v(x)|^2 dx \right)^{1/2} = \|u\|_2 + \|v\|_2$$

Problem II.

By definition, $T_n(x) = \cos(n \arccos(x))$,

(a) For any m, n , we have

$$\begin{aligned} \langle T_m, T_n \rangle &= \int_{-1}^1 \rho(t) T_n(t) \overline{T_m(t)} dt \\ &= \int_{-1}^1 \frac{\cos(n \arccos t) \cos(m \arccos t)}{\sqrt{1-t^2}} dt \\ &= \int_0^\pi \cos(m\theta) \cos(n\theta) d\theta \\ &= \int_0^\pi \frac{\cos(m\theta + n\theta)}{\cos(m\theta - n\theta)} d\theta \\ &= \begin{cases} \cos \frac{\pi}{2}, & m = n \neq 0 \\ 0, & m \neq n \\ \pi, & m = n = 0 \end{cases} \end{aligned}$$

Therefore, T_n are orthogonal.

(b) We have $T_0(x) = 1$, $T_1(x) = x$ and $T_2(x) = 2x^2 - 1$. After normalization, we obtain $T_0^*(x) = \frac{1}{\sqrt{\pi}}$,

$$T_1^*(x) = \sqrt{\frac{\pi}{2}}x \text{ and } T_2^*(x) = \sqrt{\frac{2}{\pi}}(2x^2 - 1).$$

Problem III.

(a) With the basis (T_0^*, T_1^*, T_2^*) , the Fourier coefficients are $\langle y, T_0^* \rangle = \frac{2}{\sqrt{\pi}}$, $\langle y, T_1^* \rangle = 0$, $\langle y, T_2^* \rangle = -\frac{2}{3}\sqrt{\frac{2}{\pi}}$,

the approximate function is $\hat{\phi}(x) = \frac{2}{\sqrt{\pi}}T_0^* + 0T_1^* - \frac{2}{3}\sqrt{\frac{2}{\pi}}T_2^* = \frac{10}{3\pi} - \frac{8}{3\pi}x^2$.

(b) Since

$$G(1, x, x^2) = \begin{bmatrix} \langle 1, 1 \rangle & \langle 1, x \rangle & \langle 1, x^2 \rangle \\ \langle 1, 1 \rangle & \langle 1, x \rangle & \langle 1, x^2 \rangle \\ \langle 1, 1 \rangle & \langle 1, x \rangle & \langle 1, x^2 \rangle \end{bmatrix} = \begin{bmatrix} \pi & 0 & \frac{\pi}{2} \\ 0 & \frac{\pi}{2} & 0 \\ \frac{\pi}{2} & 0 & \frac{3\pi}{2} \end{bmatrix},$$

$$c = (\langle y, 1 \rangle, \langle y, x \rangle, \langle y, x^2 \rangle)^T = (2, 0, 3)^T,$$

By solving the equation $G^T a = c$, we obtain $a = (\frac{10}{3\pi}, 0, -\frac{8}{3\pi})^T$. Hence the approximate function is

$$\hat{\phi}(x) = \frac{10}{3\pi} - \frac{8}{3\pi}x^2.$$

Problem IV.

(a) Using the monomials $(1, x, x^2)$, with inner product $\langle u, v \rangle = \sum_i^{12} u(t_i)v(t_i)$, we have

$$\begin{aligned} u_1 &= v_1 = 1, \|v_1\| = \sqrt{12}, u_1^* = \frac{1}{2\sqrt{3}}, \\ v_2 &= u_2 - \langle u_2, u_1^* \rangle u_1^* = x - \frac{13}{2}, u_2^* = \frac{1}{\sqrt{143}}(x - \frac{13}{2}), \\ v_3 &= u_3 - \langle u_3, u_1^* \rangle u_1^* - \langle u_3, u_2^* \rangle u_2^* = x^2 - 13x + \frac{91}{3}, u_3^* = \sqrt{\frac{3}{4004}}(x^2 - 13x + \frac{91}{3}). \end{aligned}$$

(b) The best approximate function is

$$\begin{aligned} \hat{\varphi}(x) &= \langle y, u_1^* \rangle u_1^* + \langle y, u_2^* \rangle u_2^* + \langle y, u_3^* \rangle u_3^* \\ &= \frac{831}{\sqrt{3}} u_1^* + \frac{589}{\sqrt{143}} u_2^* + \frac{12068\sqrt{3}}{\sqrt{4004}} u_3^* \\ &\approx 9.042x^2 - 113.4266x + 386.0013 \end{aligned}$$

(c) The orthonormal polynomials can be reused but the normal equation cannot be reused. Due to we need to recalculated G and solving equation but the previous method just renew index of basis, therefore orthonormal polynomials has advantage over normal equations.

Problem V.

Proof of Thm 5.60. (PDI-1) For any $x \in \mathbb{F}^n$, we have

$$AA^+x = A \left(\sum_{j=1}^r \frac{1}{\sigma_j} \langle x, v_j \rangle u_j \right) = A \frac{\sigma_j}{\sigma_j} x = Ax.$$

Hence $AA^+A = A$ since x is arbitrary.

(PDI-2) For $j = 1, 2, \dots, r$, $A^+AA^+v_j = A^+A \frac{1}{\sigma_j} u_j = A^+v_j$; for $j = r+1, r+2, \dots, n$, $A^+AA^+v_j = 0 = A^+v_j$.

(PDI-3) From above conclusions, for $v \in \mathbb{F}^m$,

$$AA^+v = \text{diag}(1, \dots, 1, 0, \dots, 0) \begin{pmatrix} v_1 \\ \vdots \\ v_r \\ \vdots \\ v_m \end{pmatrix} = \begin{pmatrix} v_1 \\ \vdots \\ v_m \\ 0 \\ \vdots \\ 0 \end{pmatrix}.$$

Hence $(AA^+)^* = AA^+$. Similarly we have $(A^+A)^* = A^+A$

□

Proof of Lemma 5.61. Let A be a matrix with linearly independent columns. Then the product A^*A is invertible. To show this, consider any vector x in the kernel of A^*A , such that $A^*Ax = 0$. Pre-multiplying by x^* gives $x^*A^*Ax = 0$, which implies $(Ax)^*(Ax) = 0$. Therefore, $Ax = 0$. Since A has linearly independent columns, this implies $x = 0$, and the kernel of A^*A only contains the zero vector, making A^*A full rank and invertible.

Now, for any matrix A with linearly independent columns, the pseudoinverse A^+ is given by $A^+ = (A^*A)^{-1}A^*$. This is a left inverse of A because:

$$\begin{aligned} A^+A &= (A^*A)^{-1}A^*A \\ &= I. \end{aligned}$$

Similarly, if A has linearly independent rows, then AA^* is invertible, and the pseudoinverse A^+ is given by $A^+ = A^*(AA^*)^{-1}$, which is a right inverse of A because:

$$\begin{aligned} AA^+ &= AA^*(AA^*)^{-1} \\ &= I. \end{aligned}$$

□